

### CodeZoo CATM1 Hands-On

- Jetson Nano (with PPP)-

version 1.0

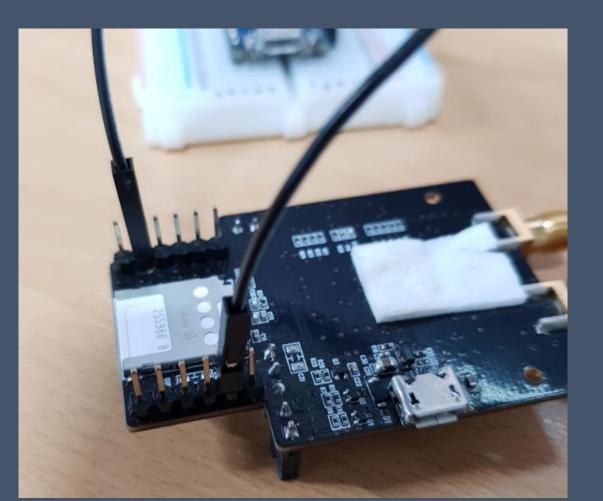
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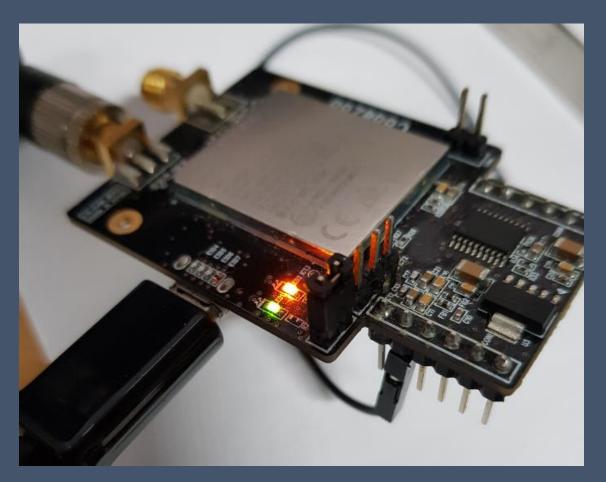
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### 1. CAT.M1 Hardware 준비

USB 연결 후 AT Command 테스트 절차

- 1. 후면 좌측 5번과 우측 2번을 점퍼선으로 연결 2. Micro USB 케이블을 라즈베리파이 USB 포트에 연결



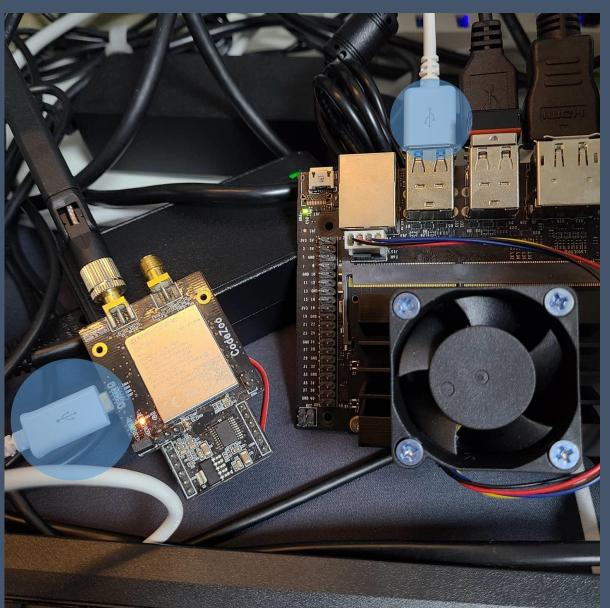


### 2. CAT.M1 실습 (Jetson Nano Image install)

- 1. Introduction https://developer.nvidia.com/embedded/learn/get-started-jetson-nano-devkit#intro
- 2. Prepare for Setup https://developer.nvidia.com/embedded/learn/get-started-jetson-nano-devkit#prepare
- 3. Write Image to the microSD Card https://developer.nvidia.com/embedded/learn/get-started-jetson-nano-devkit#write
- 4. Setup and First Boot https://developer.nvidia.com/embedded/learn/get-started-jetson-nano-devkit#setup

## 3. CAT.M1 연결

마이크로 USB 케이블로 CATM1과 Jetson Nano 연결



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### 4. CAT.M1 WvDial install

Cat.M1 모뎀과 Jetson Nano를 PPP(Point to Point Protocol)로 연결하기 위해 WvDial 을 사용합니다.

- 1. WvDial 설치: sudo apt-get install wvdial
- 2. 기본 WvDial 구성 파일을 편집 합니다. sudo nano /etc/wvdial.conf
- 3. 파일 편집 후 시스템을 재부팅 합니다.

#### wvdial.conf

[Dialer Defaults]

Modem = /dev/ttyUSB3

Baud = 115200

Init1 = AT+CFUN=1

Init2 = ATZ

Init3 = AT+CGDCONT=1,"IP","internet.lte.cxn"

Phone = \*99\*\*\*1#

Dial Command = ATD

Username = codezoo

Password = codezoo

Auto DNS = 1

Check Def Route = 1

Carrier Check = 0

Stupid Mode = 1

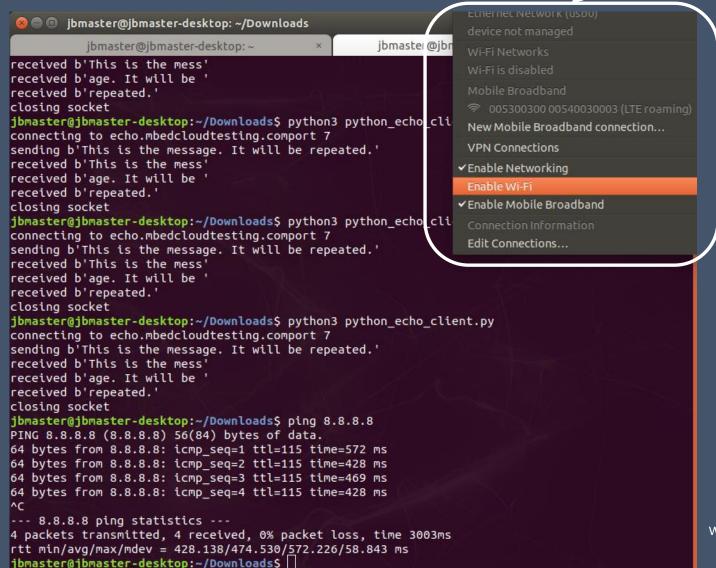
Dial Attempts = 3

ISDN = 0

#### 5. CAT.M1 PPP Test



1. Jetson Nano Wi-Fi 기능을 Disable 시킵니다. (클릭해서 Enable Wi-Fi 를 해제)

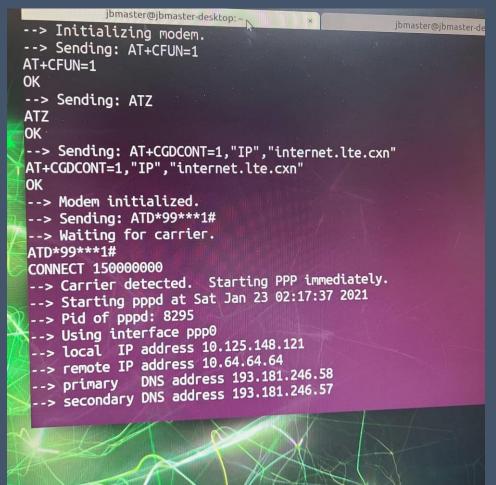


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#### 5. CAT.M1 PPP Test

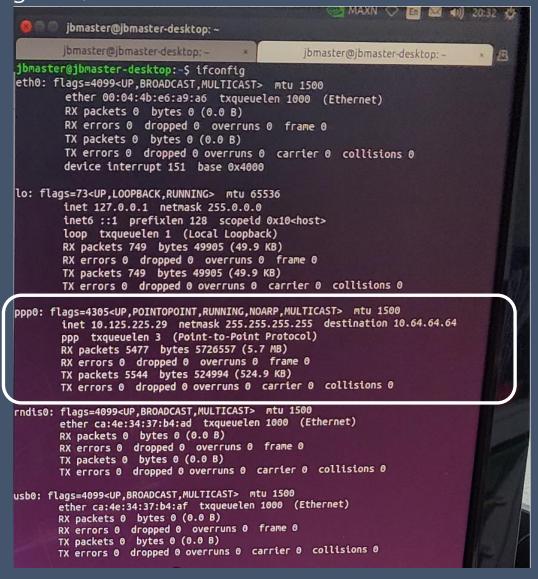
2. WvDial을 실행하여 연결을 확인하십시오. sudo wvdial

연결된 경우 다음과 유사한 출력이 표시되어야 합니다.



### 5. CAT.M1 PPP 동작 확인

3. Jetson Nano 터미널에서 ifconfig 실행, PPPO 디바이스 확인



### 5. CAT.M1 PPP 동작 확인

4. 파이썬 테스트 코드로 통신 테스트

python3 python\_echo\_client.py

```
import socket
import sys
#Create a TCP/IP socket
sock = socket.socket(socket.AF_INET, socket.SOCK_STREAM)
#Connect the socket to the port where the server is listening
server address = ('echo.mbedcloudtesting.com',7)
print('connecting to {}port {}'.format(*server_address))
sock.connect(server_address)
try:
  #Send data
  message = b'This is the message. It will be repeated.'
  print('sending {!r}'.format(message))
  sock.sendall(message)
  #Look for the response
  amount received = 0
  amount_expected = len(message)
  while amount_received < amount_expected:
    data = sock.recv(16)
    amount_received += len(data)
    print('received {!r}'.format(data))
finally:
  print('closing socket')
  sock.close()
```

# 감사합니다.