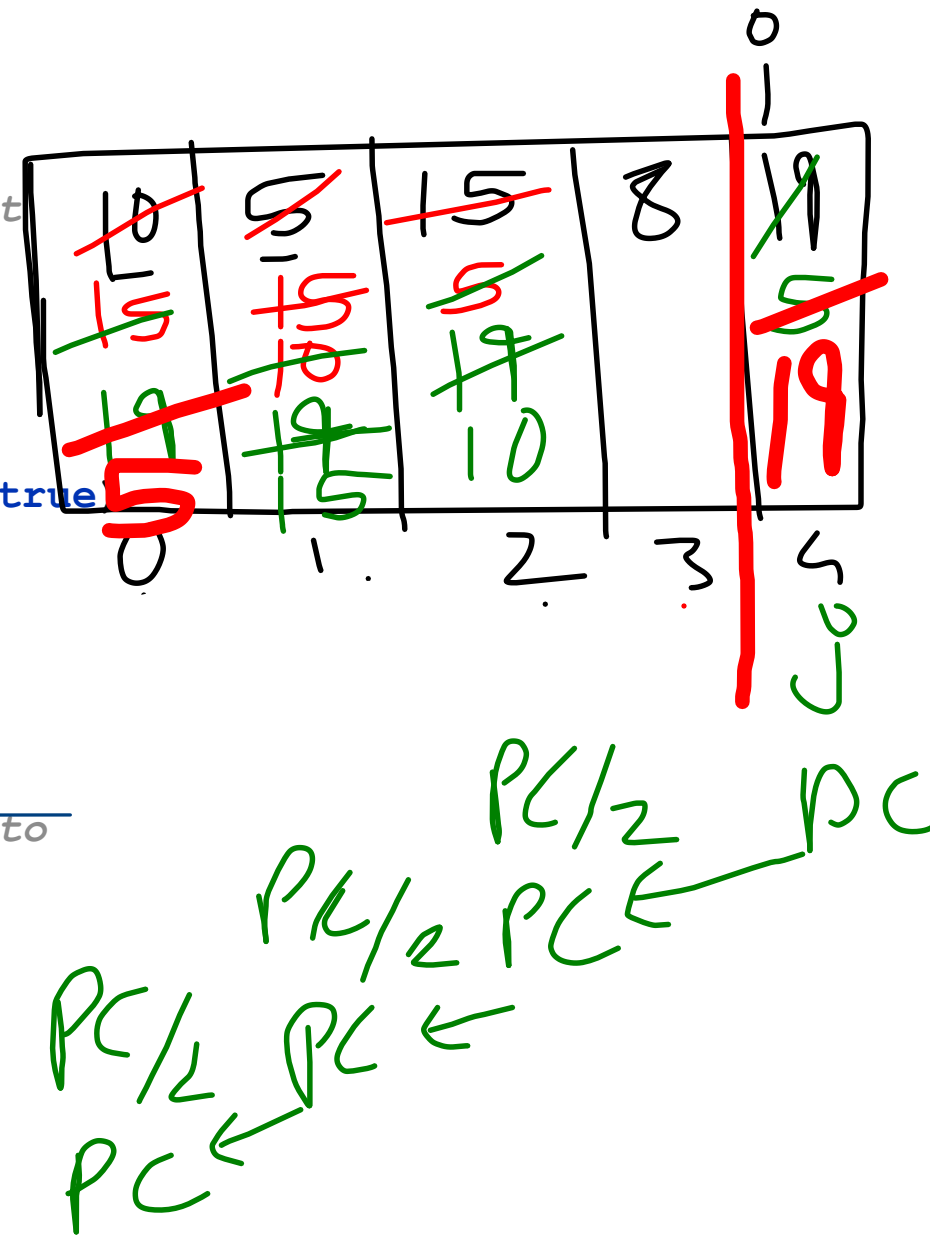


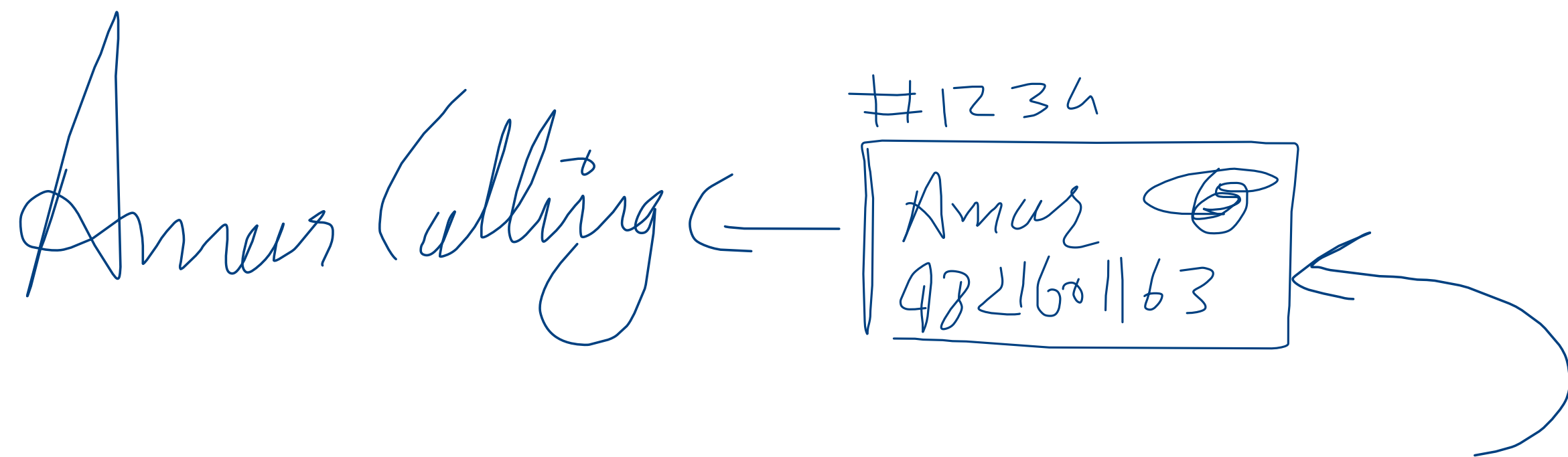
```

static void heap_sort(int a[])
{
    int temp, i, j, pc; // pc: parent-child
    boolean done;
    for (i = a.length - 1; i > 0; i--) // last to first
    {
        for (j = 0; j <= i; j++)
        {
            done = false;
            pc = j;
            while (pc > 0 && pc / 2 >= 0 && done != true)
            {
                if (a[pc] > a[pc / 2])
                {
                    temp = a[pc]; a[pc] = a[pc / 2];
                    a[pc / 2] = temp;
                    pc = pc / 2; // go to parent to
                    check
                }
                done = false;
            }
            else
            {
                done = true;
            }
        }
    } // j closed
    temp = a[0]; a[0] = a[i]; a[i] = temp; // swap
    largest to last
}

```



Hashing:



Parts:

1 Hash function

CONVERTS DATA TO INDEX FOR STORAGE

2 Hash Table

SAVES DATA AT INDEX PROVIDED BY HASH FUNCTION

IF ANY COLLISION HANDLE IT

3 Data

INFO TO STORE FOR LATER TO ACCESS.

Hash Functions:

1.direct hash:

Data is treated as index.

Use only when one-on-one mapping of data and index is possible.

STUDENT 1 has Rollno 1

$$\frac{X \% 10}{}$$

$$\begin{array}{r} 12 \\ 21 \\ \hline 100 \end{array}$$

longer sequential search called clustering before saying yes/no

large memory space used 10X100--->1000

dynamic but too complex to use

40

400!

0	100	40	
1	21		i+1
2	12		i+2
3	40		
4	40		i+4
5			
6			
7	87		
8			
9			

87