

PreprocessParquet

December 11, 2023

```
[ ]: PATH = '../Dataset_GISLR/asl-signs/'  
      PROCESSED_OUTPUT_PATH = '../Dataset_GISLR_Processed/'
```

```
[ ]: import cv2  
  
      import numpy as np  
      import pandas as pd  
      from PIL import Image  
  
      from ipywidgets import interact, interactive, fixed, interact_manual  
      import ipywidgets as widgets  
  
      import mediapipe as mp  
      from mediapipe.framework.formats import landmark_pb2  
      mp_drawing = mp.solutions.drawing_utils  
      mp_drawing_styles = mp.solutions.drawing_styles  
      mp_holistic = mp.solutions.holistic  
      import numpy as np  
      import matplotlib.pyplot as plt  
      import math  
      import json  
      import os  
      import concurrent.futures
```

Iterate over every parquet and do the following: - Find the first 10 frames that contain a consecutive left or right hand - Convert the 10 frames into a mediapipe result structure - Convert each mediapipe result into a numpy array that will be used for training - Store the numpy array into the folder with the matching label/category/sign

```
[ ]: def   
      ↪ draw_landmarks(landmarks, image, show_pose=True, show_face_contour=True, show_face_tesselation=  
      ↪  
      annotated_image = image.copy()  
      results = landmarks  
      if show_face_tesselation:  
          mp_drawing.draw_landmarks(  
              annotated_image,  
              results.face_landmarks,
```

```

        mp_holistic.FACEMESH_TESSELATION,
        landmark_drawing_spec=None,
        connection_drawing_spec=mp_drawing_styles
            .get_default_face_mesh_tesselation_style())
    if show_face_contour:
        mp_drawing.draw_landmarks(
            annotated_image,
            results.face_landmarks,
            mp_holistic.FACEMESH_CONTOURS,
            landmark_drawing_spec=None,
            connection_drawing_spec=mp_drawing_styles
                .get_default_face_mesh_contours_style())
    if show_pose:
        mp_drawing.draw_landmarks(
            annotated_image,
            results.pose_landmarks,
            mp_holistic.POSE_CONNECTIONS,
            landmark_drawing_spec=mp_drawing_styles
                .get_default_pose_landmarks_style())
    if show_left_hand:
        mp_drawing.draw_landmarks(
            annotated_image,
            results.left_hand_landmarks,
            mp_holistic.HAND_CONNECTIONS,
            landmark_drawing_spec=mp_drawing_styles
                .get_default_hand_landmarks_style())
    if show_right_hand:
        mp_drawing.draw_landmarks(
            annotated_image,
            results.right_hand_landmarks,
            mp_holistic.HAND_CONNECTIONS,
            landmark_drawing_spec=mp_drawing_styles
                .get_default_hand_landmarks_style())
    return annotated_image

def display_image(img):
    plt.imshow(img)
    plt.axis('off') # Turn off the axis
    plt.show()

```

```

[ ]: def get_avg(example_landmark):
    filtered_landmarks = example_landmark.dropna(subset=["x", "y", "z"])
    filtered_landmarks = filtered_landmarks[(filtered_landmarks[["x", "y", "z"]]
↪ "z"] != 0).all(axis=1)]

    # Get the number of landmarks with x, y, z data per type
    landmarks_count = filtered_landmarks["type"].value_counts()

```

```

meta = landmarks_count.to_dict()
meta["frames"] = filtered_landmarks["frame"].nunique()

# Identify unique frames with left and right hand landmarks
left_hand_frames = filtered_landmarks[filtered_landmarks['type'] == 'left_hand']['frame'].nunique()
right_hand_frames = filtered_landmarks[filtered_landmarks['type'] == 'right_hand']['frame'].nunique()
print(f"Left hand frames: {left_hand_frames}")
print(f"Right hand frames: {right_hand_frames}")

```

```

[ ]: from mediapipe.framework.formats import landmark_pb2

class Landmarks(object):
    pass

def get_landmarks_from_parquet(pf, frame):
    f = pf[pf.frame == frame]
    face = landmark_pb2.NormalizedLandmarkList()
    for t in f[f.type == 'face'][['x', 'y', 'z']].itertuples(index=False):
        face.landmark.add(x=t.x, y=t.y, z=t.z)
    pose = landmark_pb2.NormalizedLandmarkList()
    for t in f[f.type == 'pose'][['x', 'y', 'z']].itertuples(index=False):
        pose.landmark.add(x=t.x, y=t.y, z=t.z)
    left_hand = landmark_pb2.NormalizedLandmarkList()
    for t in f[f.type == 'left_hand'][['x', 'y', 'z']].itertuples(index=False):
        left_hand.landmark.add(x=t.x, y=t.y, z=t.z)
    right_hand = landmark_pb2.NormalizedLandmarkList()
    for t in f[f.type == 'right_hand'][['x', 'y', 'z']].itertuples(index=False):
        right_hand.landmark.add(x=t.x, y=t.y, z=t.z)
    result = Landmarks()
    result.face_landmarks = face
    result.pose_landmarks = pose
    result.left_hand_landmarks = left_hand
    result.right_hand_landmarks = right_hand
    return result

```

```

[ ]: df = pd.read_csv(PATH + 'train.csv')
df.head()

```

```

[ ]:

```

	path	participant_id	sequence_id	\
0	train_landmark_files/26734/1000035562.parquet	26734	1000035562	
1	train_landmark_files/28656/1000106739.parquet	28656	1000106739	
2	train_landmark_files/16069/100015657.parquet	16069	100015657	
3	train_landmark_files/25571/1000210073.parquet	25571	1000210073	
4	train_landmark_files/62590/1000240708.parquet	62590	1000240708	

```

    sign
0   blow
1   wait
2   cloud
3   bird
4   owie

```

```

[ ]: def decide_which_array_to_use(left_hand_frames, right_hand_frames):
    if left_hand_frames and right_hand_frames:
        # right hand is more important
        return right_hand_frames
    elif left_hand_frames:
        return left_hand_frames
    elif right_hand_frames:
        return right_hand_frames
    else:
        return None

def are_landmarks_valid(landmarks):
    return all(not math.isnan(landmark.x) and not math.isnan(landmark.y) and
↳not math.isnan(landmark.z) for landmark in landmarks.landmark)

def display_all_frames(landmarks_array):
    for i in range(len(landmarks_array)):
        if are_landmarks_valid(landmarks_array[i].pose_landmarks):
            annotated_image = np.zeros((1024,1024,3),dtype=np.uint8)
            annotated_image = draw_landmarks(landmarks_array[i],annotated_image)
            display_image(annotated_image)

def find_first_10_consecutive_frames(landmarks_array, hand_type):
    consecutive_frames = []
    first_10_frames = []

    for landmarks in landmarks_array:
        if hand_type == "left":
            has_valid_hand = are_landmarks_valid(landmarks.left_hand_landmarks)
        elif hand_type == "right":
            has_valid_hand = are_landmarks_valid(landmarks.right_hand_landmarks)
        else:
            raise ValueError("Hand type must be 'left' or 'right'")

        if has_valid_hand:
            consecutive_frames.append(landmarks)
            if len(consecutive_frames) == 10:
                first_10_frames = consecutive_frames.copy()
                break
    else:

```

```

        consecutive_frames = []

    return first_10_frames

def process_parquet_file(parquet_file):
    pf = pd.read_parquet(PATH + parquet_file)
    frame_numbers = pf.frame.unique()
    landmarks_array = [get_landmarks_from_parquet(pf, frame) for frame in
↳frame_numbers]

    first_10_frames_with_left_hand =
↳find_first_10_consecutive_frames(landmarks_array, "left")
    first_10_frames_with_right_hand =
↳find_first_10_consecutive_frames(landmarks_array, "right")
    chosen_frames = decide_which_array_to_use(first_10_frames_with_left_hand,
↳first_10_frames_with_right_hand)
    return chosen_frames

```

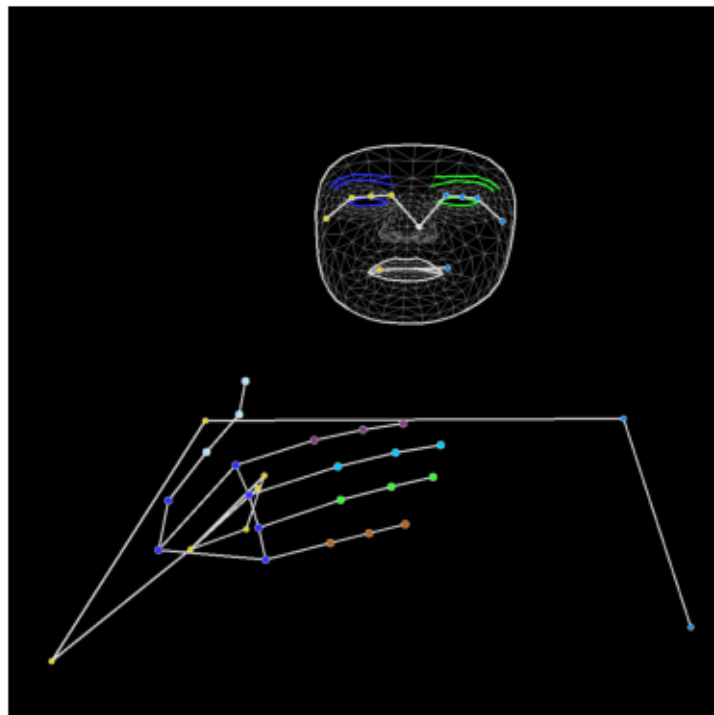
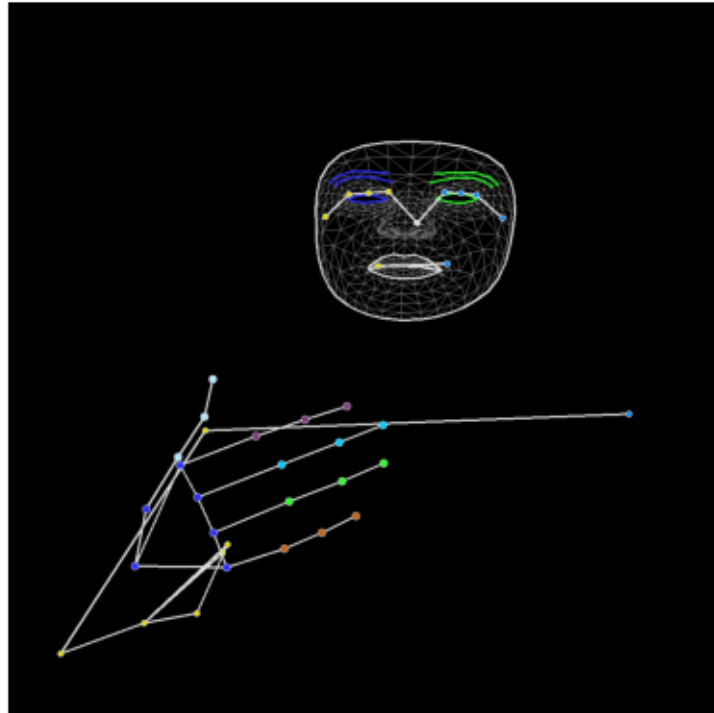
```

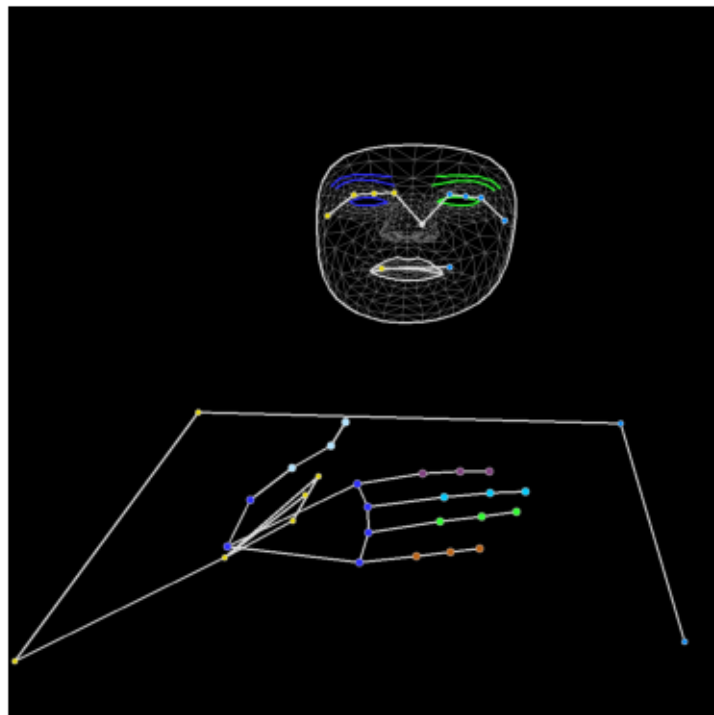
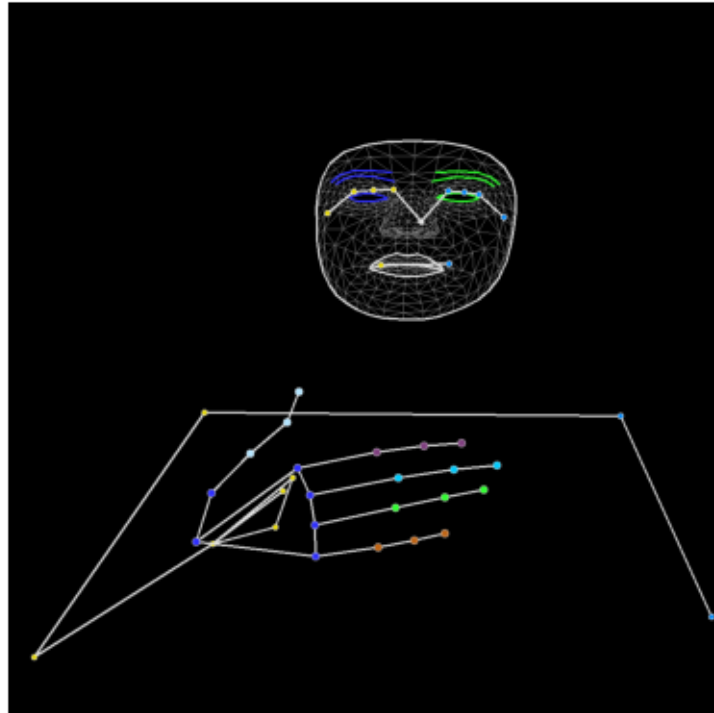
[ ]: def display_index(index):
    parquet_file = df.iloc[index].path
    print(f"Sign: {df.iloc[index].sign}")
    chosen_frames = process_parquet_file(parquet_file)
    if chosen_frames is None:
        return None
    display_all_frames(chosen_frames)

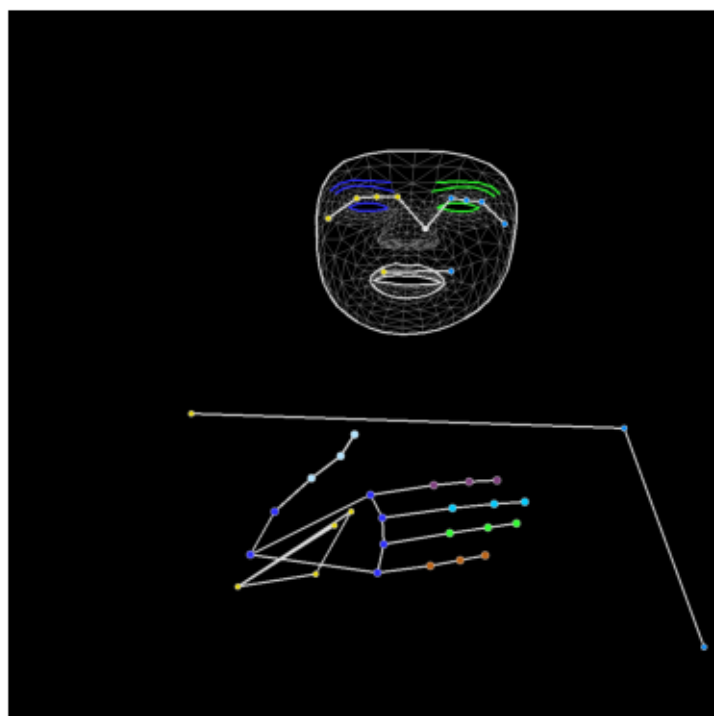
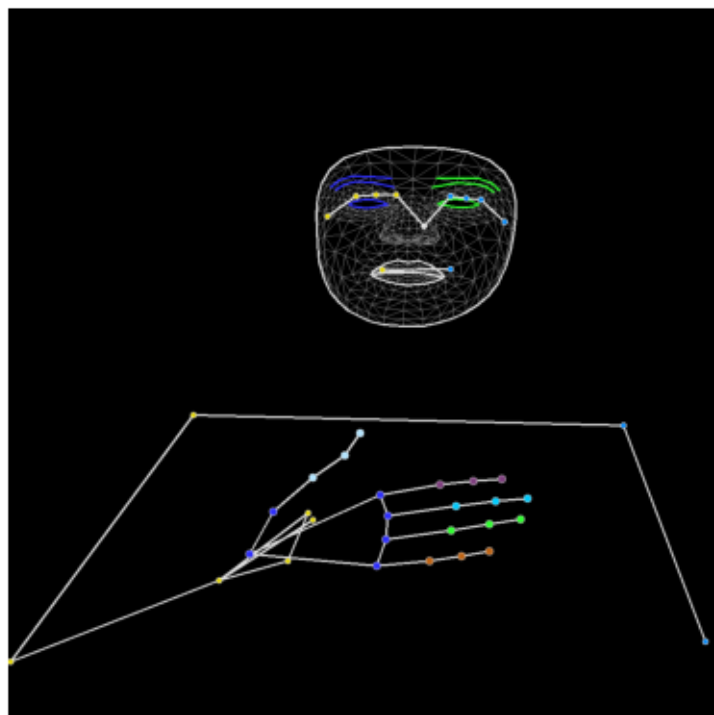
display_index(6)

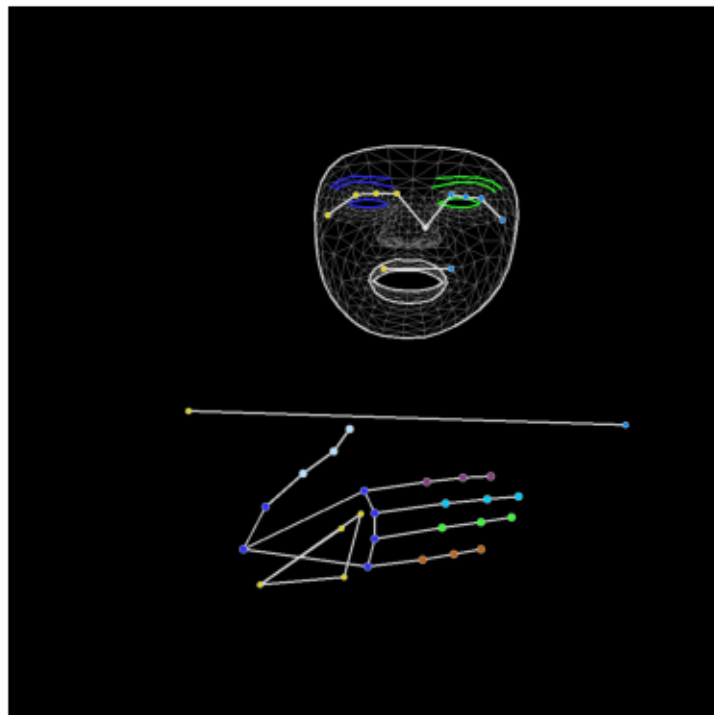
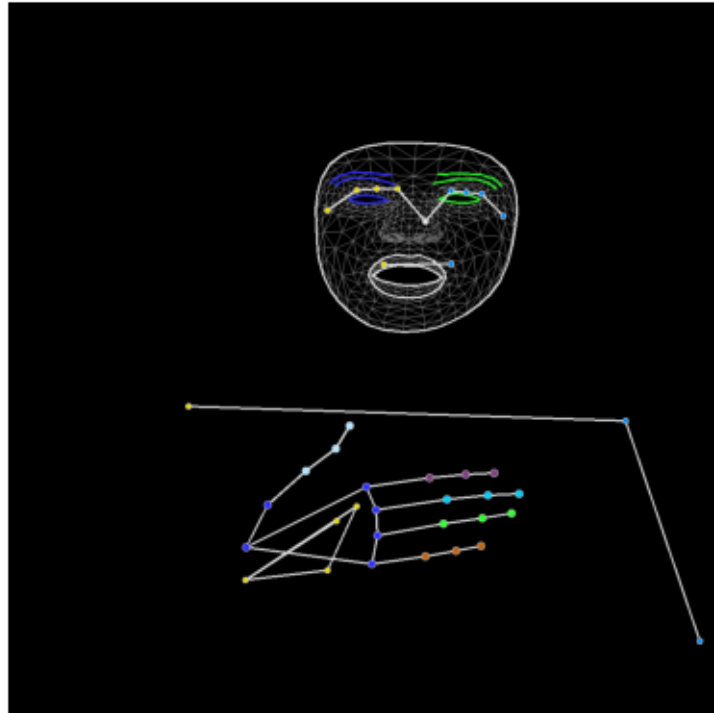
```

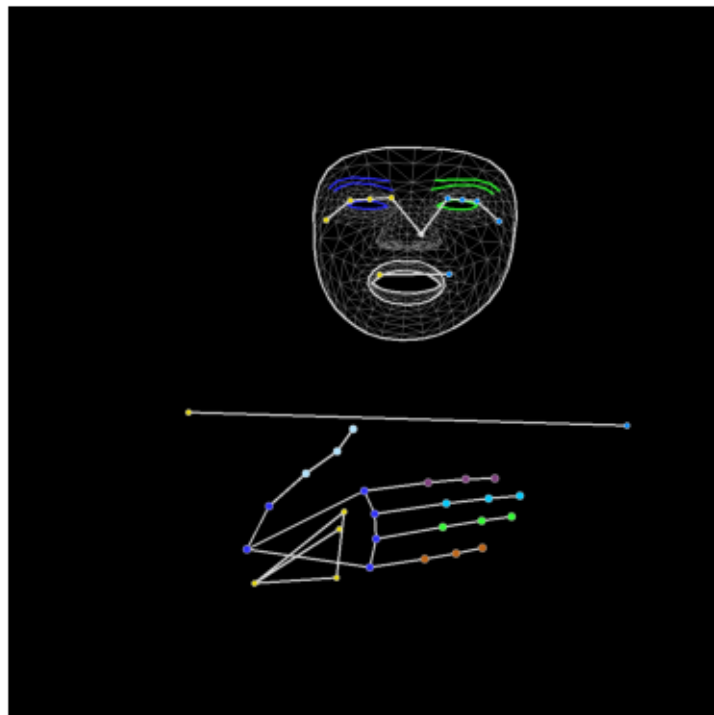
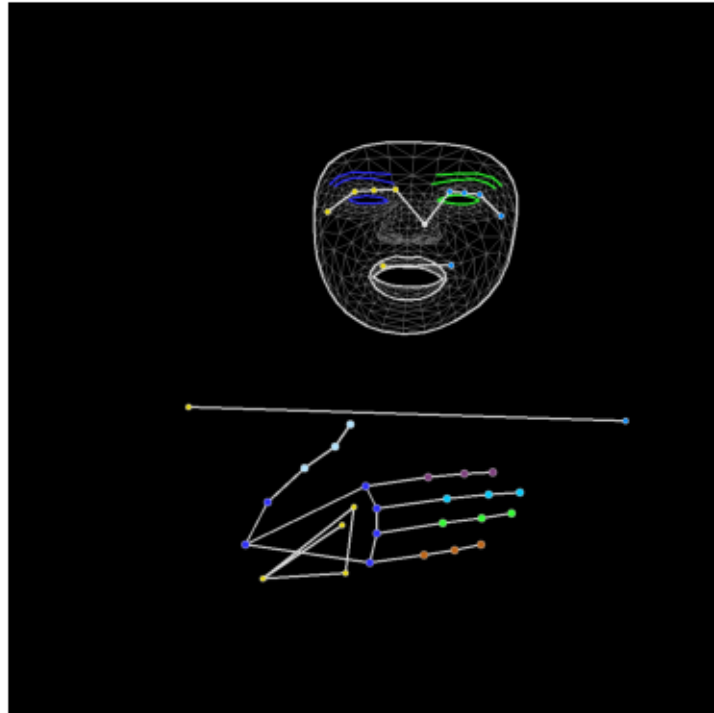
Sign: minemy











```
[ ]: def load_json_file(file_path):
    with open(file_path, 'r') as file:
        data = json.load(file)
    return data
json_file_path = PATH + 'sign_to_prediction_index_map.json'
category_dict = load_json_file(json_file_path)
print(category_dict)
```

```
{'TV': 0, 'after': 1, 'airplane': 2, 'all': 3, 'alligator': 4, 'animal': 5,
'another': 6, 'any': 7, 'apple': 8, 'arm': 9, 'aunt': 10, 'awake': 11,
'backyard': 12, 'bad': 13, 'balloon': 14, 'bath': 15, 'because': 16, 'bed': 17,
'bedroom': 18, 'bee': 19, 'before': 20, 'beside': 21, 'better': 22, 'bird': 23,
'black': 24, 'blow': 25, 'blue': 26, 'boat': 27, 'book': 28, 'boy': 29,
'brother': 30, 'brown': 31, 'bug': 32, 'bye': 33, 'callonphone': 34, 'can': 35,
'car': 36, 'carrot': 37, 'cat': 38, 'cereal': 39, 'chair': 40, 'cheek': 41,
'child': 42, 'chin': 43, 'chocolate': 44, 'clean': 45, 'close': 46, 'closet':
47, 'cloud': 48, 'clown': 49, 'cow': 50, 'cowboy': 51, 'cry': 52, 'cut': 53,
'cute': 54, 'dad': 55, 'dance': 56, 'dirty': 57, 'dog': 58, 'doll': 59,
'donkey': 60, 'down': 61, 'drawer': 62, 'drink': 63, 'drop': 64, 'dry': 65,
'dryer': 66, 'duck': 67, 'ear': 68, 'elephant': 69, 'empty': 70, 'every': 71,
'eye': 72, 'face': 73, 'fall': 74, 'farm': 75, 'fast': 76, 'feet': 77, 'find':
78, 'fine': 79, 'finger': 80, 'finish': 81, 'fireman': 82, 'first': 83, 'fish':
84, 'flag': 85, 'flower': 86, 'food': 87, 'for': 88, 'frenchfries': 89, 'frog':
90, 'garbage': 91, 'gift': 92, 'giraffe': 93, 'girl': 94, 'give': 95,
'glasswindow': 96, 'go': 97, 'goose': 98, 'grandma': 99, 'grandpa': 100,
'grass': 101, 'green': 102, 'gum': 103, 'hair': 104, 'happy': 105, 'hat': 106,
'hate': 107, 'have': 108, 'haveto': 109, 'head': 110, 'hear': 111, 'helicopter':
112, 'hello': 113, 'hen': 114, 'hesheit': 115, 'hide': 116, 'high': 117, 'home':
118, 'horse': 119, 'hot': 120, 'hungry': 121, 'icecream': 122, 'if': 123,
'into': 124, 'jacket': 125, 'jeans': 126, 'jump': 127, 'kiss': 128, 'kitty':
129, 'lamp': 130, 'later': 131, 'like': 132, 'lion': 133, 'lips': 134, 'listen':
135, 'look': 136, 'loud': 137, 'mad': 138, 'make': 139, 'man': 140, 'many': 141,
'milk': 142, 'minemy': 143, 'mitten': 144, 'mom': 145, 'moon': 146, 'morning':
147, 'mouse': 148, 'mouth': 149, 'nap': 150, 'napkin': 151, 'night': 152, 'no':
153, 'noisy': 154, 'nose': 155, 'not': 156, 'now': 157, 'nuts': 158, 'old': 159,
'on': 160, 'open': 161, 'orange': 162, 'outside': 163, 'owie': 164, 'owl': 165,
'pajamas': 166, 'pen': 167, 'pencil': 168, 'penny': 169, 'person': 170, 'pig':
171, 'pizza': 172, 'please': 173, 'police': 174, 'pool': 175, 'potty': 176,
'pretend': 177, 'pretty': 178, 'puppy': 179, 'puzzle': 180, 'quiet': 181,
'radio': 182, 'rain': 183, 'read': 184, 'red': 185, 'refrigerator': 186, 'ride':
187, 'room': 188, 'sad': 189, 'same': 190, 'say': 191, 'scissors': 192, 'see':
193, 'shhh': 194, 'shirt': 195, 'shoe': 196, 'shower': 197, 'sick': 198,
'sleep': 199, 'sleepy': 200, 'smile': 201, 'snack': 202, 'snow': 203, 'stairs':
204, 'stay': 205, 'sticky': 206, 'store': 207, 'story': 208, 'stuck': 209,
'sun': 210, 'table': 211, 'talk': 212, 'taste': 213, 'thankyou': 214, 'that':
215, 'there': 216, 'think': 217, 'thirsty': 218, 'tiger': 219, 'time': 220,
'tomorrow': 221, 'tongue': 222, 'tooth': 223, 'toothbrush': 224, 'touch': 225,
'toy': 226, 'tree': 227, 'uncle': 228, 'underwear': 229, 'up': 230, 'vacuum':
```

```
231, 'wait': 232, 'wake': 233, 'water': 234, 'wet': 235, 'weus': 236, 'where':
237, 'white': 238, 'who': 239, 'why': 240, 'will': 241, 'wolf': 242, 'yellow':
243, 'yes': 244, 'yesterday': 245, 'yourself': 246, 'yucky': 247, 'zebra': 248,
'zipper': 249}
```

```
[ ]: # size of df
print(len(df))
NUM_TO_TRAIN = len(df)
print(NUM_TO_TRAIN)
```

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```
[ ]: def extract_keypoints(results):
    pose = np.array([res.x, res.y, res.z, res.visibility] for res in results.
    ↪pose_landmarks.landmark]).flatten() if results.pose_landmarks else np.
    ↪zeros(33*4)
    face = np.array([res.x, res.y, res.z] for res in results.face_landmarks.
    ↪landmark]).flatten() if results.face_landmarks else np.zeros(468*3)
    lh = np.array([res.x, res.y, res.z] for res in results.left_hand_landmarks.
    ↪landmark]).flatten() if results.left_hand_landmarks else np.zeros(21*3)
    rh = np.array([res.x, res.y, res.z] for res in results.
    ↪right_hand_landmarks.landmark]).flatten() if results.right_hand_landmarks
    ↪else np.zeros(21*3)
    return np.concatenate([pose, face, lh, rh])

def process_and_save_sequences(index, output_folder):
    parquet_file = df.iloc[index].path
    label = df.iloc[index].sign
    name = df.iloc[index].sequence_id

    label_folder = os.path.join(output_folder, label)
    os.makedirs(label_folder, exist_ok=True)

    # make file name with name
    file_name = str(name) + ".npy"
    seq_file = os.path.join(label_folder, file_name)
    # print(f"Processing {seq_file}...")

    # check if file exists
    if os.path.isfile(seq_file):
        # print(f"File {seq_file} already exists. Skipping...")
        return None

    chosen_frames = process_parquet_file(parquet_file)
    if chosen_frames is None:
        return None
```

```

window = []
for frame in chosen_frames:
    window.append(extract_keypoints(frame))

np.save(seq_file, np.array(window))

max_threads = os.cpu_count() # Specify the number of threads you want to use
print(f"Using {max_threads} threads")
with concurrent.futures.ThreadPoolExecutor(max_workers=max_threads) as executor:
    futures = {executor.submit(process_and_save_sequences, i, □
        ↪ PROCESSED_OUTPUT_PATH): i for i in range(NUM_TO_TRAIN)}
    concurrent.futures.wait(futures)

```

Using 16 threads

Train

December 11, 2023

```
[ ]: PATH = '../Dataset_GISLR/asl-signs/'  
      PROCESSED_OUTPUT_PATH = '../Dataset_GISLR_Processed/'  
      MODEL_VERSION = 'high-perform-test'  
      save_low_performers = True  
      save_high_performers = False
```

```
[ ]: import cv2  
  
      import numpy as np  
      import pandas as pd  
      from PIL import Image  
  
      from ipywidgets import interact, interactive, fixed, interact_manual  
      import ipywidgets as widgets  
  
      import mediapipe as mp  
      from mediapipe.framework.formats import landmark_pb2  
      mp_drawing = mp.solutions.drawing_utils  
      mp_drawing_styles = mp.solutions.drawing_styles  
      mp_holistic = mp.solutions.holistic  
      import numpy as np  
      import matplotlib.pyplot as plt  
      import math  
      import json  
      import os  
      from sklearn.model_selection import train_test_split  
      from tensorflow.keras.utils import to_categorical  
      from tensorflow.keras.models import Sequential  
      from keras.layers import LSTM, Dense, Dropout, BatchNormalization  
      from tensorflow.keras.callbacks import TensorBoard  
      from keras.optimizers import Adam  
      from keras.callbacks import EarlyStopping, ReduceLROnPlateau  
      from tensorflow.keras.mixed_precision import set_global_policy  
      import matplotlib.pyplot as plt  
      import pandas as pd  
      from sklearn.metrics import classification_report  
      import numpy as np
```

```
from sklearn.metrics import accuracy_score, precision_score, recall_score,
    f1_score, mean_squared_error, mean_absolute_error
```

```
2023-12-02 08:37:44.380617: E
tensorflow/compiler/xla/stream_executor/cuda/cuda_dnn.cc:9342] Unable to
register cuDNN factory: Attempting to register factory for plugin cuDNN when one
has already been registered
2023-12-02 08:37:44.380665: E
tensorflow/compiler/xla/stream_executor/cuda/cuda_fft.cc:609] Unable to register
cuFFT factory: Attempting to register factory for plugin cuFFT when one has
already been registered
2023-12-02 08:37:44.380683: E
tensorflow/compiler/xla/stream_executor/cuda/cuda_blas.cc:1518] Unable to
register cuBLAS factory: Attempting to register factory for plugin cuBLAS when
one has already been registered
2023-12-02 08:37:44.385081: I tensorflow/core/platform/cpu_feature_guard.cc:182]
This TensorFlow binary is optimized to use available CPU instructions in
performance-critical operations.
To enable the following instructions: AVX2 FMA, in other operations, rebuild
TensorFlow with the appropriate compiler flags.
/usr/lib/python3/dist-packages/scipy/__init__.py:146: UserWarning: A NumPy
version >=1.17.3 and <1.25.0 is required for this version of SciPy (detected
version 1.26.2
    warnings.warn(f"A NumPy version >={np_minversion} and <{np_maxversion}")
```

Load the Labels from the PreProcessed Data. Optionally filter out labels to remove any identified low performing labels.

```
[ ]: signs_to_train = [name for name in os.listdir(PROCESSED_OUTPUT_PATH) if os.path.
    isdir(os.path.join(PROCESSED_OUTPUT_PATH, name))]

low_performing_labels_file_path = 'low_performing_labels.npy'
low_performing_labels = np.array([])
if os.path.exists(low_performing_labels_file_path):
    low_performing_labels = np.load(low_performing_labels_file_path,
    allow_pickle=True)
print(len(low_performing_labels))

high_performing_labels_file_path = 'high_performing_labels.npy'
high_performing_labels = np.array([])
if os.path.exists(high_performing_labels_file_path):
    high_performing_labels = np.load(high_performing_labels_file_path,
    allow_pickle=True)
print(len(high_performing_labels))

# remove low performing labels from signs_to_train
signs_to_train = [x for x in signs_to_train if x not in low_performing_labels]
print(len(signs_to_train))
```

```

# remove all non high performers
if (len(high_performing_labels) > 0):
    signs_to_train = [x for x in signs_to_train if x in high_performing_labels]
    print(len(signs_to_train))

signs_to_train.sort()
actions = np.array(signs_to_train)
print(actions)

```

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53

```

['aunt' 'bird' 'black' 'brother' 'brown' 'bug' 'callonphone' 'cheek'
 'clown' 'cow' 'cute' 'dad' 'doll' 'donkey' 'drink' 'ear' 'eye' 'feet'
 'find' 'fireman' 'flower' 'for' 'frog' 'grandpa' 'grass' 'gum' 'hair'
 'hen' 'home' 'horse' 'lamp' 'mad' 'mom' 'mouse' 'nose' 'owl' 'pig'
 'police' 'radio' 'see' 'shhh' 'shirt' 'sick' 'stairs' 'stuck' 'taste'
 'thirsty' 'tiger' 'uncle' 'water' 'who' 'yucky' 'zebra']

```

Load all of the pre processed data

```

[ ]: label_map = {label:num for num, label in enumerate(actions)}

sequences, labels = [], []

for label_folder in os.listdir(PROCESSED_OUTPUT_PATH):
    label = label_folder # Use the folder name as the label
    if (label not in signs_to_train):
        continue

    if (label in low_performing_labels):
        print("Skipping label: ", label)
        continue

    label_folder_path = os.path.join(PROCESSED_OUTPUT_PATH, label_folder)

    # Iterate through the files in the label folder (each file is a sequence)
    for sequence_file in os.listdir(label_folder_path):
        if sequence_file.endswith('.npy'):
            # Load the sequence from the file
            sequence = np.load(os.path.join(label_folder_path, sequence_file))

            # Append the sequence and label to the respective lists
            sequences.append(sequence)
            labels.append(label_map[label])

```

```

[ ]: X = np.array(sequences)
print(X.shape)

```


(13288, 10, 1662)

```
[ ]: y = to_categorical(labels).astype(int)
      print(y.shape)
```

(13288, 53)

Test train split all of the data

```
[ ]: # First, split the data into training and a combined validation/test set
      X_train, X_temp, y_train, y_temp = train_test_split(X, y, test_size=0.3) #
      ↪ Adjust the test_size as needed

      # Now, split the combined validation/test set into separate validation and test
      ↪ sets
      X_val, X_test, y_val, y_test = train_test_split(X_temp, y_temp, test_size=0.5) #
      ↪ This will split the remaining 30% into two 15% sets
```

```
[ ]: print(y_test.shape)
      print(y_val.shape)
      print(y_train.shape)
```

(1994, 53)

(1993, 53)

(9301, 53)

Replace all nan else the model will not train correctly

```
[ ]: # Check for NaN values in the datasets
      print(f"NaNs in X_train: {np.isnan(X_train).any()}, NaNs in y_train: {np.
      ↪ isnan(y_train).any()}")
      print(f"NaNs in X_val: {np.isnan(X_val).any()}, NaNs in y_val: {np.isnan(y_val).
      ↪ any()}")
      print(f"NaNs in X_test: {np.isnan(X_test).any()}, NaNs in y_test: {np.
      ↪ isnan(y_test).any()}")

      # Replace NaN values in the datasets
      X_train = np.nan_to_num(X_train)
      y_train = np.nan_to_num(y_train)
      X_val = np.nan_to_num(X_val)
      y_val = np.nan_to_num(y_val)
      X_test = np.nan_to_num(X_test)
      y_test = np.nan_to_num(y_test)
```

NaNs in X_train: True, NaNs in y_train: False

NaNs in X_val: True, NaNs in y_val: False

NaNs in X_test: True, NaNs in y_test: False

Build the model WIP

```

[ ]: # v1
# model = Sequential()
# model.add(LSTM(64, return_sequences=True, activation='relu',
↳input_shape=(10,1662)))
# model.add(LSTM(128, return_sequences=True, activation='relu'))
# model.add(LSTM(64, return_sequences=False, activation='relu'))
# model.add(Dense(64, activation='relu'))
# model.add(Dense(32, activation='relu'))
# model.add(Dense(actions.shape[0], activation='softmax'))
# model.compile(optimizer='Adam', loss='categorical_crossentropy',
↳metrics=['categorical_accuracy'])

frame_length = 1662
num_classes = actions.shape[0]

# v2
model = Sequential()
model.add(LSTM(128, return_sequences=True, activation='relu', input_shape=(10,
↳frame_length)))
model.add(Dropout(0.2))
model.add(BatchNormalization())
model.add(LSTM(256, return_sequences=False, activation='relu'))
model.add(Dropout(0.2))
model.add(Dense(128, activation='relu'))
model.add(Dropout(0.2))
model.add(Dense(num_classes, activation='softmax'))

# Optimizer with Gradient Clipping
# optimizer = Adam(learning_rate=0.0001, clipvalue=0.5) # Adjust learning rate
↳and clipvalue as needed
optimizer = Adam(learning_rate=0.001)

# Compile the model
model.compile(optimizer=optimizer, loss='categorical_crossentropy',
↳metrics=['accuracy'])

# Callbacks
early_stopping = EarlyStopping(monitor='val_loss', patience=100, verbose=1,
↳mode='min')

reduce_lr = ReduceLROnPlateau(monitor='val_loss', factor=0.5, patience=25,
↳verbose=1, mode='min', min_lr=0.00001)

```

WARNING:tensorflow:Layer lstm will not use cuDNN kernels since it doesn't meet the criteria. It will use a generic GPU kernel as fallback when running on GPU.

2023-12-02 08:37:54.430084: I

tensorflow/compiler/xla/stream_executor/cuda/cuda_gpu_executor.cc:880] could not

```

open file to read NUMA node: /sys/bus/pci/devices/0000:01:00.0/numa_node
Your kernel may have been built without NUMA support.
2023-12-02 08:37:54.432988: I
tensorflow/compiler/xla/stream_executor/cuda/cuda_gpu_executor.cc:880] could not
open file to read NUMA node: /sys/bus/pci/devices/0000:01:00.0/numa_node
Your kernel may have been built without NUMA support.
2023-12-02 08:37:54.433036: I
tensorflow/compiler/xla/stream_executor/cuda/cuda_gpu_executor.cc:880] could not
open file to read NUMA node: /sys/bus/pci/devices/0000:01:00.0/numa_node
Your kernel may have been built without NUMA support.
2023-12-02 08:37:54.434702: I
tensorflow/compiler/xla/stream_executor/cuda/cuda_gpu_executor.cc:880] could not
open file to read NUMA node: /sys/bus/pci/devices/0000:01:00.0/numa_node
Your kernel may have been built without NUMA support.
2023-12-02 08:37:54.434736: I
tensorflow/compiler/xla/stream_executor/cuda/cuda_gpu_executor.cc:880] could not
open file to read NUMA node: /sys/bus/pci/devices/0000:01:00.0/numa_node
Your kernel may have been built without NUMA support.
2023-12-02 08:37:54.434757: I
tensorflow/compiler/xla/stream_executor/cuda/cuda_gpu_executor.cc:880] could not
open file to read NUMA node: /sys/bus/pci/devices/0000:01:00.0/numa_node
Your kernel may have been built without NUMA support.
2023-12-02 08:37:54.719876: I
tensorflow/compiler/xla/stream_executor/cuda/cuda_gpu_executor.cc:880] could not
open file to read NUMA node: /sys/bus/pci/devices/0000:01:00.0/numa_node
Your kernel may have been built without NUMA support.
2023-12-02 08:37:54.719921: I
tensorflow/compiler/xla/stream_executor/cuda/cuda_gpu_executor.cc:880] could not
open file to read NUMA node: /sys/bus/pci/devices/0000:01:00.0/numa_node
Your kernel may have been built without NUMA support.
2023-12-02 08:37:54.719929: I
tensorflow/core/common_runtime/gpu/gpu_device.cc:1977] Could not identify NUMA
node of platform GPU id 0, defaulting to 0. Your kernel may not have been built
with NUMA support.
2023-12-02 08:37:54.719956: I
tensorflow/compiler/xla/stream_executor/cuda/cuda_gpu_executor.cc:880] could not
open file to read NUMA node: /sys/bus/pci/devices/0000:01:00.0/numa_node
Your kernel may have been built without NUMA support.
2023-12-02 08:37:54.719971: I
tensorflow/core/common_runtime/gpu/gpu_device.cc:1886] Created device
/job:localhost/replica:0/task:0/device:GPU:0 with 21472 MB memory: -> device:
0, name: NVIDIA GeForce RTX 4090, pci bus id: 0000:01:00.0, compute capability:
8.9
2023-12-02 08:37:55.285017: I tensorflow/tsl/platform/default/subprocess.cc:304]
Start cannot spawn child process: No such file or directory

WARNING:tensorflow:Layer lstm_1 will not use cuDNN kernels since it doesn't meet
the criteria. It will use a generic GPU kernel as fallback when running on GPU.

```

Train the model

```
[ ]: # Enable mixed precision
set_global_policy('mixed_float16')

epochs = 1000 # Adjust number of epochs as needed
batch_size = 1024

history = model.fit(
    X_train, y_train,
    epochs=epochs,
    batch_size=batch_size,
    validation_data=(X_val, y_val),
    callbacks=[early_stopping, reduce_lr]
)
```

INFO:tensorflow:Mixed precision compatibility check (mixed_float16): OK
Your GPU will likely run quickly with dtype policy mixed_float16 as it has
compute capability of at least 7.0. Your GPU: NVIDIA GeForce RTX 4090, compute
capability 8.9

2023-12-02 08:37:55.529626: I
tensorflow/compiler/xla/stream_executor/cuda/cuda_gpu_executor.cc:880] could not
open file to read NUMA node: /sys/bus/pci/devices/0000:01:00.0/numa_node
Your kernel may have been built without NUMA support.

Epoch 1/1000

2023-12-02 08:38:00.429825: I tensorflow/compiler/xla/service/service.cc:168]
XLA service 0x7fb908296f30 initialized for platform CUDA (this does not
guarantee that XLA will be used). Devices:
2023-12-02 08:38:00.429869: I tensorflow/compiler/xla/service/service.cc:176]
StreamExecutor device (0): NVIDIA GeForce RTX 4090, Compute Capability 8.9
2023-12-02 08:38:00.434596: I
tensorflow/compiler/mlir/tensorflow/utils/dump_mlir_util.cc:269] disabling MLIR
crash reproducer, set env var `MLIR_CRASH_REPRODUCER_DIRECTORY` to enable.
2023-12-02 08:38:00.449839: I
tensorflow/compiler/xla/stream_executor/cuda/cuda_dnn.cc:442] Loaded cuDNN
version 8700
2023-12-02 08:38:00.518010: I ./tensorflow/compiler/jit/device_compiler.h:186]
Compiled cluster using XLA! This line is logged at most once for the lifetime
of the process.

10/10 [=====] - 7s 167ms/step - loss: 3.9674 -
accuracy: 0.0229 - val_loss: 3.9901 - val_accuracy: 0.0311 - lr: 0.0010
Epoch 2/1000

10/10 [=====] - 1s 90ms/step - loss: 3.8960 - accuracy:
0.0342 - val_loss: 3.9989 - val_accuracy: 0.0216 - lr: 0.0010

Epoch 3/1000

10/10 [=====] - 1s 78ms/step - loss: 3.7596 - accuracy:

0.0483 - val_loss: 4.0058 - val_accuracy: 0.0211 - lr: 0.0010
Epoch 4/1000
10/10 [=====] - 1s 89ms/step - loss: 3.6526 - accuracy:
0.0654 - val_loss: 3.9937 - val_accuracy: 0.0321 - lr: 0.0010
Epoch 5/1000
10/10 [=====] - 1s 81ms/step - loss: 3.5115 - accuracy:
0.0840 - val_loss: 3.7521 - val_accuracy: 0.0396 - lr: 0.0010
Epoch 6/1000
10/10 [=====] - 1s 76ms/step - loss: 3.3786 - accuracy:
0.1028 - val_loss: 3.7308 - val_accuracy: 0.0447 - lr: 0.0010
Epoch 7/1000
10/10 [=====] - 1s 84ms/step - loss: 3.2247 - accuracy:
0.1229 - val_loss: 3.6293 - val_accuracy: 0.0542 - lr: 0.0010
Epoch 8/1000
10/10 [=====] - 1s 72ms/step - loss: 3.0981 - accuracy:
0.1404 - val_loss: 3.5763 - val_accuracy: 0.0833 - lr: 0.0010
Epoch 9/1000
10/10 [=====] - 1s 77ms/step - loss: 3.0148 - accuracy:
0.1584 - val_loss: 3.5610 - val_accuracy: 0.0758 - lr: 0.0010
Epoch 10/1000
10/10 [=====] - 1s 75ms/step - loss: 2.8824 - accuracy:
0.1866 - val_loss: 3.4611 - val_accuracy: 0.0682 - lr: 0.0010
Epoch 11/1000
10/10 [=====] - 1s 73ms/step - loss: 2.7910 - accuracy:
0.2046 - val_loss: 3.6399 - val_accuracy: 0.0702 - lr: 0.0010
Epoch 12/1000
10/10 [=====] - 1s 75ms/step - loss: 2.7474 - accuracy:
0.2120 - val_loss: 3.4201 - val_accuracy: 0.0838 - lr: 0.0010
Epoch 13/1000
10/10 [=====] - 1s 75ms/step - loss: 2.5985 - accuracy:
0.2437 - val_loss: 4.9064 - val_accuracy: 0.0592 - lr: 0.0010
Epoch 14/1000
10/10 [=====] - 1s 74ms/step - loss: 2.5362 - accuracy:
0.2666 - val_loss: 3.5530 - val_accuracy: 0.0828 - lr: 0.0010
Epoch 15/1000
10/10 [=====] - 1s 78ms/step - loss: 2.4691 - accuracy:
0.2720 - val_loss: 3.1892 - val_accuracy: 0.1445 - lr: 0.0010
Epoch 16/1000
10/10 [=====] - 1s 83ms/step - loss: 2.4212 - accuracy:
0.2949 - val_loss: 3.5145 - val_accuracy: 0.0948 - lr: 0.0010
Epoch 17/1000
10/10 [=====] - 1s 77ms/step - loss: 2.3630 - accuracy:
0.3104 - val_loss: 4.0417 - val_accuracy: 0.0462 - lr: 0.0010
Epoch 18/1000
10/10 [=====] - 1s 75ms/step - loss: 2.2812 - accuracy:
0.3257 - val_loss: 3.4919 - val_accuracy: 0.0973 - lr: 0.0010
Epoch 19/1000
10/10 [=====] - 1s 74ms/step - loss: 2.2174 - accuracy:

0.3410 - val_loss: 3.4911 - val_accuracy: 0.0768 - lr: 0.0010
Epoch 20/1000
10/10 [=====] - 1s 76ms/step - loss: 2.1749 - accuracy: 0.3528 - val_loss: 4.7066 - val_accuracy: 0.0622 - lr: 0.0010
Epoch 21/1000
10/10 [=====] - 1s 82ms/step - loss: 2.1075 - accuracy: 0.3792 - val_loss: 3.6192 - val_accuracy: 0.0973 - lr: 0.0010
Epoch 22/1000
10/10 [=====] - 1s 78ms/step - loss: 2.0575 - accuracy: 0.3858 - val_loss: 4.0382 - val_accuracy: 0.0853 - lr: 0.0010
Epoch 23/1000
10/10 [=====] - 1s 92ms/step - loss: 2.0182 - accuracy: 0.3997 - val_loss: 3.4984 - val_accuracy: 0.1209 - lr: 0.0010
Epoch 24/1000
10/10 [=====] - 1s 79ms/step - loss: 2.0045 - accuracy: 0.4036 - val_loss: 3.6899 - val_accuracy: 0.0993 - lr: 0.0010
Epoch 25/1000
10/10 [=====] - 1s 77ms/step - loss: 1.9358 - accuracy: 0.4255 - val_loss: 4.0941 - val_accuracy: 0.0768 - lr: 0.0010
Epoch 26/1000
10/10 [=====] - 1s 72ms/step - loss: 1.9074 - accuracy: 0.4374 - val_loss: 6.8642 - val_accuracy: 0.0336 - lr: 0.0010
Epoch 27/1000
10/10 [=====] - 1s 73ms/step - loss: 1.9023 - accuracy: 0.4295 - val_loss: 4.4013 - val_accuracy: 0.0587 - lr: 0.0010
Epoch 28/1000
10/10 [=====] - 1s 74ms/step - loss: 1.8373 - accuracy: 0.4539 - val_loss: 3.5164 - val_accuracy: 0.0848 - lr: 0.0010
Epoch 29/1000
10/10 [=====] - 1s 72ms/step - loss: 1.8272 - accuracy: 0.4513 - val_loss: 5.1641 - val_accuracy: 0.0467 - lr: 0.0010
Epoch 30/1000
10/10 [=====] - 1s 83ms/step - loss: 1.8552 - accuracy: 0.4467 - val_loss: 3.1058 - val_accuracy: 0.1681 - lr: 0.0010
Epoch 31/1000
10/10 [=====] - 1s 77ms/step - loss: 1.7859 - accuracy: 0.4711 - val_loss: 3.5024 - val_accuracy: 0.1706 - lr: 0.0010
Epoch 32/1000
10/10 [=====] - 1s 74ms/step - loss: 1.7010 - accuracy: 0.4883 - val_loss: 12.4740 - val_accuracy: 0.0426 - lr: 0.0010
Epoch 33/1000
10/10 [=====] - 1s 71ms/step - loss: 1.7424 - accuracy: 0.4862 - val_loss: 6.0236 - val_accuracy: 0.0748 - lr: 0.0010
Epoch 34/1000
10/10 [=====] - 1s 76ms/step - loss: 1.6795 - accuracy: 0.4940 - val_loss: 4.4060 - val_accuracy: 0.1099 - lr: 0.0010
Epoch 35/1000
10/10 [=====] - 1s 73ms/step - loss: 1.6527 - accuracy:

0.5054 - val_loss: 4.4375 - val_accuracy: 0.0898 - lr: 0.0010
 Epoch 36/1000
 10/10 [=====] - 1s 80ms/step - loss: 1.6219 - accuracy:
 0.5122 - val_loss: 3.5053 - val_accuracy: 0.1676 - lr: 0.0010
 Epoch 37/1000
 10/10 [=====] - 1s 86ms/step - loss: 1.5997 - accuracy:
 0.5228 - val_loss: 4.3137 - val_accuracy: 0.1199 - lr: 0.0010
 Epoch 38/1000
 10/10 [=====] - 1s 88ms/step - loss: 1.5198 - accuracy:
 0.5409 - val_loss: 3.9728 - val_accuracy: 0.1385 - lr: 0.0010
 Epoch 39/1000
 10/10 [=====] - 1s 76ms/step - loss: 1.5888 - accuracy:
 0.5285 - val_loss: 2.1798 - val_accuracy: 0.3683 - lr: 0.0010
 Epoch 40/1000
 10/10 [=====] - 1s 73ms/step - loss: 1.5421 - accuracy:
 0.5376 - val_loss: 2.8181 - val_accuracy: 0.2353 - lr: 0.0010
 Epoch 41/1000
 10/10 [=====] - 1s 76ms/step - loss: 1.4935 - accuracy:
 0.5511 - val_loss: 4.3897 - val_accuracy: 0.1867 - lr: 0.0010
 Epoch 42/1000
 10/10 [=====] - 1s 85ms/step - loss: 1.4569 - accuracy:
 0.5661 - val_loss: 4.1782 - val_accuracy: 0.1194 - lr: 0.0010
 Epoch 43/1000
 10/10 [=====] - 1s 71ms/step - loss: 1.4148 - accuracy:
 0.5706 - val_loss: 4.1497 - val_accuracy: 0.1530 - lr: 0.0010
 Epoch 44/1000
 10/10 [=====] - 1s 79ms/step - loss: 1.3795 - accuracy:
 0.5863 - val_loss: 2.0730 - val_accuracy: 0.4155 - lr: 0.0010
 Epoch 45/1000
 10/10 [=====] - 1s 79ms/step - loss: 1.3581 - accuracy:
 0.5947 - val_loss: 3.1523 - val_accuracy: 0.2358 - lr: 0.0010
 Epoch 46/1000
 10/10 [=====] - 1s 84ms/step - loss: 1.3892 - accuracy:
 0.5823 - val_loss: 4.4175 - val_accuracy: 0.1661 - lr: 0.0010
 Epoch 47/1000
 10/10 [=====] - 1s 80ms/step - loss: 1.4069 - accuracy:
 0.5719 - val_loss: 2.6768 - val_accuracy: 0.3111 - lr: 0.0010
 Epoch 48/1000
 10/10 [=====] - 1s 79ms/step - loss: 1.3780 - accuracy:
 0.5797 - val_loss: 2.1476 - val_accuracy: 0.3859 - lr: 0.0010
 Epoch 49/1000
 10/10 [=====] - 1s 72ms/step - loss: 1.2942 - accuracy:
 0.6074 - val_loss: 2.2993 - val_accuracy: 0.3457 - lr: 0.0010
 Epoch 50/1000
 10/10 [=====] - 1s 76ms/step - loss: 1.3041 - accuracy:
 0.6066 - val_loss: 2.5976 - val_accuracy: 0.3773 - lr: 0.0010
 Epoch 51/1000
 10/10 [=====] - 1s 79ms/step - loss: 1.2611 - accuracy:

0.6214 - val_loss: 2.8531 - val_accuracy: 0.3281 - lr: 0.0010
 Epoch 52/1000
 10/10 [=====] - 1s 74ms/step - loss: 1.2445 - accuracy:
 0.6214 - val_loss: 2.5329 - val_accuracy: 0.3994 - lr: 0.0010
 Epoch 53/1000
 10/10 [=====] - 1s 76ms/step - loss: 1.2473 - accuracy:
 0.6227 - val_loss: 4.4819 - val_accuracy: 0.1977 - lr: 0.0010
 Epoch 54/1000
 10/10 [=====] - 1s 84ms/step - loss: 1.2691 - accuracy:
 0.6158 - val_loss: 3.1625 - val_accuracy: 0.2704 - lr: 0.0010
 Epoch 55/1000
 10/10 [=====] - 1s 74ms/step - loss: 1.2232 - accuracy:
 0.6283 - val_loss: 4.4479 - val_accuracy: 0.1656 - lr: 0.0010
 Epoch 56/1000
 10/10 [=====] - 1s 74ms/step - loss: 1.2235 - accuracy:
 0.6313 - val_loss: 3.3525 - val_accuracy: 0.2263 - lr: 0.0010
 Epoch 57/1000
 10/10 [=====] - 1s 71ms/step - loss: 1.2259 - accuracy:
 0.6277 - val_loss: 2.3473 - val_accuracy: 0.3552 - lr: 0.0010
 Epoch 58/1000
 10/10 [=====] - 1s 73ms/step - loss: 1.1917 - accuracy:
 0.6386 - val_loss: 4.1074 - val_accuracy: 0.1621 - lr: 0.0010
 Epoch 59/1000
 10/10 [=====] - 1s 72ms/step - loss: 1.2050 - accuracy:
 0.6334 - val_loss: 2.6640 - val_accuracy: 0.3382 - lr: 0.0010
 Epoch 60/1000
 10/10 [=====] - 1s 72ms/step - loss: 1.1889 - accuracy:
 0.6423 - val_loss: 2.1666 - val_accuracy: 0.3828 - lr: 0.0010
 Epoch 61/1000
 10/10 [=====] - 1s 76ms/step - loss: 1.1912 - accuracy:
 0.6421 - val_loss: 2.5516 - val_accuracy: 0.3387 - lr: 0.0010
 Epoch 62/1000
 10/10 [=====] - 1s 83ms/step - loss: 1.1493 - accuracy:
 0.6549 - val_loss: 2.8114 - val_accuracy: 0.3056 - lr: 0.0010
 Epoch 63/1000
 10/10 [=====] - 1s 73ms/step - loss: 1.1174 - accuracy:
 0.6605 - val_loss: 2.3602 - val_accuracy: 0.3723 - lr: 0.0010
 Epoch 64/1000
 10/10 [=====] - 1s 71ms/step - loss: 1.1263 - accuracy:
 0.6586 - val_loss: 2.3414 - val_accuracy: 0.3904 - lr: 0.0010
 Epoch 65/1000
 10/10 [=====] - 1s 72ms/step - loss: 1.0839 - accuracy:
 0.6768 - val_loss: 1.9748 - val_accuracy: 0.4596 - lr: 0.0010
 Epoch 66/1000
 10/10 [=====] - 1s 73ms/step - loss: 1.0652 - accuracy:
 0.6753 - val_loss: 3.4216 - val_accuracy: 0.2679 - lr: 0.0010
 Epoch 67/1000
 10/10 [=====] - 1s 73ms/step - loss: 1.0615 - accuracy:

0.6795 - val_loss: 6.3611 - val_accuracy: 0.1445 - lr: 0.0010
 Epoch 68/1000
 10/10 [=====] - 1s 74ms/step - loss: 1.0327 - accuracy:
 0.6914 - val_loss: 2.8259 - val_accuracy: 0.3583 - lr: 0.0010
 Epoch 69/1000
 10/10 [=====] - 1s 72ms/step - loss: 1.0158 - accuracy:
 0.6953 - val_loss: 4.2136 - val_accuracy: 0.2303 - lr: 0.0010
 Epoch 70/1000
 10/10 [=====] - 1s 75ms/step - loss: 1.0167 - accuracy:
 0.6940 - val_loss: 2.2607 - val_accuracy: 0.4596 - lr: 0.0010
 Epoch 71/1000
 10/10 [=====] - 1s 82ms/step - loss: 1.0259 - accuracy:
 0.6864 - val_loss: 3.1059 - val_accuracy: 0.2840 - lr: 0.0010
 Epoch 72/1000
 10/10 [=====] - 1s 75ms/step - loss: 1.0504 - accuracy:
 0.6798 - val_loss: 6.2830 - val_accuracy: 0.1189 - lr: 0.0010
 Epoch 73/1000
 10/10 [=====] - 1s 74ms/step - loss: 1.0328 - accuracy:
 0.6884 - val_loss: 2.7543 - val_accuracy: 0.4104 - lr: 0.0010
 Epoch 74/1000
 10/10 [=====] - 1s 71ms/step - loss: 1.0141 - accuracy:
 0.6901 - val_loss: 3.5821 - val_accuracy: 0.2935 - lr: 0.0010
 Epoch 75/1000
 10/10 [=====] - 1s 74ms/step - loss: 0.9860 - accuracy:
 0.7013 - val_loss: 4.3199 - val_accuracy: 0.2283 - lr: 0.0010
 Epoch 76/1000
 10/10 [=====] - 1s 73ms/step - loss: 1.0119 - accuracy:
 0.6930 - val_loss: 2.5538 - val_accuracy: 0.4134 - lr: 0.0010
 Epoch 77/1000
 10/10 [=====] - 1s 72ms/step - loss: 0.9395 - accuracy:
 0.7139 - val_loss: 2.2958 - val_accuracy: 0.4541 - lr: 0.0010
 Epoch 78/1000
 10/10 [=====] - 1s 75ms/step - loss: 0.9641 - accuracy:
 0.7135 - val_loss: 3.3550 - val_accuracy: 0.3557 - lr: 0.0010
 Epoch 79/1000
 10/10 [=====] - 1s 76ms/step - loss: 0.9497 - accuracy:
 0.7111 - val_loss: 2.4026 - val_accuracy: 0.4134 - lr: 0.0010
 Epoch 80/1000
 10/10 [=====] - 1s 87ms/step - loss: 1.0374 - accuracy:
 0.6870 - val_loss: 3.5296 - val_accuracy: 0.2393 - lr: 0.0010
 Epoch 81/1000
 10/10 [=====] - 1s 81ms/step - loss: 1.0288 - accuracy:
 0.6873 - val_loss: 3.0178 - val_accuracy: 0.3377 - lr: 0.0010
 Epoch 82/1000
 10/10 [=====] - 1s 76ms/step - loss: 0.9726 - accuracy:
 0.7048 - val_loss: 2.3653 - val_accuracy: 0.3954 - lr: 0.0010
 Epoch 83/1000
 10/10 [=====] - 1s 71ms/step - loss: 0.9354 - accuracy:

0.7166 - val_loss: 2.9368 - val_accuracy: 0.3402 - lr: 0.0010
 Epoch 84/1000
 10/10 [=====] - 1s 73ms/step - loss: 0.9233 - accuracy:
 0.7195 - val_loss: 4.0249 - val_accuracy: 0.2659 - lr: 0.0010
 Epoch 85/1000
 10/10 [=====] - 1s 73ms/step - loss: 0.9306 - accuracy:
 0.7159 - val_loss: 5.8567 - val_accuracy: 0.1641 - lr: 0.0010
 Epoch 86/1000
 10/10 [=====] - 1s 72ms/step - loss: 0.9423 - accuracy:
 0.7099 - val_loss: 3.9650 - val_accuracy: 0.3136 - lr: 0.0010
 Epoch 87/1000
 10/10 [=====] - 1s 83ms/step - loss: 0.9080 - accuracy:
 0.7220 - val_loss: 3.6757 - val_accuracy: 0.4205 - lr: 0.0010
 Epoch 88/1000
 10/10 [=====] - 1s 74ms/step - loss: 0.9242 - accuracy:
 0.7185 - val_loss: 2.6092 - val_accuracy: 0.3964 - lr: 0.0010
 Epoch 89/1000
 10/10 [=====] - 1s 75ms/step - loss: 0.8571 - accuracy:
 0.7409 - val_loss: 3.1556 - val_accuracy: 0.3823 - lr: 0.0010
 Epoch 90/1000
 10/10 [=====] - ETA: 0s - loss: 0.8515 - accuracy:
 0.7431
 Epoch 90: ReduceLROnPlateau reducing learning rate to 0.0005000000237487257.
 10/10 [=====] - 1s 71ms/step - loss: 0.8515 - accuracy:
 0.7431 - val_loss: 2.8203 - val_accuracy: 0.3813 - lr: 0.0010
 Epoch 91/1000
 10/10 [=====] - 1s 71ms/step - loss: 0.8870 - accuracy:
 0.7291 - val_loss: 1.7801 - val_accuracy: 0.5178 - lr: 5.0000e-04
 Epoch 92/1000
 10/10 [=====] - 1s 72ms/step - loss: 0.8258 - accuracy:
 0.7485 - val_loss: 2.0921 - val_accuracy: 0.5043 - lr: 5.0000e-04
 Epoch 93/1000
 10/10 [=====] - 1s 72ms/step - loss: 0.7697 - accuracy:
 0.7660 - val_loss: 1.5526 - val_accuracy: 0.5951 - lr: 5.0000e-04
 Epoch 94/1000
 10/10 [=====] - 1s 72ms/step - loss: 0.7515 - accuracy:
 0.7691 - val_loss: 2.0692 - val_accuracy: 0.4972 - lr: 5.0000e-04
 Epoch 95/1000
 10/10 [=====] - 1s 73ms/step - loss: 0.7604 - accuracy:
 0.7707 - val_loss: 1.8038 - val_accuracy: 0.5640 - lr: 5.0000e-04
 Epoch 96/1000
 10/10 [=====] - 1s 85ms/step - loss: 0.7413 - accuracy:
 0.7705 - val_loss: 2.0722 - val_accuracy: 0.5253 - lr: 5.0000e-04
 Epoch 97/1000
 10/10 [=====] - 1s 78ms/step - loss: 0.7405 - accuracy:
 0.7784 - val_loss: 1.7349 - val_accuracy: 0.5730 - lr: 5.0000e-04
 Epoch 98/1000
 10/10 [=====] - 1s 78ms/step - loss: 0.7504 - accuracy:

0.7716 - val_loss: 1.7426 - val_accuracy: 0.5615 - lr: 5.0000e-04
 Epoch 99/1000
 10/10 [=====] - 1s 77ms/step - loss: 0.7214 - accuracy:
 0.7792 - val_loss: 1.5014 - val_accuracy: 0.6237 - lr: 5.0000e-04
 Epoch 100/1000
 10/10 [=====] - 1s 72ms/step - loss: 0.7316 - accuracy:
 0.7758 - val_loss: 2.2792 - val_accuracy: 0.4536 - lr: 5.0000e-04
 Epoch 101/1000
 10/10 [=====] - 1s 73ms/step - loss: 0.7449 - accuracy:
 0.7723 - val_loss: 2.4033 - val_accuracy: 0.4681 - lr: 5.0000e-04
 Epoch 102/1000
 10/10 [=====] - 1s 71ms/step - loss: 0.7553 - accuracy:
 0.7726 - val_loss: 1.9451 - val_accuracy: 0.5304 - lr: 5.0000e-04
 Epoch 103/1000
 10/10 [=====] - 1s 81ms/step - loss: 0.7327 - accuracy:
 0.7765 - val_loss: 1.8414 - val_accuracy: 0.5745 - lr: 5.0000e-04
 Epoch 104/1000
 10/10 [=====] - 1s 78ms/step - loss: 0.7146 - accuracy:
 0.7814 - val_loss: 2.1518 - val_accuracy: 0.4867 - lr: 5.0000e-04
 Epoch 105/1000
 10/10 [=====] - 1s 73ms/step - loss: 0.6963 - accuracy:
 0.7880 - val_loss: 1.4173 - val_accuracy: 0.6563 - lr: 5.0000e-04
 Epoch 106/1000
 10/10 [=====] - 1s 72ms/step - loss: 0.7051 - accuracy:
 0.7851 - val_loss: 1.9284 - val_accuracy: 0.5354 - lr: 5.0000e-04
 Epoch 107/1000
 10/10 [=====] - 1s 72ms/step - loss: 0.6963 - accuracy:
 0.7842 - val_loss: 1.8459 - val_accuracy: 0.5840 - lr: 5.0000e-04
 Epoch 108/1000
 10/10 [=====] - 1s 72ms/step - loss: 0.7077 - accuracy:
 0.7801 - val_loss: 1.6991 - val_accuracy: 0.5911 - lr: 5.0000e-04
 Epoch 109/1000
 10/10 [=====] - 1s 76ms/step - loss: 0.6903 - accuracy:
 0.7844 - val_loss: 1.6777 - val_accuracy: 0.5911 - lr: 5.0000e-04
 Epoch 110/1000
 10/10 [=====] - 1s 77ms/step - loss: 0.6972 - accuracy:
 0.7829 - val_loss: 1.5008 - val_accuracy: 0.6197 - lr: 5.0000e-04
 Epoch 111/1000
 10/10 [=====] - 1s 85ms/step - loss: 0.7162 - accuracy:
 0.7814 - val_loss: 3.5267 - val_accuracy: 0.3879 - lr: 5.0000e-04
 Epoch 112/1000
 10/10 [=====] - 1s 84ms/step - loss: 0.7030 - accuracy:
 0.7835 - val_loss: 2.3600 - val_accuracy: 0.4812 - lr: 5.0000e-04
 Epoch 113/1000
 10/10 [=====] - 1s 73ms/step - loss: 0.6701 - accuracy:
 0.7946 - val_loss: 1.4935 - val_accuracy: 0.6523 - lr: 5.0000e-04
 Epoch 114/1000
 10/10 [=====] - 1s 77ms/step - loss: 0.6797 - accuracy:

0.7929 - val_loss: 2.7850 - val_accuracy: 0.4250 - lr: 5.0000e-04
Epoch 115/1000
10/10 [=====] - 1s 76ms/step - loss: 0.6739 - accuracy:
0.7941 - val_loss: 2.2523 - val_accuracy: 0.4867 - lr: 5.0000e-04
Epoch 116/1000
10/10 [=====] - 1s 72ms/step - loss: 0.6868 - accuracy:
0.7924 - val_loss: 2.0229 - val_accuracy: 0.5710 - lr: 5.0000e-04
Epoch 117/1000
10/10 [=====] - 1s 79ms/step - loss: 0.7816 - accuracy:
0.7646 - val_loss: 3.8095 - val_accuracy: 0.3823 - lr: 5.0000e-04
Epoch 118/1000
10/10 [=====] - 1s 89ms/step - loss: 0.7375 - accuracy:
0.7767 - val_loss: 2.5434 - val_accuracy: 0.4501 - lr: 5.0000e-04
Epoch 119/1000
10/10 [=====] - 1s 80ms/step - loss: 0.6743 - accuracy:
0.7926 - val_loss: 1.7208 - val_accuracy: 0.5850 - lr: 5.0000e-04
Epoch 120/1000
10/10 [=====] - 1s 72ms/step - loss: 0.6556 - accuracy:
0.7991 - val_loss: 1.8456 - val_accuracy: 0.5524 - lr: 5.0000e-04
Epoch 121/1000
10/10 [=====] - 1s 74ms/step - loss: 0.6457 - accuracy:
0.8044 - val_loss: 1.6371 - val_accuracy: 0.6152 - lr: 5.0000e-04
Epoch 122/1000
10/10 [=====] - 1s 72ms/step - loss: 0.6611 - accuracy:
0.8003 - val_loss: 2.4097 - val_accuracy: 0.4676 - lr: 5.0000e-04
Epoch 123/1000
10/10 [=====] - 1s 72ms/step - loss: 0.6436 - accuracy:
0.8029 - val_loss: 1.6785 - val_accuracy: 0.6036 - lr: 5.0000e-04
Epoch 124/1000
10/10 [=====] - 1s 75ms/step - loss: 0.6180 - accuracy:
0.8114 - val_loss: 1.6146 - val_accuracy: 0.6061 - lr: 5.0000e-04
Epoch 125/1000
10/10 [=====] - 1s 80ms/step - loss: 0.6488 - accuracy:
0.7995 - val_loss: 2.8770 - val_accuracy: 0.4240 - lr: 5.0000e-04
Epoch 126/1000
10/10 [=====] - 1s 79ms/step - loss: 0.7179 - accuracy:
0.7760 - val_loss: 2.5048 - val_accuracy: 0.4431 - lr: 5.0000e-04
Epoch 127/1000
10/10 [=====] - 1s 73ms/step - loss: 0.7209 - accuracy:
0.7797 - val_loss: 3.1209 - val_accuracy: 0.3909 - lr: 5.0000e-04
Epoch 128/1000
10/10 [=====] - 1s 71ms/step - loss: 0.6588 - accuracy:
0.7978 - val_loss: 1.7914 - val_accuracy: 0.5936 - lr: 5.0000e-04
Epoch 129/1000
10/10 [=====] - 1s 77ms/step - loss: 0.6358 - accuracy:
0.8049 - val_loss: 1.7354 - val_accuracy: 0.5896 - lr: 5.0000e-04
Epoch 130/1000
10/10 [=====] - ETA: 0s - loss: 0.6317 - accuracy:

0.8068
Epoch 130: ReduceLROnPlateau reducing learning rate to 0.0002500000118743628.
10/10 [=====] - 1s 71ms/step - loss: 0.6317 - accuracy: 0.8068 - val_loss: 1.7700 - val_accuracy: 0.6046 - lr: 5.0000e-04
Epoch 131/1000
10/10 [=====] - 1s 79ms/step - loss: 0.5887 - accuracy: 0.8224 - val_loss: 1.5718 - val_accuracy: 0.6006 - lr: 2.5000e-04
Epoch 132/1000
10/10 [=====] - 1s 79ms/step - loss: 0.5825 - accuracy: 0.8252 - val_loss: 1.4502 - val_accuracy: 0.6548 - lr: 2.5000e-04
Epoch 133/1000
10/10 [=====] - 1s 80ms/step - loss: 0.5626 - accuracy: 0.8254 - val_loss: 1.3111 - val_accuracy: 0.7030 - lr: 2.5000e-04
Epoch 134/1000
10/10 [=====] - 1s 79ms/step - loss: 0.5627 - accuracy: 0.8293 - val_loss: 1.6107 - val_accuracy: 0.6152 - lr: 2.5000e-04
Epoch 135/1000
10/10 [=====] - 1s 78ms/step - loss: 0.5610 - accuracy: 0.8294 - val_loss: 1.5372 - val_accuracy: 0.6543 - lr: 2.5000e-04
Epoch 136/1000
10/10 [=====] - 1s 77ms/step - loss: 0.5613 - accuracy: 0.8270 - val_loss: 1.3902 - val_accuracy: 0.6839 - lr: 2.5000e-04
Epoch 137/1000
10/10 [=====] - 1s 72ms/step - loss: 0.5749 - accuracy: 0.8222 - val_loss: 1.4410 - val_accuracy: 0.6729 - lr: 2.5000e-04
Epoch 138/1000
10/10 [=====] - 1s 75ms/step - loss: 0.5633 - accuracy: 0.8297 - val_loss: 1.4287 - val_accuracy: 0.6959 - lr: 2.5000e-04
Epoch 139/1000
10/10 [=====] - 1s 74ms/step - loss: 0.5405 - accuracy: 0.8369 - val_loss: 1.4379 - val_accuracy: 0.6864 - lr: 2.5000e-04
Epoch 140/1000
10/10 [=====] - 1s 74ms/step - loss: 0.5360 - accuracy: 0.8380 - val_loss: 1.4818 - val_accuracy: 0.6713 - lr: 2.5000e-04
Epoch 141/1000
10/10 [=====] - 1s 80ms/step - loss: 0.5463 - accuracy: 0.8308 - val_loss: 1.6933 - val_accuracy: 0.6272 - lr: 2.5000e-04
Epoch 142/1000
10/10 [=====] - 1s 73ms/step - loss: 0.5367 - accuracy: 0.8342 - val_loss: 1.8863 - val_accuracy: 0.5921 - lr: 2.5000e-04
Epoch 143/1000
10/10 [=====] - 1s 72ms/step - loss: 0.5504 - accuracy: 0.8336 - val_loss: 1.2888 - val_accuracy: 0.7195 - lr: 2.5000e-04
Epoch 144/1000
10/10 [=====] - 1s 72ms/step - loss: 0.5369 - accuracy: 0.8327 - val_loss: 1.8144 - val_accuracy: 0.6187 - lr: 2.5000e-04
Epoch 145/1000
10/10 [=====] - 1s 74ms/step - loss: 0.5308 - accuracy:

0.8368 - val_loss: 1.2976 - val_accuracy: 0.7045 - lr: 2.5000e-04
 Epoch 146/1000
 10/10 [=====] - 1s 86ms/step - loss: 0.5347 - accuracy:
 0.8309 - val_loss: 1.6727 - val_accuracy: 0.6372 - lr: 2.5000e-04
 Epoch 147/1000
 10/10 [=====] - 1s 72ms/step - loss: 0.5256 - accuracy:
 0.8436 - val_loss: 1.5105 - val_accuracy: 0.6834 - lr: 2.5000e-04
 Epoch 148/1000
 10/10 [=====] - 1s 72ms/step - loss: 0.5024 - accuracy:
 0.8477 - val_loss: 1.4269 - val_accuracy: 0.7015 - lr: 2.5000e-04
 Epoch 149/1000
 10/10 [=====] - 1s 76ms/step - loss: 0.5164 - accuracy:
 0.8417 - val_loss: 1.5292 - val_accuracy: 0.6618 - lr: 2.5000e-04
 Epoch 150/1000
 10/10 [=====] - 1s 89ms/step - loss: 0.5245 - accuracy:
 0.8402 - val_loss: 2.0989 - val_accuracy: 0.5815 - lr: 2.5000e-04
 Epoch 151/1000
 10/10 [=====] - 1s 75ms/step - loss: 0.5173 - accuracy:
 0.8395 - val_loss: 1.8333 - val_accuracy: 0.6267 - lr: 2.5000e-04
 Epoch 152/1000
 10/10 [=====] - 1s 71ms/step - loss: 0.5386 - accuracy:
 0.8330 - val_loss: 2.3368 - val_accuracy: 0.5263 - lr: 2.5000e-04
 Epoch 153/1000
 10/10 [=====] - 1s 72ms/step - loss: 0.5326 - accuracy:
 0.8335 - val_loss: 2.5298 - val_accuracy: 0.5309 - lr: 2.5000e-04
 Epoch 154/1000
 10/10 [=====] - 1s 73ms/step - loss: 0.5146 - accuracy:
 0.8373 - val_loss: 1.2990 - val_accuracy: 0.7175 - lr: 2.5000e-04
 Epoch 155/1000
 10/10 [=====] - 1s 75ms/step - loss: 0.5184 - accuracy:
 0.8393 - val_loss: 1.4652 - val_accuracy: 0.6949 - lr: 2.5000e-04
 Epoch 156/1000
 10/10 [=====] - 1s 74ms/step - loss: 0.5005 - accuracy:
 0.8477 - val_loss: 1.3322 - val_accuracy: 0.7180 - lr: 2.5000e-04
 Epoch 157/1000
 10/10 [=====] - 1s 82ms/step - loss: 0.5113 - accuracy:
 0.8389 - val_loss: 1.6873 - val_accuracy: 0.6463 - lr: 2.5000e-04
 Epoch 158/1000
 10/10 [=====] - 1s 78ms/step - loss: 0.5225 - accuracy:
 0.8394 - val_loss: 2.0717 - val_accuracy: 0.5750 - lr: 2.5000e-04
 Epoch 159/1000
 10/10 [=====] - 1s 75ms/step - loss: 0.5362 - accuracy:
 0.8321 - val_loss: 1.7989 - val_accuracy: 0.6247 - lr: 2.5000e-04
 Epoch 160/1000
 10/10 [=====] - 1s 74ms/step - loss: 0.5253 - accuracy:
 0.8386 - val_loss: 1.4313 - val_accuracy: 0.6994 - lr: 2.5000e-04
 Epoch 161/1000
 10/10 [=====] - 1s 74ms/step - loss: 0.5117 - accuracy:

0.8389 - val_loss: 1.4663 - val_accuracy: 0.6994 - lr: 2.5000e-04
 Epoch 162/1000
 10/10 [=====] - 1s 74ms/step - loss: 0.5022 - accuracy:
 0.8466 - val_loss: 1.3695 - val_accuracy: 0.7210 - lr: 2.5000e-04
 Epoch 163/1000
 10/10 [=====] - 1s 81ms/step - loss: 0.4998 - accuracy:
 0.8468 - val_loss: 1.8780 - val_accuracy: 0.6116 - lr: 2.5000e-04
 Epoch 164/1000
 10/10 [=====] - 1s 76ms/step - loss: 0.4942 - accuracy:
 0.8496 - val_loss: 1.5349 - val_accuracy: 0.6663 - lr: 2.5000e-04
 Epoch 165/1000
 10/10 [=====] - 1s 90ms/step - loss: 0.4979 - accuracy:
 0.8414 - val_loss: 1.3911 - val_accuracy: 0.7035 - lr: 2.5000e-04
 Epoch 166/1000
 10/10 [=====] - 1s 79ms/step - loss: 0.5081 - accuracy:
 0.8446 - val_loss: 1.8783 - val_accuracy: 0.6402 - lr: 2.5000e-04
 Epoch 167/1000
 10/10 [=====] - 1s 76ms/step - loss: 0.5085 - accuracy:
 0.8416 - val_loss: 2.3452 - val_accuracy: 0.5263 - lr: 2.5000e-04
 Epoch 168/1000
 10/10 [=====] - ETA: 0s - loss: 0.5163 - accuracy:
 0.8437
 Epoch 168: ReduceLROnPlateau reducing learning rate to 0.0001250000059371814.
 10/10 [=====] - 1s 74ms/step - loss: 0.5163 - accuracy:
 0.8437 - val_loss: 2.1829 - val_accuracy: 0.5886 - lr: 2.5000e-04
 Epoch 169/1000
 10/10 [=====] - 1s 70ms/step - loss: 0.4919 - accuracy:
 0.8492 - val_loss: 1.3812 - val_accuracy: 0.6924 - lr: 1.2500e-04
 Epoch 170/1000
 10/10 [=====] - 1s 79ms/step - loss: 0.4962 - accuracy:
 0.8429 - val_loss: 1.5853 - val_accuracy: 0.6984 - lr: 1.2500e-04
 Epoch 171/1000
 10/10 [=====] - 1s 73ms/step - loss: 0.4594 - accuracy:
 0.8578 - val_loss: 1.4123 - val_accuracy: 0.7205 - lr: 1.2500e-04
 Epoch 172/1000
 10/10 [=====] - 1s 84ms/step - loss: 0.4725 - accuracy:
 0.8559 - val_loss: 1.3743 - val_accuracy: 0.7230 - lr: 1.2500e-04
 Epoch 173/1000
 10/10 [=====] - 1s 76ms/step - loss: 0.4623 - accuracy:
 0.8586 - val_loss: 1.3640 - val_accuracy: 0.7230 - lr: 1.2500e-04
 Epoch 174/1000
 10/10 [=====] - 1s 73ms/step - loss: 0.4772 - accuracy:
 0.8559 - val_loss: 1.2681 - val_accuracy: 0.7336 - lr: 1.2500e-04
 Epoch 175/1000
 10/10 [=====] - 1s 73ms/step - loss: 0.4694 - accuracy:
 0.8583 - val_loss: 1.4537 - val_accuracy: 0.6959 - lr: 1.2500e-04
 Epoch 176/1000
 10/10 [=====] - 1s 76ms/step - loss: 0.4698 - accuracy:

0.8523 - val_loss: 1.2918 - val_accuracy: 0.7416 - lr: 1.2500e-04
 Epoch 177/1000
 10/10 [=====] - 1s 72ms/step - loss: 0.4581 - accuracy:
 0.8585 - val_loss: 1.4493 - val_accuracy: 0.6954 - lr: 1.2500e-04
 Epoch 178/1000
 10/10 [=====] - 1s 73ms/step - loss: 0.4608 - accuracy:
 0.8583 - val_loss: 1.3686 - val_accuracy: 0.7316 - lr: 1.2500e-04
 Epoch 179/1000
 10/10 [=====] - 1s 73ms/step - loss: 0.4652 - accuracy:
 0.8552 - val_loss: 1.2498 - val_accuracy: 0.7456 - lr: 1.2500e-04
 Epoch 180/1000
 10/10 [=====] - 1s 84ms/step - loss: 0.4523 - accuracy:
 0.8631 - val_loss: 1.4519 - val_accuracy: 0.7075 - lr: 1.2500e-04
 Epoch 181/1000
 10/10 [=====] - 1s 75ms/step - loss: 0.4623 - accuracy:
 0.8601 - val_loss: 1.4561 - val_accuracy: 0.7030 - lr: 1.2500e-04
 Epoch 182/1000
 10/10 [=====] - 1s 71ms/step - loss: 0.4526 - accuracy:
 0.8621 - val_loss: 1.3670 - val_accuracy: 0.7215 - lr: 1.2500e-04
 Epoch 183/1000
 10/10 [=====] - 1s 73ms/step - loss: 0.4512 - accuracy:
 0.8624 - val_loss: 1.3968 - val_accuracy: 0.7100 - lr: 1.2500e-04
 Epoch 184/1000
 10/10 [=====] - 1s 75ms/step - loss: 0.4490 - accuracy:
 0.8620 - val_loss: 1.3724 - val_accuracy: 0.7175 - lr: 1.2500e-04
 Epoch 185/1000
 10/10 [=====] - 1s 74ms/step - loss: 0.4572 - accuracy:
 0.8574 - val_loss: 1.5897 - val_accuracy: 0.6739 - lr: 1.2500e-04
 Epoch 186/1000
 10/10 [=====] - 1s 72ms/step - loss: 0.4502 - accuracy:
 0.8624 - val_loss: 1.4769 - val_accuracy: 0.7010 - lr: 1.2500e-04
 Epoch 187/1000
 10/10 [=====] - 1s 75ms/step - loss: 0.4568 - accuracy:
 0.8597 - val_loss: 1.3072 - val_accuracy: 0.7466 - lr: 1.2500e-04
 Epoch 188/1000
 10/10 [=====] - 1s 73ms/step - loss: 0.4407 - accuracy:
 0.8630 - val_loss: 1.5170 - val_accuracy: 0.6889 - lr: 1.2500e-04
 Epoch 189/1000
 10/10 [=====] - 1s 84ms/step - loss: 0.4403 - accuracy:
 0.8657 - val_loss: 1.2950 - val_accuracy: 0.7381 - lr: 1.2500e-04
 Epoch 190/1000
 10/10 [=====] - 1s 75ms/step - loss: 0.4422 - accuracy:
 0.8633 - val_loss: 1.3444 - val_accuracy: 0.7301 - lr: 1.2500e-04
 Epoch 191/1000
 10/10 [=====] - 1s 74ms/step - loss: 0.4449 - accuracy:
 0.8595 - val_loss: 1.3588 - val_accuracy: 0.7346 - lr: 1.2500e-04
 Epoch 192/1000
 10/10 [=====] - 1s 76ms/step - loss: 0.4557 - accuracy:

0.8601 - val_loss: 1.4414 - val_accuracy: 0.7280 - lr: 1.2500e-04
 Epoch 193/1000
 10/10 [=====] - 1s 77ms/step - loss: 0.4368 - accuracy:
 0.8628 - val_loss: 1.4800 - val_accuracy: 0.7175 - lr: 1.2500e-04
 Epoch 194/1000
 10/10 [=====] - 1s 70ms/step - loss: 0.4517 - accuracy:
 0.8629 - val_loss: 1.4272 - val_accuracy: 0.7346 - lr: 1.2500e-04
 Epoch 195/1000
 10/10 [=====] - 1s 74ms/step - loss: 0.4349 - accuracy:
 0.8631 - val_loss: 1.4113 - val_accuracy: 0.7291 - lr: 1.2500e-04
 Epoch 196/1000
 10/10 [=====] - 1s 73ms/step - loss: 0.4359 - accuracy:
 0.8613 - val_loss: 1.7839 - val_accuracy: 0.6739 - lr: 1.2500e-04
 Epoch 197/1000
 10/10 [=====] - 1s 85ms/step - loss: 0.4448 - accuracy:
 0.8614 - val_loss: 1.6032 - val_accuracy: 0.7025 - lr: 1.2500e-04
 Epoch 198/1000
 10/10 [=====] - 1s 75ms/step - loss: 0.4253 - accuracy:
 0.8672 - val_loss: 1.3494 - val_accuracy: 0.7321 - lr: 1.2500e-04
 Epoch 199/1000
 10/10 [=====] - 1s 72ms/step - loss: 0.4252 - accuracy:
 0.8732 - val_loss: 1.4432 - val_accuracy: 0.7190 - lr: 1.2500e-04
 Epoch 200/1000
 10/10 [=====] - 1s 79ms/step - loss: 0.4189 - accuracy:
 0.8743 - val_loss: 1.4368 - val_accuracy: 0.7155 - lr: 1.2500e-04
 Epoch 201/1000
 10/10 [=====] - 1s 71ms/step - loss: 0.4320 - accuracy:
 0.8656 - val_loss: 1.3738 - val_accuracy: 0.7321 - lr: 1.2500e-04
 Epoch 202/1000
 10/10 [=====] - 1s 75ms/step - loss: 0.4320 - accuracy:
 0.8682 - val_loss: 1.4616 - val_accuracy: 0.7110 - lr: 1.2500e-04
 Epoch 203/1000
 10/10 [=====] - 1s 76ms/step - loss: 0.4208 - accuracy:
 0.8756 - val_loss: 1.4906 - val_accuracy: 0.7155 - lr: 1.2500e-04
 Epoch 204/1000
 10/10 [=====] - ETA: 0s - loss: 0.4306 - accuracy:
 0.8676
 Epoch 204: ReduceLROnPlateau reducing learning rate to 6.25000029685907e-05.
 10/10 [=====] - 1s 80ms/step - loss: 0.4306 - accuracy:
 0.8676 - val_loss: 1.3672 - val_accuracy: 0.7301 - lr: 1.2500e-04
 Epoch 205/1000
 10/10 [=====] - 1s 87ms/step - loss: 0.4199 - accuracy:
 0.8684 - val_loss: 1.4129 - val_accuracy: 0.7275 - lr: 6.2500e-05
 Epoch 206/1000
 10/10 [=====] - 1s 77ms/step - loss: 0.4129 - accuracy:
 0.8732 - val_loss: 1.3314 - val_accuracy: 0.7386 - lr: 6.2500e-05
 Epoch 207/1000
 10/10 [=====] - 1s 72ms/step - loss: 0.4096 - accuracy:

0.8735 - val_loss: 1.3239 - val_accuracy: 0.7511 - lr: 6.2500e-05
 Epoch 208/1000
 10/10 [=====] - 1s 70ms/step - loss: 0.4086 - accuracy:
 0.8742 - val_loss: 1.3606 - val_accuracy: 0.7376 - lr: 6.2500e-05
 Epoch 209/1000
 10/10 [=====] - 1s 75ms/step - loss: 0.4130 - accuracy:
 0.8719 - val_loss: 1.4158 - val_accuracy: 0.7306 - lr: 6.2500e-05
 Epoch 210/1000
 10/10 [=====] - 1s 72ms/step - loss: 0.4145 - accuracy:
 0.8714 - val_loss: 1.2933 - val_accuracy: 0.7491 - lr: 6.2500e-05
 Epoch 211/1000
 10/10 [=====] - 1s 75ms/step - loss: 0.4068 - accuracy:
 0.8745 - val_loss: 1.3167 - val_accuracy: 0.7466 - lr: 6.2500e-05
 Epoch 212/1000
 10/10 [=====] - 1s 83ms/step - loss: 0.4046 - accuracy:
 0.8762 - val_loss: 1.3867 - val_accuracy: 0.7341 - lr: 6.2500e-05
 Epoch 213/1000
 10/10 [=====] - 1s 72ms/step - loss: 0.4245 - accuracy:
 0.8680 - val_loss: 1.3514 - val_accuracy: 0.7551 - lr: 6.2500e-05
 Epoch 214/1000
 10/10 [=====] - 1s 77ms/step - loss: 0.4049 - accuracy:
 0.8731 - val_loss: 1.3811 - val_accuracy: 0.7416 - lr: 6.2500e-05
 Epoch 215/1000
 10/10 [=====] - 1s 73ms/step - loss: 0.4071 - accuracy:
 0.8726 - val_loss: 1.3973 - val_accuracy: 0.7296 - lr: 6.2500e-05
 Epoch 216/1000
 10/10 [=====] - 1s 74ms/step - loss: 0.4183 - accuracy:
 0.8735 - val_loss: 1.4108 - val_accuracy: 0.7401 - lr: 6.2500e-05
 Epoch 217/1000
 10/10 [=====] - 1s 76ms/step - loss: 0.4184 - accuracy:
 0.8698 - val_loss: 1.4965 - val_accuracy: 0.7265 - lr: 6.2500e-05
 Epoch 218/1000
 10/10 [=====] - 1s 74ms/step - loss: 0.4084 - accuracy:
 0.8761 - val_loss: 1.3957 - val_accuracy: 0.7301 - lr: 6.2500e-05
 Epoch 219/1000
 10/10 [=====] - 1s 72ms/step - loss: 0.3964 - accuracy:
 0.8780 - val_loss: 1.3475 - val_accuracy: 0.7411 - lr: 6.2500e-05
 Epoch 220/1000
 10/10 [=====] - 1s 74ms/step - loss: 0.4115 - accuracy:
 0.8698 - val_loss: 1.3514 - val_accuracy: 0.7386 - lr: 6.2500e-05
 Epoch 221/1000
 10/10 [=====] - 1s 87ms/step - loss: 0.4121 - accuracy:
 0.8743 - val_loss: 1.3512 - val_accuracy: 0.7401 - lr: 6.2500e-05
 Epoch 222/1000
 10/10 [=====] - 1s 78ms/step - loss: 0.3977 - accuracy:
 0.8795 - val_loss: 1.3618 - val_accuracy: 0.7321 - lr: 6.2500e-05
 Epoch 223/1000
 10/10 [=====] - 1s 73ms/step - loss: 0.4019 - accuracy:

0.8775 - val_loss: 1.3527 - val_accuracy: 0.7456 - lr: 6.2500e-05
Epoch 224/1000
10/10 [=====] - 1s 73ms/step - loss: 0.4009 - accuracy:
0.8786 - val_loss: 1.3443 - val_accuracy: 0.7431 - lr: 6.2500e-05
Epoch 225/1000
10/10 [=====] - 1s 73ms/step - loss: 0.3968 - accuracy:
0.8786 - val_loss: 1.3996 - val_accuracy: 0.7275 - lr: 6.2500e-05
Epoch 226/1000
10/10 [=====] - 1s 74ms/step - loss: 0.4110 - accuracy:
0.8704 - val_loss: 1.3261 - val_accuracy: 0.7451 - lr: 6.2500e-05
Epoch 227/1000
10/10 [=====] - 1s 75ms/step - loss: 0.4052 - accuracy:
0.8755 - val_loss: 1.3752 - val_accuracy: 0.7391 - lr: 6.2500e-05
Epoch 228/1000
10/10 [=====] - 1s 87ms/step - loss: 0.4165 - accuracy:
0.8722 - val_loss: 1.3983 - val_accuracy: 0.7331 - lr: 6.2500e-05
Epoch 229/1000
10/10 [=====] - ETA: 0s - loss: 0.4133 - accuracy:
0.8712
Epoch 229: ReduceLROnPlateau reducing learning rate to 3.125000148429535e-05.
10/10 [=====] - 1s 73ms/step - loss: 0.4133 - accuracy:
0.8712 - val_loss: 1.3839 - val_accuracy: 0.7291 - lr: 6.2500e-05
Epoch 230/1000
10/10 [=====] - 1s 75ms/step - loss: 0.3955 - accuracy:
0.8804 - val_loss: 1.3327 - val_accuracy: 0.7396 - lr: 3.1250e-05
Epoch 231/1000
10/10 [=====] - 1s 82ms/step - loss: 0.3877 - accuracy:
0.8782 - val_loss: 1.2840 - val_accuracy: 0.7471 - lr: 3.1250e-05
Epoch 232/1000
10/10 [=====] - 1s 73ms/step - loss: 0.3966 - accuracy:
0.8780 - val_loss: 1.3074 - val_accuracy: 0.7466 - lr: 3.1250e-05
Epoch 233/1000
10/10 [=====] - 1s 71ms/step - loss: 0.3987 - accuracy:
0.8779 - val_loss: 1.3352 - val_accuracy: 0.7456 - lr: 3.1250e-05
Epoch 234/1000
10/10 [=====] - 1s 77ms/step - loss: 0.3958 - accuracy:
0.8736 - val_loss: 1.3660 - val_accuracy: 0.7426 - lr: 3.1250e-05
Epoch 235/1000
10/10 [=====] - 1s 83ms/step - loss: 0.4011 - accuracy:
0.8741 - val_loss: 1.3368 - val_accuracy: 0.7471 - lr: 3.1250e-05
Epoch 236/1000
10/10 [=====] - 1s 77ms/step - loss: 0.3847 - accuracy:
0.8823 - val_loss: 1.3433 - val_accuracy: 0.7441 - lr: 3.1250e-05
Epoch 237/1000
10/10 [=====] - 1s 74ms/step - loss: 0.3936 - accuracy:
0.8796 - val_loss: 1.4280 - val_accuracy: 0.7376 - lr: 3.1250e-05
Epoch 238/1000
10/10 [=====] - 1s 74ms/step - loss: 0.3936 - accuracy:

0.8783 - val_loss: 1.3677 - val_accuracy: 0.7436 - lr: 3.1250e-05
Epoch 239/1000
10/10 [=====] - 1s 73ms/step - loss: 0.3961 - accuracy:
0.8781 - val_loss: 1.3375 - val_accuracy: 0.7466 - lr: 3.1250e-05
Epoch 240/1000
10/10 [=====] - 1s 76ms/step - loss: 0.3980 - accuracy:
0.8781 - val_loss: 1.3056 - val_accuracy: 0.7461 - lr: 3.1250e-05
Epoch 241/1000
10/10 [=====] - 1s 73ms/step - loss: 0.3969 - accuracy:
0.8757 - val_loss: 1.3906 - val_accuracy: 0.7331 - lr: 3.1250e-05
Epoch 242/1000
10/10 [=====] - 1s 84ms/step - loss: 0.3882 - accuracy:
0.8817 - val_loss: 1.3279 - val_accuracy: 0.7421 - lr: 3.1250e-05
Epoch 243/1000
10/10 [=====] - 1s 80ms/step - loss: 0.4055 - accuracy:
0.8771 - val_loss: 1.3637 - val_accuracy: 0.7351 - lr: 3.1250e-05
Epoch 244/1000
10/10 [=====] - 1s 79ms/step - loss: 0.3882 - accuracy:
0.8812 - val_loss: 1.3565 - val_accuracy: 0.7416 - lr: 3.1250e-05
Epoch 245/1000
10/10 [=====] - 1s 72ms/step - loss: 0.3926 - accuracy:
0.8770 - val_loss: 1.3953 - val_accuracy: 0.7516 - lr: 3.1250e-05
Epoch 246/1000
10/10 [=====] - 1s 69ms/step - loss: 0.3907 - accuracy:
0.8799 - val_loss: 1.4296 - val_accuracy: 0.7451 - lr: 3.1250e-05
Epoch 247/1000
10/10 [=====] - 1s 72ms/step - loss: 0.3999 - accuracy:
0.8755 - val_loss: 1.3914 - val_accuracy: 0.7456 - lr: 3.1250e-05
Epoch 248/1000
10/10 [=====] - 1s 78ms/step - loss: 0.4023 - accuracy:
0.8785 - val_loss: 1.4735 - val_accuracy: 0.7255 - lr: 3.1250e-05
Epoch 249/1000
10/10 [=====] - 1s 78ms/step - loss: 0.3850 - accuracy:
0.8798 - val_loss: 1.4053 - val_accuracy: 0.7386 - lr: 3.1250e-05
Epoch 250/1000
10/10 [=====] - 1s 82ms/step - loss: 0.3932 - accuracy:
0.8789 - val_loss: 1.3613 - val_accuracy: 0.7406 - lr: 3.1250e-05
Epoch 251/1000
10/10 [=====] - 1s 73ms/step - loss: 0.3908 - accuracy:
0.8797 - val_loss: 1.3664 - val_accuracy: 0.7481 - lr: 3.1250e-05
Epoch 252/1000
10/10 [=====] - 1s 71ms/step - loss: 0.3759 - accuracy:
0.8860 - val_loss: 1.4851 - val_accuracy: 0.7316 - lr: 3.1250e-05
Epoch 253/1000
10/10 [=====] - 1s 73ms/step - loss: 0.3945 - accuracy:
0.8770 - val_loss: 1.3693 - val_accuracy: 0.7436 - lr: 3.1250e-05
Epoch 254/1000
10/10 [=====] - ETA: 0s - loss: 0.3848 - accuracy:

0.8823
Epoch 254: ReduceLROnPlateau reducing learning rate to 1.5625000742147677e-05.
10/10 [=====] - 1s 73ms/step - loss: 0.3848 - accuracy:
0.8823 - val_loss: 1.4202 - val_accuracy: 0.7265 - lr: 3.1250e-05
Epoch 255/1000
10/10 [=====] - 1s 72ms/step - loss: 0.3890 - accuracy:
0.8774 - val_loss: 1.3991 - val_accuracy: 0.7326 - lr: 1.5625e-05
Epoch 256/1000
10/10 [=====] - 1s 81ms/step - loss: 0.3874 - accuracy:
0.8799 - val_loss: 1.3768 - val_accuracy: 0.7441 - lr: 1.5625e-05
Epoch 257/1000
10/10 [=====] - 1s 76ms/step - loss: 0.3909 - accuracy:
0.8783 - val_loss: 1.3264 - val_accuracy: 0.7501 - lr: 1.5625e-05
Epoch 258/1000
10/10 [=====] - 1s 83ms/step - loss: 0.3904 - accuracy:
0.8818 - val_loss: 1.3495 - val_accuracy: 0.7436 - lr: 1.5625e-05
Epoch 259/1000
10/10 [=====] - 1s 77ms/step - loss: 0.3852 - accuracy:
0.8818 - val_loss: 1.3734 - val_accuracy: 0.7446 - lr: 1.5625e-05
Epoch 260/1000
10/10 [=====] - 1s 73ms/step - loss: 0.3858 - accuracy:
0.8799 - val_loss: 1.3787 - val_accuracy: 0.7451 - lr: 1.5625e-05
Epoch 261/1000
10/10 [=====] - 1s 76ms/step - loss: 0.3836 - accuracy:
0.8825 - val_loss: 1.3607 - val_accuracy: 0.7511 - lr: 1.5625e-05
Epoch 262/1000
10/10 [=====] - 1s 72ms/step - loss: 0.3907 - accuracy:
0.8813 - val_loss: 1.3616 - val_accuracy: 0.7496 - lr: 1.5625e-05
Epoch 263/1000
10/10 [=====] - 1s 71ms/step - loss: 0.3826 - accuracy:
0.8804 - val_loss: 1.3331 - val_accuracy: 0.7486 - lr: 1.5625e-05
Epoch 264/1000
10/10 [=====] - 1s 75ms/step - loss: 0.3802 - accuracy:
0.8849 - val_loss: 1.3200 - val_accuracy: 0.7481 - lr: 1.5625e-05
Epoch 265/1000
10/10 [=====] - 1s 74ms/step - loss: 0.3870 - accuracy:
0.8780 - val_loss: 1.3150 - val_accuracy: 0.7496 - lr: 1.5625e-05
Epoch 266/1000
10/10 [=====] - 1s 81ms/step - loss: 0.3856 - accuracy:
0.8826 - val_loss: 1.3206 - val_accuracy: 0.7461 - lr: 1.5625e-05
Epoch 267/1000
10/10 [=====] - 1s 76ms/step - loss: 0.3756 - accuracy:
0.8853 - val_loss: 1.3267 - val_accuracy: 0.7471 - lr: 1.5625e-05
Epoch 268/1000
10/10 [=====] - 1s 69ms/step - loss: 0.3704 - accuracy:
0.8843 - val_loss: 1.3497 - val_accuracy: 0.7451 - lr: 1.5625e-05
Epoch 269/1000
10/10 [=====] - 1s 70ms/step - loss: 0.3826 - accuracy:

```

0.8818 - val_loss: 1.3420 - val_accuracy: 0.7446 - lr: 1.5625e-05
Epoch 270/1000
10/10 [=====] - 1s 75ms/step - loss: 0.3809 - accuracy:
0.8833 - val_loss: 1.3188 - val_accuracy: 0.7481 - lr: 1.5625e-05
Epoch 271/1000
10/10 [=====] - 1s 77ms/step - loss: 0.3769 - accuracy:
0.8830 - val_loss: 1.3173 - val_accuracy: 0.7491 - lr: 1.5625e-05
Epoch 272/1000
10/10 [=====] - 1s 72ms/step - loss: 0.3838 - accuracy:
0.8824 - val_loss: 1.3520 - val_accuracy: 0.7446 - lr: 1.5625e-05
Epoch 273/1000
10/10 [=====] - 1s 80ms/step - loss: 0.3746 - accuracy:
0.8824 - val_loss: 1.3159 - val_accuracy: 0.7501 - lr: 1.5625e-05
Epoch 274/1000
10/10 [=====] - 1s 89ms/step - loss: 0.3733 - accuracy:
0.8864 - val_loss: 1.3117 - val_accuracy: 0.7551 - lr: 1.5625e-05
Epoch 275/1000
10/10 [=====] - 1s 74ms/step - loss: 0.3757 - accuracy:
0.8853 - val_loss: 1.3879 - val_accuracy: 0.7451 - lr: 1.5625e-05
Epoch 276/1000
10/10 [=====] - 1s 73ms/step - loss: 0.3810 - accuracy:
0.8802 - val_loss: 1.3871 - val_accuracy: 0.7436 - lr: 1.5625e-05
Epoch 277/1000
10/10 [=====] - 1s 72ms/step - loss: 0.3806 - accuracy:
0.8835 - val_loss: 1.3131 - val_accuracy: 0.7556 - lr: 1.5625e-05
Epoch 278/1000
10/10 [=====] - 1s 87ms/step - loss: 0.3776 - accuracy:
0.8838 - val_loss: 1.3273 - val_accuracy: 0.7521 - lr: 1.5625e-05
Epoch 279/1000
10/10 [=====] - ETA: 0s - loss: 0.3857 - accuracy:
0.8814
Epoch 279: ReduceLROnPlateau reducing learning rate to 1e-05.
10/10 [=====] - 1s 75ms/step - loss: 0.3857 - accuracy:
0.8814 - val_loss: 1.3669 - val_accuracy: 0.7401 - lr: 1.5625e-05
Epoch 279: early stopping

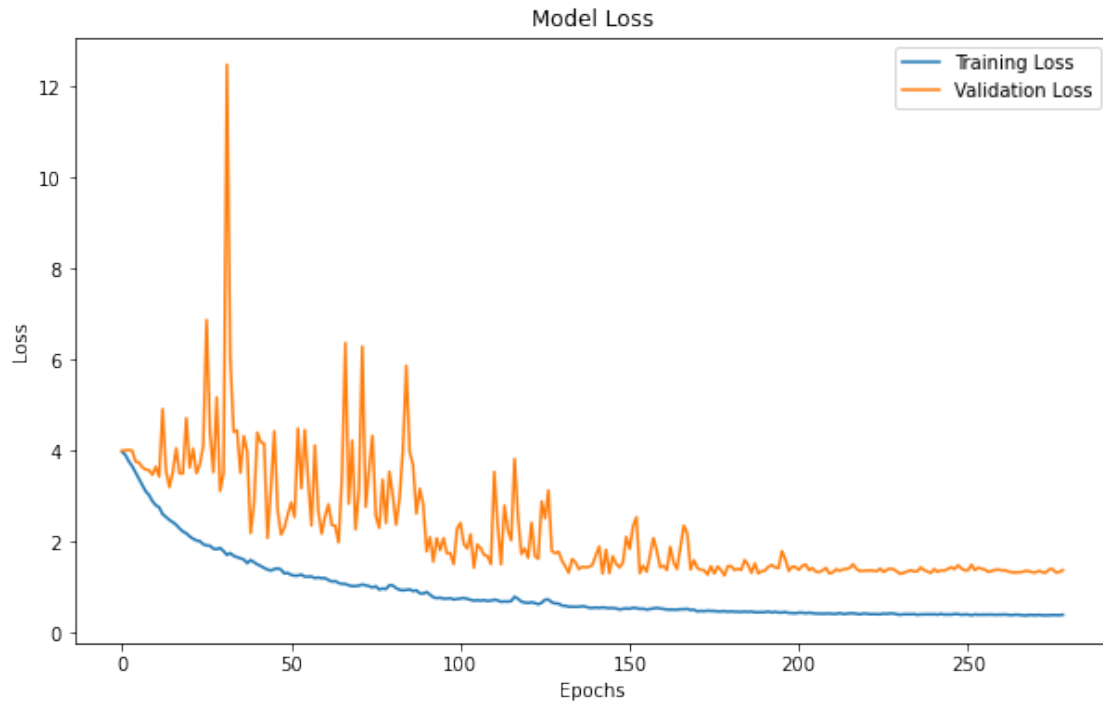
```

Gather metrics

```

[ ]: plt.figure(figsize=(10, 6))
plt.plot(history.history['loss'], label='Training Loss')
plt.plot(history.history['val_loss'], label='Validation Loss')
plt.title('Model Loss')
plt.ylabel('Loss')
plt.xlabel('Epochs')
plt.legend()
plt.show()

```



```
[ ]: model.summary()
```

Model: "sequential"

Layer (type)	Output Shape	Param #
lstm (LSTM)	(None, 10, 128)	916992
dropout (Dropout)	(None, 10, 128)	0
batch_normalization (Batch Normalization)	(None, 10, 128)	512
lstm_1 (LSTM)	(None, 256)	394240
dropout_1 (Dropout)	(None, 256)	0
dense (Dense)	(None, 128)	32896
dropout_2 (Dropout)	(None, 128)	0
dense_1 (Dense)	(None, 53)	6837

=====
Total params: 1351477 (5.16 MB)

Trainable params: 1351221 (5.15 MB)
Non-trainable params: 256 (1.00 KB)

Store the model data for later use in the Inference

```
[ ]: model_dir = 'model-' + MODEL_VERSION + '/'
model_name = 'model-' + MODEL_VERSION + '.h5'
model.save(model_dir + model_name)
labels_name = 'labels-' + MODEL_VERSION + '.npy'
np.save(model_dir + labels_name, actions)

df_csv = pd.DataFrame(actions)
labels_csv_name = 'labels-' + MODEL_VERSION + '.csv'
df_csv.to_csv(model_dir + labels_csv_name, index=False)
```

```
/home/user/.local/lib/python3.10/site-
packages/keras/src/engine/training.py:3079: UserWarning: You are saving your
model as an HDF5 file via `model.save()`. This file format is considered legacy.
We recommend using instead the native Keras format, e.g.
`model.save('my_model.keras')`.
  saving_api.save_model(
```

```
[ ]: predictions = model.predict(X_test)
predicted_classes = np.argmax(predictions, axis=1)
true_classes = np.argmax(y_test, axis=1)

accuracy = accuracy_score(true_classes, predicted_classes)
precision = precision_score(true_classes, predicted_classes, average='weighted')
recall = recall_score(true_classes, predicted_classes, average='weighted')
f1 = f1_score(true_classes, predicted_classes, average='weighted')
report = classification_report(true_classes, predicted_classes,
    target_names=actions)

with open(model_dir + 'model_metrics.txt', 'w') as file:
    file.write(f"Accuracy: {accuracy}\n")
    file.write(f"Precision: {precision}\n")
    file.write(f"Recall: {recall}\n")
    file.write(f"F1 Score: {f1}\n")
    file.write(f"\nClassification Report:\n{report}")

print(report)
```

```
63/63 [=====] - 1s 11ms/step
      precision    recall  f1-score   support
```

aunt	0.92	0.83	0.87	41
bird	0.85	0.72	0.78	46
black	0.74	0.70	0.72	20

brother	0.61	0.67	0.64	21
brown	0.86	0.95	0.90	44
bug	0.87	0.82	0.85	40
callonphone	0.81	0.71	0.76	42
cheek	0.69	0.67	0.68	36
clown	0.84	0.84	0.84	61
cow	0.76	0.74	0.75	46
cute	0.90	0.76	0.83	34
dad	0.60	0.68	0.64	38
doll	0.78	0.58	0.67	43
donkey	0.61	0.79	0.69	34
drink	0.76	0.70	0.73	37
ear	0.83	0.89	0.86	44
eye	0.81	0.69	0.75	32
feet	0.82	0.85	0.84	39
find	0.86	0.76	0.81	33
fireman	0.64	0.81	0.71	37
flower	0.79	0.74	0.76	35
for	0.81	0.55	0.65	31
frog	0.83	0.78	0.81	37
grandpa	0.63	0.65	0.64	26
grass	0.74	0.72	0.73	32
gum	0.69	0.80	0.74	44
hair	0.85	0.79	0.81	42
hen	0.82	0.66	0.73	41
home	0.57	0.71	0.63	24
horse	0.81	0.68	0.74	50
lamp	0.53	0.55	0.54	31
mad	0.53	0.55	0.54	31
mom	0.66	0.66	0.66	35
mouse	0.66	0.71	0.68	58
nose	0.95	0.83	0.89	42
owl	0.86	0.80	0.83	46
pig	0.82	0.86	0.84	36
police	0.79	0.78	0.79	54
radio	0.78	0.86	0.82	44
see	0.76	0.93	0.84	41
shhh	0.78	0.90	0.83	48
shirt	0.63	0.94	0.76	18
sick	0.83	0.83	0.83	29
stairs	0.72	0.66	0.69	35
stuck	0.68	0.71	0.70	21
taste	0.78	0.86	0.82	37
thirsty	0.69	0.72	0.71	25
tiger	0.74	0.72	0.73	36
uncle	0.77	0.79	0.78	52
water	0.88	0.88	0.88	48
who	0.70	0.77	0.73	48

yucky	0.80	0.64	0.71	25
zebra	0.72	0.75	0.73	24
accuracy			0.76	1994
macro avg	0.76	0.75	0.75	1994
weighted avg	0.77	0.76	0.76	1994

```
[ ]: if (save_high_performers):
    # Generate the classification report
    report = classification_report(true_classes, predicted_classes,
    ↪target_names=actions, output_dict=True)

    # Convert report to a DataFrame
    report_df = pd.DataFrame(report).transpose()

    # The last few rows are overall metrics (accuracy, macro avg, weighted
    ↪avg), so we remove them
    report_df = report_df[:-3]

    # Display the DataFrame sorted by F1-score
    report_df_sorted = report_df.sort_values(by='f1-score')

    high_performance_threshold = 0.82 # Define your threshold
    high_performing_categories = report_df_sorted[report_df_sorted['f1-score']
    ↪> high_performance_threshold]
    print(high_performing_categories.count())
    print(high_performing_categories)

    high_performing_labels = high_performing_categories.index.to_numpy()
    print(high_performing_labels)

    np.save(model_dir + 'high_performing_labels.npy', high_performing_labels)
```

```
precision    15
recall       15
f1-score     15
support      15
dtype: int64
```

	precision	recall	f1-score	support
taste	0.780488	0.864865	0.820513	37.0
cute	0.896552	0.764706	0.825397	34.0
sick	0.827586	0.827586	0.827586	29.0
owl	0.860465	0.804348	0.831461	46.0
shhh	0.781818	0.895833	0.834951	48.0
see	0.760000	0.926829	0.835165	41.0
feet	0.825000	0.846154	0.835443	39.0
clown	0.836066	0.836066	0.836066	61.0

```

pig      0.815789  0.861111  0.837838      36.0
bug      0.868421  0.825000  0.846154      40.0
ear      0.829787  0.886364  0.857143      44.0
aunt     0.918919  0.829268  0.871795      41.0
water    0.875000  0.875000  0.875000      48.0
nose     0.945946  0.833333  0.886076      42.0
brown    0.857143  0.954545  0.903226      44.0
['taste' 'cute' 'sick' 'owl' 'shhh' 'see' 'feet' 'clown' 'pig' 'bug' 'ear'
 'aunt' 'water' 'nose' 'brown']

```

```

[ ]: if (save_low_performers):
    # Generate the classification report
    report = classification_report(true_classes, predicted_classes,
    ↪target_names=actions, output_dict=True)

    # Convert report to a DataFrame
    report_df = pd.DataFrame(report).transpose()

    # The last few rows are overall metrics (accuracy, macro avg, weighted
    ↪avg), so we remove them
    report_df = report_df[:-3]

    # Display the DataFrame sorted by F1-score
    report_df_sorted = report_df.sort_values(by='f1-score')

    low_performance_threshold = 0.6 # Define your threshold
    low_performing_categories = report_df_sorted[report_df_sorted['f1-score'] <
    ↪low_performance_threshold]
    print(low_performing_categories.count())
    print(low_performing_categories)

    low_performing_labels = low_performing_categories.index.to_numpy()
    print(low_performing_labels)

    np.save(model_dir + 'low_performing_labels.npy', low_performing_labels)

```

```

[ ]: res = model.predict(X_test)

```

```

[ ]: test_index = 10
    print(actions[np.argmax(res[test_index])])
    print(actions[np.argmax(y_test[test_index])])

```