MPMC LAB RECORD

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Joel Scaria | CSE B | 106118042

Experiment 1:

Aim:

Assembly program for addition and subtraction of 16 bit numbers

ASM code:

Addition :

```
data segment
    a dw 0202h
    b dw 0901h
    c dw ?
data ends

code segment
assume cs:code, ds:data
start:
    mov ax, data
    mov ds, ax
    mov ax, a
    mov bx, b
    add ax,bx
    mov c,ax
    lea si,c
    int 3
code ends

end start
```

Subtraction :

```
data segment
    a dw 000ah
    b dw 0001h
    c dw ?
data ends

code segment
assume cs:code, ds:data
start:
    mov ax, data
    mov ds, ax
    mov ax, a
    mov bx, b
    sub ax, bx
    mov c, ax
    int 3
```

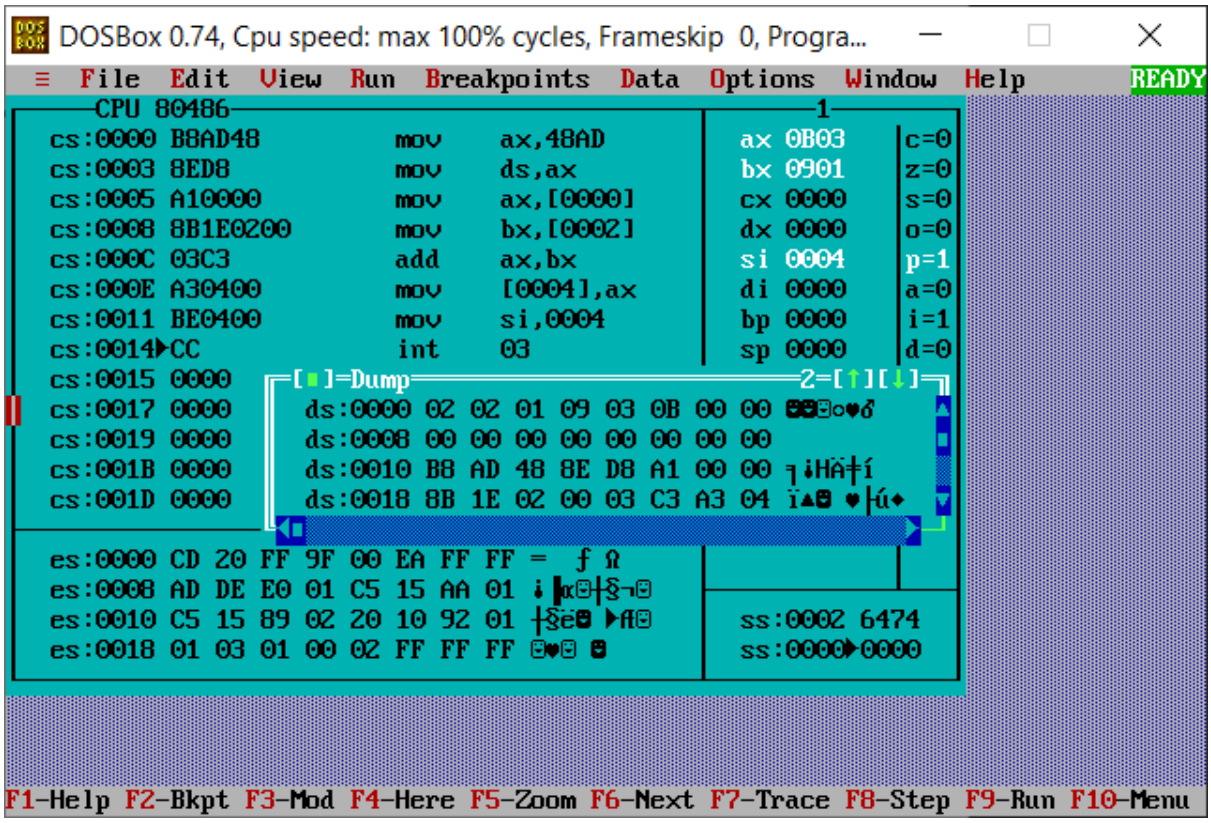
```
code ends
end start
```

Explanation:

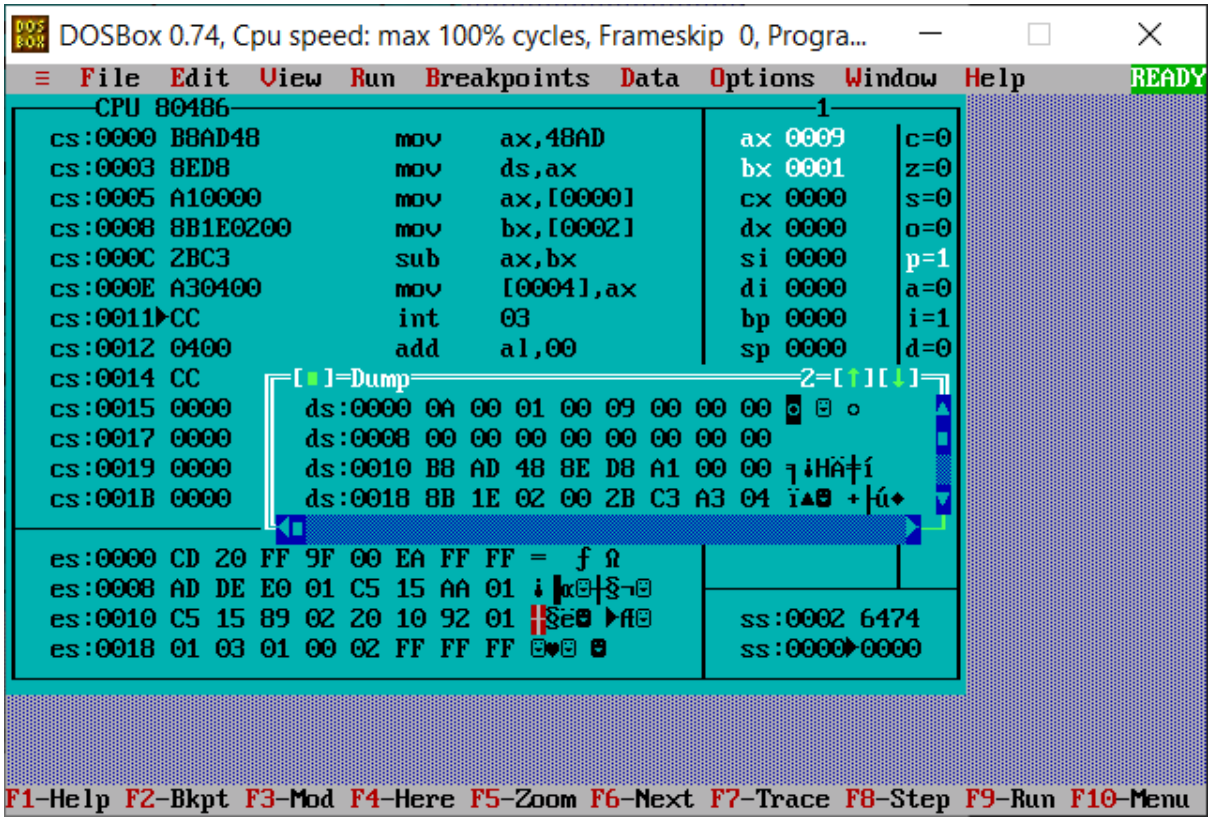
- 16 bit is nothing but 2 bytes
- ax and bx registers are used for storing the numbers
- result is stored in c
- program ends with interrupt 3

Output:

(a) addition



(b) Subtraction



Experiment 2:

Aim:

Assembly program for multiplication and division of 16 bit numbers

ASM code:

Multiplication

```
data segment
    a dw 0fffh
    b dw 0ffffh
    c dd ?
data ends

code segment
assume cs:code, ds:data
start:
    mov ax, data
    mov ds, ax
    mov ax, a
    mov bx, b
    ; Multiplying a and b
    ; mul bx is equivalent to ax = ax * bx
```

```
    ; the extra 16bits are saved in dx registed
    ; the whole 32bit number (=a*b) is dx:ax
    mul bx
    ; Copy the values of the ans dx:ax to c
    lea si,c
    mov [si],ax
    mov [si+2],dx
    int 3h
code ends
end start
```

Division

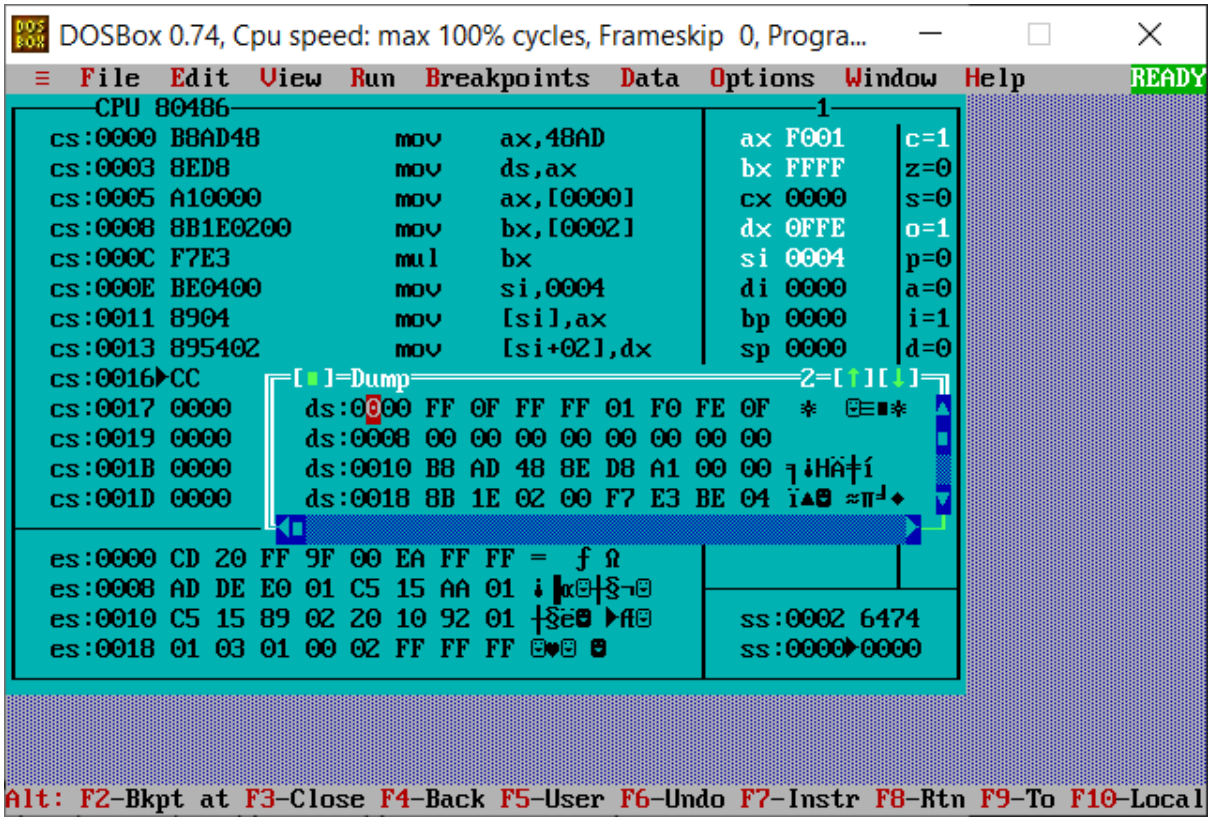
```
data segment
    a dw 0901h
    b dw 0202h
    c dw ?
data ends

code segment
assume cs:code, ds:data
start:
    mov ax, data
    mov ds, ax
    mov ax, a
    mov bx, b
    ; Divding a and b
    ; div bx is equivalent to ax = ax / bx
    div bx
    mov c, ax
    int 3h
code ends
end start
```

Explanation:

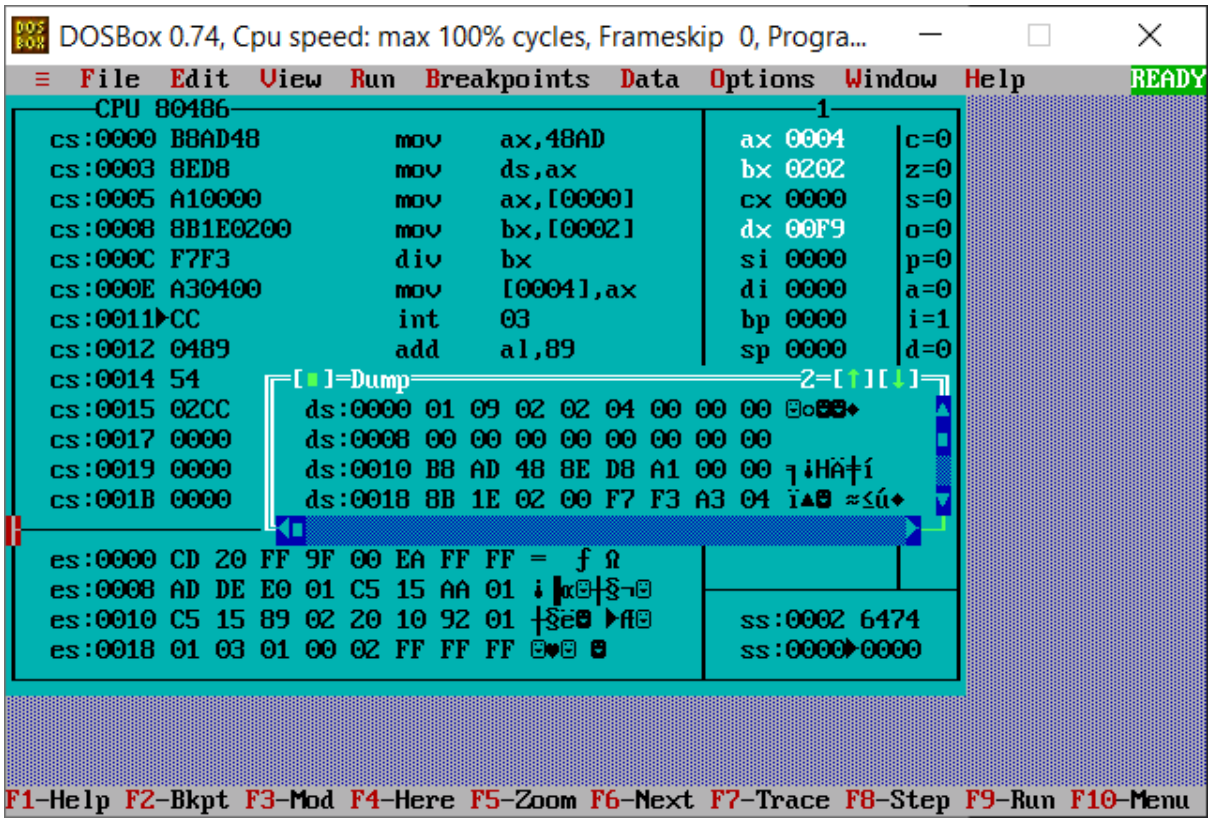
- Process is similar to addition and subtraction
- For multiplication, product is 32 bit number (16 x 2) and is stored in 2 separate registers
- The final answer is dx:ax

Output:

(a) Multiplication


DOSBox 0.74, Cpu speed: max 100% cycles, Frameskip 0, Progra...
File Edit View Run Breakpoints Data Options Window Help READY
CPU 80486
cs:0000 B8AD48 mov ax,48AD
cs:0003 8ED8 mov ds,ax
cs:0005 A10000 mov ax,[0000]
cs:0008 8B1E0200 mov bx,[0002]
cs:000C F7E3 mul bx
cs:000E BE0400 mov si,0004
cs:0011 8904 mov [si],ax
cs:0013 895402 mov [si+02],dx
cs:0016 CC
cs:0017 0000
cs:0019 0000
cs:001B 0000
cs:001D 0000
ax F001 c=1
bx FFFF z=0
cx 0000 s=0
dx 0FFE o=1
si 0004 p=0
di 0000 a=0
bp 0000 i=1
sp 0000 d=0
Dump
ds:0000 FF 0F FF FF 01 F0 FE 0F
ds:0008 00 00 00 00 00 00 00 00
ds:0010 B8 AD 48 8E D8 A1 00 00
ds:0018 8B 1E 02 00 F7 E3 BE 04
es:0000 CD 20 FF 9F 00 EA FF FF
es:0008 AD DE E0 01 C5 15 AA 01
es:0010 C5 15 89 02 20 10 92 01
es:0018 01 03 01 00 02 FF FF FF
ss:0002 6474
ss:0000 0000
Alt: F2-Bkpt at F3-Close F4-Back F5-User F6-Undo F7-Instr F8-Rtn F9-To F10-Local

(b) Division


DOSBox 0.74, Cpu speed: max 100% cycles, Frameskip 0, Progra...
File Edit View Run Breakpoints Data Options Window Help READY
CPU 80486
cs:0000 B8AD48 mov ax,48AD
cs:0003 8ED8 mov ds,ax
cs:0005 A10000 mov ax,[0000]
cs:0008 8B1E0200 mov bx,[0002]
cs:000C F7F3 div bx
cs:000E A30400 mov [0004],ax
cs:0011 CC int 03
cs:0012 0489 add al,89
cs:0014 54
cs:0015 02CC
cs:0017 0000
cs:0019 0000
cs:001B 0000
ax 0004 c=0
bx 0202 z=0
cx 0000 s=0
dx 00F9 o=0
si 0000 p=0
di 0000 a=0
bp 0000 i=1
sp 0000 d=0
Dump
ds:0000 01 09 02 02 04 00 00 00
ds:0008 00 00 00 00 00 00 00 00
ds:0010 B8 AD 48 8E D8 A1 00 00
ds:0018 8B 1E 02 00 F7 F3 A3 04
es:0000 CD 20 FF 9F 00 EA FF FF
es:0008 AD DE E0 01 C5 15 AA 01
es:0010 C5 15 89 02 20 10 92 01
es:0018 01 03 01 00 02 FF FF FF
ss:0002 6474
ss:0000 0000
F1-Help F2-Bkpt F3-Mod F4-Here F5-Zoom F6-Next F7-Trace F8-Step F9-Run F10-Menu

Experiment 3:

Aim:

Sorting numbers in ascending and descending orders (Bubble sort)

ASM code:

```
;106118042 - joel scaria - bubble sort
data segment
  arr db 20h,16h,42h,39h,08h
  len db len-arr
  desc_bit db 00h
data ends

code segment
assume cs:code, ds:data
start:
  mov ax, data
  mov ds, ax

  mov ch, len
  dec ch
OuterLoop:
  mov cl, ch
  lea si, arr


InnerLoop:
  mov al, [si]
  mov bl, [si + 1]
  cmp desc_bit,00h
  je Ascend
  cmp al,bl
  jnc Continue
```

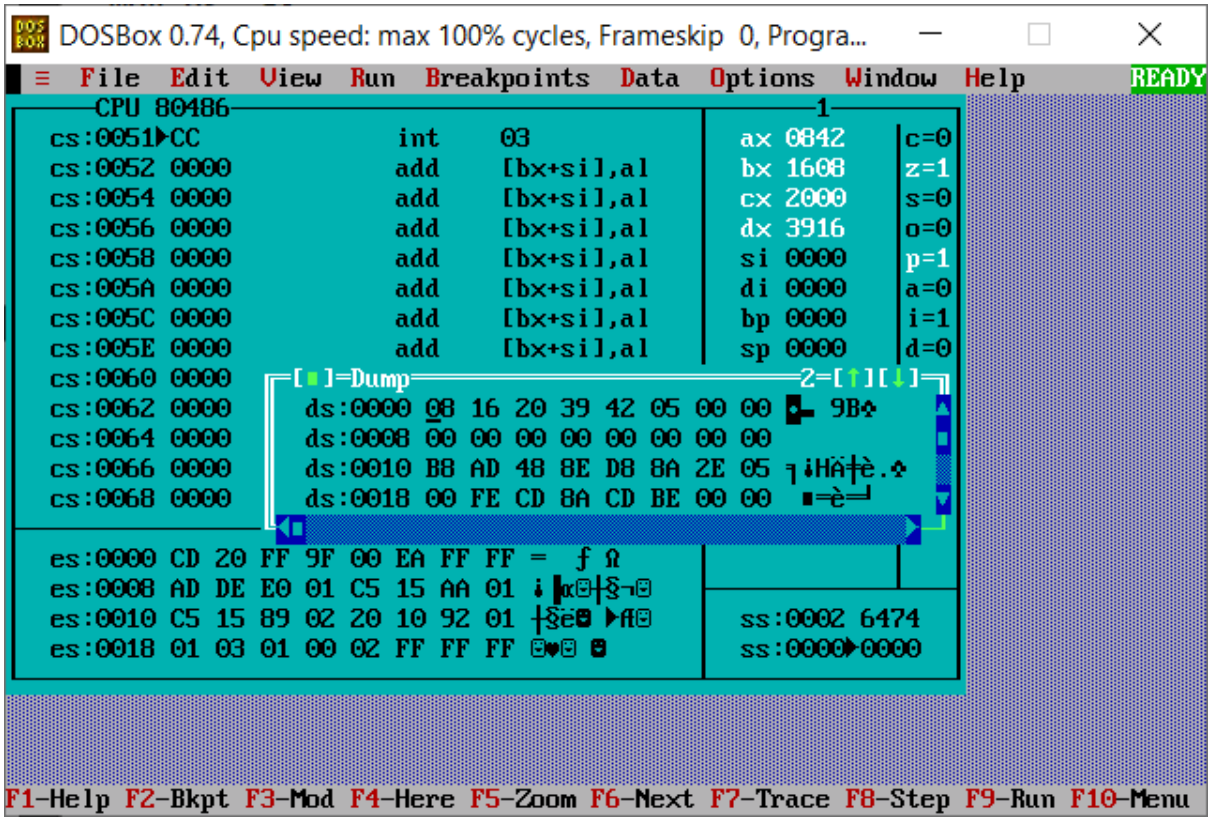
```
  jmp swap

Ascend:
  cmp al,bl
  jc Continue
  jmp swap

Continue:
  inc si
  dec cl
  jnz InnerLoop
  dec ch
  jnz OuterLoop
  jmp stop

swap:
  mov dl, [si + 1]
  xchg [si], dl
  mov [si + 1], dl
  jmp Continue

stop:
  lea si,arr
  ;loading the values in array to view them in data registers
  mov ah,[si]
  mov bh,[si+1]
  mov ch,[si+2]
  mov dh,[si+3]
  mov al,[si+4]
  int 3

code ends
```

```
end start
```

Explanation:

- Input is the 5 numbers , length of array i.e. 5 in this case and a single bit used for determining if sort is in ascending or descending
- 2 loops are used ; innerloop and outerloop (Complexity >> O(n^2))
- Consecutive bits [si] and [si+1] are selected and compared
- If ascending, [si] and [si+1] swapped if [si]>[si+1]
- If descending, [si] and [si+1] swapped if [si]<[si+1]
- Then [si] is incremented by one and process repeated till [si+5]
- Process repeated 5 times

Output:



Experiment 4:

Aim:

Factorial of a number greater than 6

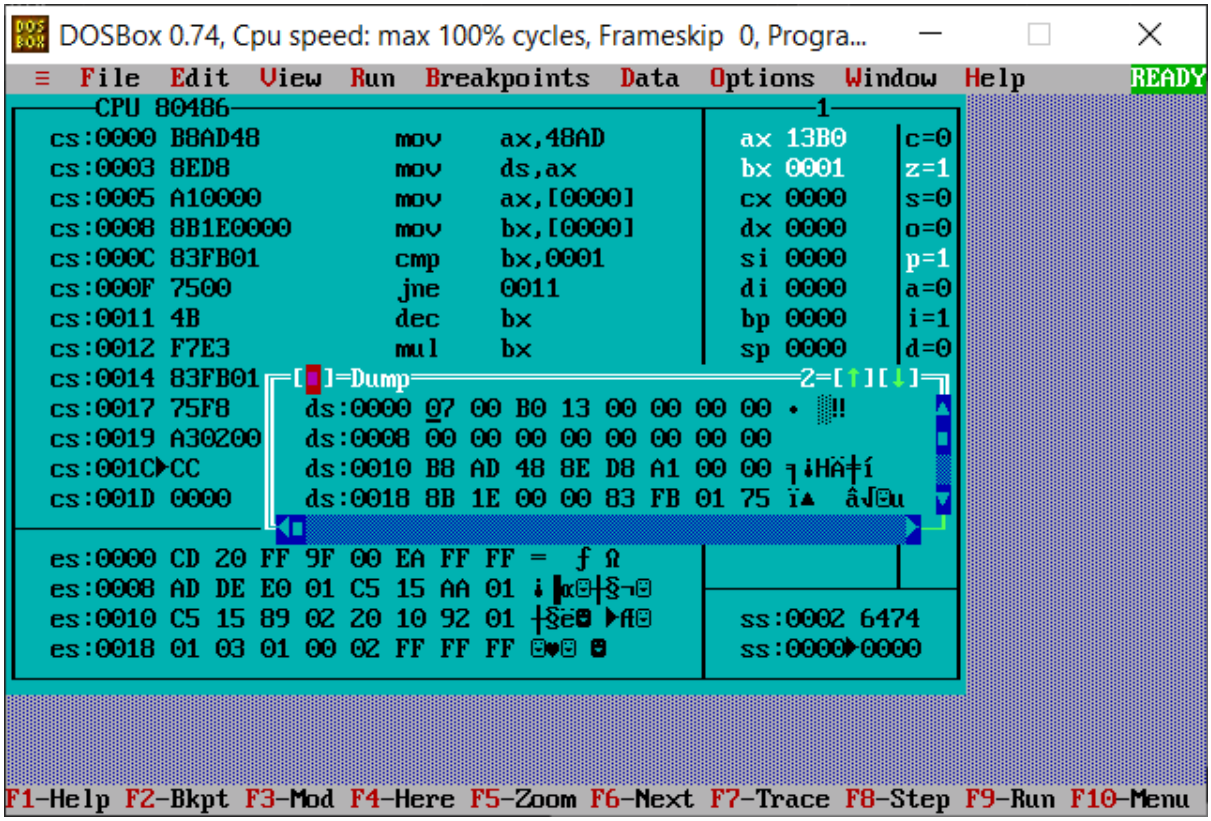
ASM code:

```
; 106118042 Joel Scaria - Factorial
data segment
  a dw 0007h
  b dw ?
data ends

code segment
assume cs:code, ds:data

start:
  mov ax, data
  mov ds, ax

  ; Starting factorial code
  mov ax, a ; Load data
  mov bx, a ; Value of bx decreases by 1 from a to 1

  cmp bx, 01
  jnz factorial
factorial:
  dec bx
  mul bx
  cmp bx, 01
  jnz factorial

  mov b, ax
  int 3

code ends
end start
```

Explanation:

- bx=7
- ax=bx
- bx=bx-1
- ax=ax*bx
- if bx is not 1, go to third step
- else move ax (answer) to b (dump)

Output:



NB: factorial of 7 is 13B0

Experiment 5:

Aim:

Matrix multiplication of two matrices m and n where m!=n

ASM code:

```
; 106118042 - Joel Scaria - Matrix Multiplication

data segment

  ; Declare 3x2 size array

  mat1 db 1h, 2h, 3h, 4h, 5h, 6h


  ; Declare 2x3 size array
```

```
  mat2 db 1h, 1h, 1h, 1h, 1h, 1h

  ; Declare an empty 3x3 size array
  mat3 db 09h dup(?)

  small_a db 3h
  small_b db 2h
  small_c db 3h

  a dw 3h
  b dw 2h
  c dw 3h

data ends

code segment
assume cs:code, ds:data
start:
  mov ax, data
  mov ds, ax

  ; ch register store value of index i
  mov ch, small_a ; = i

  ; offset is the address from the beginning of memory segment where
the variable is stored
  mov bx, offset mat3
  mov si, offset mat1

NextRow:
  ; di represents the index at mat2
  mov di, offset mat2
```

```
  ; Store the value of iterator j in cl
  mov cl, small_c ; j = c

NextCol:
  ; Store the value of iterator k in dl
  mov dl, small_b

  ; Store value of mat[i][j] in bp
  mov bp, 0h

NextElement:
  mov ax, 0h
  mov al, [si]
  mul byte ptr[di]
  add bp, ax
  inc si ; Go to next element in same row for mat1
  add di, c ; Go to next element in same col for mat2

  dec dl ; --k
  ; Continue iterating k from (b to 1)
  jnz NextElement

  ; Here k = 0
  ; Copy calculated value to mat3
  mov [bx], bp

  ; start again from beginning of current row
  sub si, b

  ; Go to beginning of next column
  mov ax, a
```

```
  mul b
  dec ax
  sub di, ax

  ; increment mat3
  inc bx

  ; one less column to traverse
  dec cl ; --j

  cmp cl, 0
  jnz NextCol

  ; End of loop having iterator j
  ; Go to beginning of next row
  add si, b

  ; one less row to traverse
  dec ch; --i

  cmp ch, 0
  jnz NextRow

  ; End of iterator i
  int 3 ; breakpoint

code ends
end start
```

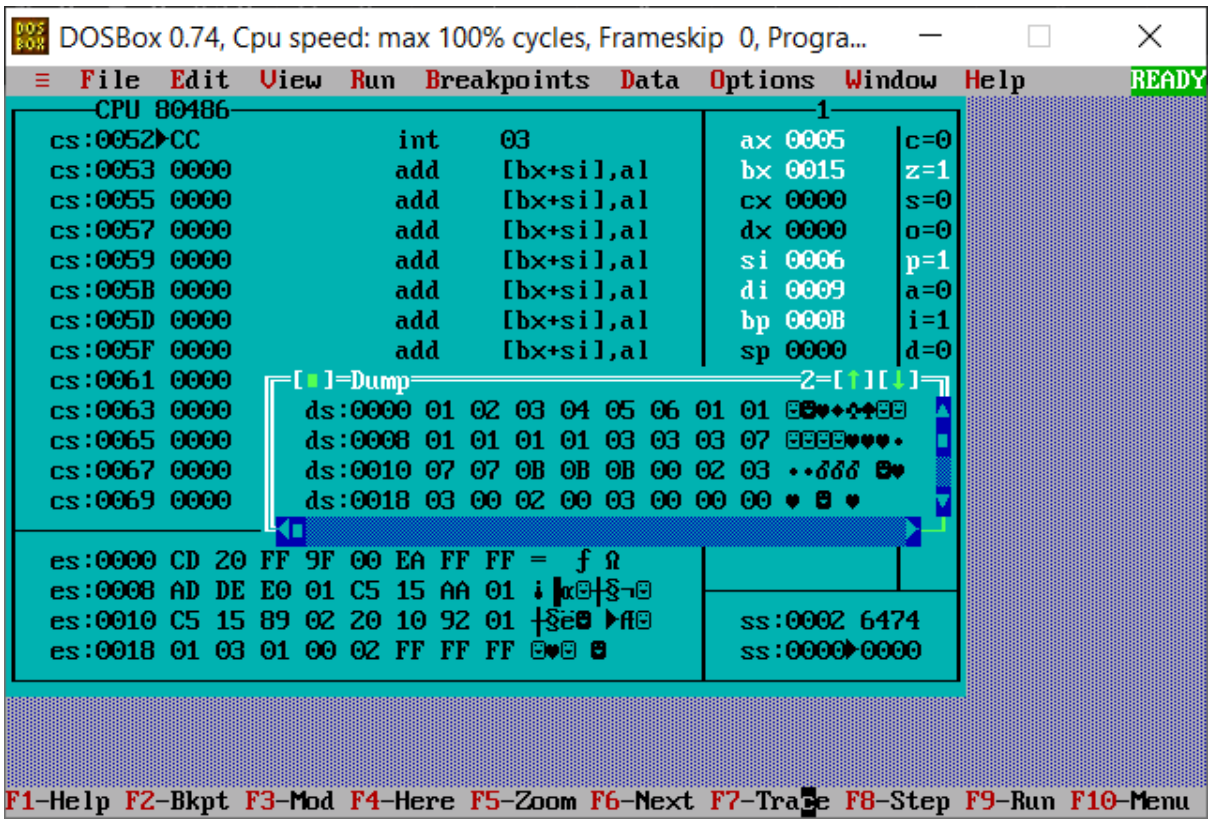
Explanation:

- mat1
  1 2
  3 4

5 6

- mat2
  1 1 1
  1 1 1
- [si]=mat1
- [bx]=new empty 3x3 matrix
  a=3,b=2,c=3
  ch=3 (no of rows in mat1)
- Outer loop:
  [di]=mat2
  cl=3 (no of columns in mat2)
- Inner loop:
  dl=2
  bp=0(initial value of cell in new matrix)
- Innermost loop:
  ax=0
  al=si
  ax=ax*[di]
  bp=bp+ax
  si=si+1(goes to next element in same row in mat1)
  [di]=[di]+c(goes to next element in same column in mat2.here c=3)
  dl=dl-1
  Go to Innermost loop again if dl is not 0 else continue
- [bx]=bp(save value to new mat variable)
  [si]=[si]-b (restart current row of mat1 for next element)
  [di]=[di]-((a*b)-1) (move to next column of mat2 for next element)
  [bx]=[bx+1] (new element is to be stored in [bx+1]
  cl=cl-1 (one less column to be traversed)
  Go to Inner loop again if cl is not zero else continue
- [si]=[si]+b (move to first element of next row for mat1)
  ch=ch-1 (one less row to be traversed)
  Go to Outer loop again if ch is not zero else continue
- program ends

Output:



Experiment 6:

Aim:

Matrix subtraction of 2 matrices m and n where m!=n

ASM code:

```
;106118042 - joel scaria - matrix subtraction
data segment

  ; 3x2 matrices mat1 and mat2

  mat1 dw 1h, 2h, 3h, 4h, 5h, 6h

  mat2 dw 1h, 1h, 1h, 1h, 1h, 1h

  a dw 3h
  b dw 2h
```

```
data ends

code segment
assume cs:code, ds:data
start:
    mov ax, data
    mov ds, ax

    mov ax, a
    mul b

    mov cx, ax
    lea si, mat1
    lea di, mat2

Loop_i:
    mov ax, [si]
    mov bx, [di]
    sub ax, bx

    mov [si], ax
    add si, 2h
    add di, 2h
    sub cx, 0001h

    cmp cx, 0
    jnz Loop_i

    lea si,mat1
    mov ah,[si]
    mov al,[si+2]
```

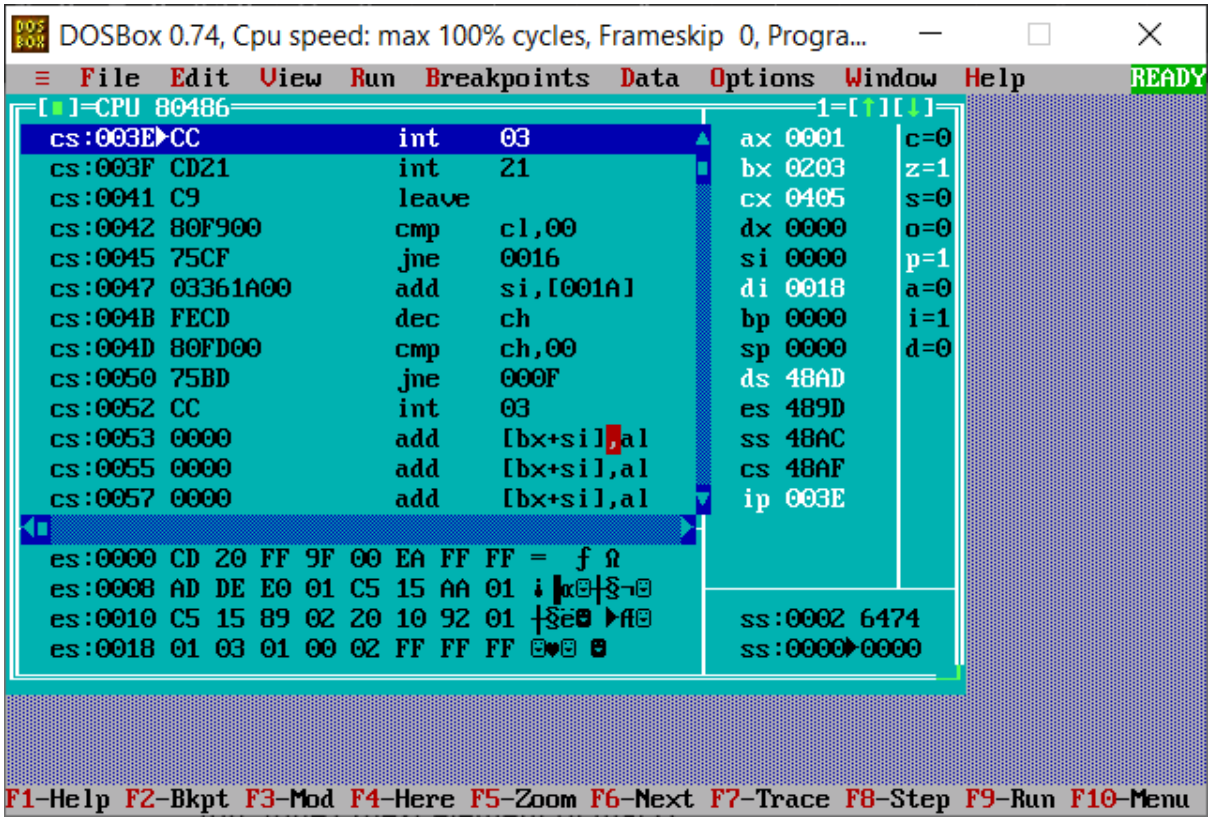
```
    mov bh,[si+4]
    mov bl,[si+6]
    mov ch,[si+8]
    mov cl,[si+10]

    int 3

    int 21h
code ends
end start
```

Explanation:

- mat1= 1 2
  3 4
  5 6
- mat2= 1 1
  1 1
  1 1
- required output =mat1-mat2= 0 1
  2 3
  4 5
- a=3 (no of rows) b=2 (no of columns)
- cx=3*2=6 (total no of subtractions)
- [si]=mat1, [di]=mat2
- Loop:
  ax=[si]
  bx=[di]
  ax=ax-bx
  [si]=ax (output will be in [si])
  [si]=[si]+1 (next element of mat1)
  [di]=[di]+1 (next element of mat2)
  cx=cx-1 (one less subtraction to go)
  Go to Loop if cx is not zero else continue
- program ends

Output:

NB: Output matrix is displayed using ax,bx and cx registers



Experiment 7:

Aim:

Generate Fibonacci series

ASM code:

```
; Program for calculating n'th fibonacci number
; 106118042 - Joel Scaria


data segment
    n dw 8h
data ends


code segment
assume cs:code, ds:data
start:
```

```
  mov ax, data
  mov ds, ax

  mov bx, 0
  mov cx, 1

  ; Initialize iterator
  mov dx, n
  mov ax, 0
  cmp dx, 1
  jz end_i
  mov ax, 1
  cmp dx, 2
  jz end_i
  sub dx, 2

Loop_i:
  ; This loop runs untill dx is 0
  mov ax, 0
  add ax, bx
  add ax, cx

  ; Update values
  mov bx, cx
  mov cx, ax

  dec dx
  cmp dx, 0
  jnz Loop_i

end_i:
  int 3
```

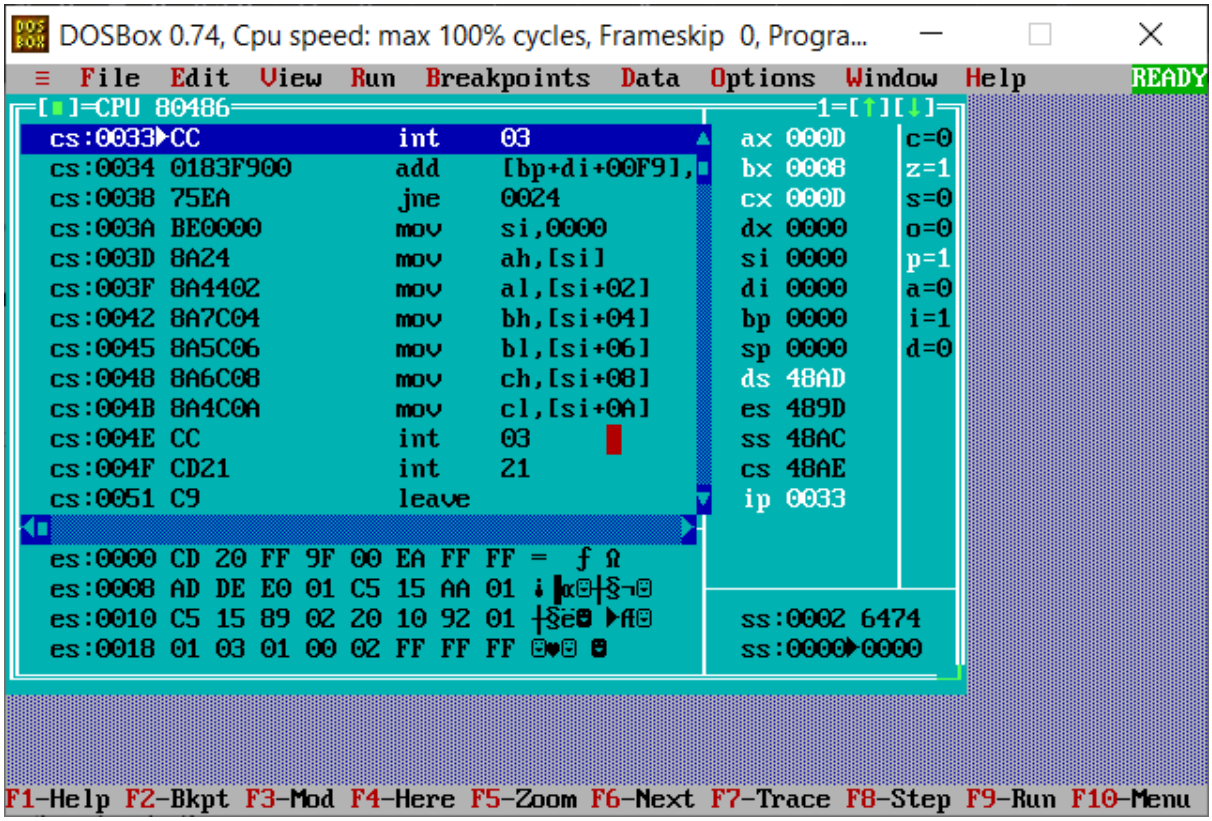
```
code ends
end start
```

Explanation:

- input = 8
- required output = 8th Fibonacci number = D (13 in decimal)
- let bx=0, cx=1, dx=8
- ax=0
- if dx is 1, end program else continue
- ax=1
- if dx is 2, end program else continue
- dx=dx-2
- Loop:
    - ax=0
    - ax=ax+bx
    - ax=ax+cx (so finally, ax=ax+(bx+cx))
    - bx=cx(swapping 2nd last element)
    - cx=ax(swapping last element)
    - dx=dx-1 (loop runs till dx=0 i.e. 8 times in total)
    - Go to Loop again if dx is not 0 else continue
- program ends

Output:

NB: Output is in ax register



Experiment 8:

Aim:

(a) Binary to grey conversion
(b) decimal to hexadecimal conversion

ASM code:

Binary to grey

```
; 106118042 JOEL SCARIA binary to grey
data segment
      opr db 2Ch
      ; 0010 1100 -> 2C
      ; 0001 0110 (after right shift)
      ; 0011 1010 -> 3A (output)
      res db ?
data ends

code segment
assume cs:code,ds:data
```

```
start:

      mov ax,data
      mov ds,ax
      mov al,opr
      mov bl,al
      shr al,01h
      xor al,bl
      mov res,al
      int 3
code ends
end start
```

decimal to hexadecimal

```
; 106118042 JOEL SCARIA decimal to hexadecimal
data segment
      a db 19h
      ; 19 -> 25
      ; 0001 1001
      ; 13
      b db ?
data ends
code segment
assume cs:code,ds:data
start:
      mov ax,data
      mov ds,ax
      mov bl,a
      and bl,0fh
      mov al,a
      mov dx,00f0h
      and al,dl
      mov cl,04h
      ror al,cl
      mov dl,0ah
      mul dl
      add al,bl
      mov b,al
      int 3
code ends
end start
```

Explanation:

(a) binary to grey

- input opr= 2C

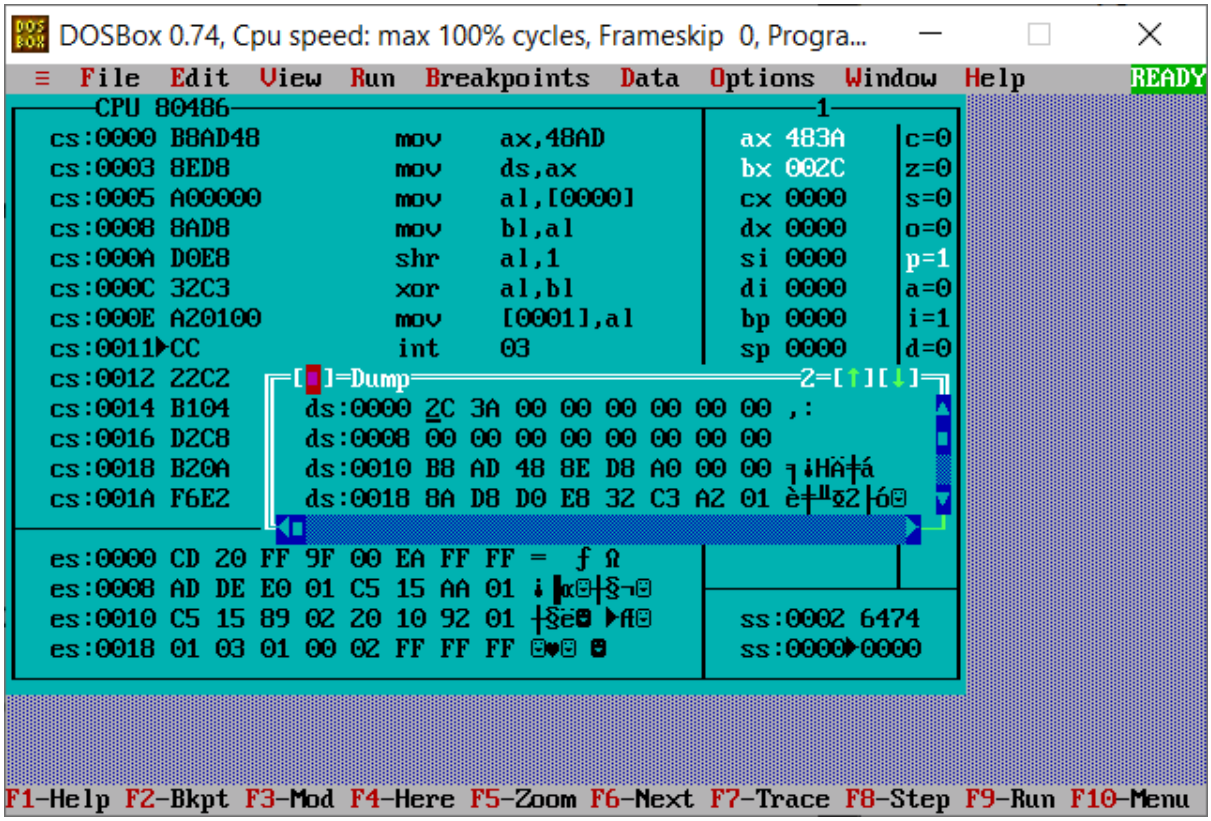
- required output = 3A
- al=bl=opr
- shift al to the right by 1 bit
- xor bl and new al which is obtained after shifting
- store result i.e. grey code in res
- program ends

(b) decimal to hexadecimal

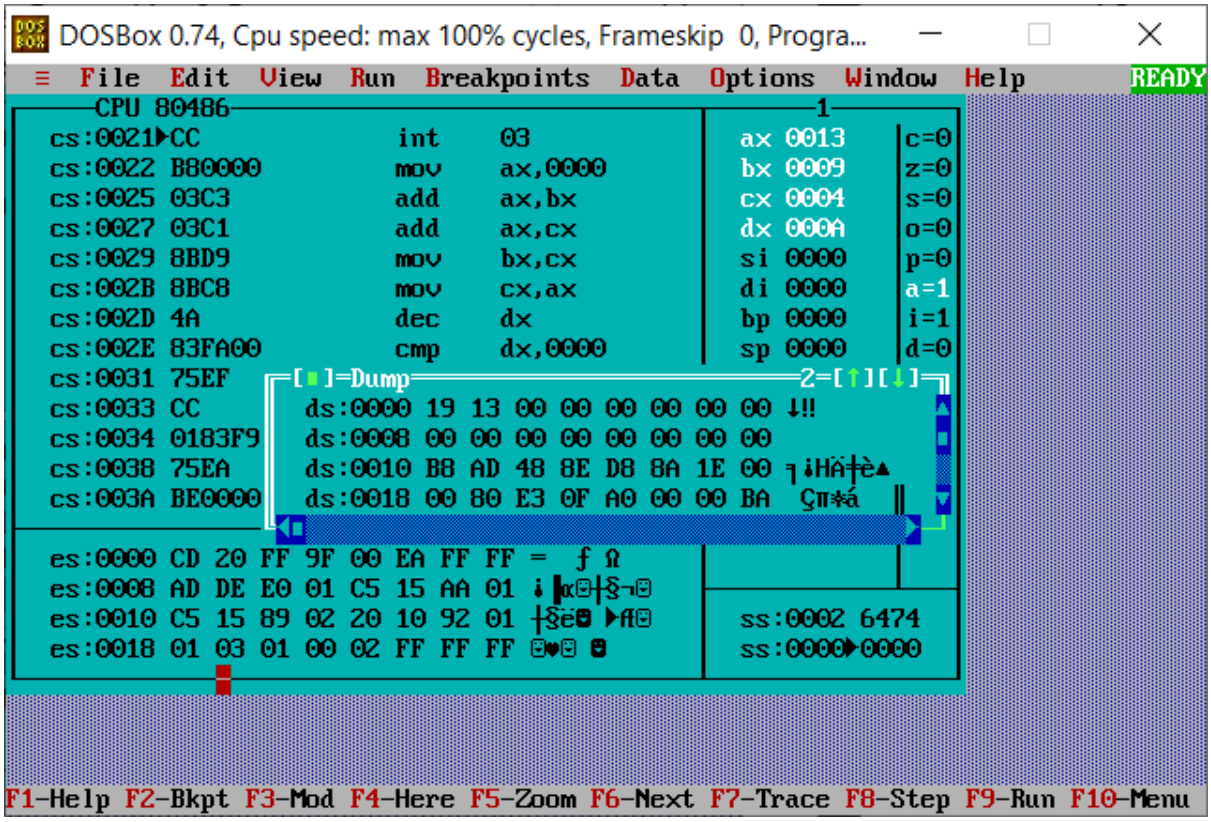
- input= a = 19
- required output = 13
- bl=a
- bl= bl & 0fh=0001 1001 & 0000 1111= 0000 1001 = 9
- al=a
- al=al & 0f0h=0001 1001 & 1111 0000= 0001 0000= 10
- shift al to the right by 4 bits -> al = 0000 0001=1
- al= al*Ah=1*Ah=A
- al=al+bl=Ah + 9h=13h
- store output al into b (dump)
- program ends

Output:

(a) Binary to grey



(b) decimal to hexadecimal



Experiment 9:

Aim:

Compute nCr using recursive procedure

ASM code:

```
; 106118042 | Joel Scaria | tasm program for finding nCr (n<=8)


data segment
  n dw ?
  r dw ?
  str_n db 'Enter n: $'
  str_r db 'Enter r: $'
  str_ans db 'Answer: $'
data ends
```

```
code segment
assume cs:code, ds:data

start:
  mov ax, data
  mov ds, ax

  call PrintNextLine
  mov ah, 09h
  lea dx, str_n
  int 21h
  call ReadNumber
  mov n, bx

  call PrintNextLine
  mov ah, 09h
  lea dx, str_r
  int 21h
  call ReadNumber
  mov r, bx

  mov bx, n
  call Factorial
  push bx ; Save n! to stack

  mov bx, r
  call Factorial
  push bx ; Save r! to stack

  mov bx, n
  sub bx, r
  call Factorial
```

```
  push bx ; Save (n-r)! to stack

  pop cx
  pop bx
  pop ax
  div bx
  div cx
  aam
  mov bx, ax
  call PrintNextLine
  mov ah, 09h
  lea dx, str_ans
  int 21h

  ; Print the number

  call PrintBx



  ;to terminate the program
  mov ah, 1
  int 21h
  mov ah, 4ch
  int 21h

Factorial proc
  push ax
  mov ax, 1
  call FactorialHelper
  mov bx, ax
  pop ax
  ret
```

```
Factorial endp


FactorialHelper proc
  cmp bx, 1
  jle FactorialHelperResult
  mul bx
  sub bx, 1
  call FactorialHelper
FactorialHelperResult:
  ret
endp

; Procedure to input a number and save to bx register
ReadNumber proc
    ; Save values of ax, cx & dx registers
    push ax
    push cx
    push dx

    ; Make bx = 0
    mov bx, 0h
LoopReadNumber:
    xor ax, ax ; ax = 0

    ; Read a character in al register
    mov ah, 1
    int 21h ; Using DOS API to take input

    ; Check if the input digit is [0-9]
    cmp al, '0'
    jb BreakReadNumber
```

```
    cmp al, '9'
    ja BreakReadNumber


    sub al, 30h
    cbw ; byte to word
    ;cwd  word to dword

    ; Make bx = (bx * 10) + ax
    push ax
    mov ax, bx
    mov cx, 10
    mul cx ; ax = ax * 10
    mov bx, ax
    pop ax
    add bx, ax
    jmp LoopReadNumber

BreakReadNumber:
    pop dx
    pop cx
    pop ax
    ret
ReadNumber endp

; Prints newline
PrintNextLine proc
    push ax
    push dx

    mov dl, 10
    mov ah, 02h
```

```
    int 21h
    mov dl, 13
    mov ah, 02h
    int 21h

    pop dx
    pop ax
    ret
PrintNextLine endp

; Print number
PrintBx proc
    add bx, 3030h
    mov dl, bh
    ;add dl, 30h
    mov ah, 02h
    int 21h
    mov dl, bl
    ;add dl, 30h
    mov ah, 02h
    int 21h
    ret
PrintBx endp

code ends
end start
```

Explanation:

- Input and output done using interrupts
- Input:
    - bx=0
    - LoopReadNumber:
        - ax=0
        - accept single character from user using interrupt and store in al

if al is not digit, stop Input else continue
al=al-30h(convert ascii to number)
bx=bx*10 + ax (where bx= 10s place and ax= unit place)
Go to LoopReadNumber (Loop continues till user enters non-digit)

- Using Input, n and r obtained from user
- Factorial:

assume we need n!
bx=n
ax=1
Factorial helper:
if bx=1, stop factorial else continue
ax=ax*bx
bx=bx-1
Go to Factorial helper

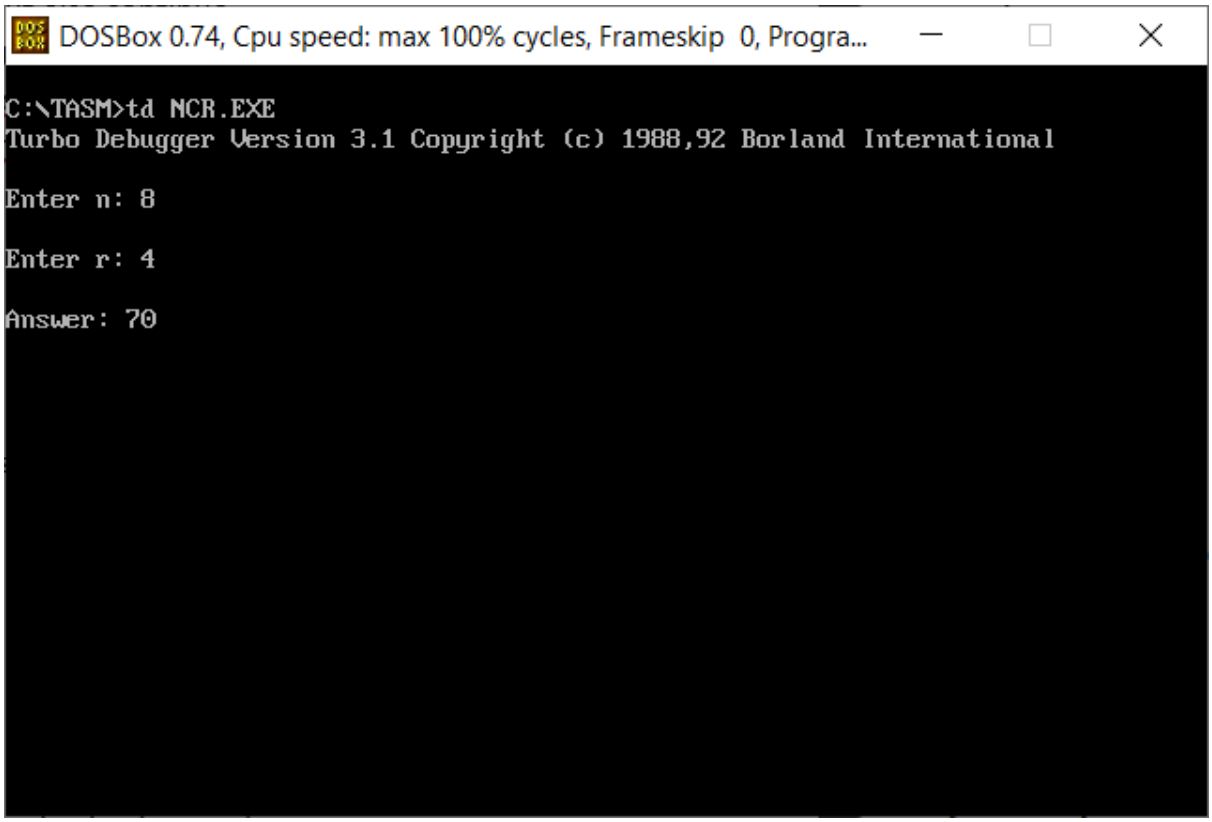
NB : n! present in ax

- ax=factorial(n)/factorial(r)*factorial(n-r)
- bx=ax
- Print:

bx=bx+3030h(converting number back into ascii)
output bl and bh separately using interrupts

- Print(bx)
- program ends

Output:



Experiment 10:

Aim:

check if string is palindrome or not

ASM code:

```
; 106118042 - JOEL SCARIA - Tasm pgm for palindrome check


data segment
    str_inp db 'Enter string: $'
    str_success db 'OK - Input is palindrome$'
    str_fail db 'FAIL - Input is not palindrome$'
    new db '$'
    s db 20 dup(0)
data ends
```

```
code segment
assume cs:code,ds:data

start:
    mov ax,data
    mov ds,ax

    lea dx, str_inp
    mov ah, 09h
    int 21h

    call ReadString

    call CheckPalidrome

    mov ah, 01h
    int 21h

    mov ah, 4ch
    int 21h


ReadString proc
    push ax
    mov bx, 00

ReadStringTakeMore:
    mov ah, 01h
    int 21h
    cmp al, 0dh
    je ReadStringDone
    mov [s+bx], al
```

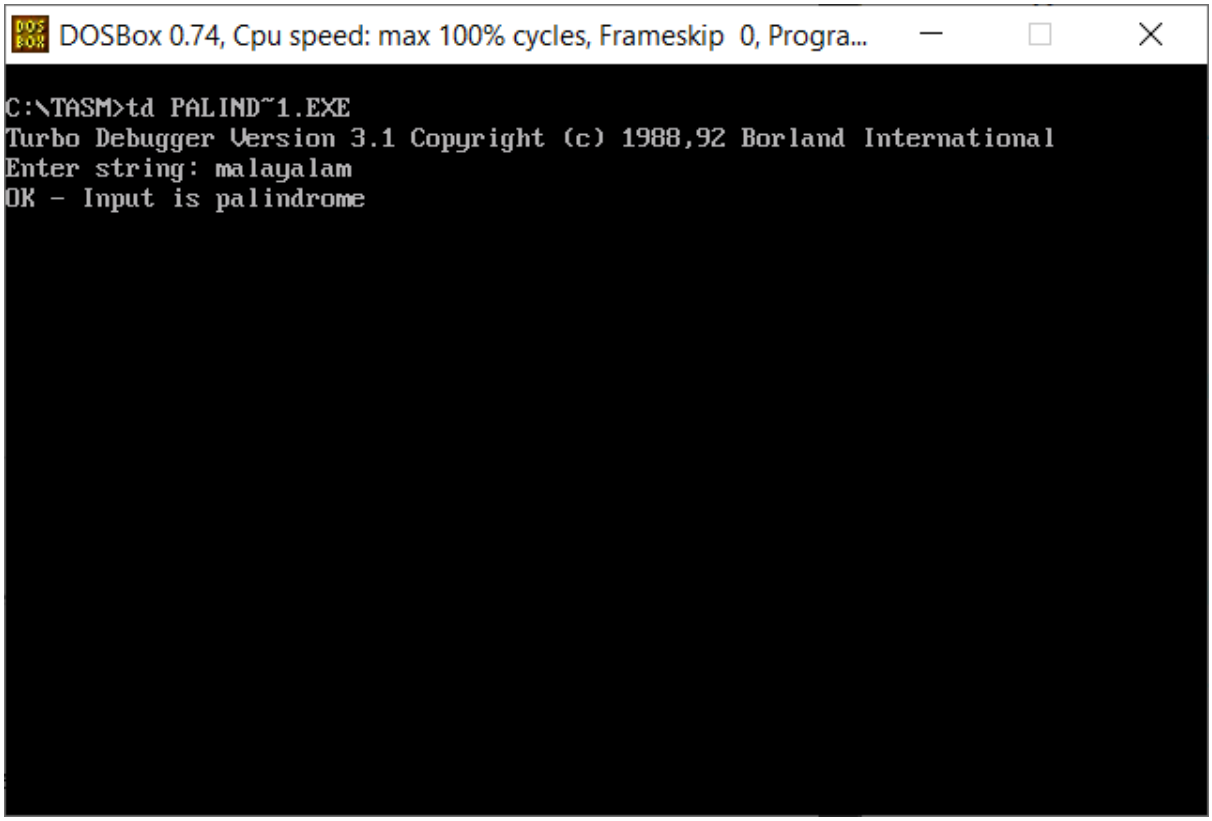
```
    inc bx
    loop ReadStringTakeMore

ReadStringDone:
    pop ax
    ret

ReadString endp


CheckPalidrome proc
    push di
    mov di, 0
    dec bx

CheckPalidromeChar:
    mov al, [s+bx]
    cmp al, [s+di]
    jne CheckPalidromeFail
    inc di
    dec bx
    jnz CheckPalidromeChar

    lea dx, str_success
    mov ah, 09h
    int 21h
    jmp CheckPalidromeEnd

CheckPalidromeFail:
    lea dx, str_fail
    mov ah,09h
    int 21h
```

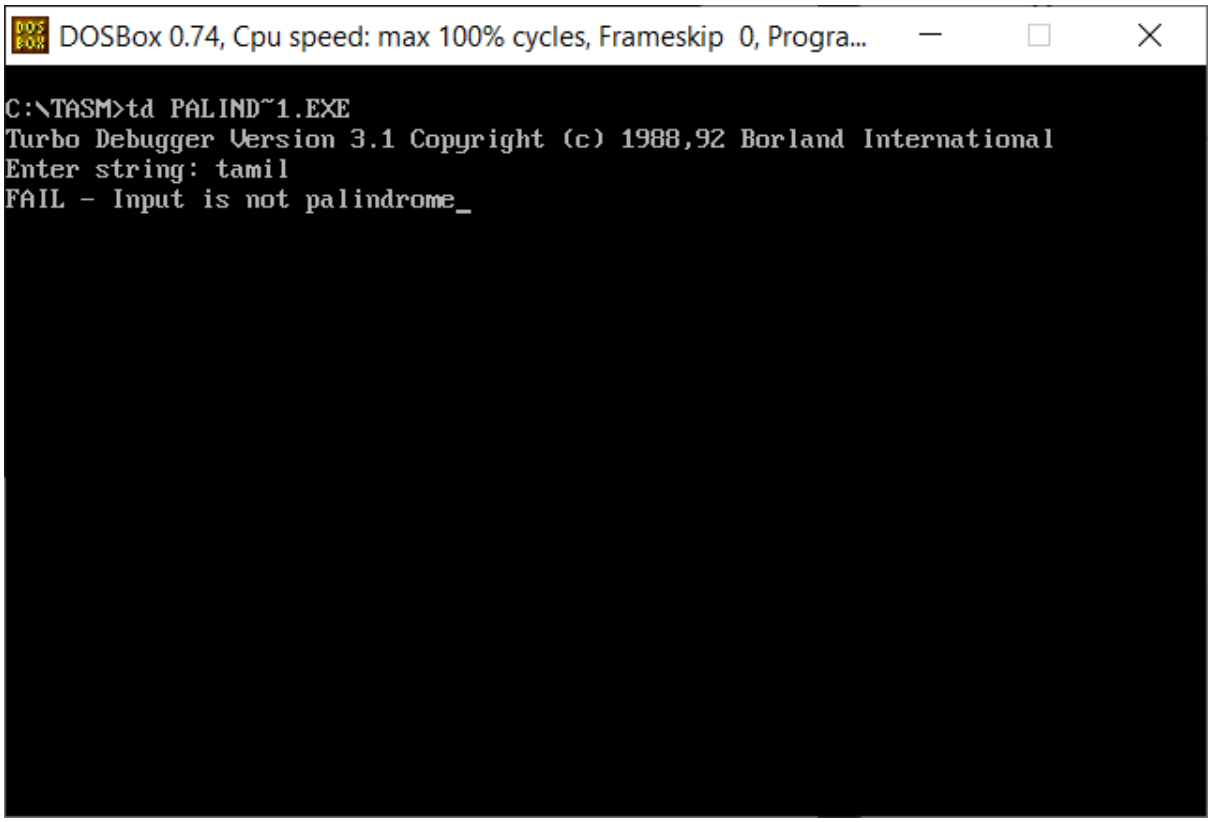
```
CheckPalidromeEnd:
    pop di
    ret

CheckPalidrome endp

code ends
end start
```

Explanation:

- bx=0
- We will be storing the input string in [s]
- Input:
  Input single character from user using interrupt and store in al
  [s+bx]=al
  bx=bx+1(finally bx will be equal to length of string)
  Go to input if al!=0dh (user enters new line) else continue
- di=0
- Palindrome:
  al=[s+bx]
  if al!=[s+di], not palindrome else continue
  di=di+1
  bx=bx-1
  Repeat Palindrome till di=length of string and bx=0
- Output corresponding string using interrupt
- program ends

Output:


DOSBox 0.74, Cpu speed: max 100% cycles, Frameskip 0, Progra...
C:\TASM>td PALIND~1.EXE
Turbo Debugger Version 3.1 Copyright (c) 1988,92 Borland International
Enter string: malayalam
OK - Input is palindrome


DOSBox 0.74, Cpu speed: max 100% cycles, Frameskip 0, Progra...
C:\TASM>td PALIND~1.EXE
Turbo Debugger Version 3.1 Copyright (c) 1988,92 Borland International
Enter string: tamil
FAIL - Input is not palindrome_

Experiment 11:

Aim:

Proteus experiment for Unipolar stepper motor running in full drive mode

ASM code for 8051 micro controller:

```
ORG 00H
      MAIN: MOV A, #09H
      MOV P2, A
      ACALL DELAY
      MOV A,#0CH
      MOV P2, A
      ACALL DELAY
      MOV A,#06H
      MOV P2, A
      ACALL DELAY
      MOV A, #03H
      MOV P2, A
      ACALL DELAY
      SJMP MAIN
      DELAY:  MOV R3,   #08H
      DELAY1: MOV R2,   #0FFH
      DELAY2: MOV R1,   #0FFH
      BASE: DJNZ R1, BASE
      DJNZ R2, DELAY2
      DJNZ R3, DELAY1
      RET
      END
```

Explanation:

- Stepper motor is a synchronous DC motor in which rotation is divided into steps
- The angle covered in each step is called stepper angle
- Stepper motor is divided into mainly 2 types depending on the type of winding:
  - Unipolar
  - Bipolar

- Unipolar stepper motors are again divided into mainly 3 execution modes:
  - Wave drive
  - Full drive
  - Half drive
- I have selected Full drive for my experiment
- In this mode two electromagnets are energized at a time, so the torque generated will be larger when compared to Wave Drive. This drive is commonly used than others. Power consumption will be higher than other modes.
- In my asm code, 1st I have given 09h which is nothing but 1001 in binary form
- The 1st and last bits are 1 which represents consecutive energised electromagnets of the stepper motor
- In next step, 0Ch is sent which is nothing but 1100.Here also we can see that another pair of consecutive electromagnets have been energised.
- Similarly, 0Ch is followed by 06h(0110) and 03h(0011)
- The 1s represent energised electromagnets and 0s represent non-energised ones
- When 2 consecutive magnets are energised, polarity will be in 45 degrees in between them
- For given setup, stepper angle = +90 degrees
- Delay is created by executing large number of empty loops(8*256*256)

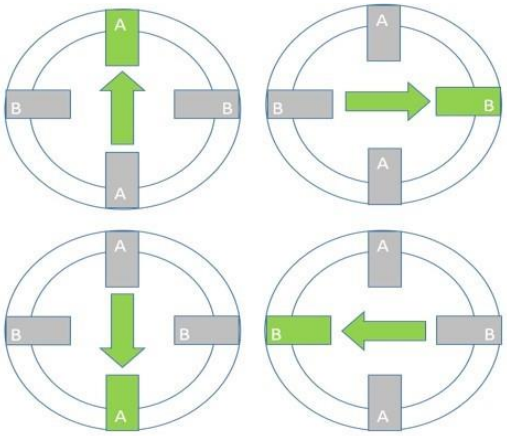


Fig 1 – One phase on – full step

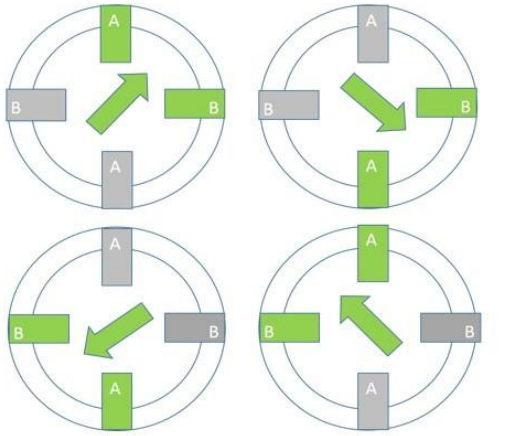


Fig2 – Two phase on – full step

The above image shows accurate diagram of wave drive (left) and full drive (right) execution modes.

Output:

C:\Users\joels\Desktop\mpmcLabFinalProject\test.uvproj - µVision

File Edit View Project Flash Debug Peripherals Tools SVCS Window Help

Target 1

Project

Project: test
Target 1
Source Group 1
test.a51

test.a51

```
1  ORG 00H
2      MAIN: MOV A, #09H
3      MOV P2, A
4      ACALL DELAY
5      MOV A,#0CH
6      MOV P2, A
7      ACALL DELAY
8      MOV A,#06H
9      MOV P2, A
10     ACALL DELAY
11     MOV A, #03H
12     MOV P2, A
13     ACALL DELAY
14     SJMP MAIN
15     DELAY:  MOV R3,   #08H
16     DELAY1: MOV R2,   #0FFH
17     DELAY2: MOV R1,   #0FFH
18     BASE: DJNZ R1, BASE
19     DJNZ R2, DELAY2
20     DJNZ R3, DELAY1
21     RET
22     END
23
```

Build Output

```
Program Size: data=8.0 xdata=0 code=39
creating hex file from ".\Objects\test"...
".\Objects\test" - 0 Error(s), 0 Warning(s).
Build Time Elapsed:  00:00:03
```

Simulation L:15 C:5 CAP NUM SCRL OVR R/W

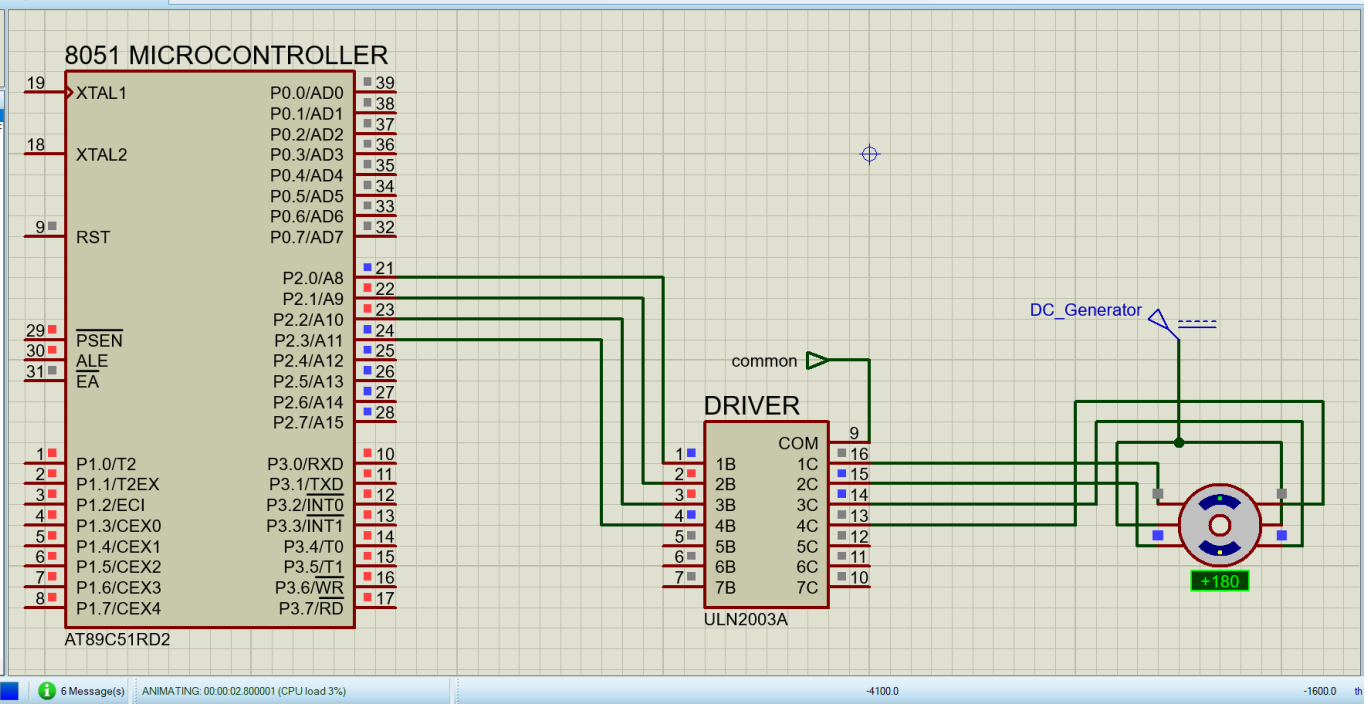
proteusTest - Proteus 8 Professional - Schematic Capture

File Edit View Tool Design Graph Debug Library Template System Help

Base Design

Home Page | Schematic Capture

DEVICES
AT89C51RD2
MOTOR-STEPPEF
ULN2003A



6 Message(s) ANIMATING: 00:00:02.800001 (CPU load 3%) -4100.0 -1600.0

THANK YOU !!