02/07/2021 rbfn

0:02 hrs Install and import packages

```
! pip install numpy
! pip install matplotlib
! pip install sklearn

import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D
from sklearn.model_selection import train_test_split
```

```
Requirement already satisfied: numpy in /home/pjaworsk/miniconda3/lib/python3.8/site-packages (1.19.5)
WARNING: You are using pip version 21.0.1; however, version 21.1.3 is available.
You should consider upgrading via the '/home/pjaworsk/miniconda3/bin/python -m pip install --upgrade pip' command.
Requirement already satisfied: matplotlib in /home/pjaworsk/miniconda3/lib/python3.8/site-packages (3.3.3)
Requirement already satisfied: pillow>=6.2.0 in /home/pjaworsk/miniconda3/lib/python3.8/site-packages (from matplotlib)
 (8.1.0)
Requirement already satisfied: python-dateutil>=2.1 in /home/pjaworsk/miniconda3/lib/python3.8/site-packages (from matpl
otlib) (2.8.1)
Requirement already satisfied: numpy>=1.15 in /home/pjaworsk/miniconda3/lib/python3.8/site-packages (from matplotlib)
 (1.19.5)
Requirement already satisfied: cycler>=0.10 in /home/pjaworsk/miniconda3/lib/python3.8/site-packages (from matplotlib)
 (0.10.0)
Requirement already satisfied: pyparsing!=2.0.4,!=2.1.2,!=2.1.6,>=2.0.3 in /home/pjaworsk/miniconda3/lib/python3.8/site-
packages (from matplotlib) (2.4.7)
Requirement already satisfied: kiwisolver>=1.0.1 in /home/pjaworsk/miniconda3/lib/python3.8/site-packages (from matplotl
ib) (1.3.1)
Requirement already satisfied: six in /home/pjaworsk/miniconda3/lib/python3.8/site-packages (from cycler>=0.10->matplotl
ib) (1.15.0)
WARNING: You are using pip version 21.0.1; however, version 21.1.3 is available.
You should consider upgrading via the '/home/pjaworsk/miniconda3/bin/python -m pip install --upgrade pip' command.
Requirement already satisfied: sklearn in /home/pjaworsk/miniconda3/lib/python3.8/site-packages (0.0)
Requirement already satisfied: scikit-learn in /home/pjaworsk/miniconda3/lib/python3.8/site-packages (from sklearn) (0.2
Requirement already satisfied: numpy>=1.13.3 in /home/pjaworsk/miniconda3/lib/python3.8/site-packages (from scikit-learn
->sklearn) (1.19.5)
Requirement already satisfied: joblib>=0.11 in /home/pjaworsk/miniconda3/lib/python3.8/site-packages (from scikit-learn-
>sklearn) (1.0.1)
Requirement already satisfied: threadpoolctl>=2.0.0 in /home/pjaworsk/miniconda3/lib/python3.8/site-packages (from sciki
t-learn->sklearn) (2.1.0)
Requirement already satisfied: scipy>=0.19.1 in /home/pjaworsk/miniconda3/lib/python3.8/site-packages (from scikit-learn
->sklearn) (1.6.0)
WARNING: You are using pip version 21.0.1; however, version 21.1.3 is available.
You should consider upgrading via the '/home/pjaworsk/miniconda3/bin/python -m pip install --upgrade pip' command.
```

Create a class to hold our RBFN

```
class RRF.
   Parameters
       n_inputs: int
           number of input nodes
       n_hidden: int
           number of rbf nodes
       n_outputs: int
          number output nodes
       centers: (1xn_hidden) array
           rbf function centers
       widths: (1xn_hidden) array
       rbf widths / std_dev
       self.n_inputs = n_inputs
       self.n_hidden = n_hidden
       self.n_outputs = n_outputs
       self.centers = centers
       self.widths = widths
       self.verbose = verbose
       weight init range = 0.5
       \verb|self.weights| = \verb|np.random.uniform(-weight_init_range, weight_init_range, (n_hidden, n_outputs))|
   def gauss_kernel_func(self, x):
       Applies the gauss kernel with the instantiated widths and centers for all rbf nodes to the single input.
       Returns the output of each rbf node on the single input.
       Parameters
       x: np.array (n inputs, )
           an input from the series of inputs
       return np.exp((-1*(np.linalg.norm(x-self.centers, axis=1)**2)/(2*self.widths**2)))
   def inference(self, x):
```

```
Takes a set of input data and applies the gauss kernel function on them, then does the weighted summation
       to obtain network outputs of shape (n_input_data, n_output)
       Parameters
       x: np.array (n_input_data, n_inputs)
       if self.verbose:
              print('====INFERENCE====')
       activities = []
       for input_val in x:
              activity = self.gauss_kernel_func(input_val)
              activities.append(activity)
       activities = np.asarray(activities)
       # outputs = np.sum(self.weights * activities, axis=1)
       # outputs = np.asarray(outputs)
       outputs = activities @ self.weights
       return outputs
def forward(self, x):
       Takes a set of input data and applies the gauss kernel function on them, then does the weighted summation
       to obtain network outputs of shape (n_input_data, n_output).
       Differs from self inference because here we store the inputs, activities, and output to self variables that
       are used during inference.
       Parameters
       x: np.array (n_input_data, n_inputs)
       if self.verbose:
              print('====FORWARD=====')
       self.input = x
       self.activities = []
       for input_val in self.input:
              activity = self.gauss kernel func(input val)
              self.activities.append(activity)
       self.activities = np.asarray(self.activities)
       self.output = self.activities @ self.weights
       if self.verbose:
              print('weights| (n_hiddenxn_output): ', self.weights.shape)
print('input| (n_samplesxn_input): ', self.input.shape)
              print('activities| (n_samplesxn_hidden): ', self.activities.shape)
              print('output: | (n_hiddenx1)', self.output.shape)
       return self.output
def backward(self, target_output):
       Run this after running self.forward where we determine and store our series of activities.
       Accepts the matching target outputs for the inputs used during the forward pass. Performs
       the matrix (pseudo)inverse using the series of activities and target output obtain the output weights.
       Parameters
       target_output: np.array (n_input_data, n_outputs)
              the target outputs of the inputs used during self.forward
       if target output.ndim == 1:
              target_output = np.expand_dims(target_output, 1)
       if self.verbose:
              print('====BACKWARD===')
              print('activities series: ', self.activities.shape)
print('target_output series: ', target_output.shape)
              print('weights: ', self.weights.shape)
       # normal inverse
       # if self.n_hidden >= len(self.input):
       if np.linalg.matrix_rank(self.activities) >= target_output.shape[0]:
              if self.verbose:
                     print('Inverse')
              \# \ np. savez\_compressed('test\_data.npz', \ activities=self.activities, \ weights=self.weights, \ targets=target\_outplace and the savez\_compressed('test\_data.npz', \ activities=self.activities, \ weights=self.weights, \ targets=target\_outplace and the savez\_compressed('test\_data.npz', \ activities=self.activities, \ weights=self.weights, \ targets=target\_outplace and the savez\_compressed('test\_data.npz', \ activities=self.activities, \ weights=self.weights, \ targets=target\_outplace and \ targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=targets=
              self.weights = np.linalg.inv(self.activities) @ target_output
       # pseudo inverse
       else:
              if self.verbose:
                     print('Pseudo-inverse')
              self.weights = np.linalg.pinv(self.activities) @ target output
       # print('activities: ', self.activities[:10, :10])
       # sanity_check = self.activities @ self.weights
```

```
0:02 hrs
```

```
# print('target_out: ', target_output[:10])
# print('sanity check: ', sanity_check[:10])
```

Define the function we're trying to model

```
In [3]:
# The function we're trying to model
def ground_truth_func(x):
    if x[0]**2 + x[1]**2 <= 1:
        return 1
    else:
        return -1</pre>
```

Generate our target inputs using

```
xi = -2 + 0.2i

xj = -2 + 0.2j

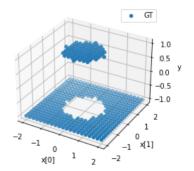
where i = 0, 1, ..., 20
```

where $i = 0, 1, \ldots, 20$ then calculate the corresponding outputs using our target function

```
input original shape: (21, 21, 2)
input flattened shape: (441, 2)
target output shape: (441,)
```

Plot our inputs and their corresponding outputs on a 3d scatterplot as a sanity check.

```
In [5]:
    plt.figure()
    a1 = plt.subplot(111, projection='3d')
    a1.scatter(x[:, 0], x[:, 1], y, label='GT')
    a1.set_xlabel('x[0]')
    a1.set_ylabel('x[1]')
    a1.set_zlabel('y')
    plt.legend()
    plt.show()
```



Split our data into a 80-20 train-test split

```
In [6]:
    train_data, test_data, train_labels, test_labels = train_test_split(x, y, test_size=0.2, random_state=0)
    print('train_data shape: ', train_data.shape)
    print('train labels shape: ', train_labels.shape)
    print('train labels shape: ', train_labels.shape)

train_data shape: (352, 2)
    test_data shape: (89, 2)
    train labels shape: (352,)
    test labels shape: (89,)
```

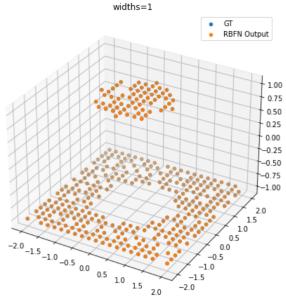
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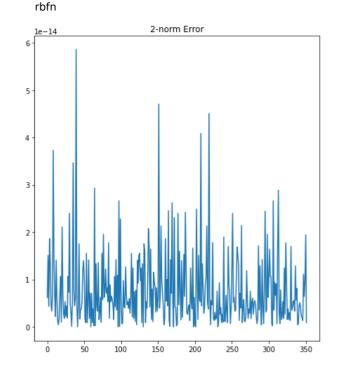
0:02 hrs Train RBFN output weights

```
# Create our rbf network with the number of hidden node matches the number of input data points
          # set our layer sizes
          n input = 2
          n_hidden = train_data.shape[0]
          n_{output} = 1
          # set our width to 0.2 at first, we will vary it later
          width = 0.2
          widths = np.ones(n_hidden) * width
           # set our centers to the training data
          centers = train_data
          print('widths: ', widths.shape)
print('centers: ', centers.shape)
           # Using training data as rbf centers
          print("Creating RBFN with %i input, %i hidden, and %i output' % (n input, n hidden, n output))
           rbf = RBF(n_input, n_hidden, n_output, centers=centers, widths=widths)
          widths: (352,)
                    (352, 2)
          centers:
          Creating RBFN with 2 input, 352 hidden, and 1 output
         Run the forward and backward pass on the training data to obtain our weights
 In [8]:
          # run forward and backward pass to get weights
          train out = rbf.forward(train data)
          print('train output shape: ', train_out.shape)
           rbf.backward(train_labels)
          train output shape: (352, 1)
         sanity check, this should match our data exactly if activities is invertable
 In [9]:
          train_inference_out = rbf.inference(train_data)
          print('inference output shape: ', train_inference_out.shape)
          inference output shape: (352, 1)
         As a sanity check, run the inference on the training data. Since our number of hidden dimensions matches the number of input data points, we should
         be able to perfectly model the input data. However, this will not hold if the set of activities is non-singular (ie. rank(activities) < activities.ndim)
In [10]:
          def plot_outputs_and_error(train_data, train_labels, x, y, title):
               plt.figure(figsize=(16, 8))
               # plot the actual data
               al = plt.subplot(121, projection='3d')
               al.set title(title)
               a1.scatter(train_data[:, 0], train_data[:, 1], train_labels, label='GT')
               a1.scatter(x[:, 0], x[:, 1], np.squeeze(y), label='RBFN Output')
               plt.legend()
               # plot the error
               a2 = plt.subplot(122)
               a2.set_title('2-norm Error')
               #test_out = np.squeeze(test_out)
               train_labels = np.reshape(train_labels, (len(train_labels), 1))
               a2.plot(np.linalg.norm(train_labels-y, axis=1))
               plt.show()
          plot_outputs_and_error(train_data, train_labels, train_data, train_inference_out, 'Inference on train_data\nwidths=1')
```

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Since our inferred output on the training data is all zero (within numerical error of floating points), our model is correctly performing the RBFN. Now we can run the same test on our test data to see how the network performs.

Part 1.

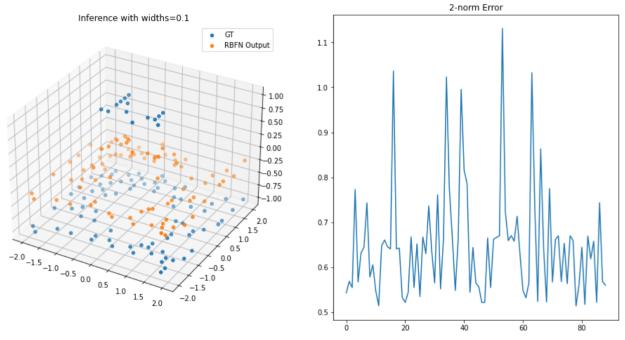
Carry out the design of RBF NN based on Gaussian kernel functions with constant spread function and using all the points in the training set as centers of the RB functions. Compare the performance results (mean square error) as you vary the spread parameter while keeping it the same for all kernel functions. Discuss your findings.

```
In [11]:
            test out = rbf.inference(test data)
            print('test output shape: ', test_out.shape)
            plot_outputs_and_error(test_data, test_labels, test_data, test_out, 'Inference with widths=0.2')
           test output shape: (89, 1)
                                                                                                                2-norm Error
                              Inference with widths=0.2
                                                                                   1.6
                                                               GT
                                                               RBFN Output
                                                                                   14
                                                                                   1.2
                                                                        1.0
                                                                                   1.0
                                                                        0.5
                                                                        -0.5
                                                                        -1.0
                                                                        -1.5
                                                                        -2.0
                                                                                   0.6
                                                                      2.0
                                                                                   0.4
                                                                  1.0
               ^{-2.0}_{-1.5}_{-1.0}_{-0.5} _{0.0} _{0.5}
                                                                0.5
                                                           -0.5
                                                                                   0.2
                                                         -1.0
                                      1.0
                                                     -2.0
                                                                                   0.0
```

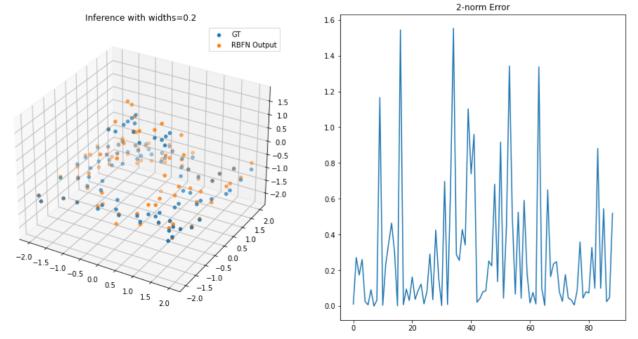
Note that the above is with a constant width across all RBF nodes of 1. Now let's vary the width and see what happens.

```
In [12]:
          centers = train_data
          width vals = np.linspace(0.1, 1, 10)
          for width in width_vals:
```

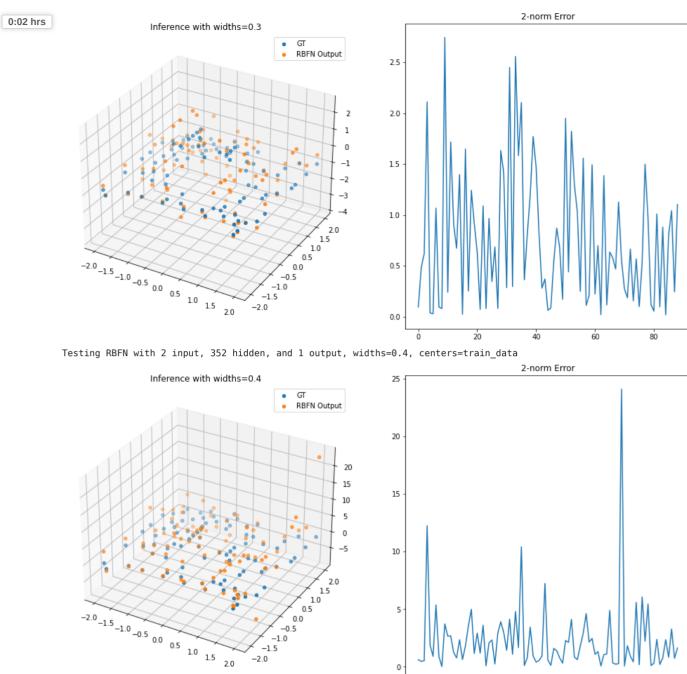
Testing RBFN with 2 input, 352 hidden, and 1 output, widths=0.1, centers=train_data



Testing RBFN with 2 input, 352 hidden, and 1 output, widths=0.2, centers=train_data

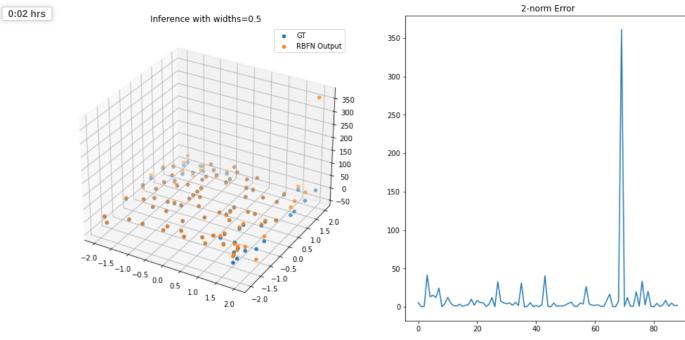


Testing RBFN with 2 input, 352 hidden, and 1 output, widths=0.3, centers=train_data

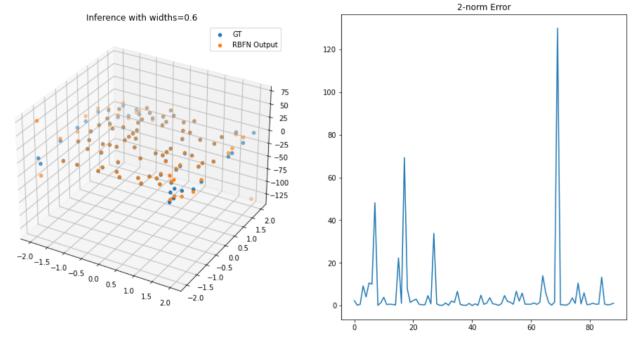


Testing RBFN with 2 input, 352 hidden, and 1 output, widths=0.5, centers=train_data

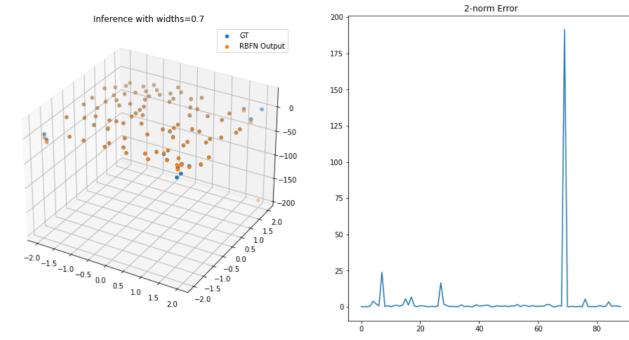
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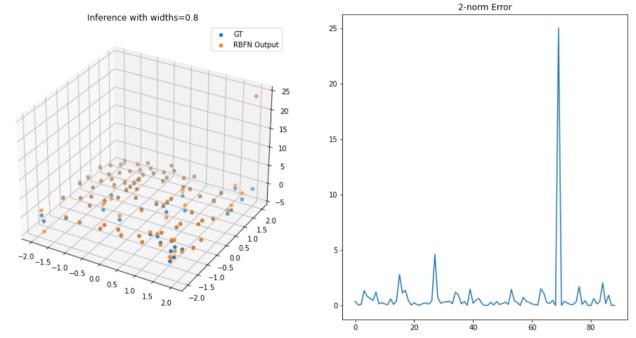
Testing RBFN with 2 input, 352 hidden, and 1 output, widths=0.6, centers=train_data



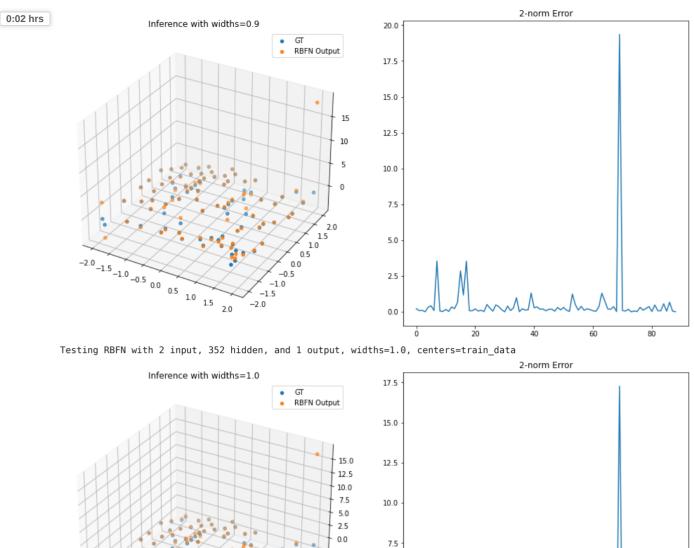
Testing RBFN with 2 input, 352 hidden, and 1 output, widths=0.7, centers=train_data



Testing RBFN with 2 input, 352 hidden, and 1 output, widths=0.8, centers=train_data



Testing RBFN with 2 input, 352 hidden, and 1 output, widths=0.9, centers=train_data



When the spread matches the spread of our data (0.2) we get the closest match

1.0

Part 2.

 $-2.0_{-1.5}^{}$ $-1.0_{-0.5}^{}$ 0.0 0.5

Perform the design of the RBF NN, using this time only 150 centers, choosing the centers using two approaches:

2.0

0.5

× −1.5 −2.0 5.0

2.5

0.0

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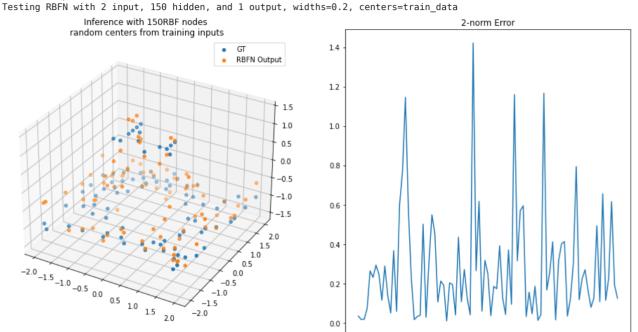
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a) Randomly select the centers from the input data.

```
n_hidden=centers.shape[0],
n_outputs=1,
centers=centers,
widths=widths)

# run forward and backward pass to get weights
train_out = rbf.forward(train_data)
rbf.backward(train_labels)
test_out = rbf.inference(test_data)
plot_outputs_and_error(test_data, test_labels, test_data, test_out, "Inference with 150RBF nodes\n random centers from t
centers shape: (150, 2)
```



It is clear the error is larger with fewer nodes to model the input. The matrix inversion now has to use the pseudo-inverse since our activities series matrix is non-singular.

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b) Use K-Means algorithm to find the centers. You can use a Kmeans function defined in sklearn

(https://scikit-learn.org/stable/modules/generated/sklearn.cluster.KMeans.html)

First we have to calculate our centers through clustering.

Note need to make this (150,2)

```
In [14]:
          #Do sci-kit learn stuff to get clusters training data into 150 points for our centers
          from sklearn.cluster import KMeans
          kmeans = KMeans(n clusters=150, random state = 0)
          kmeans.fit(train data)
          centers = kmeans.cluster_centers_
In [15]:
          print('centers shape: ', centers.shape)
          width = 0.2
          widths = np.ones(centers.shape[0]) * width
          # Using training data as rbf centers
          print('Testing RBFN with %i input, %i hidden, and %i output, widths=%.lf, centers=train_data' % (
              (n_input, centers.shape[0], n_output, width))
          rbf = RBF(
              n_inputs=2,
              n_hidden=centers.shape[0],
              n_outputs=1,
              centers=centers,
              widths=widths)
          # run forward and backward pass to get weights
          train_out = rbf.forward(train_data)
          rbf.backward(train_labels)
```

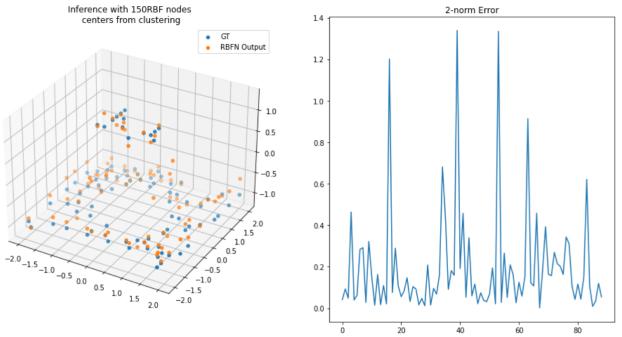
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0:02 hrs

test_out = rbf.inference(test_data)
plot_outputs_and_error(test_data, test_labels, test_data, test_out, "Inference with 150RBF nodes\n centers from clusteri

centers shape: (150, 2)

Testing RBFN with 2 input, 150 hidden, and 1 output, widths=0.2, centers=train_data



The resulting error for using the K-means clustering to find all the centers, provides an overall lower error. This is because we are choosing centers that encompass more points within the set width, due to the clustering. With respect to part 1, using k-means to determine our centers mitigates the overfitting when using all of the training data as centers. We see this when running inference on test data, thus leading to a more generalized model.

In []: