



Instance-dependent Sample Complexity Bounds for Zero-sum Matrix Games

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Two player zero-sum games

We have two players X and Y.

X player has m different strategies

Y player has n different strategies

If X chooses a strategy i and Y chooses a strategy j , then X receives a reward $A(i,j)$ and Y receives a reward $-A(i,j)$



+1



-1

Two player zero-sum matrix games

Zero-sum games can be represented by a matrix $A \in \mathbb{R}^{n \times m}$.

Let Δ_m be m-dimensional probability simplex.

$(x^*, y^*) \in \Delta_n \times \Delta_m$ is a Nash Equilibrium if the following holds:

$$\langle x, Ay^* \rangle \leq \langle x^*, Ay^* \rangle \leq \langle x^*, Ay \rangle$$

for all $(x, y) \in \Delta_n \times \Delta_m$

Example

$$A = \begin{bmatrix} 3 & 2 \\ 1 & 4 \end{bmatrix} \quad x^* = (0.75, 0.25) \quad y^* = (0.5, 0.5)$$
$$\langle x^*, Ay^* \rangle = 2.5$$

$$A^\top x^* = \begin{bmatrix} 2.5 \\ 2.5 \end{bmatrix} \quad Ay^* = \begin{bmatrix} 2.5 \\ 2.5 \end{bmatrix}$$

Two player zero-sum matrix games

Let $V_A^* := \langle x^*, Ay^* \rangle$ denote the value of the game.

Due to Von Neumann's minimax theorem we have:

$$V_A^* = \max_{x \in \Delta_n} \min_{y \in \Delta_m} \langle x, Ay \rangle = \min_{y \in \Delta_m} \max_{x \in \Delta_n} \langle x, Ay \rangle$$

One can formulate any zero-sum game as an LP and find the Nash Equilibrium.

Noisy setting

In this setting, the matrix A is not directly available.

Instead, one can query an element (i,j) of the matrix A and receive a value $X_{i,j} = A_{i,j} + \eta$ where η is zero-mean 1-sub-gaussian noise.

The aim is now to compute some kind of approximate solution concept.

Solution concepts

1. ε -good solution: We aim to find $(x, y) \in \Delta_n \times \Delta_m$ such that:

$$|V_A^* - \langle x, Ay \rangle| \leq \varepsilon$$

2. ε -Nash Equilibrium: We aim to find $(x, y) \in \Delta_n \times \Delta_m$ such that:

$$\langle x, Ay \rangle \geq \langle x', Ay \rangle - \varepsilon$$

$$\langle x, Ay' \rangle \geq \langle x, Ay \rangle - \varepsilon$$

for all $(x', y') \in \Delta_n \times \Delta_m$

Goal

Minimize the number of samples required to find the approximate solution concepts

Simple Algorithm

Sample each element of the matrix $A \in \mathbb{R}^{n \times m}$
for $\frac{8 \log(2mn/\delta)}{\varepsilon^2}$ times.

Return the Nash Equilibrium of the empirical matrix \bar{A}

Minimax Upper Bound

Using sub-gaussian tail bounds, we get the following:

$$|\bar{A}_{ij} - A_{ij}| \leq \varepsilon/2 \text{ for all } (i, j) \in [m] \times [n]$$

Minimax Upper Bound

For any x' in the m -dimensional simplex, we have the following:

$$\begin{aligned}\langle x, Ay \rangle &= \langle x, \bar{A}y \rangle + \sum_{i,j} (A_{ij} - \bar{A}_{i,j})x_i y_j \\ &\geq \langle x, \bar{A}y \rangle - \frac{\varepsilon}{2} \\ &\geq \langle x', \bar{A}y \rangle - \frac{\varepsilon}{2} \quad (\text{as } (x, y) \text{ is a NE of } \bar{A}) \\ &\geq \langle x', Ay \rangle - \varepsilon\end{aligned}$$

Minimax Upper Bound

Similarly, for any y' in the n -dimensional simplex, we have the following:

$$\langle x, Ay' \rangle \geq \langle x, Ay \rangle - \varepsilon$$

Hence, (x, y) is an ε -Nash Equilibrium of A .

Instance-dependent bounds

Stochastic Multi-armed bandits is a special case of our noisy setting. Instance dependent sample complexity bounds to find the best arm is well studied.

We aim to establish similar instance dependent bounds to find either ϵ -good solution or ϵ -Nash Equilibrium in zero-sum games.

Multi-Armed Bandits

We have n arms with means $\mu_1 > \mu_2 \geq \dots \geq \mu_n$

The problem can be considered an $n \times 1$ game as follows.

$$\text{Optimal strategy} \rightarrow \left[\begin{array}{c} \mu_1 \\ \mu_2 \\ \vdots \\ \mu_n \end{array} \right] \} \Delta_g > 0$$

$n \times 2$ matrix games ($n > 2$)

Consider a matrix game $A \in \mathbb{R}^{n \times 2}$ with unique Nash Equilibrium (x^*, y^*) which is not a PSNE.

It can be shown that $|Supp(x^*)| = |Supp(y^*)| = 2$

$$Supp(x^*) \left\{ \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \\ a_{31} & a_{32} \\ \vdots & \vdots \\ a_{n1} & a_{n2} \end{bmatrix} \right.$$

$n \times 2$ matrix games ($n > 2$)

Consider a matrix game $A \in \mathbb{R}^{n \times 2}$ with unique Nash Equilibrium (x^*, y^*) which is not a PSNE.

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Examples

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0.05 & 0.85 \end{bmatrix}$$

$$\mathbf{x}^* \quad (0.5, 0.5, 0)$$

$$\mathbf{y}^* \quad (0.5, 0.5)$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0.1 & 0.9 \end{bmatrix}$$

$$\begin{aligned} \mathbf{x}^* & \quad (0.5, 0.5, 0) \\ & \quad (4/9, 0, 5/9) \end{aligned}$$

$$\mathbf{y}^* \quad (0.5, 0.5)$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0.15 & 0.95 \end{bmatrix}$$

$$\mathbf{x}^* \quad (4/9, 0, 5/9)$$

$$\mathbf{y}^* \quad (19/36, 17/36)$$

Examples

$$y^* \quad (0.5, 0.5)$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0.05 & 0.85 \end{bmatrix}$$

$$(0.5, 0.5)$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0.1 & 0.9 \end{bmatrix}$$

$$(19/36, 17/36)$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0.15 & 0.95 \end{bmatrix}$$

$$\langle y^*, (A_{i1}, A_{i2}) \rangle \quad \begin{bmatrix} 0.5 \\ 0.5 \\ 0.45 \end{bmatrix}$$

$$\begin{bmatrix} 0.5 \\ 0.5 \\ 0.5 \end{bmatrix}$$

$$\begin{bmatrix} 19/36 \\ 17/36 \\ 19/36 \end{bmatrix}$$

Examples

$$y^* \quad (0.5, 0.5)$$

$$\begin{bmatrix} \boxed{1} & \boxed{0} \\ \boxed{0} & \boxed{1} \\ 0.05 & 0.85 \end{bmatrix}$$

$$\langle y^*, (A_{i1}, A_{i2}) \rangle \quad \begin{bmatrix} \boxed{0.5} \\ \boxed{0.5} \\ 0.45 \end{bmatrix}$$

$$(0.5, 0.5)$$

$$\begin{bmatrix} \boxed{1} & \boxed{0} \\ \boxed{0} & \boxed{1} \\ \boxed{0.1} & \boxed{0.9} \end{bmatrix}$$

$$\begin{bmatrix} \boxed{0.5} \\ \boxed{0.5} \\ \boxed{0.5} \end{bmatrix}$$

$$(19/36, 17/36)$$

$$\begin{bmatrix} \boxed{1} & \boxed{0} \\ 0 & 1 \\ \boxed{0.15} & \boxed{0.95} \end{bmatrix}$$

$$\begin{bmatrix} \boxed{19/36} \\ 17/36 \\ \boxed{19/36} \end{bmatrix}$$

Instance dependent parameters for $n \times 2$ games

Suppose that A has a unique Nash equilibrium (x^*, y^*) such that $\text{Supp}(x^*) = \{i_1, i_2\}$. Let $A_{i_1 1} > A_{i_1 2}$ and $A_{i_2 1} > A_{i_2 2}$ and define

$$\Delta_g := \min_{i \in [n] \setminus \{i_1, i_2\}} r_i \cdot (V_A^* - \langle y^*, (A_{i1}, A_{i2}) \rangle)$$

where

$$r_i = \frac{|A_{i_1 1} - A_{i_1 2}| + |A_{i_2 1} - A_{i_2 2}|}{|A_{i_1 1} - A_{i_1 2}| + |A_{i_2 1} - A_{i_2 2}| + |A_{i1} - A_{i2}|}$$

Instance dependent parameters for $n \times 2$ games

$$\Delta_{\min} = \min\{\min_i\{|A_{i1} - A_{i2}|\}, \min_{j,k:j \neq k}\{|A_{j1} - A_{k1}|\}, \min_{j,k:j \neq k}\{|A_{j2} - A_{k2}|\}\}$$

$$A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \\ a_{31} & a_{32} \\ \vdots & \vdots \\ a_{n1} & a_{n2} \end{bmatrix}$$

Results for $n \times 2$ games

Consider a game defined by a fixed 3×2 matrix A which has a unique Nash equilibrium which is not a pure-strategy Nash equilibrium.

We show under some mild assumptions that to find an ε -good solution for the matrix game A with probability at least $1 - \delta$, we require at least $\Omega\left(\frac{1}{\Delta_g^2} \log(1/\delta)\right)$ samples from A

Results for $n \times 2$ games

We complement our lower bound result by designing an algorithm that, with probability at least $1 - \delta$, samples each element of an $n \times 2$ matrix A for

$$O \left(\min \left\{ \frac{1}{\varepsilon^2}, \max \left\{ \frac{1}{\Delta_{\min}^2}, \frac{1}{\Delta_g^2} \right\} \right\} \log(1/\delta) \right)$$

times (ignoring some logarithmic factors) and either returns $\text{Supp}(x^*)$ and $\text{Supp}(y^*)$ or concludes that Δ_g is not sufficiently large compared to ε .

Key ideas behind the Algorithm to find Support

$$\Delta_g \approx V_A^* - \min_{i \notin \text{Supp}(x^*)} \langle y^*, (A_{i1}, A_{i2}) \rangle$$

$$\bar{\Delta}_g \approx V_{\bar{A}}^* - \min_{i \notin \text{Supp}(x^*)} \langle \bar{y}^*, (\bar{A}_{i1}, \bar{A}_{i2}) \rangle$$

$$\underbrace{\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \\ a_{31} & a_{32} \\ \vdots & \vdots \\ a_{n1} & a_{n2} \end{bmatrix}}_A \} \Delta_g$$

$$\underbrace{\begin{bmatrix} \bar{a}_{11} & \bar{a}_{12} \\ \bar{a}_{21} & \bar{a}_{22} \\ \bar{a}_{31} & \bar{a}_{32} \\ \vdots & \vdots \\ \bar{a}_{n1} & \bar{a}_{n2} \end{bmatrix}}_{\bar{A}} \} \bar{\Delta}_g$$

(\bar{x}^*, \bar{y}^*) is the NE in \bar{A}

If every element of A is sampled for $\frac{1}{\Delta_g^2}$ then $\Delta_g \approx \bar{\Delta}_g$

Key ideas behind the Algorithm to find Support

$$\Delta_g \approx V_A^* - \min_{i \notin \text{Supp}(x^*)} \langle y^*, (A_{i1}, A_{i2}) \rangle$$

$$\bar{\Delta}_g \approx V_{\bar{A}}^* - \min_{i \notin \text{Supp}(x^*)} \langle \bar{y}^*, (\bar{A}_{i1}, \bar{A}_{i2}) \rangle$$

If we sample each element of A for $\frac{1}{\Delta^2}$ times then $|\Delta_g - \bar{\Delta}_g| \leq \Delta$

So in $\frac{1}{\Delta_g^2}$ steps we can estimate Δ_g and we are done.

What's the problem here?

Key ideas behind the Algorithm to find Support

$$\Delta_g \approx V_A^* - \min_{i \notin \text{Supp}(x^*)} \langle y^*, (A_{i1}, A_{i2}) \rangle$$

$$\bar{\Delta}_g \approx V_{\bar{A}}^* - \min_{i \notin \text{Supp}(x^*)} \langle \bar{y}^*, (\bar{A}_{i1}, \bar{A}_{i2}) \rangle$$

If we sample each element of A for $\frac{1}{\Delta^2}$ times then $|\Delta_g - \bar{\Delta}_g| \leq \Delta$

So in $\frac{1}{\Delta_g^2}$ steps we can estimate Δ_g and we are done.

What's the problem here?

We don't know $\text{Supp}(x^*)$ hence can't measure $\bar{\Delta}_g$

Key ideas behind the Algorithm to find Support

What we can measure is instead the following:

$$\tilde{\Delta}_g \approx V_{\bar{A}}^* - \min_{i \notin \text{Supp}(\bar{x})} \langle \bar{y}, (\bar{A}_{i1}, \bar{A}_{i2}) \rangle$$

where (\bar{x}, \bar{y}) is the NE of the \bar{A}

$$\left[\begin{array}{cc} \bar{a}_{11} & \bar{a}_{12} \\ \bar{a}_{21} & \bar{a}_{22} \\ \bar{a}_{31} & \bar{a}_{32} \\ \vdots & \vdots \\ \bar{a}_{n1} & \bar{a}_{n2} \end{array} \right] \} \tilde{\Delta}_g$$

Key ideas behind the Algorithm to find Support

$$\tilde{\Delta}_g \approx V_A^* - \min_{i \notin \text{Supp}(\bar{x})} \langle \bar{y}, (\bar{A}_{i1}, \bar{A}_{i2}) \rangle$$

Saving grace:

$$\Delta'_g = V_A^* - \min_{i \in \text{Supp}(x)} \langle y, (A_{i1}, A_{i2}) \rangle < 0$$

where (x, y) is the NE of the submatrix of A with rows $\text{Supp}(\bar{x})$

$$\left[\begin{array}{cc} a_{11} & a_{12} \\ a_{21} & a_{22} \\ a_{31} & a_{32} \\ \vdots & \vdots \\ a_{n1} & a_{n2} \end{array} \right] \} \Delta'_g < 0 \quad \left[\begin{array}{cc} \bar{a}_{11} & \bar{a}_{12} \\ \bar{a}_{21} & \bar{a}_{22} \\ \bar{a}_{31} & \bar{a}_{32} \\ \vdots & \vdots \\ \bar{a}_{n1} & \bar{a}_{n2} \end{array} \right] \} \tilde{\Delta}_g < \Delta \text{ if we sample for } \frac{1}{\Delta^2} \text{ times}$$

Key ideas behind the Algorithm to find Support

$$\tilde{\Delta}_g \approx V_{\bar{A}}^* - \min_{i \notin \text{Supp}(\bar{x})} \langle \bar{y}, (\bar{A}_{i1}, \bar{A}_{i2}) \rangle$$

Hence, if we have sampled each element for $\frac{1}{\Delta^2}$ times, we stop only when the following holds:

$$\tilde{\Delta}_g > \Delta$$

And then we return the support of the empirical matrix.

Key ideas behind the Algorithm to find Support

$$\tilde{\Delta}_g \approx V_{\bar{A}}^* - \min_{i \notin \text{Supp}(\bar{x})} \langle \bar{y}, (\bar{A}_{i1}, \bar{A}_{i2}) \rangle$$

Hence, if we have sampled each element for $\frac{1}{\Delta^2}$ times, we stop only when the following holds:

$$\tilde{\Delta}_g > \Delta$$

Are we done? **NO**

Key ideas behind the Algorithm to find Support

$$\tilde{\Delta}_g \approx V_{\bar{A}}^* - \min_{i \notin \text{Supp}(\bar{x})} \langle \bar{y}, (\bar{A}_{i1}, \bar{A}_{i2}) \rangle$$

Hence, if we have sampled each element for $\frac{1}{\Delta^2}$ times, we stop only when the following holds:

$$\tilde{\Delta}_g > \Delta$$

Are we done? **NO**

Why? $\tilde{\Delta}_g > \Delta$ may-not hold at any time step

Key ideas behind the Algorithm to find Support

$$\tilde{\Delta}_g \approx V_{\bar{A}}^* - \min_{i \notin \text{Supp}(\bar{x})} \langle \bar{y}, (\bar{A}_{i1}, \bar{A}_{i2}) \rangle$$

$$\Delta_g \approx V_A^* - \min_{i \notin \text{Supp}(x^*)} \langle y^*, (A_{i1}, A_{i2}) \rangle$$

Hence, if we have sampled each element for $\frac{1}{\Delta^2}$ times, we stop only when the following holds:

$$\tilde{\Delta}_g > \Delta$$

$$\bar{\Delta}_g \approx V_{\bar{A}}^* - \min_{i \notin \text{Supp}(x^*)} \langle \bar{y}^*, (\bar{A}_{i1}, \bar{A}_{i2}) \rangle$$

It can be shown that $\tilde{\Delta}_g \geq \bar{\Delta}_g$ and eventually $\bar{\Delta}_g$ becomes greater than Δ as $\Delta_g > 0$

Key ideas behind the Algorithm to find Support

$$\tilde{\Delta}_g \approx V_{\bar{A}}^* - \min_{i \notin \text{Supp}(\bar{x})} \langle \bar{y}, (\bar{A}_{i1}, \bar{A}_{i2}) \rangle$$

Hence, if we have sampled each element for $\frac{1}{\Delta^2}$ times, we stop only when the following holds:

$$\tilde{\Delta}_g > \Delta$$

In this case the support of the NE of the empirical matrix will be equal to $\text{Supp}(x^*)$

2X2 matrix games

Instance dependent parameters for 2X2 games

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

Let $a > c$, $a > b$, $d > b$, $d > c$. Then we have the following closed form solution for the Nash Equilibrium.

$$x^* = \left(\frac{d-c}{D}, \frac{a-b}{D} \right) \quad y^* = \left(\frac{d-b}{D}, \frac{a-c}{D} \right)$$

Here $D = a - b - c + d$

Instance dependent parameters for 2×2 games

$$D = A_{11} - A_{12} - A_{21} + A_{22}$$

$$\Delta_{\min} = \min\{|A_{11} - A_{12}|, |A_{11} - A_{21}|, |A_{22} - A_{21}|, |A_{22} - A_{12}|\}$$

$$\Delta_{m_2} = \max\{\min\{|A_{11} - A_{12}|, |A_{22} - A_{21}|\}, \min\{|A_{11} - A_{21}|, |A_{22} - A_{12}|\}\}$$

$$\begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix}$$

Results for 2×2 games: ε -good solution

Consider a game defined by a fixed 2×2 matrix A which has a unique Nash equilibrium which is not a pure-strategy Nash equilibrium.

We show under some mild assumptions that to find an ε -good solution for the matrix game A with probability at least $1 - \delta$, we require at least

$$\Omega \left(\min \left\{ \frac{1}{\varepsilon^2}, \max \left\{ \frac{1}{\Delta_{\min}^2}, \frac{1}{\varepsilon |D|} \right\} \right\} \log(1/\delta) \right)$$

samples from A

Proof Idea

$$\begin{bmatrix} a - \Delta & b + \Delta \\ c - \Delta & d + \Delta \end{bmatrix} \quad \begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad \begin{bmatrix} a + \Delta & b - \Delta \\ c + \Delta & d - \Delta \end{bmatrix}$$

There is no pair (x,y) which is an ε -good solution for all the three matrices

Results for 2×2 games: ϵ -good solution

Complementing the lower bound result, we design an algorithm that, with probability $1 - \delta$, identifies an ϵ -good solution using a number of samples matching the lower bound up to logarithmic factors.

Easy Instance for 2×2 games: ε -good solution

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\min \left\{ \frac{1}{\varepsilon^2}, \max \left\{ \frac{1}{\Delta_{\min}^2}, \frac{1}{\varepsilon|D|} \right\} \right\}$$

$$\approx \frac{1}{\varepsilon}$$

Hard Instance for 2×2 games: ε -good solution

$$\begin{bmatrix} 0.5 + \varepsilon & 0.5 \\ 0.5 & 0.5 + \varepsilon \end{bmatrix}$$

$$\min \left\{ \frac{1}{\varepsilon^2}, \max \left\{ \frac{1}{\Delta_{\min}^2}, \frac{1}{\varepsilon|D|} \right\} \right\}$$

$$\approx \frac{1}{\varepsilon^2}$$

Results for 2×2 games: ε -Nash Equilibrium

Consider a game defined by a fixed 2×2 matrix A which has a unique Nash equilibrium which is not a pure-strategy Nash equilibrium.

We show under some mild assumptions that to find an ε -Nash Equilibrium for the matrix game A with probability at least $1 - \delta$, we require at least

$$\Omega \left(\min \left\{ \frac{1}{\varepsilon^2}, \max \left\{ \frac{1}{\Delta_{\min}^2}, \frac{\Delta_{m_2}^2}{\varepsilon^2 D^2} \right\} \right\} \log(1/\delta) \right)$$

samples from A

Results for 2×2 games: ε -Nash Equilibrium

Complementing the lower bound result, we design an algorithm that, with probability $1 - \delta$, identifies an ε -Nash Equilibrium using a number of samples matching the lower bound up to logarithmic factors.

Hard Instance for 2×2 games: ε -Nash Equilibrium

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\min \left\{ \frac{1}{\varepsilon^2}, \max \left\{ \frac{1}{\Delta_{\min}^2}, \frac{\Delta_{m_2}^2}{\varepsilon^2 D^2} \right\} \right\}$$

$$\approx \frac{1}{\varepsilon^2}$$

Easy Instance for 2×2 games: ε -Nash Equilibrium

$$\begin{bmatrix} 1 & 1 - \sqrt{\varepsilon} \\ 0 & 1 \end{bmatrix}$$

$$\min \left\{ \frac{1}{\varepsilon^2}, \max \left\{ \frac{1}{\Delta_{\min}^2}, \frac{\Delta_{m_2}^2}{\varepsilon^2 D^2} \right\} \right\}$$

$$\approx \frac{1}{\varepsilon}$$

Results for 2×2 games with Non-unique Nash Equilibrium

We show under some mild assumptions that to find an ε -good solution for the matrix game A with probability at least $1 - \delta$, we require at least $\Omega(\frac{1}{\varepsilon^2})$ samples from A .

$n \times m$ games with unique Nash Equilibrium

Our techniques can be extended to the case $n \times m$ games with unique Nash Equilibrium. However, they are not optimal.

Open Question: Find tight upper and lower bounds for $n \times m$ games.

Thank You