Faculty of

Engineering



School of Electrical, Electronic & Computer Engineering

EERI 418

Practical 1

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Submitted to:

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ABSTRACT

THIS IS THE ABSTRACT, LOCATED IN FRONTBACKMATTER. EDIT OR UNCOMMENT

DECLARATION

I, MJ Bezuidenhout, declare that this report is a presentation of my own original work. Whenever contributions of others are involved, every effort was made to indicate this clearly, with due reference to the literature. No part of this work has been submitted in the past, or is being submitted, for a degree or examination at any other university or course.

Potchefstroom, February 23, 2017

MJ Bezuidenhout, February 23, 2017

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| AC | RONYMS | | |
| PID | Proportional,Integral & differential Controller | | |
| ΡΙ | Proportional& differential Controller | | |
| Ts | Settling Time | | |
| РО | Percent Overshoot | | |

INTRODUCTION



Figure 1: example image for code reference

| LABITUR BONORUM PRI NO | QUE VISTA | HUMAN |
|------------------------|-----------|--------------|
| fastidii ea ius | germano | demonstratea |
| suscipit instructior | titulo | personas |
| quaestio philosophia | facto | demonstrated |

Table 1: Autem usu id.

PROBLEM STATEMENT

METHODOLOGY

RESULTS

CONCLUSION

BIBLIOGRAPHY