

Table 2.2 Summary of Governing Differential Equations for Ideal Elements

Type of Element	Physical Element	Governing Equation	Energy E or Power \mathcal{P}	Symbol
Inductive storage	Electrical inductance	$v_{21} = L \frac{di}{dt}$	$E = \frac{1}{2} Li^2$	
	Translational spring	$v_{21} = \frac{1}{k} \frac{dF}{dt}$	$E = \frac{1}{2} \frac{F^2}{k}$	
	Rotational spring	$\omega_{21} = \frac{1}{k} \frac{dT}{dt}$	$E = \frac{1}{2} \frac{T^2}{k}$	
	Fluid inertia	$P_{21} = I \frac{dQ}{dt}$	$E = \frac{1}{2} IQ^2$	
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Capacitive storage	Electrical capacitance	$i = C \frac{dv_{21}}{dt}$	$E = \frac{1}{2} Cv_{21}^2$	
	Translational mass	$F = M \frac{dv_2}{dt}$	$E = \frac{1}{2} Mv_2^2$	
	Rotational mass	$T = J \frac{d\omega_2}{dt}$	$E = \frac{1}{2} J\omega_2^2$	
	Fluid capacitance	$Q = C_f \frac{dP_{21}}{dt}$	$E = \frac{1}{2} C_f P_{21}^2$	
	Thermal capacitance	$q = C_t \frac{dT_2}{dt}$	$E = C_t T_2$	
Energy dissipators	Electrical resistance	$i = \frac{1}{R} v_{21}$	$\mathcal{P} = \frac{1}{R} v_{21}^2$	
	Translational damper	$F = bv_{21}$	$\mathcal{P} = bv_{21}^2$	
	Rotational damper	$T = b\omega_{21}$	$\mathcal{P} = b\omega_{21}^2$	
	Fluid resistance	$Q = \frac{1}{R_f} P_{21}$	$\mathcal{P} = \frac{1}{R_f} P_{21}^2$	
	Thermal resistance	$q = \frac{1}{R_t} T_{21}$	$\mathcal{P} = \frac{1}{R_t} T_{21}$	

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Percent Peak Overshoot Versus Damping Ratio for Second-Order System							
Damping ratio	0.9	0.8	0.7	0.6	0.5	0.4	0.3
Percent overshoot	0.2	1.5	4.6	9.5	16.3	25.4	37.2

$$T_s = 4\tau = \frac{4}{\zeta\omega_n}$$

$$T_p = \frac{\pi}{\omega_n\sqrt{1-\zeta^2}}$$

$$P.O. = 100e^{-\zeta\pi/\sqrt{1-\zeta^2}}$$

Table 2.3 Important Laplace Transform Pairs

$f(t)$	$F(s)$
Step function, $u(t)$	$\frac{1}{s}$
e^{-at}	$\frac{1}{s + a}$
$\sin \omega t$	$\frac{\omega}{s^2 + \omega^2}$
$\cos \omega t$	$\frac{s}{s^2 + \omega^2}$
t^n	$\frac{n!}{s^{n+1}}$
$f^{(k)}(t) = \frac{d^k f(t)}{dt^k}$	$s^k F(s) - s^{k-1}f(0^-) - s^{k-2}f'(0^-) - \dots - f^{(k-1)}(0^-)$
$\int_{-\infty}^t f(t) dt$	$\frac{F(s)}{s} + \frac{1}{s} \int_{-\infty}^0 f(t) dt$
Impulse function $\delta(t)$	1
$e^{-at} \sin \omega t$	$\frac{\omega}{(s + a)^2 + \omega^2}$
$e^{-at} \cos \omega t$	$\frac{s + a}{(s + a)^2 + \omega^2}$
$\frac{1}{\omega}[(\alpha - a)^2 + \omega^2]^{1/2} e^{-at} \sin(\omega t + \phi),$ $\phi = \tan^{-1} \frac{\omega}{\alpha - a}$	$\frac{s + \alpha}{(s + a)^2 + \omega^2}$
$\frac{\omega_n}{\sqrt{1 - \xi^2}} e^{-\xi \omega_n t} \sin \omega_n \sqrt{1 - \xi^2} t, \xi < 1$ $\frac{1}{a^2 + \omega^2} + \frac{1}{\omega \sqrt{a^2 + \omega^2}} e^{-at} \sin(\omega t - \phi),$ $\phi = \tan^{-1} \frac{\omega}{-a}$	$\frac{\omega_n^2}{s^2 + 2\xi \omega_n s + \omega_n^2}$ $\frac{1}{s[(s + a)^2 + \omega^2]}$
$1 - \frac{1}{\sqrt{1 - \xi^2}} e^{-\xi \omega_n t} \sin(\omega_n \sqrt{1 - \xi^2} t + \phi),$ $\phi = \cos^{-1} \xi, \xi < 1$ $\frac{\alpha}{a^2 + \omega^2} + \frac{1}{\omega} \left[\frac{(\alpha - a)^2 + \omega^2}{a^2 + \omega^2} \right]^{1/2} e^{-at} \sin(\omega t + \phi).$ $\phi = \tan^{-1} \frac{\omega}{\alpha - a} - \tan^{-1} \frac{\omega}{-a}$	$\frac{\omega_n^2}{s(s^2 + 2\xi \omega_n s + \omega_n^2)}$ $\frac{s + \alpha}{s[(s + a)^2 + \omega^2]}$

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