

Animals of the Complexity Zoo

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Results of last course evaluations

- This chapter is not understood by students. Needs to be expanded.

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- As my kids used to say, "Do these sound alike?"
 - Although seemingly related and superficially similar, the first of each pair is trivial; the second, probably not.

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Why do we cover this in Algorithm design?

- As a computer scientist: Proving a problem to be NP-Complete is interesting
- As a software engineer: Knowing that a problem is NP-Complete means "try approximations"

- In this course, we will hand-wave the fine points of complexity classes. To really understand the material you need to take **Theory of Computation**.
 - Need precise definition of *language*.
 - Need precise definition of *Turing machine*.
 - Alternatively, need precise definition of *Lambda calculus*.
- Technically, only problems with Yes/No answers should be considered here but the conversion from an optimization problem to a Yes/No problem is trivial (assuming one knows how to binary search).

- We will discuss only problems with binary answers (Yes/No) or (True/False).
- Many problems we have seen are optimization problem.
- But we can always recast an optimization problem into a Yes/No problem.

Convert optimization to Yes/No

Optimization Problem

Find the shortest path on a graph G from s to t .

Yes/No version

Is there a path in G from s to t of cost at most k ?

Conversion

- Solve the optimization problem.
- Say the shortest path has cost l . Return $l \leq k$.

Conclusion

If you can solve optimization problems fast, you can solve the Yes/No problem fast.

The reverse also holds.

Convert Yes/No to optimization

Yes/No version

Is there a path in G from s to t of cost at most k ?

Optimization Problem

Find the shortest path on a graph G from s to t .

Conversion

- Let l be zero and h be the sum of all edge costs
- While $l \leq h$
 - Let $m = \lceil (l + h)/2 \rceil$
 - Is there a path of cost at most m ?
 - If yes let $h = m$ and save this path
 - If no let $l = m + 1$
- Return the saved path

Can you do this for all optimization problem?

Yes, as long as you have a lower and upper bound on optimal value.

What **is** a problem?

Abstract problem Q

A mapping between the set I of problem instances and the set S of problem solutions.

Example: Shortest paths (SP)

An instance of SP is a triple of a graph and two vertices, s and t from this graph. A solution is a sequence of adjacent vertices starting at s and ending at t (Or possible the empty sequence to indicate that no path exists.)

Concrete problem statement

Encoding

An encoding of a set S of objects is a mapping from s to the set $\{0, 1\}^*$ (the set of all finite binary strings.)

Example Integers, ASCII

- $0, 1, 2, 3 \rightarrow 000, 001, 010, 011$
- $A, B, C \rightarrow 1000001, 1000010, 1000011$

A concrete problem

Is an encoding of an instance of a problem.

Solvable

An algorithm solves a concrete problem in time $O(T(n))$ if, when it is provided by an instance of length n bits, the algorithm can produce the solution in time $O(T(n))$.

Polynomial-time solvable

A concrete problem of length n is polynomial-time solvable if there exists an algorithm to solve it in time $O(n^k)$ for some k .

Warning

We have never used this definition before when talking about runtime. The dependence on the **number of bits** is crucial. Before we simply used a loosely stated dependence on the **input**.

Our first definition.

The class \mathcal{P}

The set of concrete decision problems that are polynomial-time solvable.

Dependence on encoding

- Consider a problem where the input is a simple integer k .
- And an algorithm running in time $O(k)$.
- If the encoding is unary (an integer k is encoded by k bits) then the runtime is linear
- If the encoding is two-complement, then the number of bits is $\approx \log k$ and the runtime is exponential!

Assumption

From here onward, we will assume a “reasonable” encoding.

Example

Before

Sorting an array of n elements by Heapsort is done in time proportional to $n \log n$.

Now

Sorting an array of n elements each of 64 bits can be done in time bounded above by a polynomial in n .

Polynomial-time computable

A function $f : \{0, 1\}^* \rightarrow \{0, 1\}^*$ is polynomial-time computable if there exists a polynomial-time algorithm that, given any input $x \in \{0, 1\}^*$, produces $f(x)$.

Examples of problems in \mathcal{P}

Pretty much all problems we considered during the past months
For example:

- Sorting n integers on 64 bits ($n \log n$).
- Searching a sorted n long array of 64 bits integers ($\log n$).
- Matrix multiplication of $n \times n$ matrices of 64 bits floats ($n^{2.7}$).
 - Assuming scalar multiplication of floats is constant.

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- Why? We have solved all of the above!
 - Yes, in time proportional to 2^n (or worse)

Our second definition.

The class \mathcal{NP}

A problem P , formulated such that it can be answered with either Yes or No, is in the class \mathcal{NP} if there is a method, given a problem instance and some additional data (called the certificate) to verify in polytime that the answer **Yes** is correct.

Note

NP does **not** stand for non-polynomial; it stands for non-deterministic polynomial.

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Can you prove that these are in \mathcal{P} , in \mathcal{NP} ?

- Given a graph and weights on the edge, is there a spanning tree of weight at most K ?
- Given a graph and weights of the node, is there an independent set of vertices of weight at least k ?
- Given a graph, is there a set of edges of size at most k that, if deleted, disconnects the graph?

Stop and think

- We have defined two sets of problems.
 - \mathcal{P}
 - \mathcal{NP}
- What is the relation, if any, between the two sets?

$$\mathcal{P} \subseteq \mathcal{NP}$$

Since any problem in \mathcal{P} can be solved in polytime, we can ignore whatever certificate is provided.

Open questions

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- $\mathcal{P} = \mathcal{NP}$?

Our third definition

The class $co - \mathcal{NP}$

A problem P , formulated such that it can be answered with either Yes or No, is in the class $co - \mathcal{NP}$ if there is a method, given a problem instance and some additional data (called the certificate) to verify in polytime that the answer **No** is correct.

Examples of problems in $co - \mathcal{NP}$

- Given a logical expression with and, or, and negation.

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Contrast and understand

The class \mathcal{NP}

A problem P , formulated such that it can be answered with either Yes or No, is in the class \mathcal{NP} if there is a method, given a problem instance and some additional data (called the certificate) to verify in polytime that the answer **Yes** is correct.

The class $co - \mathcal{NP}$

A problem P , formulated such that it can be answered with either Yes or No, is in the class $co - \mathcal{NP}$ if there is a method, given a problem instance and some additional data (called the certificate) to verify in polytime that the answer **No** is correct.

Are there any problems in $co - \mathcal{NP} \cap \mathcal{NP}$?

Discuss

Problems in $\text{co-NP} \cap \text{NP}$?

- All of \mathcal{P}

Problems in $\text{co-}\mathcal{NP} \cap \mathcal{NP}$?

- All of \mathcal{P}
- More interesting: Integer factorization.

Second set relation

$$\mathcal{P} \subseteq co - \mathcal{NP}$$

Since any problem in \mathcal{P} can be solved in polytime, the certificate can be the empty set.

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- $\mathcal{NP} = co - \mathcal{NP}$?

Reducibility

A problem instance Q can be **reduced** to problem instance Q' if there is a mechanism to construct Q' from Q in such a manner that, if we answer Q' , we can extract the answer to Q .

We can also add constraints on the difficulty of the reduction. For instance, requiring that the transformation be done in polytime.

- We use the concept of reducibility to
 - Transform a new problem into a problem we already know how to solve. (A practical application.)
 - Transform a problem A into a problem B to show that A cannot be any more difficult to solve than B. (A theoretical application.)

- Exponentiation is trivially reduced to multiplication.
- We considered the problem of computing integer square roots using only the four basic arithmetic operators. This reduces square roots to the basic operations.

Theoretical reducibility

Problem: Hamiltonian cycle (HC)

Given a graph G , is there a Hamiltonian tour, a tour visiting each node exactly once?

Problem: Travelling Salesman tour (TSP)

Given a graph complete K and a set of weights on the edges, what is the smallest cost tour?

Reducible?

Can you transform an instance of HC, in polytime, into an instance of TSP such that, if you solve the TSP, you can answer the HC question in the original graph?

Reducing Hamiltonian cycle to TSP.

Assume we know how to solve TSP and want to solve HC.

- Q: HC on graph G
- Q': Construct the complete graph K with same nodes as G . If edge (i,j) exists in G , put weight 1 on edge (i,j) in G' . Otherwise put weight 2.
- Solve TSP on K . If the minimal tour is of cost $|V|$, then Yes, there is a Hamiltonian tour in G (namely the same one as the TSP tour in K). If the cost is higher, then there is no such tour in G .
- Conclusion: HC is no harder than TSP.

Why do we care? Here is the first reason:

Theorem: If P_1 is polytime reducible to P_2 and $P_2 \in \mathcal{P}$ then $P_1 \in \mathcal{P}$

The main requirement, of course, is that the transformation is done in polytime. This means that if we can reduce a problem to an 'easy' problem, it is also 'easy'.

Fifth definition

The class \mathcal{NPC} (NP-Complete)

A problem P is in class \mathcal{NPC} if it is in \mathcal{NP} and if **all** other problems in \mathcal{NP} can be reduced to P . (Informally, these are the most difficult problems in \mathcal{NP} .)

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- This class currently has thousands of problems.
- We do not have to do thousands of reductions to add a problem P to this class; we need only to take one problem of this class and reduce it to P .
- The textbook also defines the class \mathcal{NP} -Hard as the class of problems that satisfy the definition of \mathcal{NPC} except that they may not be in \mathcal{NP} .

Why do we care? Here is the second reason:

Theorem: if P_1 is polytime reducible to P_2 and $P_1 \in \mathcal{NPC}$ then $P_2 \in \mathcal{NPC}$.

This, informally, means that P_2 is no easier than P_1 . So, if P_1 is 'hard' then P_2 is 'hard'.

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 - Therefore if you can solve satisfiability, you can solve them all!
 - (The proof is somewhat more complicated :-)

- Thousands of problems were shown to be no easier than SAT.
- To show a problem to be in \mathcal{NPC} you need
 - To show it is in \mathcal{NP} (Typically easy)
 - Pick a problem already in \mathcal{NPC} (Thousands to choose from)
 - Reduce it to your “new” problem. (Needs clever constructions)
 - Show the reduction can be done in polytime. (Usually easy)
 - Show that an answer to one problem provides an answer to the other.

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 - Construct a graph $G = (V, E)$

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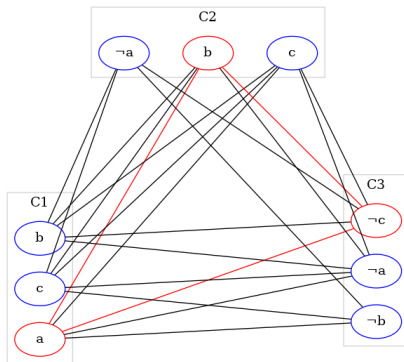
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 - Claim: ϕ is satisfiable if and only if G has a clique of size k .

Clique is in \mathcal{NP}

- Consider $(a \vee b \vee c) \wedge (\neg a \vee b \vee c) \wedge (\neg a \vee \neg b \vee \neg c)$



- The red clique indicates $a, b, \neg c$ true, satisfying the expression.

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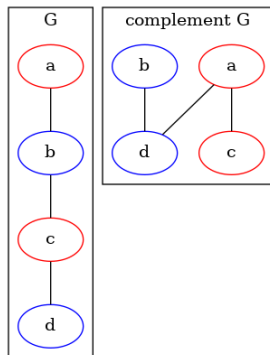
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Vertex cover is in \mathcal{NPC}



- Vertex cover of size 2 in G : Clique of size $4 - 2$ in \overline{G}
- No Vertex cover of size 1 in G : No Clique of size $4 - 1$ in \overline{G}

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 - Construct $T = k4^{|E|} + \sum_{j=0}^{|E|-1} 2 \cdot 4^j$
 - Claim: G has a vertex cover of size k iff there is a subset of the rows summing to T .

Subset sum example

- Consider the graph

$(x_0, x_1, x_2, x_3, x_4, (x_0, x_3), (x_0, x_4), (x_1, x_2), (x_1, x_4), (x_2, x_4))$

- Its incidence matrix is

$$\begin{bmatrix} 0 & 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 \end{bmatrix}$$

Subset sum example

- Graph

$$G = (\{x_0, x_1, x_2, x_3, x_4\}, \{(x_0, x_3), (x_0, x_4), (x_1, x_2), (x_1, x_4), (x_2, x_4)\})$$

- The embedding is

$$\begin{array}{rcll} x_0 & = & 1 & 0 & 0 & 1 & 0 & 1 & = & 1041 \\ x_1 & = & 1 & 1 & 0 & 0 & 1 & 0 & = & 1284 \\ x_2 & = & 1 & 1 & 1 & 0 & 0 & 0 & = & 1344 \\ x_3 & = & 1 & 0 & 0 & 1 & 0 & 0 & = & 1040 \\ x_4 & = & 1 & 0 & 1 & 0 & 1 & 1 & = & 1093 \\ & & 0 & 1 & 0 & 0 & 0 & 0 & = & 256 \\ & & 0 & 0 & 1 & 0 & 0 & 0 & = & 64 \\ & & 0 & 0 & 0 & 1 & 0 & 0 & = & 16 \\ & & 0 & 0 & 0 & 0 & 1 & 0 & = & 4 \\ & & 0 & 0 & 0 & 0 & 0 & 1 & = & 1 \\ T & = & 3 & 2 & 2 & 2 & 2 & 2 & = & 3754 \end{array}$$

- G has a VC of size 3 iff there is a subset of $\{1041, 1284, \dots, 1\}$ summing to 3754.

What we have shown

- SAT is as hard as anything in \mathcal{NP} hence in \mathcal{NPC}
- Clique is no easier than SAT
- Vertex Cover is no easier than Clique
- Subset Sum is no easier than Vertex Cover
- Hence all of the above are in \mathcal{NPC}

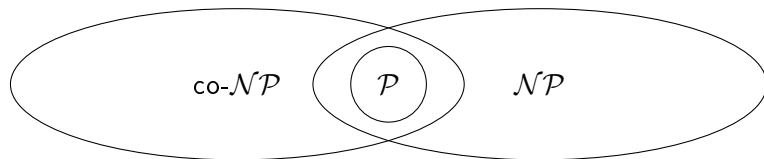
Third set relation

$$\mathcal{NPC} \subseteq \mathcal{NP}$$

By definition.

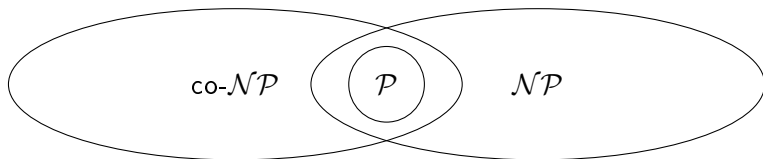
- $\mathcal{P} = \mathcal{NP} = \text{co-}\mathcal{NP} = \mathcal{NPC}$?

Fact (though very misleading picture)



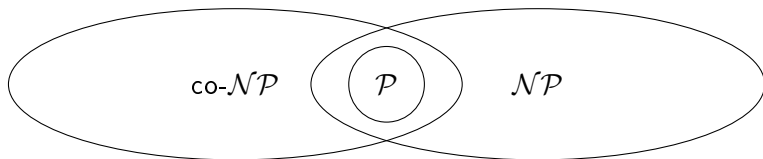
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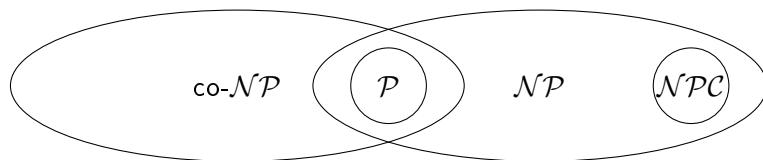
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 - Because there is not a single instance of a problem known to be in the bubbles but not in \mathcal{P} .

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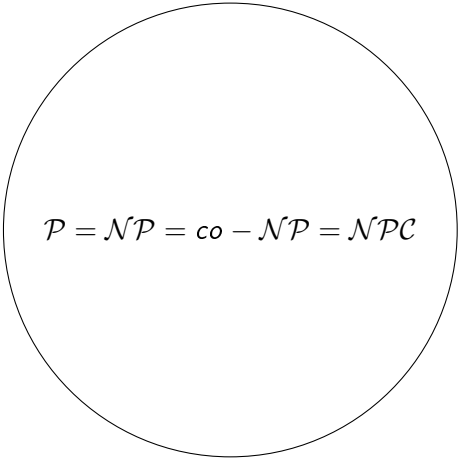


- Why misleading?
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- Where is NPC ?

Conjecture ($\mathcal{P} \neq \mathcal{NP}$)



Conjecture ($\mathcal{P} = \mathcal{NP}$)


$$\mathcal{P} = \mathcal{NP} = co - \mathcal{NP} = \mathcal{NPC}$$

So I'll state, as one of the few definite conclusions of this survey, that $\mathcal{P} = \mathcal{NP}?$ is either true or false. It's one or the other. But we may not be able to prove which way it goes, and we may not be able to prove that we can't prove it.

– Lance Fortnow, University of Chicago

This is not the full story

Have a look

https://complexityzoo.uwaterloo.ca/Complexity_Zoo

- There **are** problems harder than \mathcal{NPC} .
- We ignored space.

- What would you conclude if I proved that TSP is in \mathcal{P} ?
- What would you conclude if I proved that TSP is not in \mathcal{P} ?