

Agenda



- Contributions of OpenFlow, Open vSwitch and P4
- OpenFlow features missing in P4, and P4 features missing in OpenFlow
- Architecture of Open vSwitch accelerated by a SmartNIC
- Architecture of a P4 SmartNIC datapath
- Performance considerations
- Next steps: proposals towards convergence and alignment



Architectural Principle:

- Logically Centralized, Decoupled Control

Model:

 Defined by specification: dataplane protocols, pipeline of match-action tables

(Soon: dataplane protocols no longer in main specification, dynamic dataplane protocol definition being considered)

Interface:

Protocol (handcrafted, binary C struct style)

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Well known SDN (and older) principle - not unique to OpenFlow

No plans to abandon — perhaps add selective delegation, hierarchies

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Too limited: annoying to have to create specification revisions to add protocols, behavior

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NETRONGME

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Software usually built using libraries with callable APIs

Protocol can be a language independent interface (but prefer automated marshalling, e.g. Thrift)

Need faster interface mechanism (e.g. callable API) for datapath extension code



Architectural Principle:

- Language enabling datapath programming
- Deployable with central or distributed control, as switch or part of switch

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 Datapath protocols and behavior are defined by a program (not enshrined in a standard)

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Convenient for initial experimentation

 need to link with different library for each version of each program However complicates matters for controllers

Consider generic interface instead

乙四十刀口乙GMM

Widely deployed virtual switch

- Integrated with many controllers, cloud management systems (OpenStack, ODL, ONOS...)

Accepted into Linux kernel

 Uses Linux kernel facilities where appropriate, e.g. for connection tracking or QoS

Developed by community as open source project

Frequently leading OpenFlow standards

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OpenFlow Features not in P4

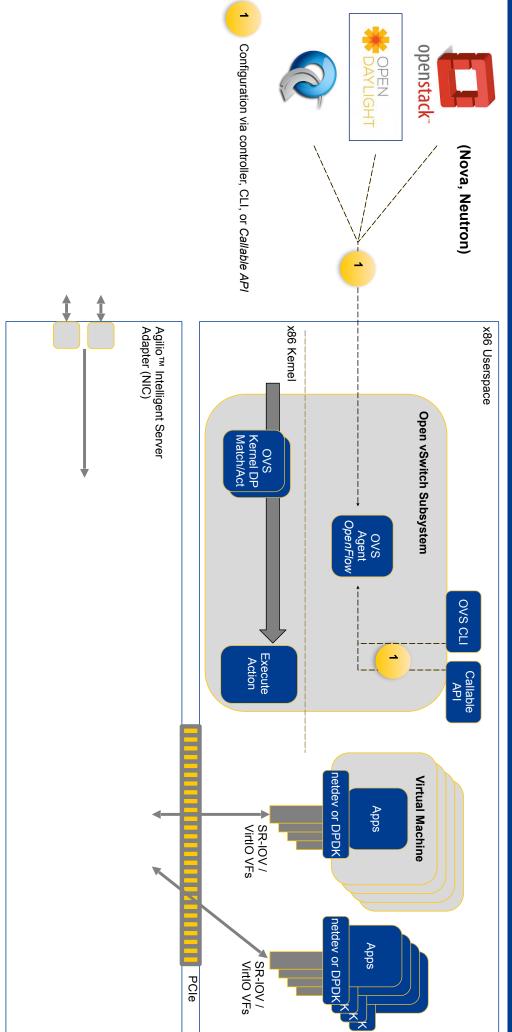


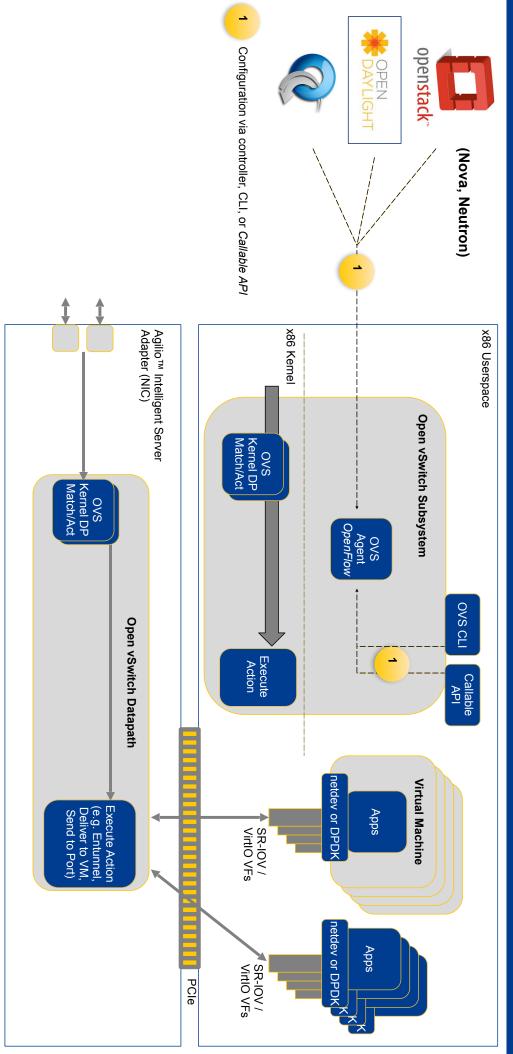
- At any time, the SDN controller can send a flow add or flow modify message:
- creating a new table or a new control flow path,
- ... matching an additional field or invoking an additional action, etc.
- In P4, actions, tables, and control flow options are pre-declared in the program
- Solutions to retain dynamic functionality with OpenFlow compatibility:
- JIT compile program variant with a capability once it is first required [analogous to PyPy]
- Cache these variants remember last used (issue: when to "garbage collect")
- Solutions to avoid need for dynamic functionality
- Model (e.g. TTP) is used to declare required functionality (e.g. action list patterns) at start time
- No changes needed to OpenFlow otehrwise (device returns error if functionality unsupported)

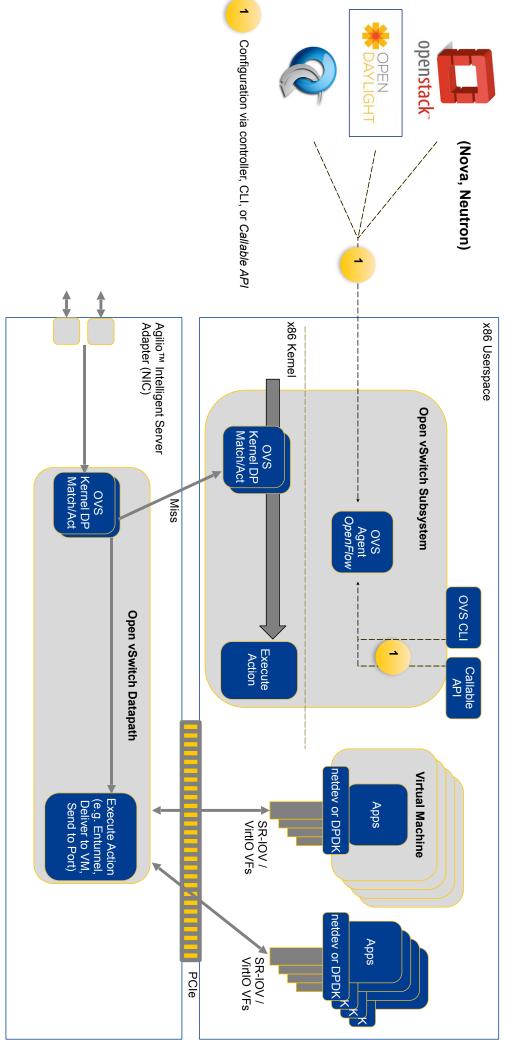
P4 Features not in OpenFlow

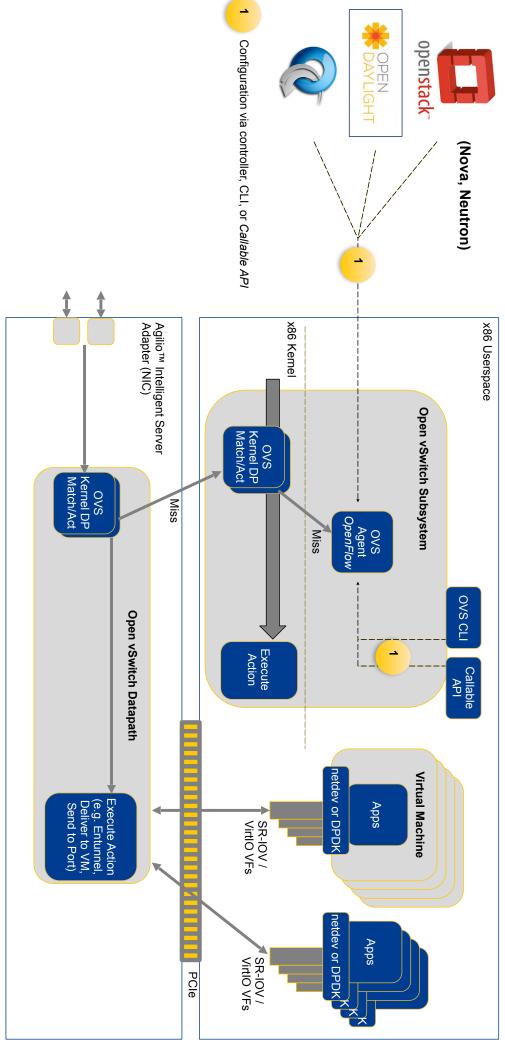


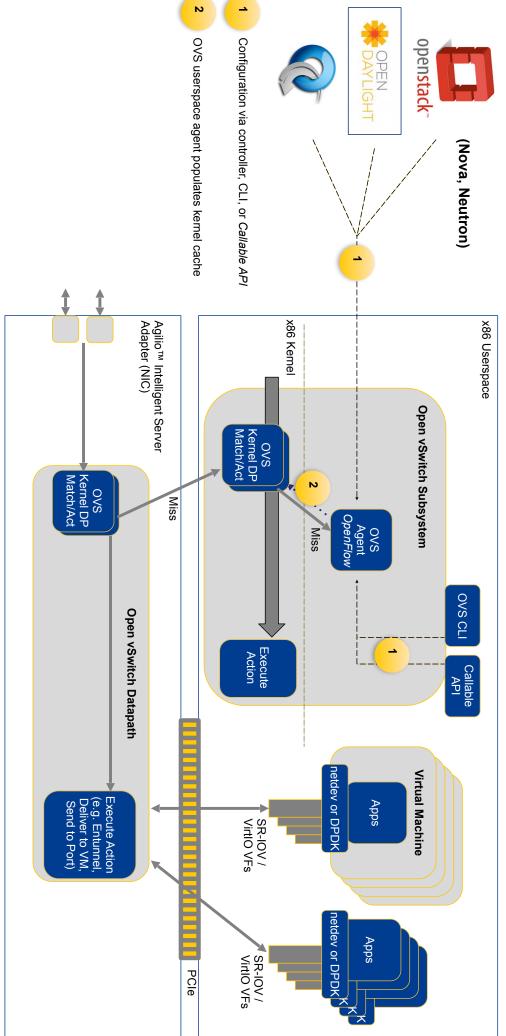
- Too many to list here!
- Nice!
- Flexibility can actually be a problem for controllers, cloud management systems: difficult to generically support all datapath programs / program versions
- Solution: "plugin" into controller to go along with datapath program
- Run time interface becomes distributed system infrastructure (RPC)
- Solution: implement functionality with a well defined (less rapidly evolving) interface
- Run-time interface generated from program is problematic too many libraries / modules for controller writers to consume
- Consider generic interface also: APIs to discover and access objects
- Generated interface remains useful for fast datapath extension software (... see demo ...)

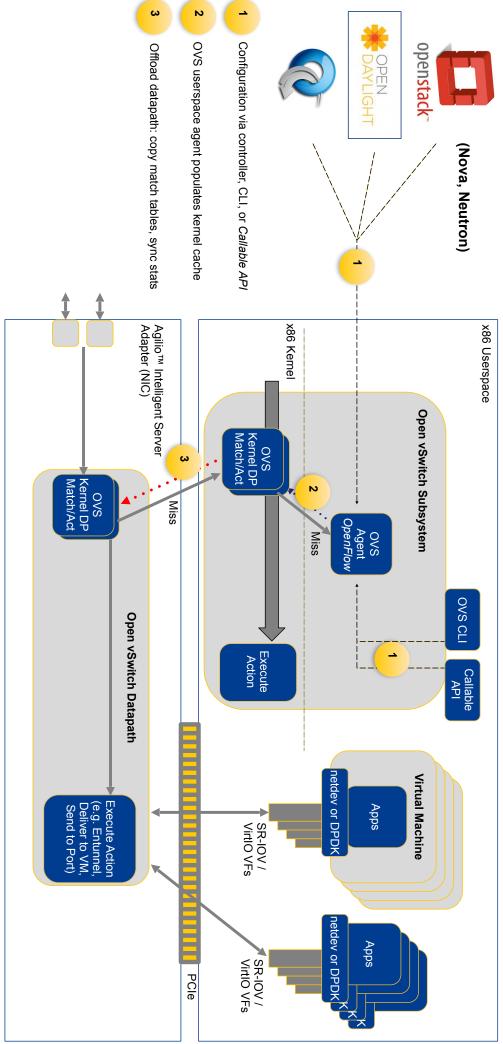


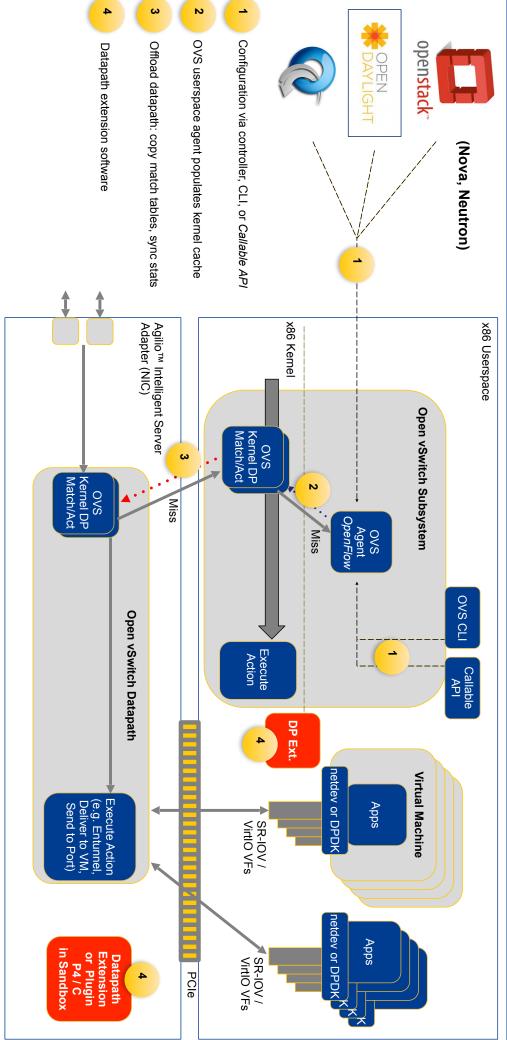




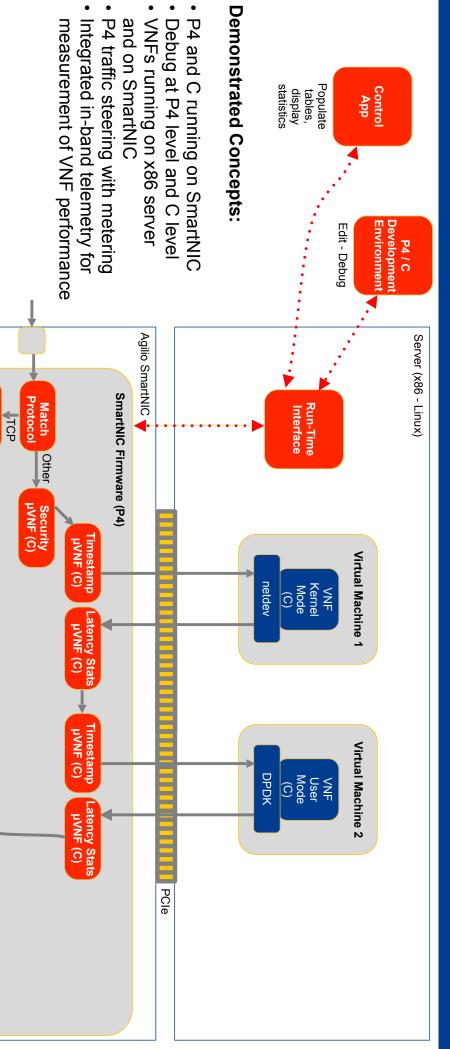




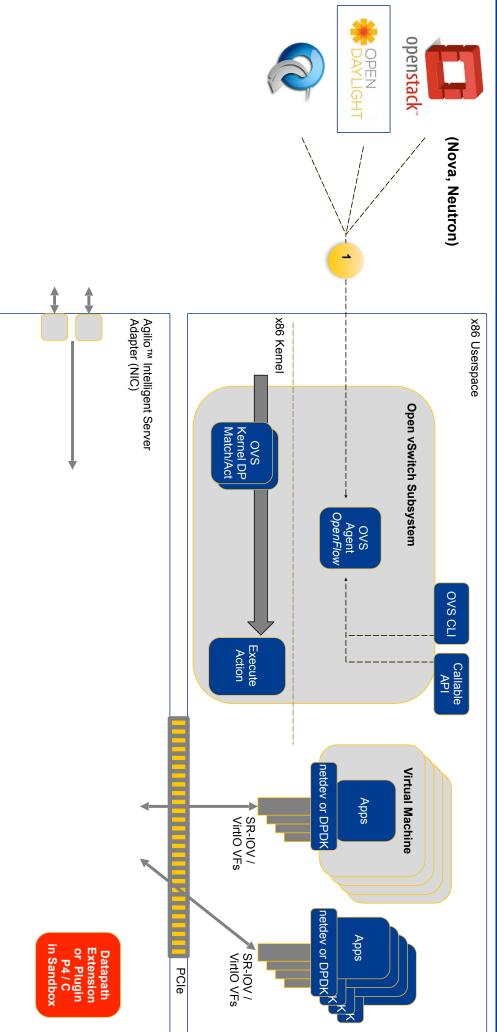


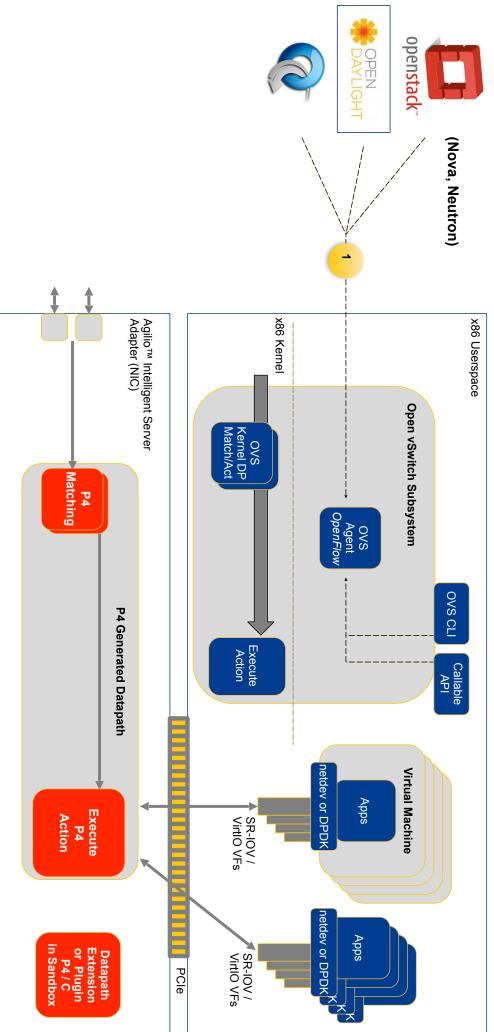


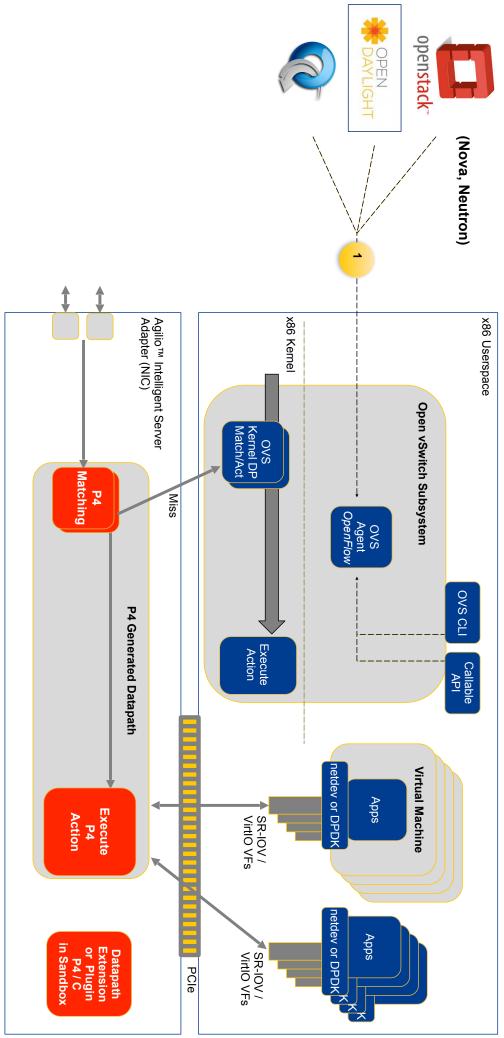
P4 for SmartNICs with VNF and µVNF chaining

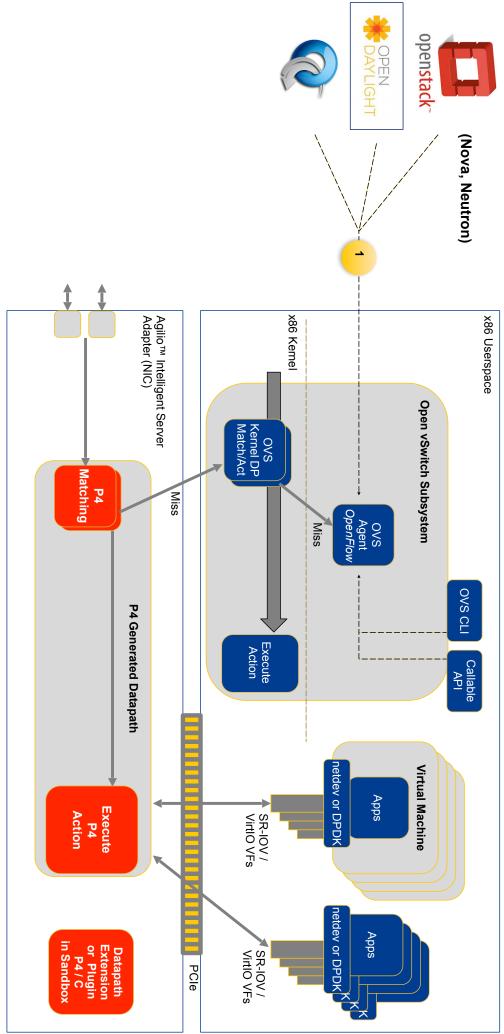


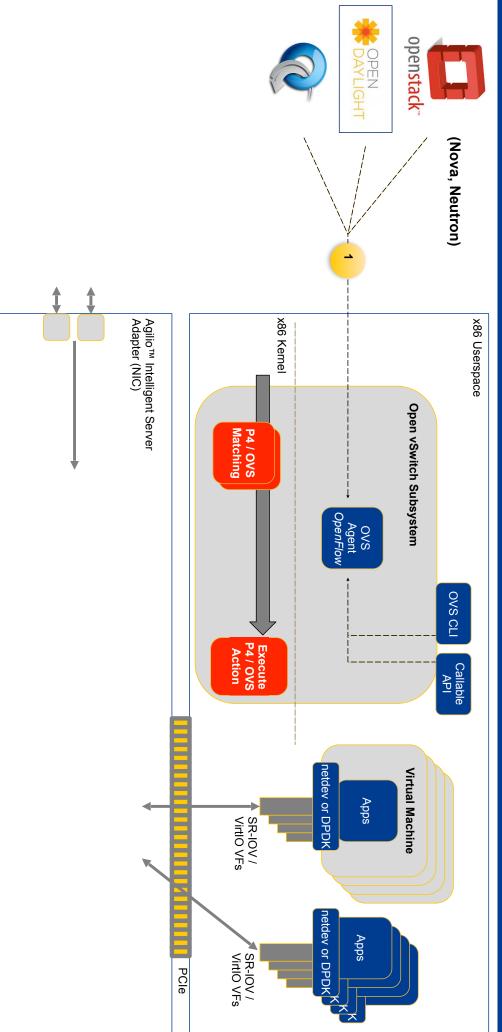
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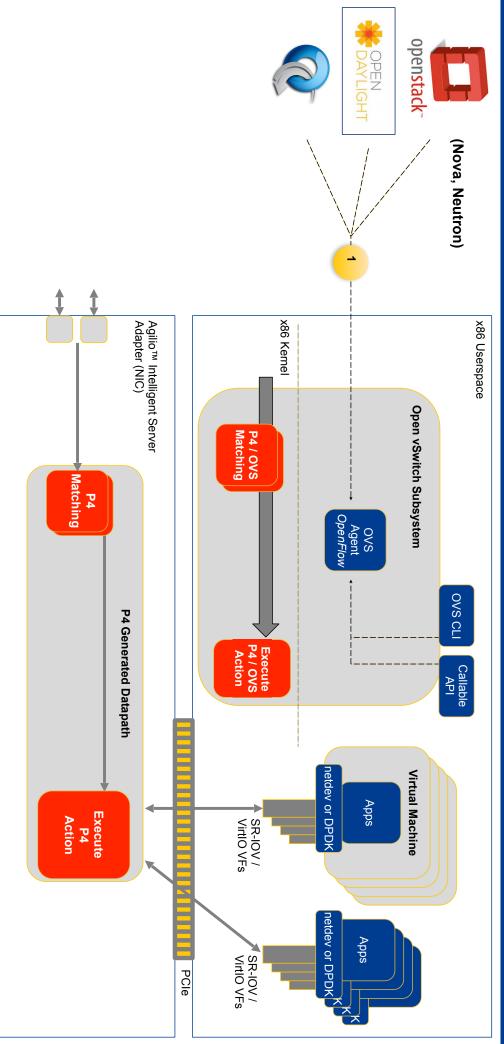


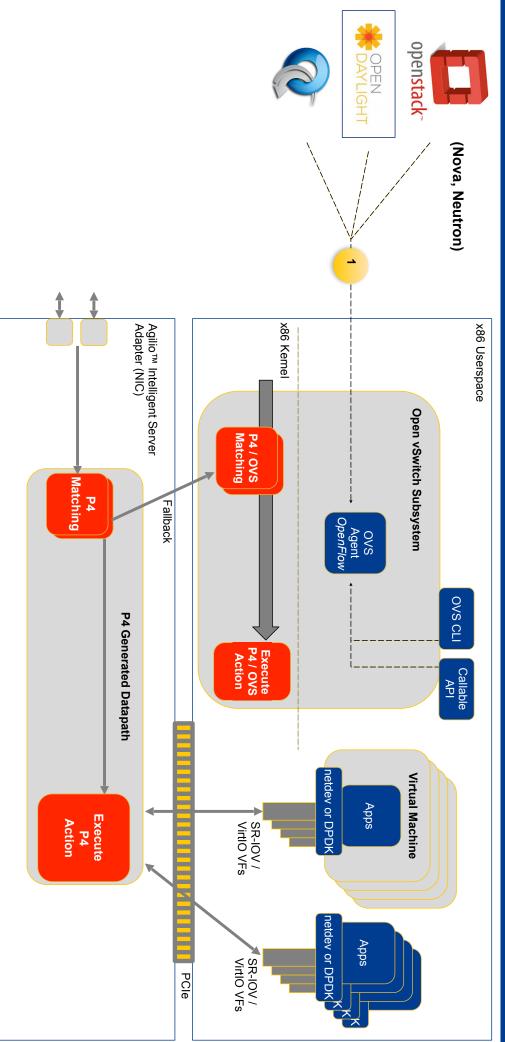


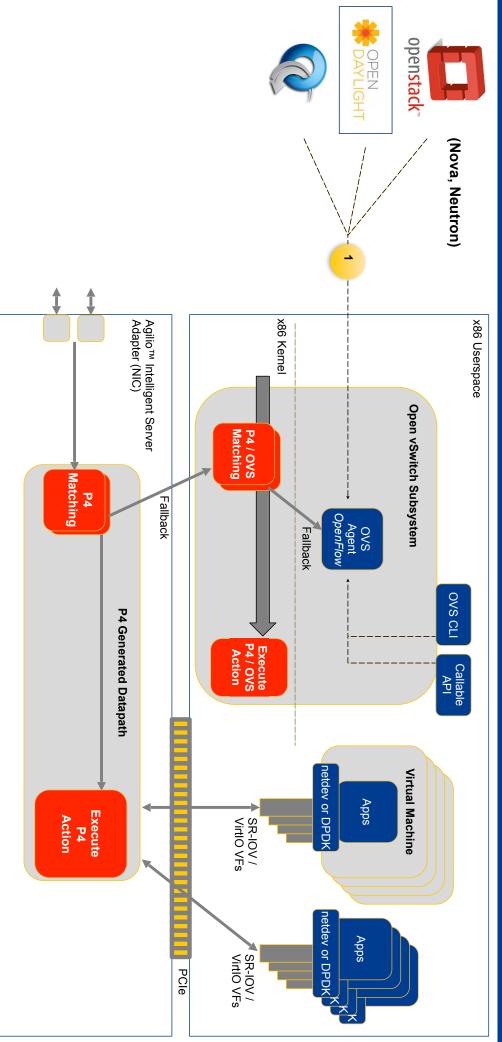




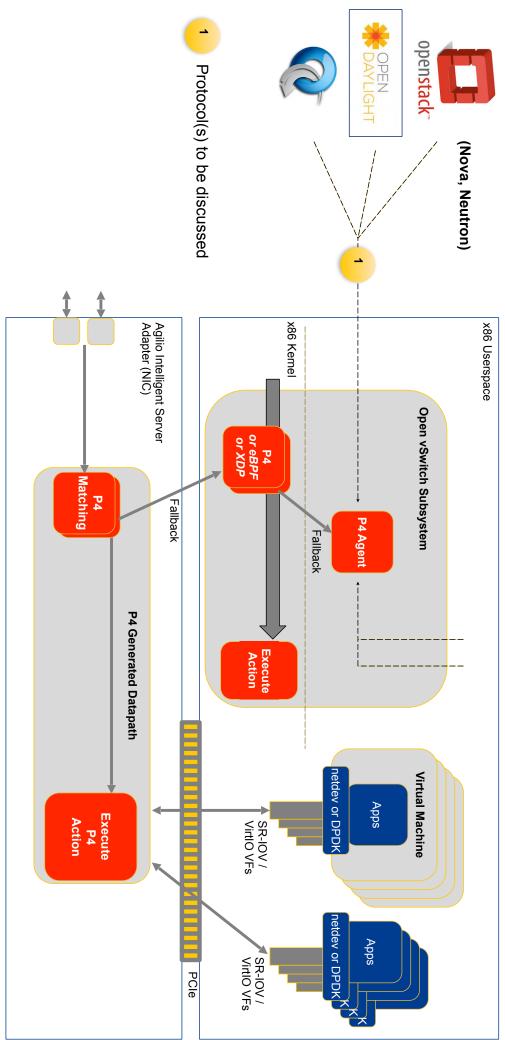








P4 "instead of" OVS (Datapath and Control)



Performance Observations (Agilio ™-CX SmartNIC)

- Simple scenario
- SmartNIC accelerated OVS: 35 Mpps @ < 1 core
- P4 on SmartNIC: 36 Mpps @ < 1 core
- Despite high level language overhead, only deploying the packet processing operations required by the application yields high performance



- More complex scenario
- Unaccelerated OVS: 11 Mpps @ 22 server cores
- SmartNIC accelerated OVS: 33 Mpps @ < 1 server core (>60x efficiency)
- P4 on SmartNIC: 21 Mpps @ < 1 server core (>40x efficiency)
- => Hand-tuned implementation beats P4 (currently beta compiler: room for improvement)
- => Both offer significantly better efficiency (throughput per server core) than unaccelerated OVS

Next Steps



- Enable migration from existing OpenFlow network / cloud control interface to a P4 capable control interface (generated / generic)
- ... collaborating with e.g. ONF, Open vSwitch, OpenStack, ODL, ONOS, NFV bodies...
- Standardize a persistent IR with a simple to parse format (YAML / JSON) and a stable schema .. collaborating with e.g. OpenSourceSDN.org, ONF..
- Use subset (extract) of IR as model, also as a description of the run-time interface
- Equivalent: ".h" for ".c"
- In effect a "TTP"
- Supports multiple P4 language versions (or, in future, other languages)
- Behavioral model v2 developers discovered the usefulness of a JSON based "IR"
- Enables ecosystem of tools (optimizers, visualizers, front / back end compilers, etc.)
- Use Agilio[™] SmartNICs
- . to accelerate existing datapaths OVS (OpenFlow), Contrail vRouter, Linux…
- ... to implement new datapaths P4, eBPF/XDP...

