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Overview of the course



Mechanical Engineering Department

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Electronics and Communication Engineering Department

Course Coordinator

Dr. Poonam Verma

Assistant Professor

Electronics and Communication Engineering Department



ENGINEERING DESIGN PROJECT-I UTA016

Lecture - 4

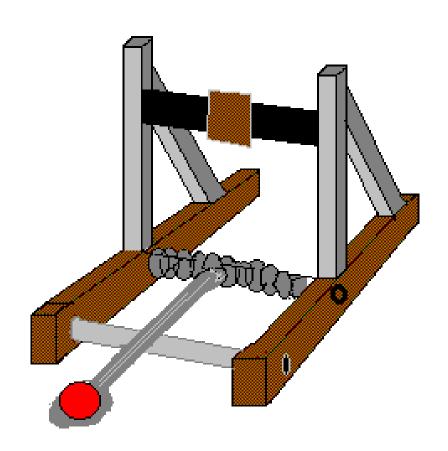
Dynamics of Mangonel

Instructional objective



- Failure of Materials
- Different forces
- >Static stress analysis
- > Dynamic stress analysis







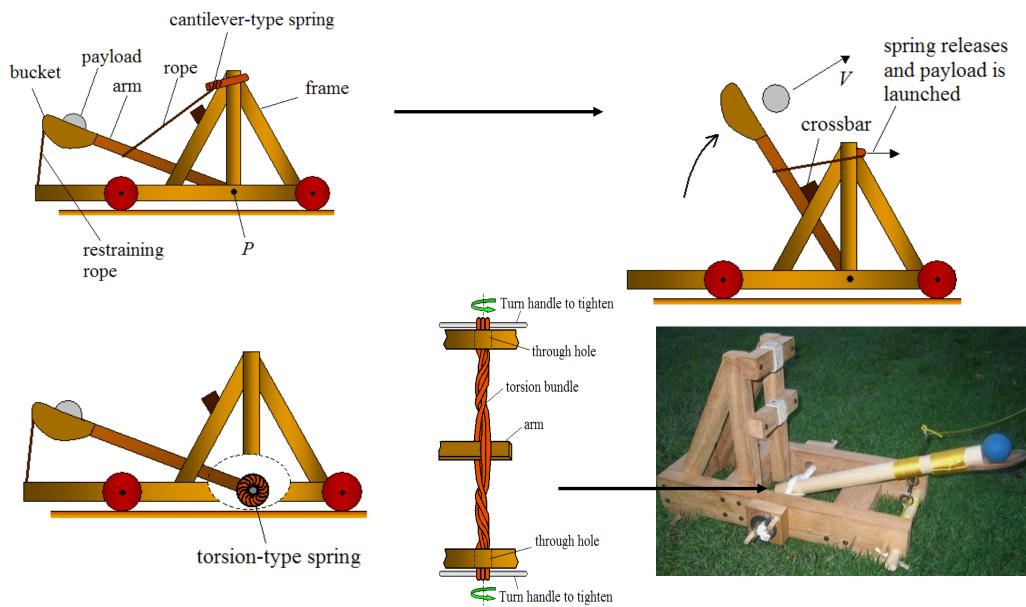








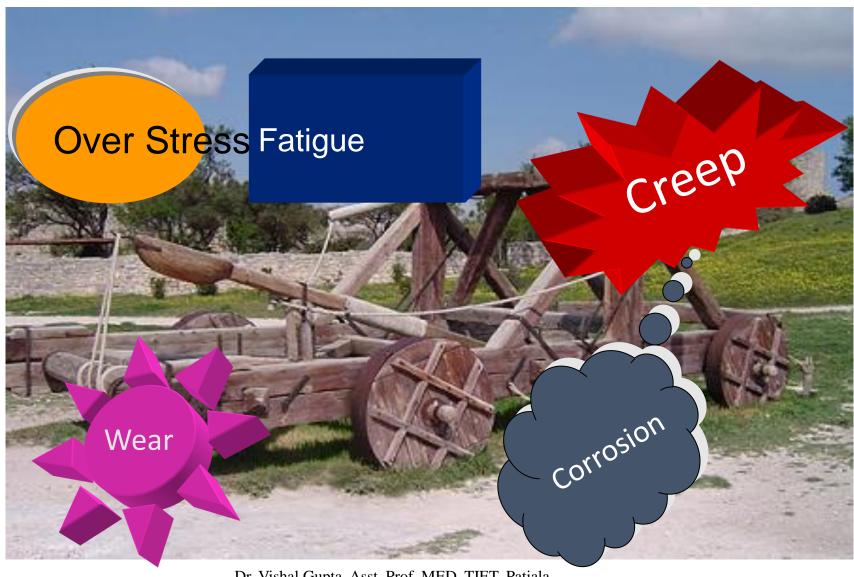




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Failure of Materials



Different forces



Static Force- Load is applied slowly (Time required for application of load is less than the time period of natural frequency)

Dynamic Force (Time varying)

Gradually applied load

- People walking on floor
- Vehicles on road

Suddenly applied load without velocity (Force Impact)

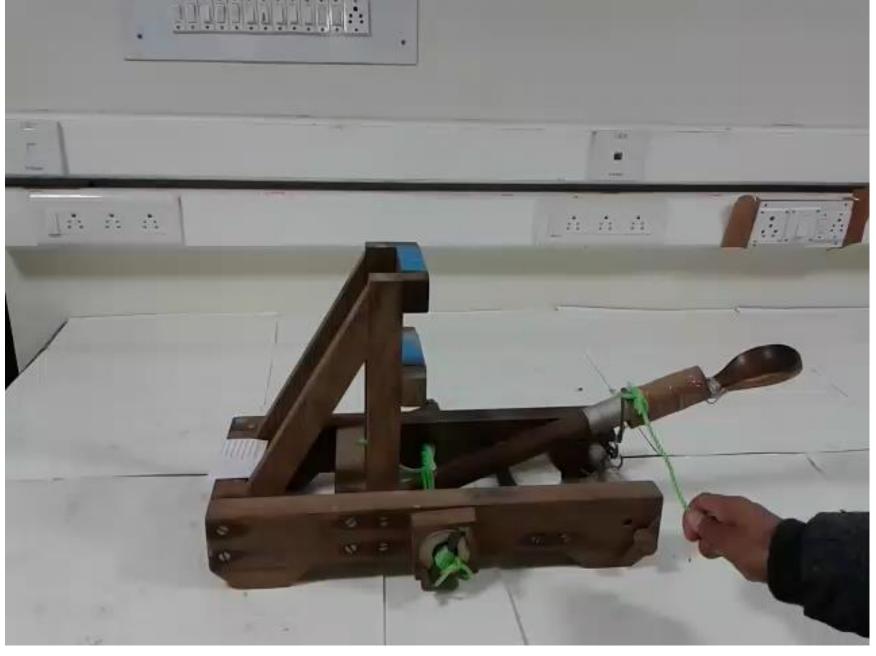
- Clutch, brake
- A person slowly sitting on a chair
- Placing a television on a table.
- Placing a bundle of books on a table

Suddenly applied load with velocity (Striking Impact)

- Piston of IC engine
- Crashing between two cars
- hammering is another example of impact load
- Striking ball with the bat is impact load
- Falling of an object from the hand and striking the

foot is impact load.





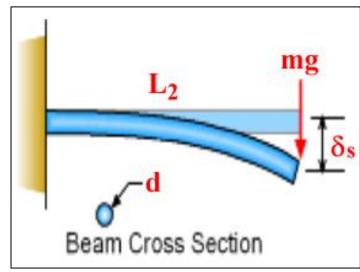
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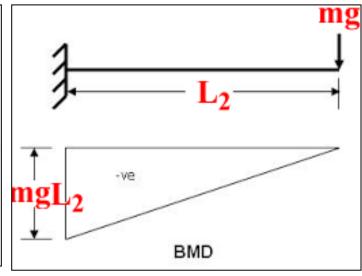
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Static stress analysis L2









$$m = m_{\text{ball}} + m_{\text{spoon}} + m_{\text{beam}}$$

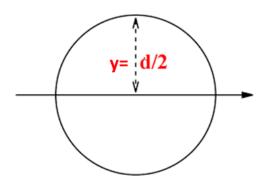
$$m_{\text{beam}} = \frac{\pi d^2}{4} L_2 \rho$$

 $\frac{\sigma_{\rm S}}{\rm v} = \frac{M}{I} \quad \Rightarrow \sigma_{\rm S} = \frac{My}{I} \quad \Rightarrow \sigma_{\rm S} = \frac{(mgL_2)(d/2)}{(\pi d^4/64)} \Rightarrow \sigma_{\rm S} = \frac{4\rho gL_2^2}{d}$

Neglecting mass of ball and spoon

For Mehogany wood, $\rho = 700 \text{ kg/m}^3$





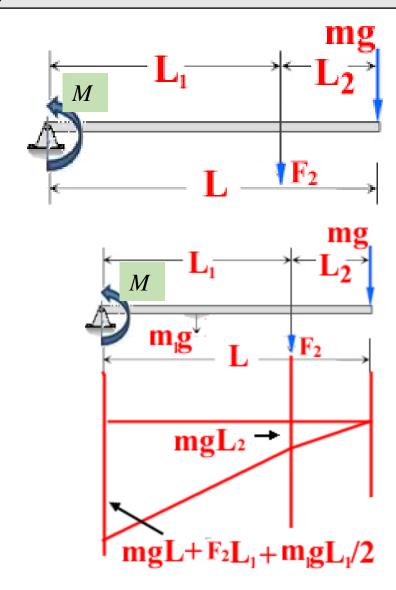
Static stress analysis





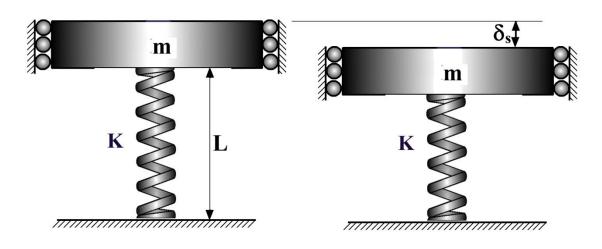
$$M = mgL + F_2L_1 + \frac{m_1gL_1}{2}$$

$$\sigma_{\rm S} = \frac{(M)(d/2)}{(\pi d^4/64)}$$



Dynamic stress analysis





From Hooke's law: $F_{\rm S} = K \delta_{\rm S}$

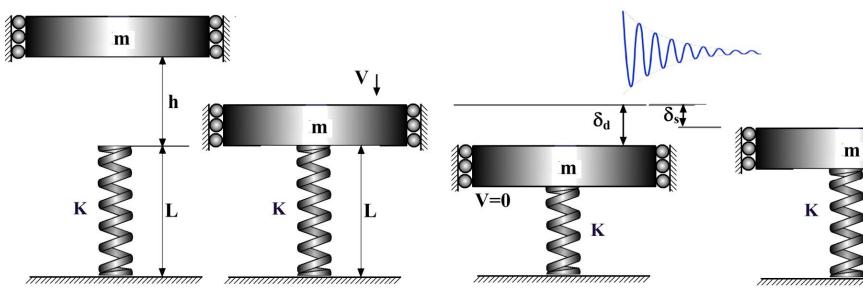
$$F_{\rm S} = mg$$

$$\delta_{\rm s} < \delta_{\rm d}$$

$$\delta_{\rm s} < \delta_{\rm d}$$
 $F_{\rm d} = K\delta_{\rm d}$

$$DMF = \frac{F_{d}}{F_{s}} = \frac{\delta_{d}}{\delta_{s}}$$
 Dynamic magnification factor = Dynamic force/Static force

Impact load







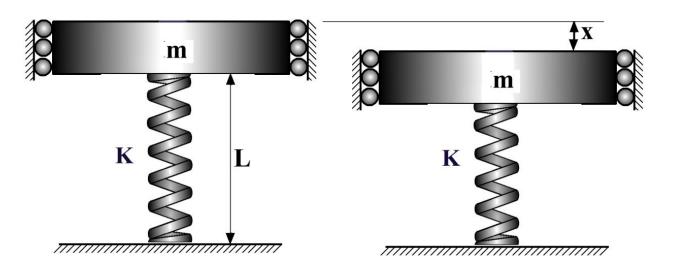
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Energy stored in spring and mass









$$F_{\rm S} = mg$$

$$F_{\rm S} = mg \qquad W = \int F_{\rm S} \ dx \quad W = \int Kx \ dx$$

$$W = \int Kx \, dx$$

Energy stored in the spring

$$W = K \int_{0}^{\delta} x \, dx = K \left| \frac{x^2}{2} \right|_{0}^{\delta} = \frac{K\delta^2}{2}$$

$$F = ma$$

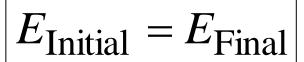
Energy due to movement

$$W_{\text{KE}} = \int ma \ dx = m \int \frac{dv}{dt} \ dx = m \int_{0}^{V} v \ dv = m \left| \frac{v^2}{2} \right|_{0}^{V} = \frac{mV^2}{2}$$

Energy method

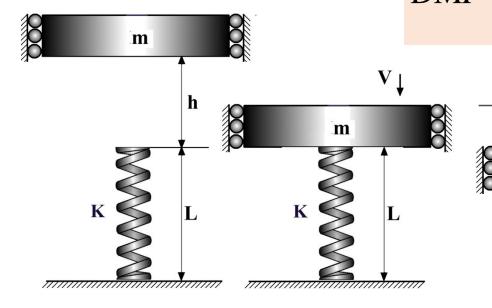
DMF =
$$\frac{F_{\rm d}}{F_{\rm s}} = \frac{\delta_{\rm d}}{\delta_{\rm s}}$$

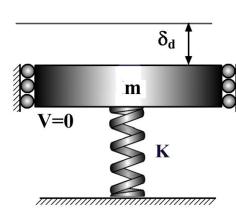




$$mg(h+L) = mg(L-\delta_{d}) + \frac{1}{2}K\delta_{d}^{2}$$

$$mgh = -mg\delta_{d} + \frac{1}{2}K\delta_{d}^{2}$$





$$2h = -2\delta_{\rm d} + \frac{K}{mg}\delta_{\rm d}^2$$

$$2h = -2\delta_{\rm d} + \frac{1}{\delta_{\rm s}} \delta_{\rm d}^2$$

$$\frac{2h}{\delta_{\rm s}} = -2\frac{\delta_{\rm d}}{\delta_{\rm s}} + \frac{\delta_{\rm d}^2}{\delta_{\rm s}^2}$$

$$2h = -2\delta_{\mathrm{d}} + \frac{K}{mg}\delta_{\mathrm{d}}^{2} \quad 2h = -2\delta_{\mathrm{d}} + \frac{1}{\delta_{\mathrm{s}}}\delta_{\mathrm{d}}^{2} \quad \frac{2h}{\delta_{\mathrm{s}}} = -2\frac{\delta_{\mathrm{d}}}{\delta_{\mathrm{s}}} + \frac{\delta_{\mathrm{d}}^{2}}{\delta_{\mathrm{s}}^{2}} \quad (\mathrm{DMF})^{2} - 2(\mathrm{DMF}) - \frac{2h}{\delta_{\mathrm{s}}} = 0$$

$$\mathrm{DMF} = \frac{2\pm\sqrt{4+\frac{8h}{\delta_{\mathrm{s}}}}}{2}$$

$$DMF = \frac{2 \pm \sqrt{4 + \frac{8h}{\delta_s}}}{2}$$

$$DMF = 1 + \sqrt{1 + \frac{2h}{\delta_s}}$$

$$DMF = 1 + \sqrt{1 + \frac{2h}{\delta_s}} \quad DMF = \frac{F_d}{F_s} = 2 \quad \text{if} \quad h = 0 \quad \text{mgh} = \frac{mV^2}{2} \quad DMF = \frac{\sigma_d}{\sigma_s} = 1 + \sqrt{1 + \frac{V^2}{g\delta_s}} \quad DMF = 1 + \sqrt{1 + \frac{V^2}{g\delta_s}}$$

$$mgh = \frac{mV^2}{2}$$

DMF =
$$\frac{\sigma_{\rm d}}{\sigma_{\rm s}} = 1 + \sqrt{1 + \frac{V^2}{g\delta_{\rm s}}}$$

$$DMF = 1 + \sqrt{1 + \frac{V^2}{g\delta_s}}$$

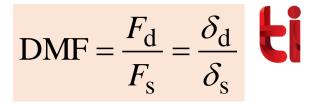
$$DMF = 1 + \sqrt{1 + \frac{V^2}{g\delta_s}}$$

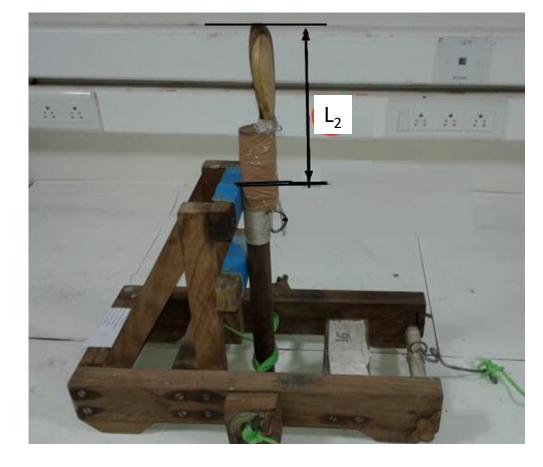
DMF = 1 +
$$\sqrt{1 + \frac{V^2}{g\delta_s}}$$
 $\delta_s = \frac{F_s L_2^3}{3EI} = \frac{16\rho L_2^4 g}{3Ed^2}$

$$F_{\rm s} = \frac{\pi d^2}{4} L_2 \rho g$$

$$F_{\rm s} = \frac{\pi d^2}{4} L_2 \rho g \qquad \sigma_{\rm d} = \left(1 + \sqrt{1 + \frac{V^2}{g \delta_{\rm s}}}\right) \sigma_{\rm s}$$

$$\sigma_{d} = \left(1 + \sqrt{1 + \frac{3Ed^{2}V^{2}}{16\rho L_{2}^{4}g^{2}}}\right) \times \frac{4\rho g L_{2}^{2}}{d}$$









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