

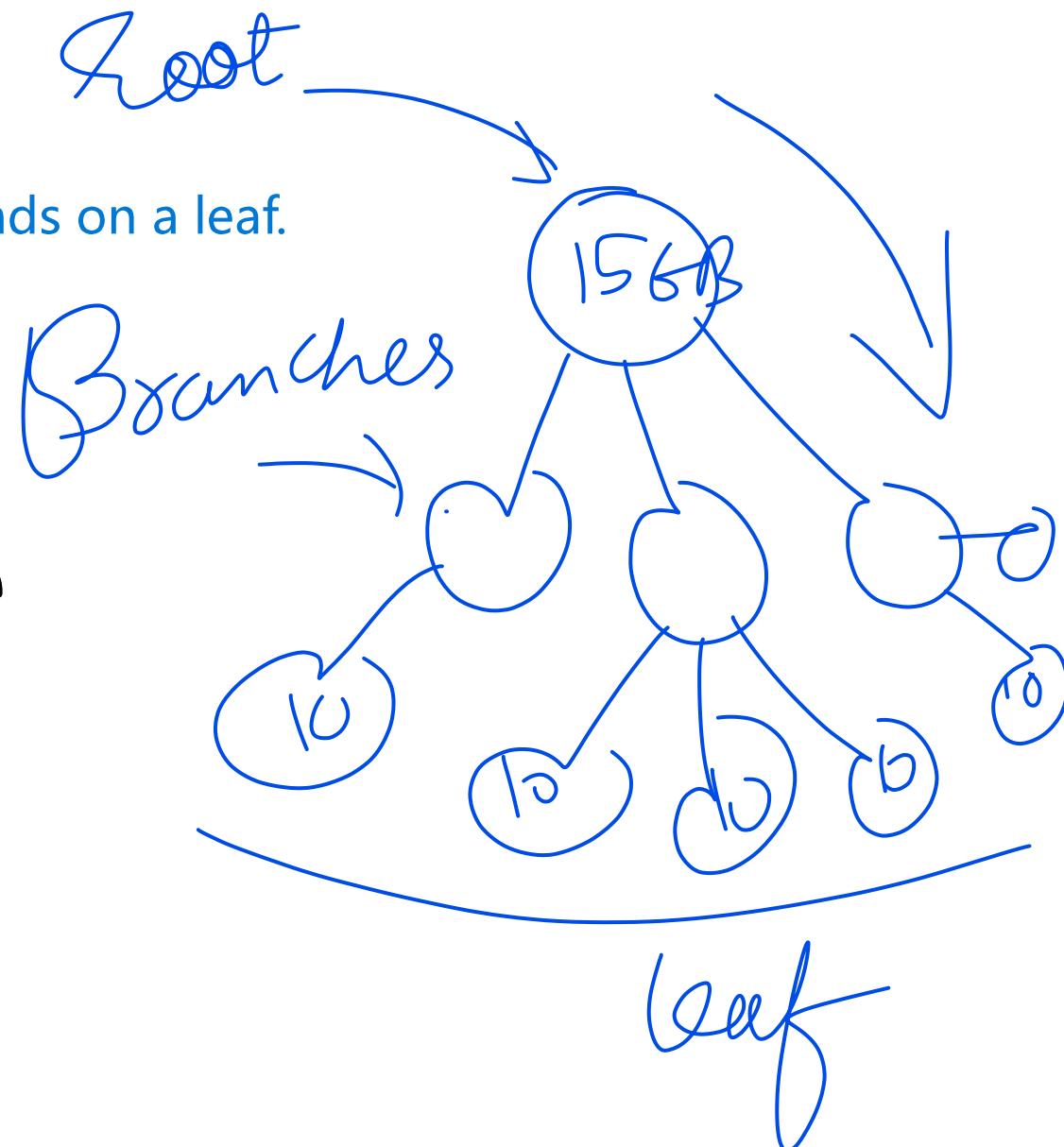
Tree is a hierarchical structure.

Requires guided function for providing access.

Starts with the root grows with the branches and ends on a leaf.

tree: most imp root(only stored others referred)

Tree



TREE

Application:

Hierarchical storage.

Large-scale data searching and sorting.

In Geographical Information System for Imaging.

Auto-complete, auto-correct

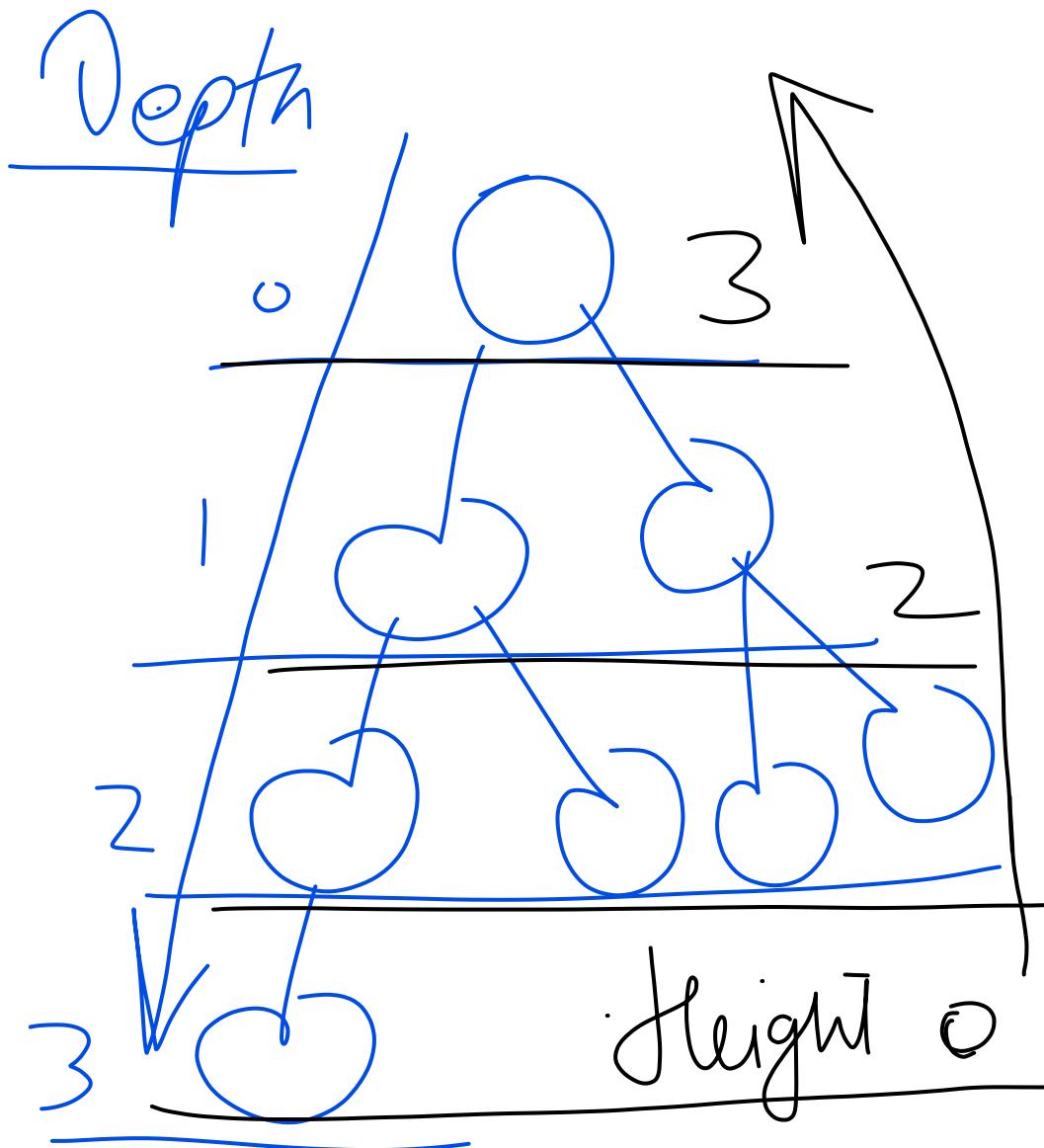
Used by AI in decision-making called state space tree



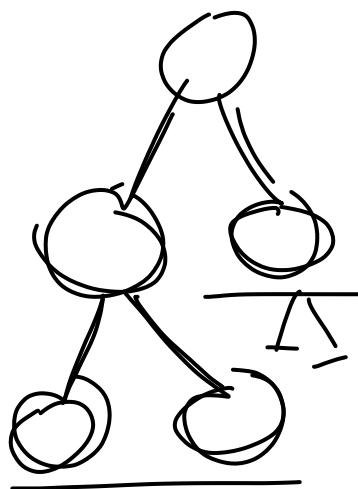
Binary Tree

At most two children.

- Terms
 - Depth Length of longest running branch. decides speed of access.
 - Height Lesser The depth, higher the speed Higher the height, higher the speed
 - Subtree part of tree
 - Ancestor root of tree
 - Leaf node last node of tree
 - Root node start of tree, at most/at least one
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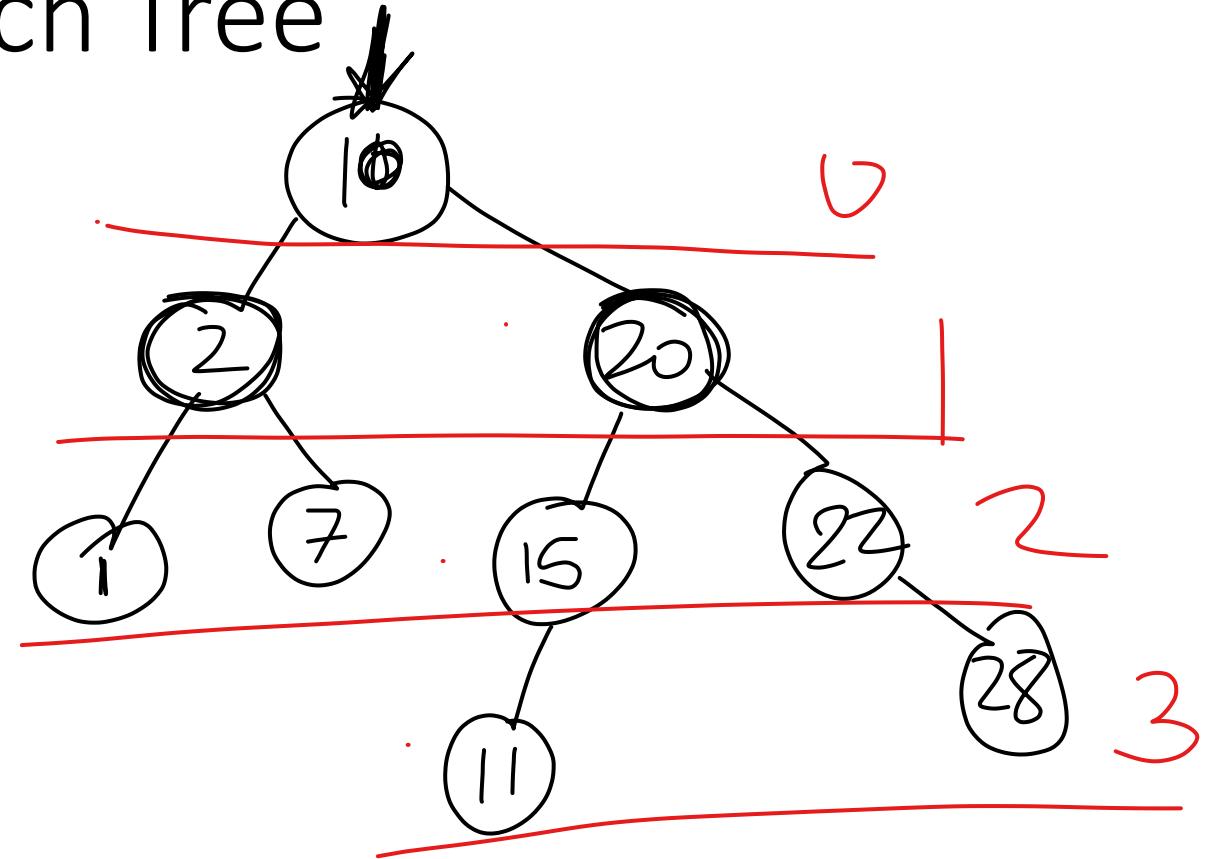


Types of Binary Tree

- Complete All leaf nodes are at exact one depth. 
- Nearly complete All leaf nodes except one is at depth +1 or -1
- Strict Each node can either have two children or zero.
- **Binary Search Tree**
 - tree is specially designed for faster searching and sorting.
 - All elements lesser than the parent are to the left of the parent.
 - All elements greater than or equal to the parent are to the right of the parent.

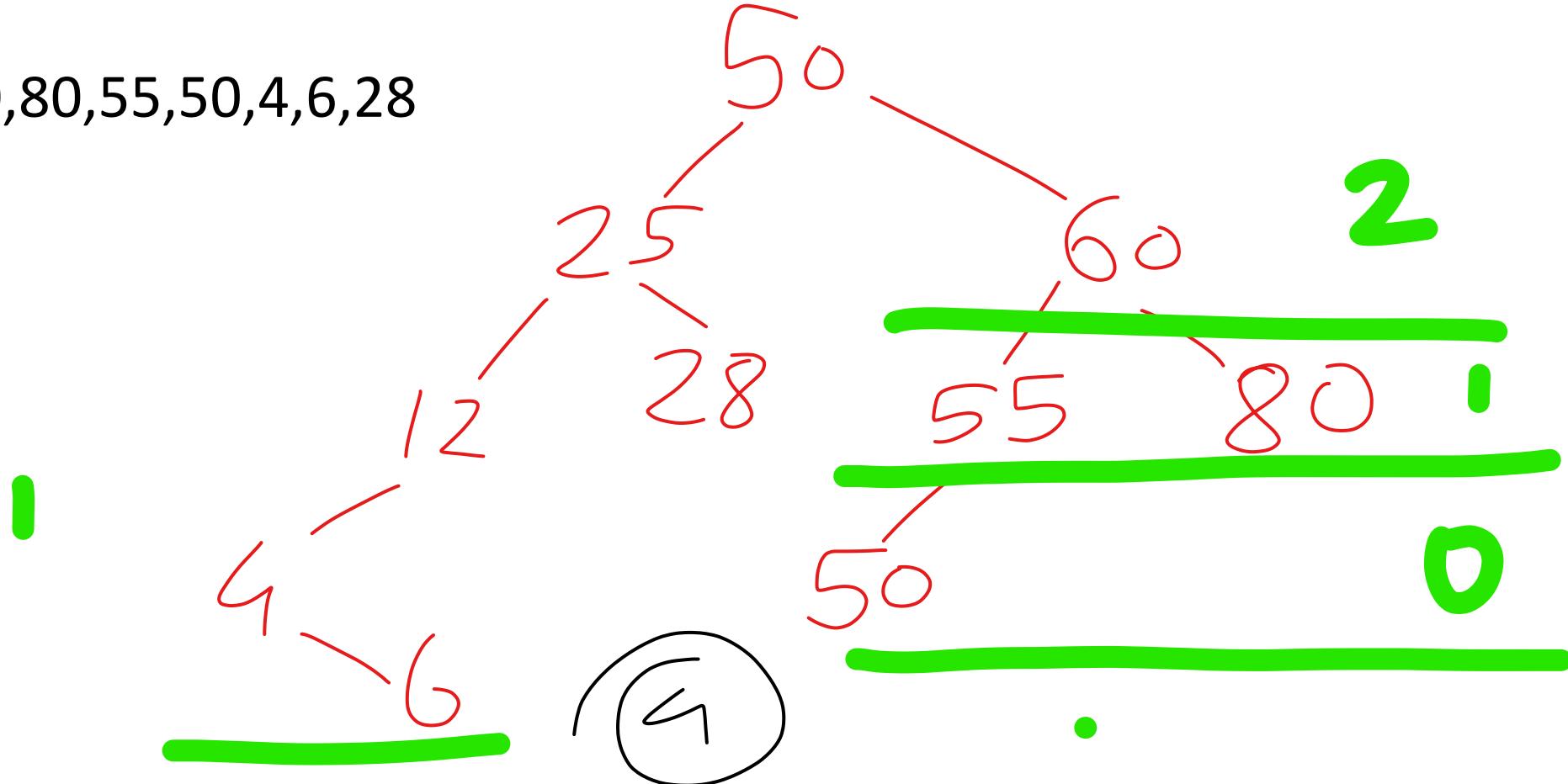
Construct Binary Search Tree

- ~~10, 2, 7, 1, 20, 15, 11, 22, 28~~



Construct Binary Search Tree

- 50,25,12,60,80,55,50,4,6,28



Tree Traversal

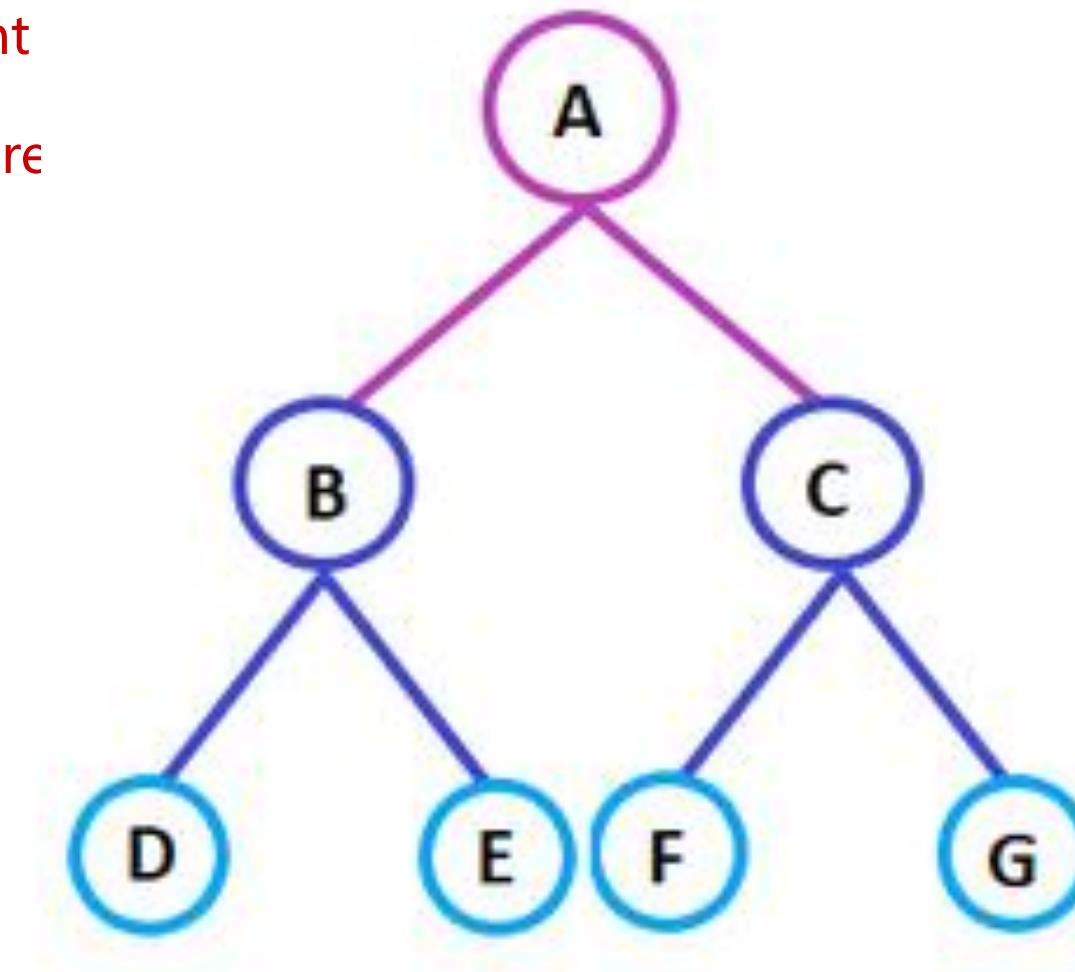
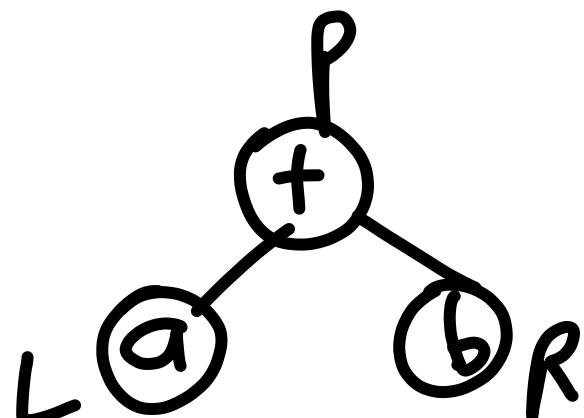
Order of visiting every no sequence

when u cut L:go to left
when u cut R:go to right
when u cut P:print
when all done go to pare

preorder:PLR
+ab

inorder:LPR
a+b

postorder:LRP
ab+

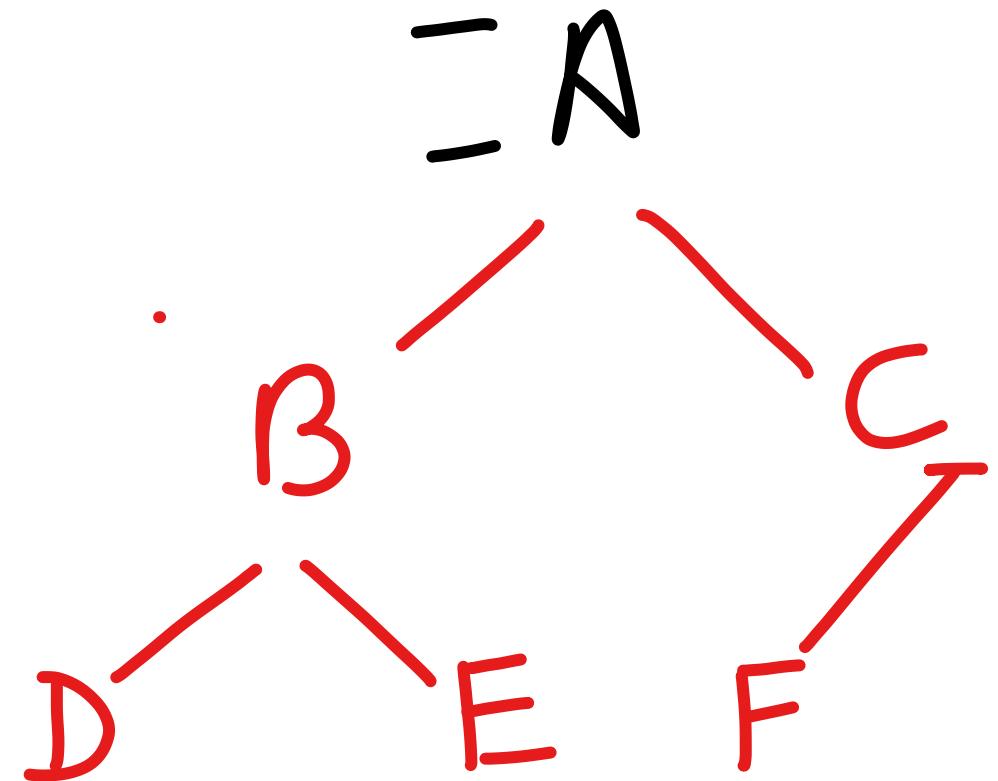


Construct tree

- Inorder sequence: D B E A F C
- Preorder sequence: A B D E C F

We will write in order sequence and use post-order or pre-order for the construction of a tree.

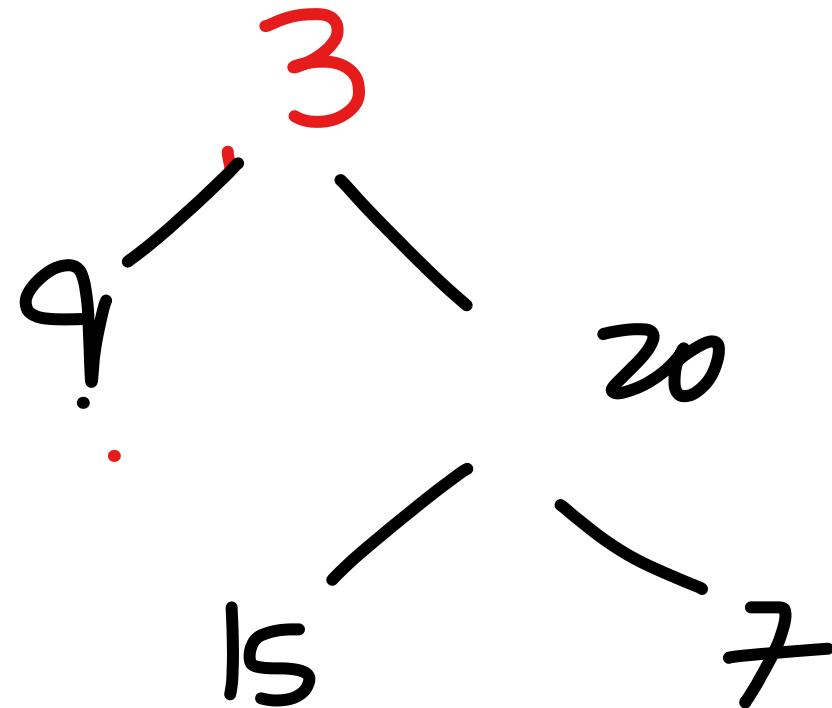
In pre-order go first(root) to last
Cut one node at a time.
Construct left child and right child.
Repeat the process till tree is constructed



Construct tree

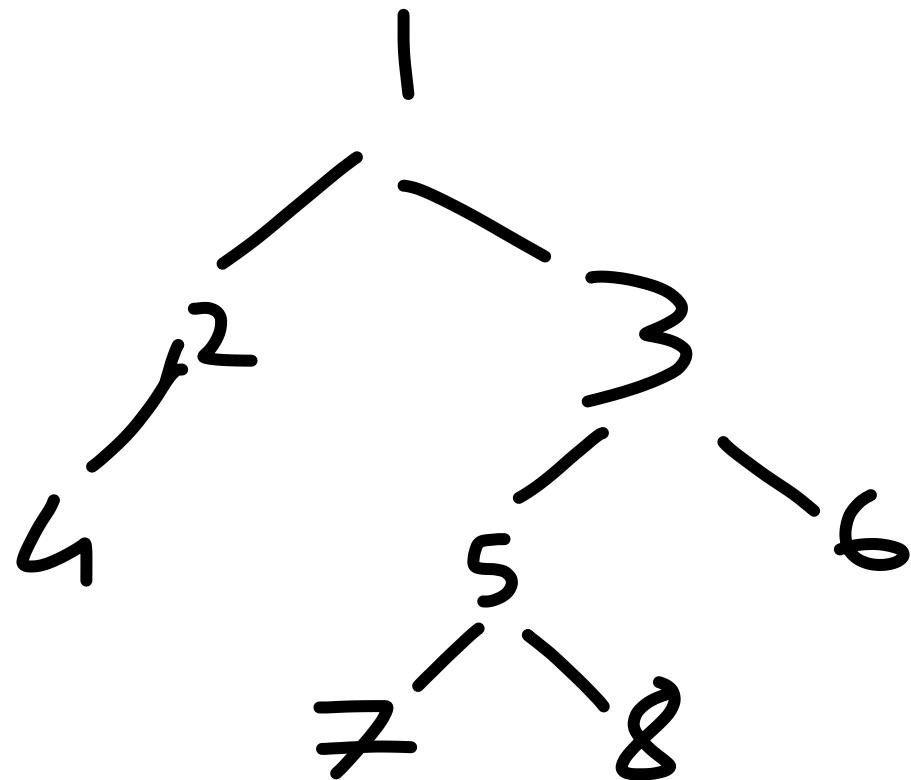
- preorder ~~[3,9,20,15,7]~~
- inorder = [9,3,15,20,7]

In pre-order go first(root) to last
Cut one node at a time.
Construct left child and right child.
Repeat the process till tree is constructed.



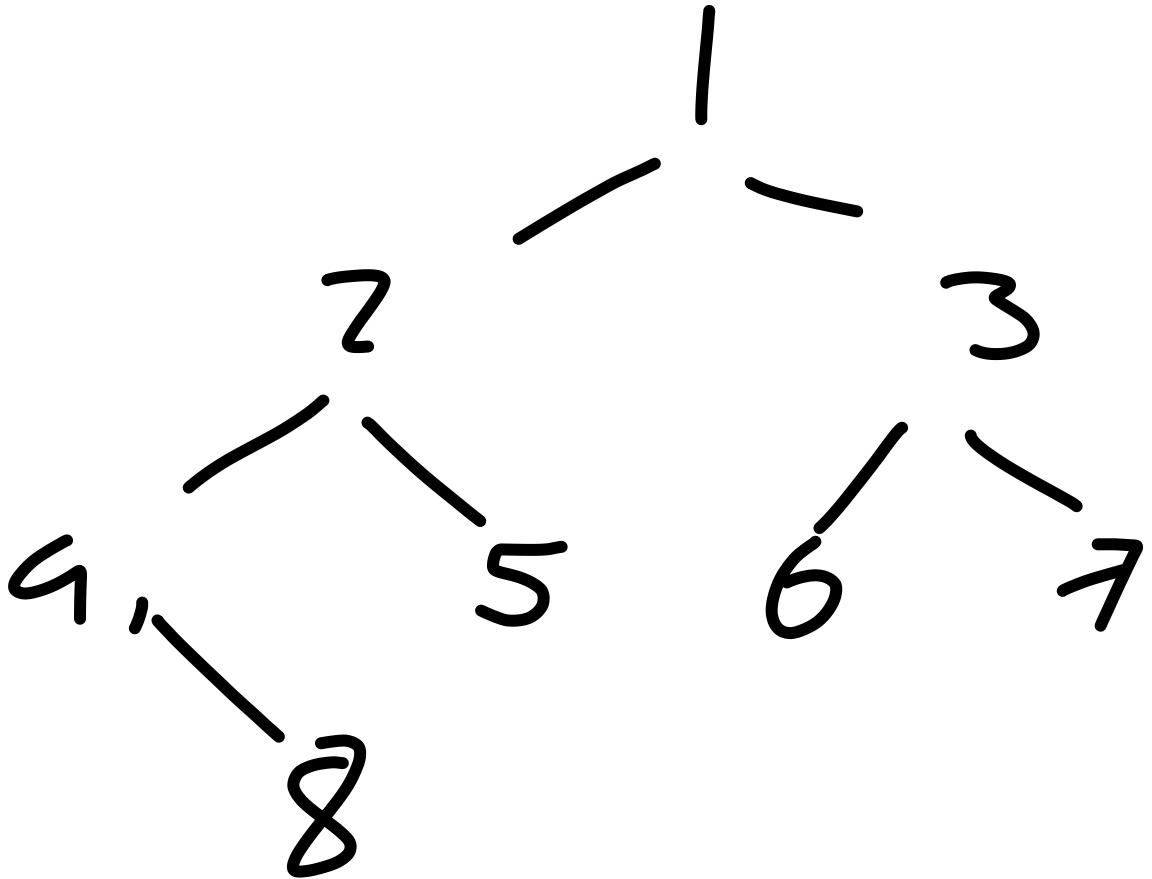
Construct tree

- Inorder Traversal : { 4, 2, 1, 7, 5, 8, 3, 6 }
- Preorder Traversal: { ~~1, 2, 4, 3,~~ 5, 7, 8, ~~6~~ }



Construct tree

- $\text{in[]} = \{4, 8, 2, 5, 1, 6, 3, 7\}$
- $\text{post[]} = \{8, 4, \cancel{5}, \cancel{2}, \cancel{8}, \cancel{7}, \cancel{3}, \cancel{1}\}$



Construct tree

- inorder = [9,3,15,20,7]
- postorder = [9,15,7,20,3]

Construct tree

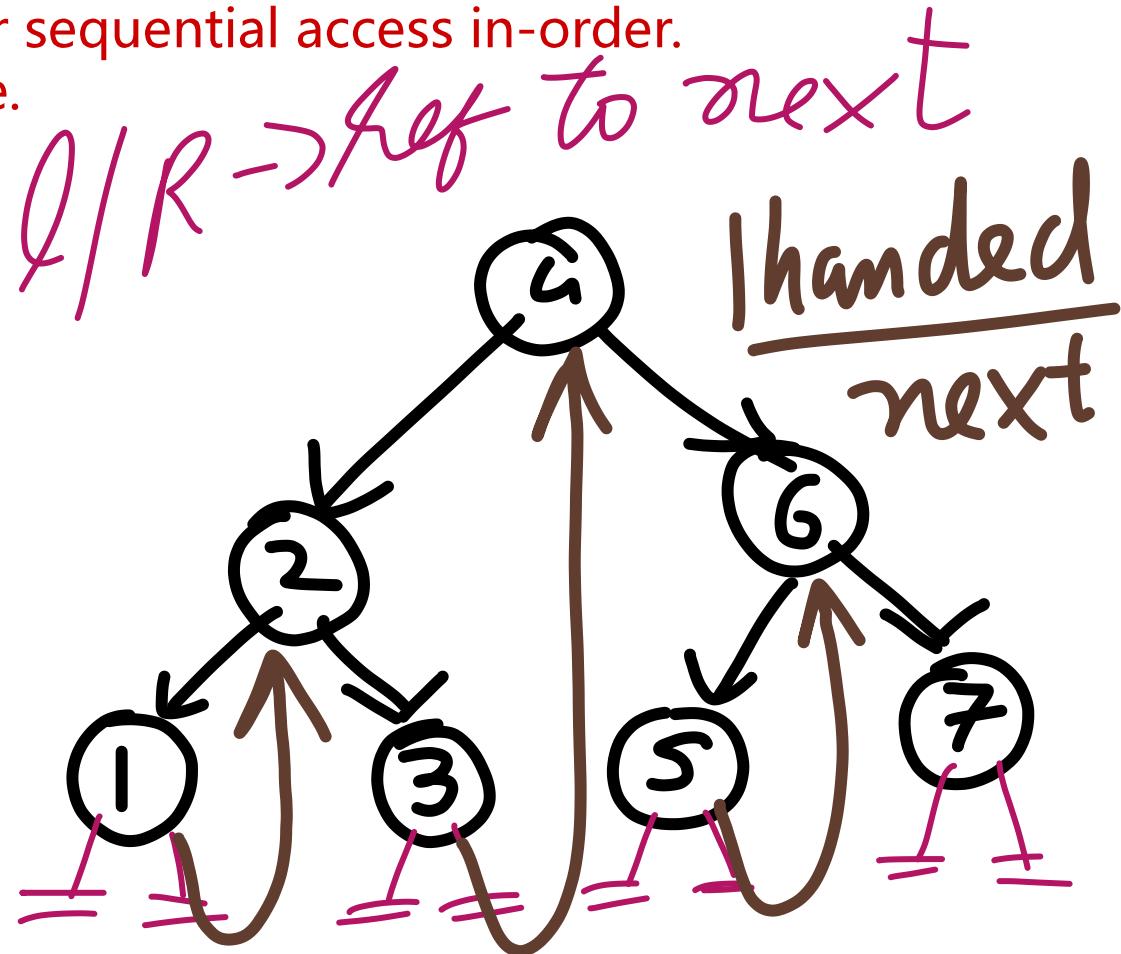
- Inorder Traversal : { 4, 2, 1, 7, 5, 8, 3, 6 }
Postorder Traversal : { 4, 2, 7, 8, 5, 6, 3, 1 }

Threaded Tree

A special version of a binary tree enhanced for sequential access in-order.

By default, data nature has a sequential nature.

- Inorder traversal of a Binary tree can either be done using recursion or with the use of a auxiliary stack. The idea of threaded binary trees is to make inorder traversal faster and do it without stack and without recursion. A binary tree is made threaded by making all right child pointers that would normally be NULL point to the inorder successor of the node (if it exists).



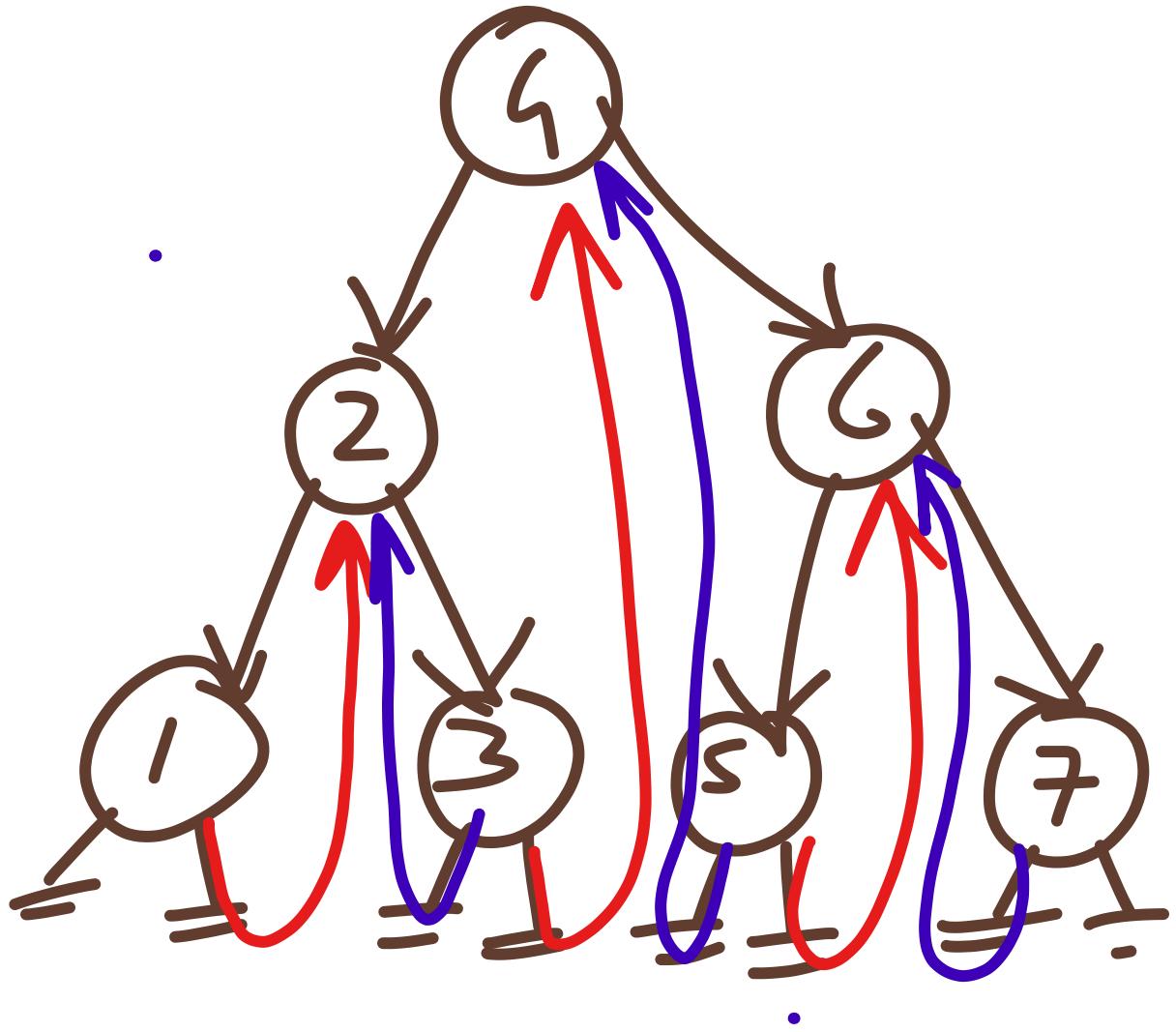
Threaded Tree

- Single Threaded: Where a NULL right pointers is made to point to the inorder successor (if successor exists)

Threaded Tree

- Double Threaded: Where both left and right NULL pointers are made to point to inorder predecessor and inorder successor respectively. The predecessor threads are useful for reverse inorder traversal and postorder traversal.

L : Prev
R : next



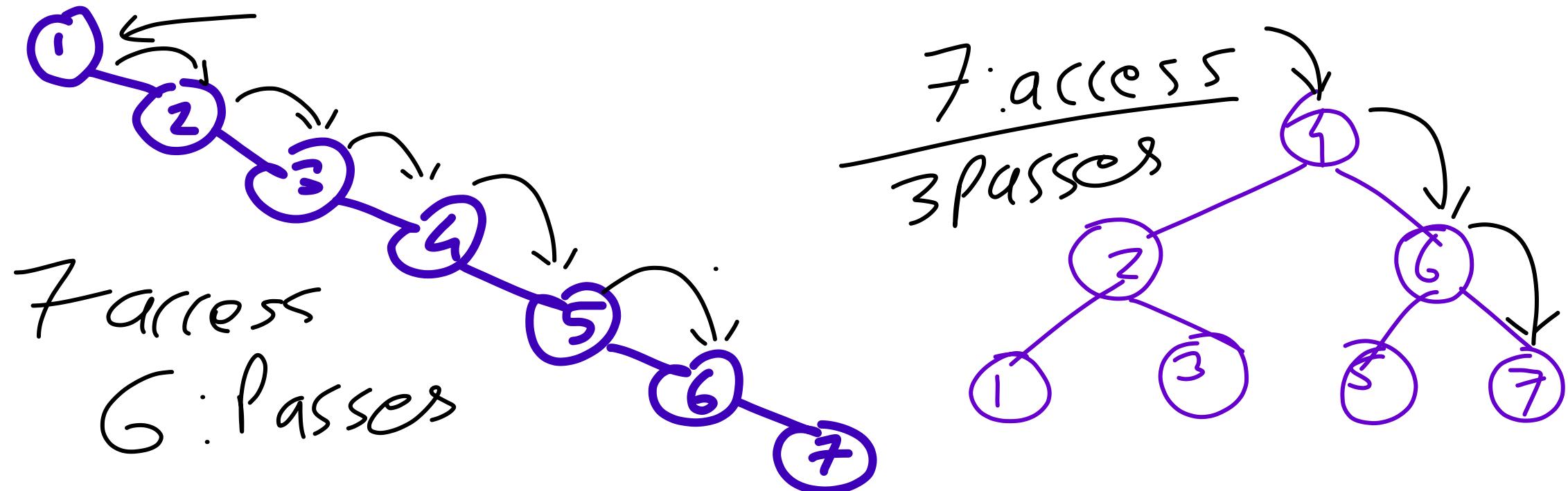
AVL TREE

It is self-balancing(if goes out of balance, it will rotate itself to achieve balance)

nearly balanced tree(factor can be between +1 to -1.(+1,0,-1)

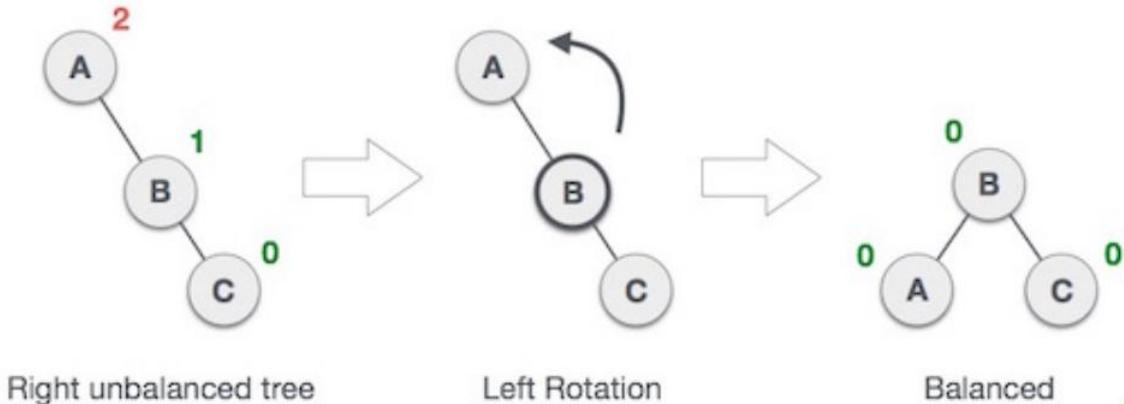
balance factor=height of left sub tree-height of right sub tree

If a tree is balanced, it takes lesser time to access the data, increasing the speed of access.



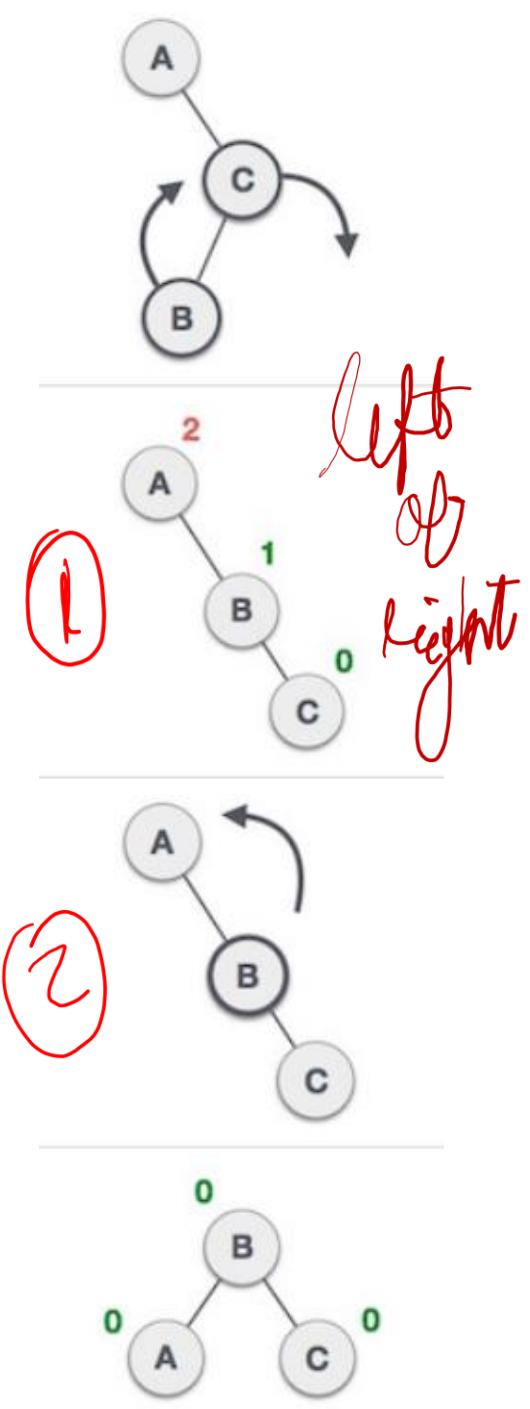
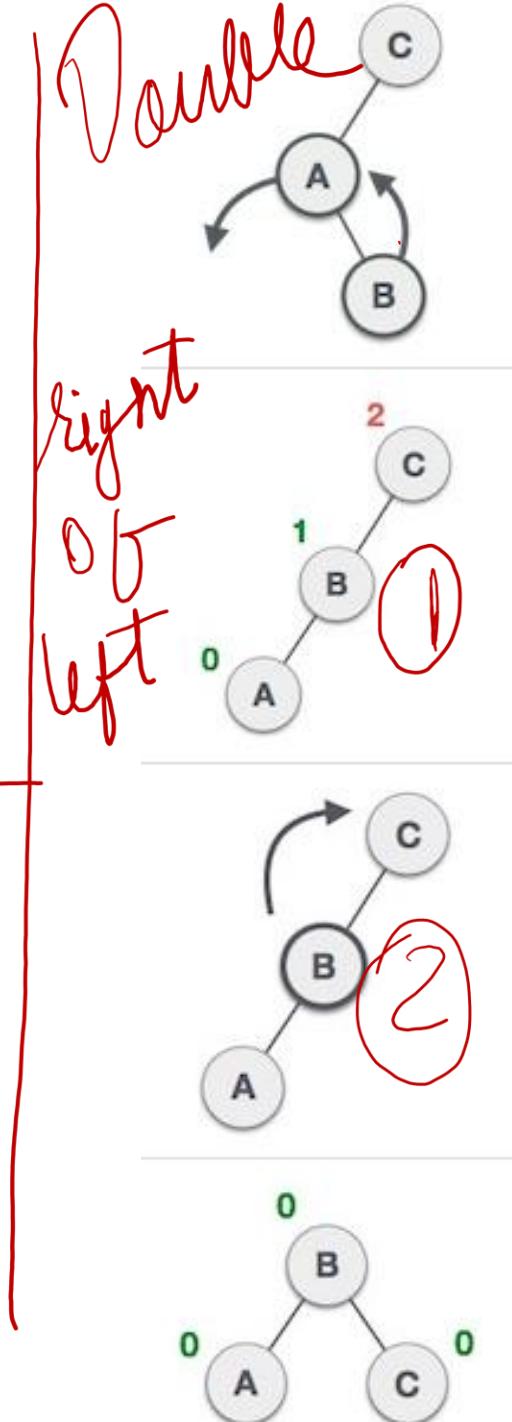
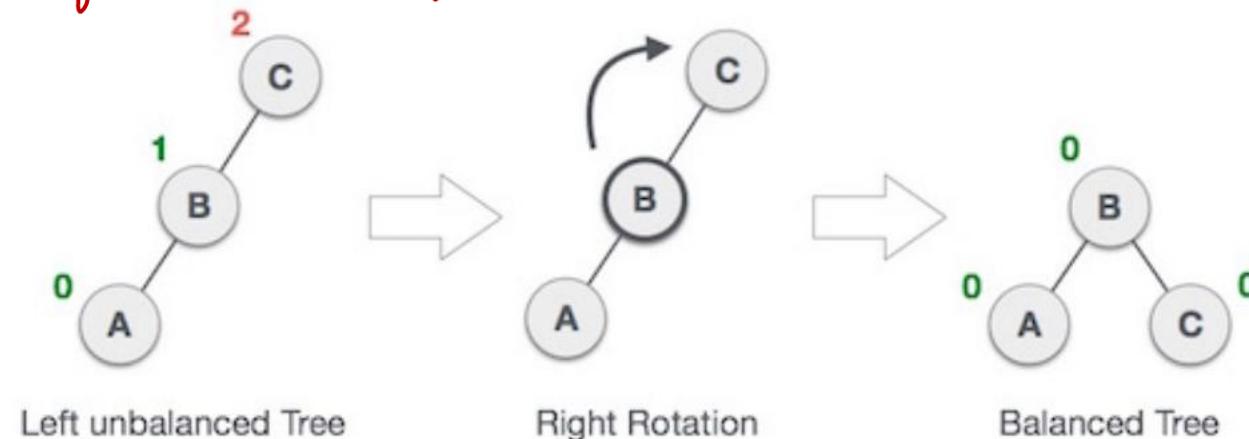
Rotations

single



right of right

left of left



B-Tree

- B-Tree is a **self-balancing search tree**.
- Single node consist multiple elements this reduces number of read write and memory swaps.
- the B-Tree node size is kept equal to the disk block size
- All leaves are at the same level.
- B-Tree is defined by the term **minimum degree 'M'**.
- M is odd.
- On Order M:
 - Maximum M-1 elements at a node
 - Minimum M/2 elements at a node
 - Split when M elements reached
- All keys of a node are sorted in increasing order.
- B-Tree grows and shrinks from the root which is unlike Binary Search Tree.
- Like other balanced Binary Search Trees, the time complexity to search, insert and delete is O(log n).
- Insertion of a Node in B-Tree happens only at Leaf Node in order and BST form.

It is an example of a multi-way search tree.

In multi-way search tree, a particular node has multiple elements decided by its order m. Multi-way search tree allows faster reading and writing. In a single pass, multiple elements in a node can be filled.

B+ Tree

BST IMPLEMENTATION

- Static Array
 - Dynamic Linked List
 - Dynamic Tree node
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