

CodeZoo CATM1 Hands-On

- Raspberry Pi (with Python)-

version 1.0

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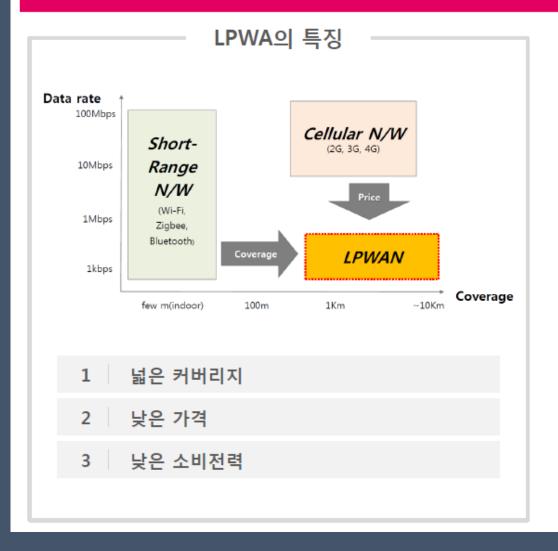
www.**Code**Zoo.co.kr

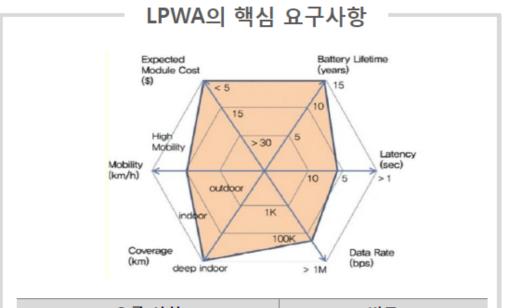
- CAT.M1 특징
- CAT.M1 하드웨어 구성 및 설계 살펴보기
- CAT.M1 어떻게 개발 하나요? (AT Command)
- CAT.M1 실습 (RaspberryPi준비, 소스코드 다운로드, Basic, Socket)

1. Cat.M1 일반적인 특징 - LPWA

폭발적으로 증가하는 IoT 회선 수에 대응하기 위해, 데이터 전송 속도가 낮고 전력 소모량이적으며 넓은 지역을 커버할 수 있는 LPWA* 기술이 필요

* LPWA: Low Power Wide Area

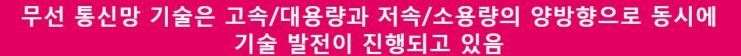




요구 사항	비고
저전력 소모 / Long battery life	10년
저가 단말기 공급 / Low cost chipset	기기 당 \$5 이하
낮은 구축 비용 / Low cost Network	HW 추가 보다는 간단한 SW 업그레이드
안정적 커버리지 / Wide area connectivity	빌딩 내,지하,외곽지역 등
데그ㅁ 다마기 저소	동시 접속/수용 (10 만↑ 디바이스 per cell)*

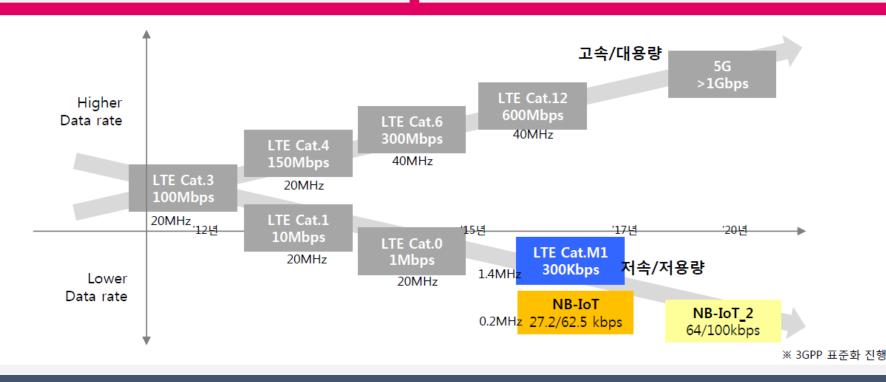
1. Cat.M1 일반적인 특징 - Cat.M1 & NB-IoT

LPWA: 표준 기술의 진화 방향



고속/대용량: 멀티미디어 서비스 → 4G, 5G

저속/소용량 : IoT 서비스 → LPWA (NB-IoT)



2. CAT.M1 소프트웨어 개발자 측면의 특징

1회 전송 데이터 TCP Sample

"TCP 패킷헤더(주소 정보) + 보내고자 하는 데이터"



TCP 송신 헤더패킷 사이즈 : 230byte TCP 수신 헤더패킷 사이즈 : 199byte

1회 전송 데이터 UDP Sample

"UDP 패킷헤더(주소 정보) + 보내고자 하는 데이터"

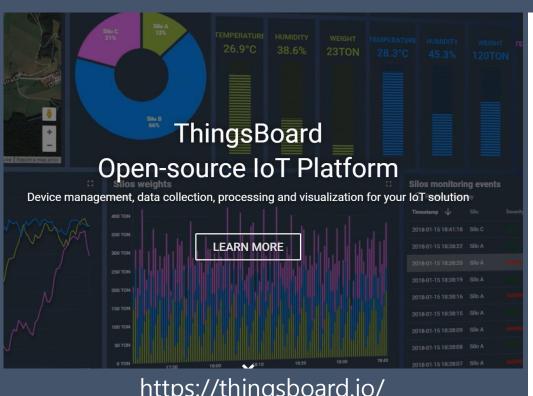


UDP 송신 헤더패킷 사이즈 : 40byte UDP 수신 헤더패킷 사이즈 : 40byte

BG96 TCP(IP) AT Commands Manual V1.1

Send Size The maximum data length is 1460 bytes Read Size The maximum data length is 1500 bytes

3. RaspberryPi CAT.M1 소프트웨어 특징

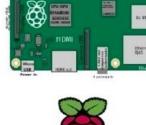


https://thingsboard.io/





Any Microcontroller





Blynk App

https://www.youtube.com/watch?v=sLPbp49LB6g

LoRa Local Server (RPI) RS485...

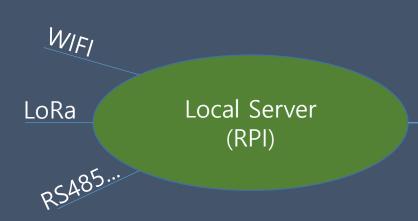
WIFI

CAT.M1 (TCP/UDP)

Main Server or Cloud

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3. RaspberryPi CAT.M1 소프트웨어 특징



외부로 내보내야 하는 데이터/ 외부에서 받아야 하는 데이터

CAT.M1 (TCP/UDP) Main Server or Cloud





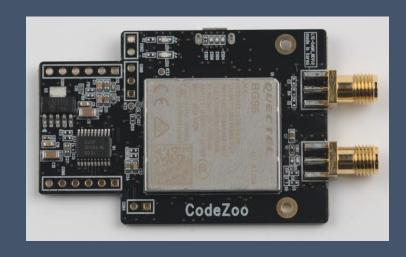




https://www.industrynews.co.kr/news/articleView.html?idxno=28113

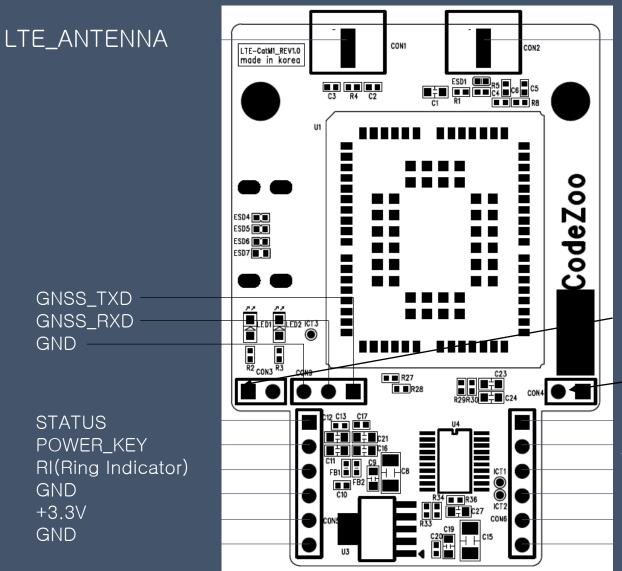
http://www.libelium.com/

www.**Code**Zoo.co.kr





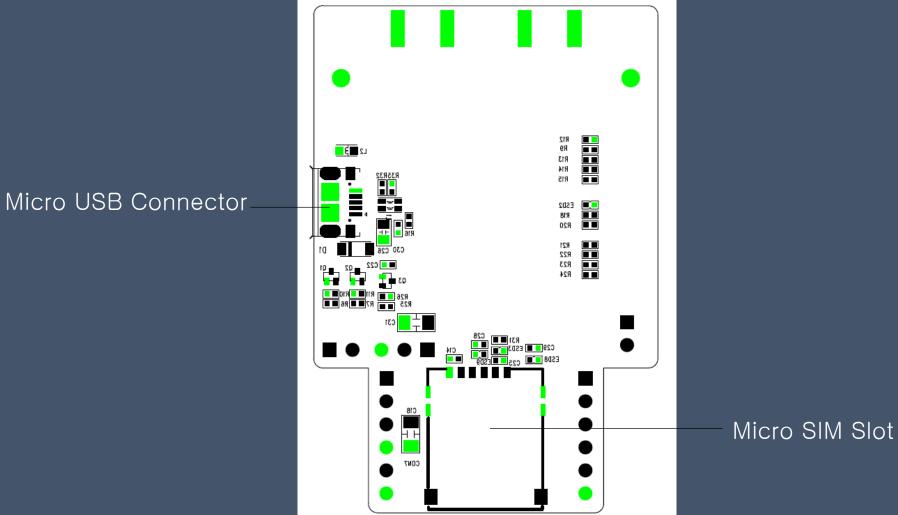




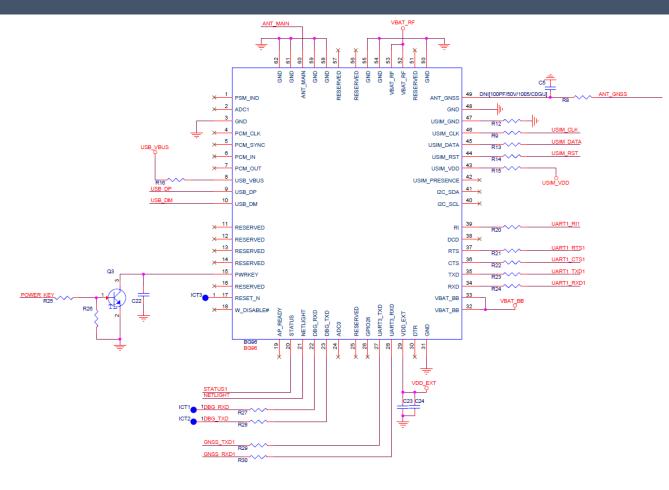
GNSS_ANTENNA

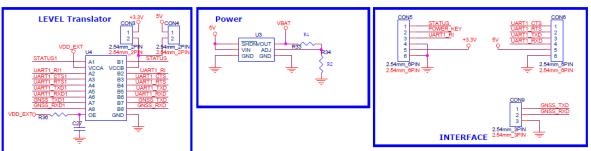
TTL LEVEL SELECT (3.3 or 5V)
CON3 (CLOSE) & CON4 (OPEN) 3.3V
CON3 (OPEN) & CON4 (CLOSE) 5V

CTS RTS TXD RXD +5V GND



구분 (classification)	규 격 (Standard)
1. 제품명 (Product Name)	CodeZoo LTE-CAT.M1 Board
2. 제품 모델명 (Product Model)	CZ-CATM1
3. 제품 제조사 (Product Manufacturer)	CodeZoo
4. 통신모듈 모델명/제조사 (Module Model/Vendor)	BG96 / Quectel
5. 통신칩셋 모델명/제조사 (Chipset Model/Vendor)	MDM9206 / Qualcomm
6. 외형크기 (Dimension) [단위: mm]	Width(38.0)*Height(65.0)*Depth(4.0)
7. 기능용도 (Function-Use)	LTE 통신 모듈
8. 전원 타입 (Power Supply Type)	USB, 3.3~5V
9. 동작 전압/전류 (Voltage/Ampere)	(5 V), (0.25A)
10. 안테나 타입 (Antenna Type)	외장형
11. 지원 통신규격 주파수 (Frequency Band)	LTE Cat1





> 회로도 다운로드 (제품 도면 dxf 파일 포함)

https://github.com/codezoo-ltd/CodeZoo_CATM1_Arduino/tree/master/Schematics_Dimension/

BG96 Module 회로도.pdf

> 메뉴얼 다운로드 (하드웨어, 소프트웨어) https://github.com/codezoo-ltd/CodeZoo CATM1 Arduino/tree/master/BG96 Manual

> 제품 사양서

https://github.com/codezoo-ltd/CodeZoo_CATM1_Arduino/tree/master/Product_Specification

The "AT" or "at" prefix must be set at the beginning of each command line. To terminate a command line

enter **<CR>**. Commands are usually followed by a response that includes "**<CR><LF>**". Throughout this document, only the responses are presented,

"<CR><LF>" are omitted intentionally.

"AT"또는"at"접두사는 각 명령 줄의 시작 부분에 설정해야합니다. 명령 행을 종료하려면 <CR>을 입력하십시오. 명령 뒤에는 일반적으로"<CR> <LF> <response> <CR> <LF>"가 포함 된 응답이 이어집니다. 이 문서 전체에서" <CR> <LF>"는 의도적으로 생략 된 답변 만 제공됩니다.

Quectel_BG96_AT_Commands _Manual_V2.3.pdf, 10page

Table 1: Types of AT Commands and Responses				
Test Command	AT+ <x>=?</x>	This command returns the list of parameters and value ranges set by the corresponding Write Command or internal processes.		
Read Command	AT+ <x>?</x>	This command returns the currently set value of the parameter or parameters.		
Write Command	AT+ <x>=<></x>	This command sets the user-definable parameter values.		
Execution Command	AT+ <x></x>	This command reads non-variable parameters affected by internal processes in the UE.		

Quectel_BG96_AT_Commands _Manual_V2.3.pdf, 11page

1.5. Unsolicited Result Code

As an Unsolicited Result Code and a report message, URC is not issued as part of the response related to an executed AT command. URC is issued by BG96 without being requested by the TE and it is issued automatically when a certain event occurs. Typical events leading to URCs are incoming calls (**RING**),

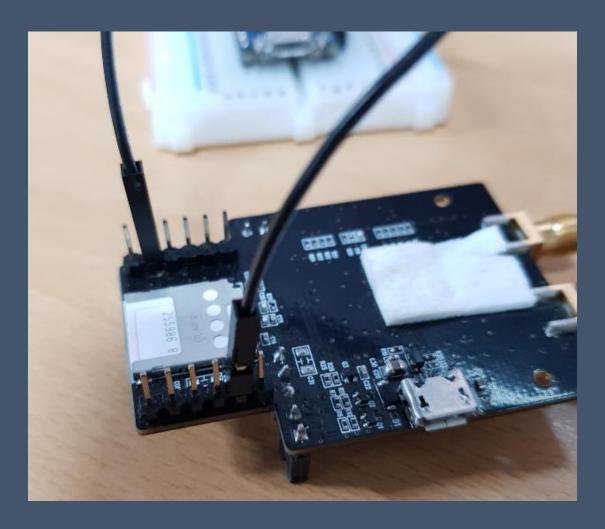
received short messages, high/low voltage alarm, high/low temperature alarm, etc.

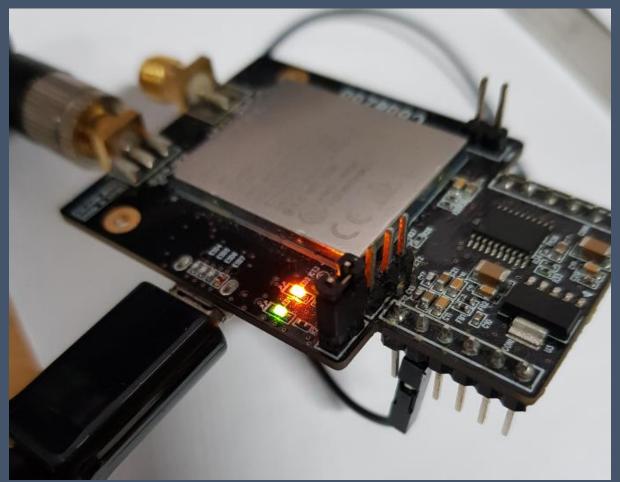
요청하지 않은 결과 코드 및 보고서 메시지로서 URC는 실행 된 AT 명령과 관련된 응답의 일부로 발행되지 않습니다. URC는 TE의 요청없이 BG96에 의해 발행되며 특정 이벤트가 발생하면 자동으로 발행됩니다. URC로 이어지는 일반적인 이벤트는 수신 전화 (RING), 수신 된 짧은 메시지, 고 / 저 전압 경보, 고 / 저 온도 경보 등입니다.

언제 들어올지 알수 없는 모뎀 메시지에 대한 처리 루틴을 어떻게 만들것 인지?

- 1. Python 쓰레드
- 2. Daemon Process
- 3. 상황에 맞는 소프트웨어 설계

Quectel_BG96_AT_Commands _Manual_V2.3.pdf, 12page





2.9. AT+CGSN Request Product Serial Number Identification

The command returns International Mobile Equipment Identity (IMEI). It is identical with AT+GSN.

AT+CGSN Request Product Serial Number Identification		
Test Command AT+CGSN=?	Response OK	
Execution Command AT+CGSN	Response <imei></imei>	
Maximum Response Time	300ms	
Reference 3GPP TS 27.007		

Parameter

<IMEI> IMEI of the ME

NOTE

The serial number (IMEI) varies with the individual ME device.

Quectel_BG96_AT_Commands _Manual_V2.3.pdf, 18page

QCOM_V1.0	- □ X
About	
COM Port Setting	Command List—
COM Port: ■ ■ Baudrate: 9600 ■ StopBits: 1 ■ Parity: None ■	☐ Choose All Commands HEX ☐ Enter Delay(mS)
	▼ 1: AT+CFUN=1 □ ▼ 1 □
ByteSize: 8 ▼ Flow Control: No Ctrl Flow ▼ Open Port	Z: AT+CGDCONT=1,"IP","internet,lguplus,co,kr"
	▼ 3: AT+COPS=1,2,"45006"
	▼ 4: AT+CGATT=1
	▼ 5: AT+NSOCR=DGRAM,17,5683,1
	▼ 6: AT+NSOST=0,210,120,128,192,5683,89,3c3d3€
	▼ 7: AT+CSCON? □ 7 ▼ 8: AT+CGATT? ■ 8
	▼ 9: AT+CGDCONT? 9 ▼ 10: AT+CISI 10
	▼ 11: AT+NBAND? □ ▼ 11
	▼ 12: AT+NBAND=5
	▼ 13: AT+CFUN=0
	▼ 14: AT+NRB
	▼ 15: AT+CGMR
	▼ 16: +CPIN? □ □ 16 □
	▼ 17: AT+CGATT=0
	☐ 18: ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐
	▼ 19: at\$lgtver?
	□ 20: □ □ □ □ □ □ □ □
	21:
	☐ 22: ☐ ☐ ☐ 22 ☐ ☐
	☐ 23: ☐ ☐ <u>23</u> ☐
Operation—	☐ 24: ☐ ☐ ☐ 24 ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐
	25:
Input String: ☐ HEX String ☐ Show In HEX ☐ Send With Enter	
^	☐ 28: ☐ ☐ ☐ 28 ☐ ☐ ☐ 29: ☐ ☐ ☐ 29 ☐ ☐ ☐ 29 ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐
▼ Send Command	
Select File Send File	Load Test Script Delay Time(mS): 1000
Save Log Z:\#02,PROJECTS\#70, NB_loT\#5,Driver\#QUECTEL\#Tools\#QCOM_V1,0\#QCOM_L	Save As Script Run Stop

CAT.M1 모뎀 구현 명세서 검토



AT Command Manual 참조하여 구현 시나리오 작성



PC + CAT.M1
Program(Qcom)
활용하여 시나리오 검증 동작 불가시 이전단계로 복귀



구현 시나리오대로 동작되면 CAT.M1 라이브러리를 이용하여 MCU + CAT.M1 동작 구현

Downloads

Raspberry Pi OS (previously called Raspbian) is our official operating system for **all** models of the Raspberry Pi.

Use **Raspberry Pi Imager** for an easy way to install Raspberry Pi OS and other operating systems to an SD card ready to use with your Raspberry Pi:

- Raspberry Pi Imager for Windows
- Raspberry Pi Imager for macOS
- Raspberry Pi Imager for Ubuntu

Version: 1.4

Install Raspberry Pi Imager to Raspberry Pi OS by running

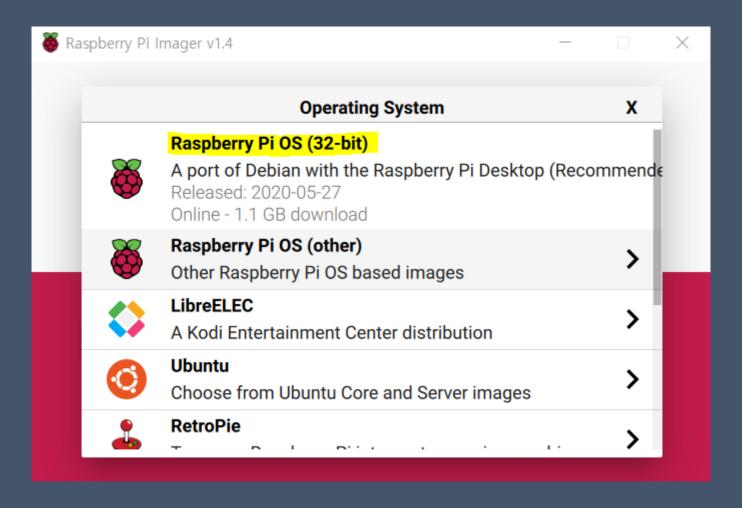
sudo apt install rpi-imager in a terminal window

Alternatively, use the links below to download OS images which can be manually copied to an SD card.

https://www.raspberrypi.org/downloads/











시리얼 포트 설정 라즈베리파이 터미널에서

- \$ sudo raspi-config
- 5. Interfacing Options 선택

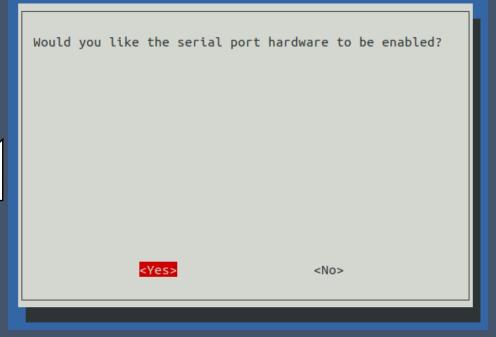
```
Raspberry Pi Software Configuration Tool (raspi-config)
1 Change User Password Change password for the current user
2 Network Options
                      Configure network settings
3 Boot Options
                      Configure options for start-up
4 Localisation Options Set up language and regional settings to match your location
5 Interfacing Options Configure connections to peripherals
6 Overclock
                      Configure overclocking for your Pi
7 Advanced Options
                      Configure advanced settings
8 Update
                      Update this tool to the latest version
9 About raspi-config
                      Information about this configuration tool
                   <Select>
                                                     <Finish>
```

P6 Serial 선택

```
Raspberry Pi Software Configuration Tool (raspi-config)
               Enable/Disable connection to the Raspberry Pi Camera
P1 Camera
               Enable/Disable remote command line access to your Pi using SSH
P2 SSH
P3 VNC
               Enable/Disable graphical remote access to your Pi using RealVNC
               Enable/Disable automatic loading of SPI kernel module
P4 SPI
               Enable/Disable automatic loading of I2C kernel module
P5 I2C
P6 Serial
               Enable/Disable shell and kernel messages on the serial connection
P7 1-Wire
               Enable/Disable one-wire interface
P8 Remote GPIO Enable/Disable remote access to GPIO pins
                  <Select>
                                                    <Back>
```

Would you like a login shell to be accessible over serial?

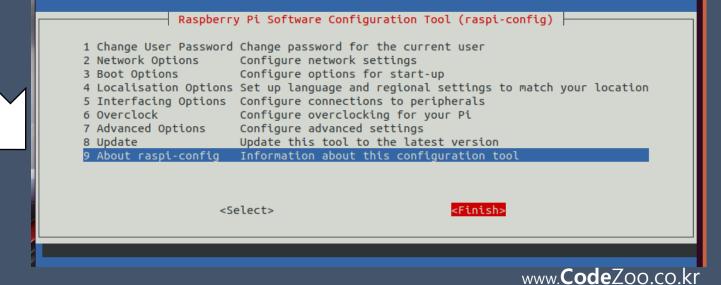
Yes 선택



OK 선택

The serial login shell is disabled
The serial interface is enabled

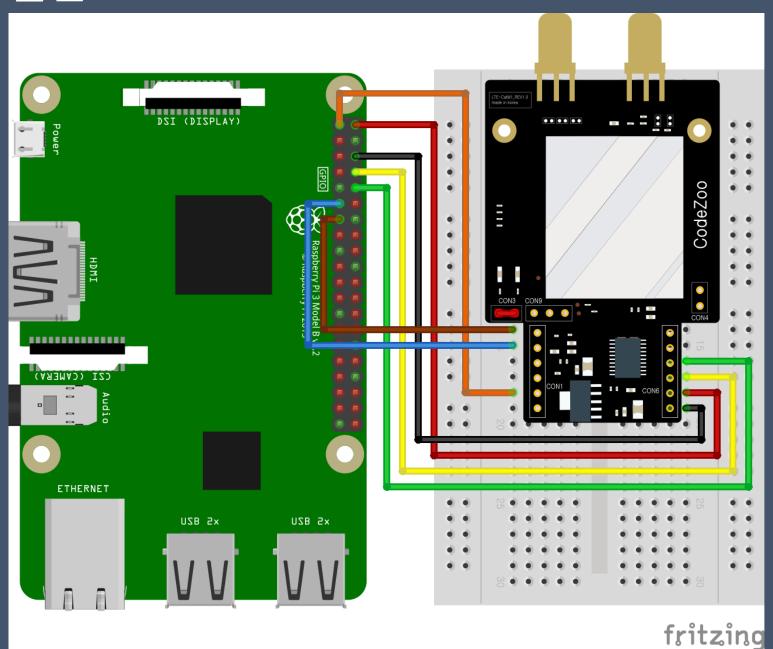
Finish 선택



라즈베리파이 다시 부팅 합니다 부팅후 "/dev/ttyS0" 파일이 생성 됩니다.

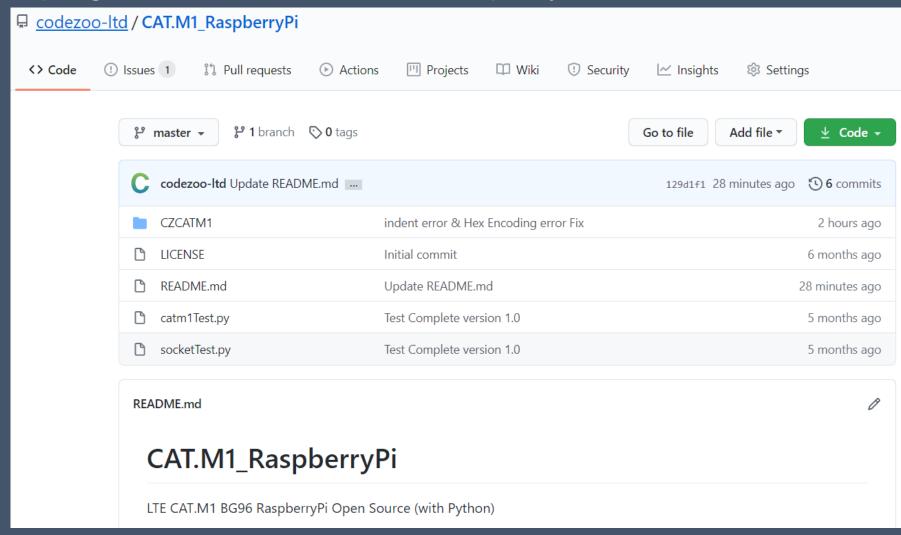
```
pi@raspberrypi:~ $
pi@raspberrypi:~ $ ls /dev/ttyS0
/dev/ttyS0
pi@raspberrypi:~ $
```

5. CAT.M1 실습

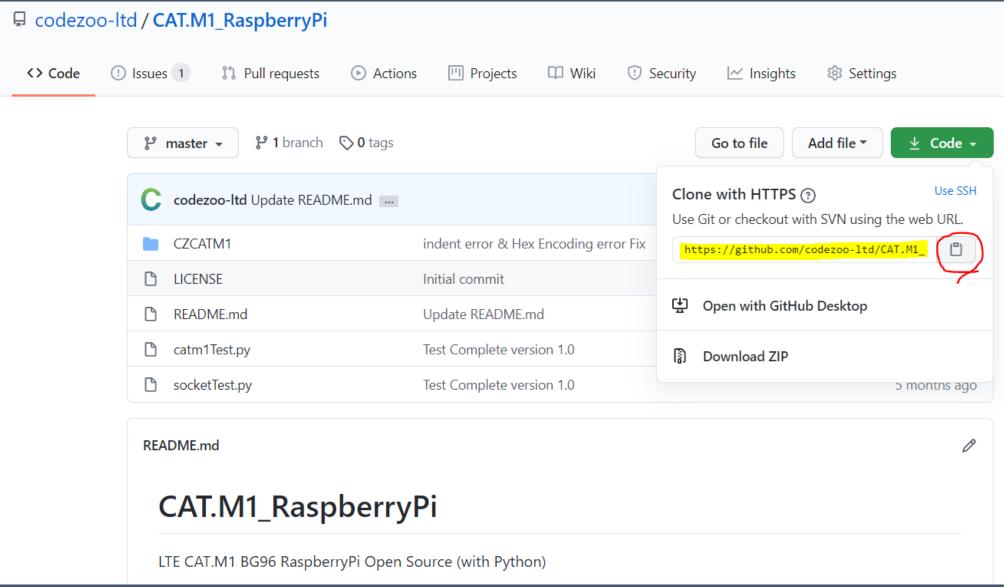


5. CAT.M1 실습 (다운로드)

https://github.com/codezoo-ltd/CAT.M1_RaspberryPi



5. CAT.M1 실습 (다운로드)



www.**Code**Zoo.co.kr

5. CAT.M1 실습 (다운로드)

```
jbmaster@jbmaster:~/work$ git clone https://github.com/codezoo-ltd/CAT.M1_RaspberryPi.git
Cloning into 'CAT.M1_RaspberryPi'...
remote: Enumerating objects: 27, done.
remote: Counting objects: 100% (27/27), done.
remote: Compressing objects: 100% (19/19), done.
remote: Total 27 (delta 7), reused 17 (delta 5), pack-reused 0
Unpacking objects: 100% (27/27), done.
jbmaster@jbmaster:~/work$
```

5. CAT.M1 실습 (실습예제1)

```
jbmaster@jbmaster:~/work/CAT.M1_RaspberryPi$ ls -al
total 32
drwxr-xr-x 4 jbmaster jbmaster 4096 8월 18 03:24 .
drwxr-xr-x 39 jbmaster jbmaster 4096 8월 18 03:24 ...
-rw-r--r-- 1 jbmaster jbmaster 529 8월 18 03:24 catm1Test.py
drwxr-xr-x 2 jbmaster jbmaster 4096 8월 18 03:24 CZCATM1
drwxr-xr-x 8 jbmaster jbmaster 4096 8월 18 03:24 .git
-rw-r--r-- 1 jbmaster jbmaster 1064 8월 18 03:24 LICENSE
-rw-r--r-- 1 jbmaster jbmaster 210 8월 18 03:24 README.md
-rw-r--r-- 1 jbmaster jbmaster 1246 8월 18 03:24 socketTest.py
jbmaster@jbmaster:~/work/CAT.M1_RaspberryPi$ python3 catm1Test.py
```

5. CAT.M1 실습 (실습예제2)

```
jbmaster@jbmaster:~/work/CAT.M1_RaspberryPi$ ls -al
total 32
drwxr-xr-x 4 jbmaster jbmaster 4096 8월 18 03:24 .
drwxr-xr-x 39 jbmaster jbmaster 4096 8월 18 03:24 ...
-rw-r--r-- 1 jbmaster jbmaster 529 8월 18 03:24 catm1Test.py
drwxr-xr-x 2 jbmaster jbmaster 4096 8월 18 03:24 CZCATM1
drwxr-xr-x 8 jbmaster jbmaster 4096 8월 18 03:24 .git
-rw-r--r-- 1 jbmaster jbmaster 1064 8월 18 03:24 LICENSE
-rw-r--r-- 1 jbmaster jbmaster 210 8월 18 03:24 README.md
-rw-r--r-- 1 jbmaster jbmaster 1246 8월 18 03:24 socketTest.py
jbmaster@jbmaster:~/work/CAT.M1_RaspberryPi$ python3 socketTest.py
```

감사합니다.