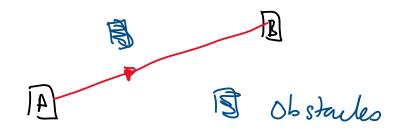
Trajectory Optimization



Ophnization

min
$$f(x) = 100 (x_2 - x_1^2)^2 + (1 - x_1)^2$$

 $x_{1,3}x_2$

ways to solve



(I) Guess

Guess
Maybe
$$f(x) = 0$$

 $\chi_2 = \chi_1 = 0$

(a) Calculus $\frac{df}{dx} = 0 \quad (extremum) = x_1 = x_2 = 1$

 $d^2f > 0$ minimum $\int_{-\infty}^{\infty} d^2f < 0$ maximum

 $\frac{d^2f}{dx^2} > 0$ minimum $\left| \frac{d^2f}{dx^2} < 0 \right|$ maximum

IN Numerically using scipy optimize.

(1) Unconstrained optimization

 $e^{-1}y^{-1} = 100(x_2 - x_1^2)^2 + (1-x_1)^2$ Cost

Con strained optimization

Cost $f(x_1, x_2) = x_1^2 + (x_1 - x_2)^3$

constraints: e.g. x1+x2 = 5 $x_1^2 + e^{X_2} < 2$

Constrained Optimization

min $f(x) = x_1^2 + x_2^2 + x_3^2 + x_4^2 + x_5^2$ $X = \{x_1, x_2, x_3, x_4, x_5\}$

subject to:

-00 5 x3 55

X3+ X4=5 Bounds $0.3 \leq x_1 \leq \infty$

 $X^1 > 0.3$

X₃ ≤ 5

X4+ X5 <5

Non linear Inequality con s Haint

Non linear

equality constraint

-00 5x2, x4, x5 < 00