

# **Computer Science 112**

## **Data Structures**

### **Lecture 21:**

### **Graphs:**

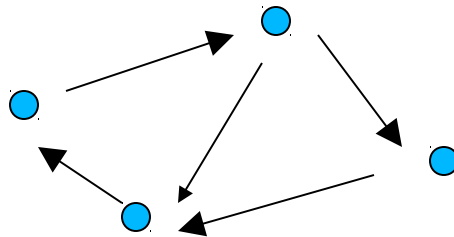
### **Depth First Search**

### **Topsort**

# Review: Graphs

## Generalization of trees

- **Digraph (Directed Graph)**
  - Like a tree but any vertex can point to any other

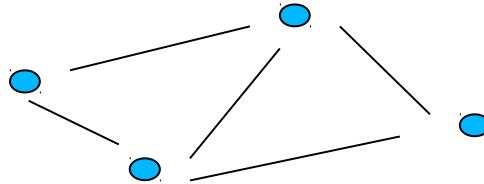


- E.g., Twitter follows relationship

# Graphs

## Generalization of trees

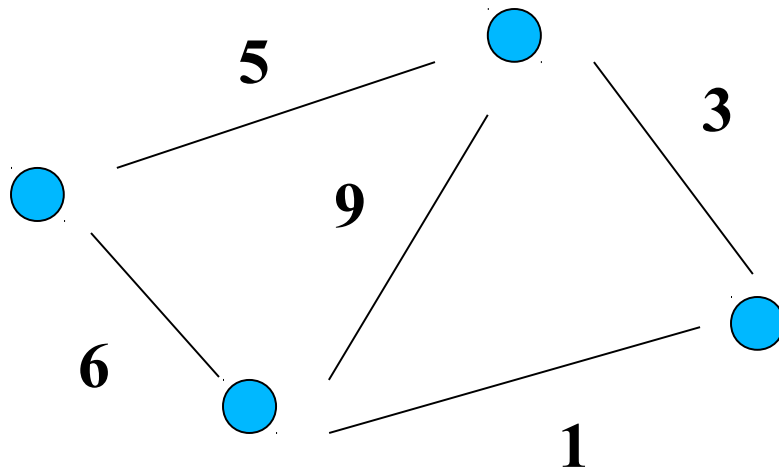
- **Graph**
  - like digraph but arcs have no direction



- **E.g., Facebook friends relationship**

# Graphs

- **Weighted Graph**
  - **Positive integer weights on each edge**

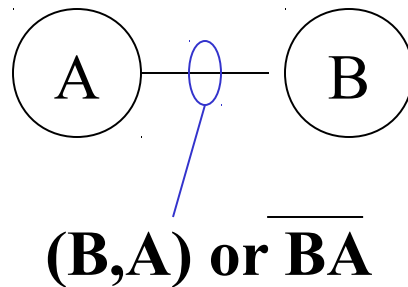


# Applications

- **Lots**

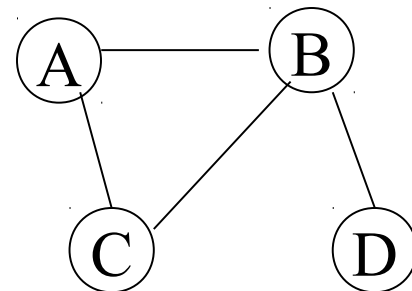
# Notation

- **Arcs are named by the vertices they connect**



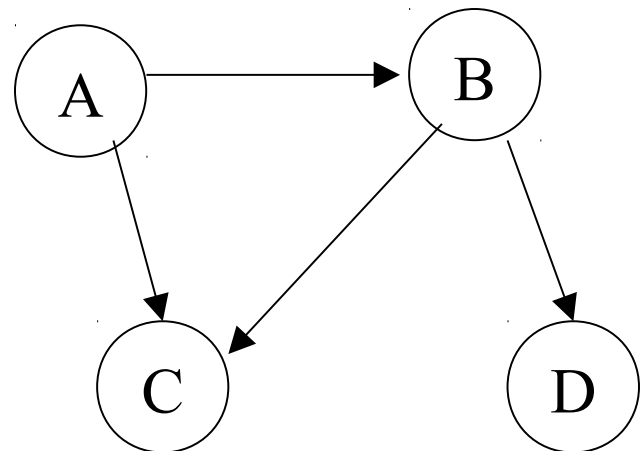
# Graph Concepts

- **Neighbors of a vertex:** vertices that it shares an arc with
  - Neighbors of A are B and C
- **Degree of a vertex:** number of neighbors
  - Degree of A is 2, degree of B is 3



# Graph Concepts

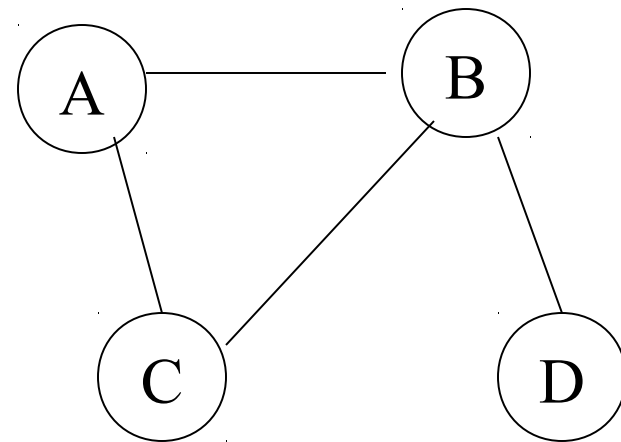
- **In degree (in a digraph):** number of vertices that have arcs to this vertex
  - In degree of B is 1
- **Out degree (in a digraph):** number of vertices that have arcs from this vertex
  - Out degree of B is 2





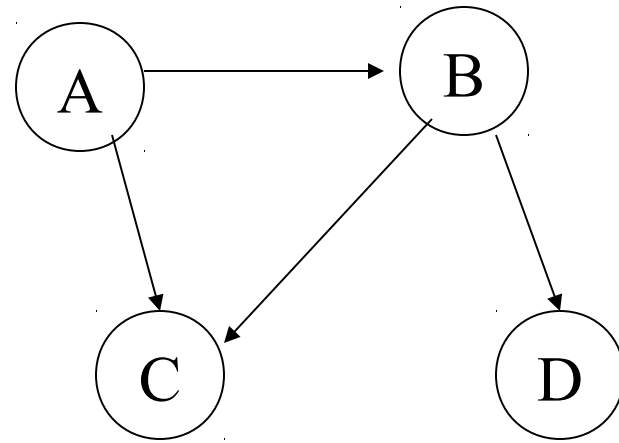
# Graph Concepts

- **(Simple) Path**
  - **Sequence of arcs**  
 $(A,B),(B,C)$
  - **May not revisit a vertex**  
 ~~$(B,A),(A,C),(C,B),(B,D)$~~
  - **Except last vertex may = first**  
 $(B,A),(A,C),(C,B)$
- **Vertex A is reachable from B**  
**if there is a path from B to A**



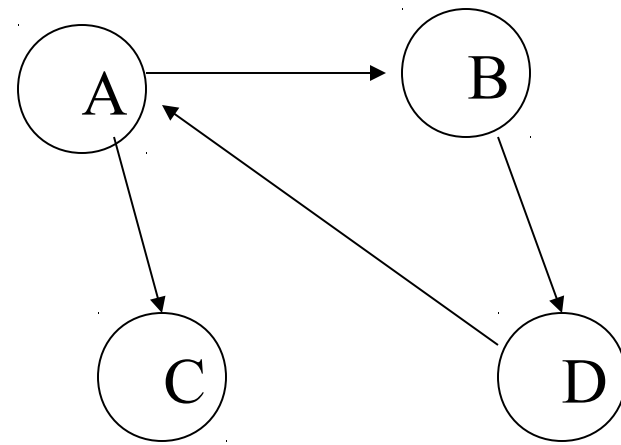
# Graph Concepts

- **Path**
  - On digraph must follow arc directions  
(A,B),(B,D)  
~~(A,C),(C,B)~~



# Graph Concepts

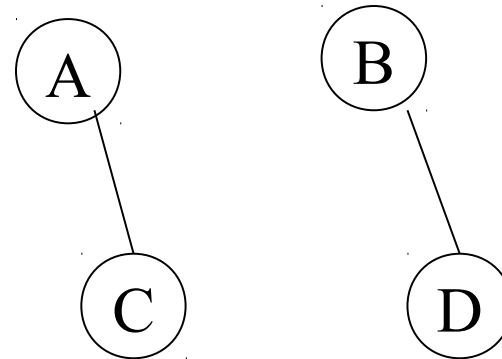
- **A cycle is a path from a node back to itself**
  - (A, B)(B, D)(D, A)
- **A graph with no cycles is called acyclic**



# Graph Concepts

- **Connected Graph**

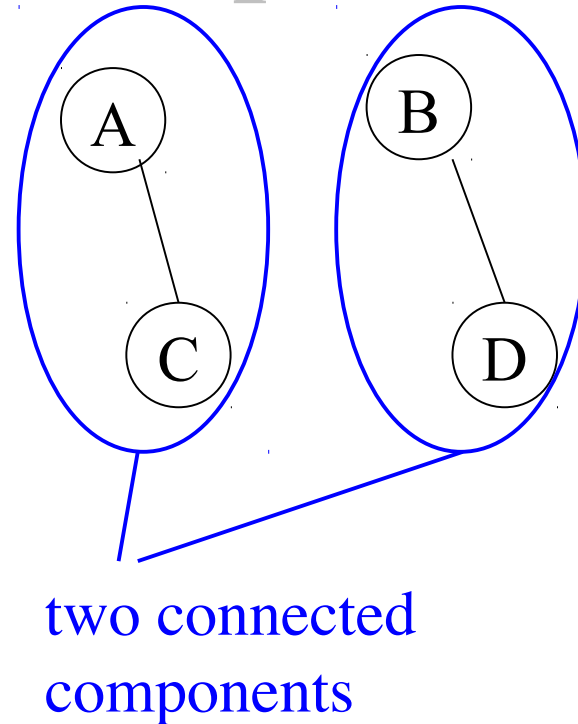
**For any two vertices X and Y  
there is a path from X to Y.**



not connected

# Graph Concepts

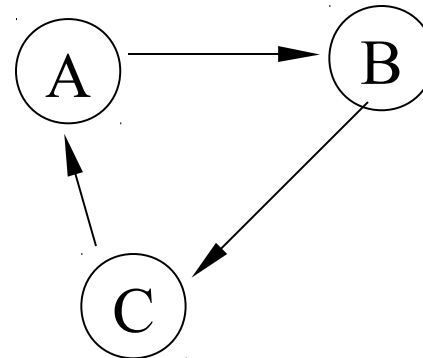
- **Connected Graph**  
For any two vertices **X** and **Y** there is a path from **X** to **Y**.
- **Connected Component**  
A subset of vertices that is connected



# Graph Concepts

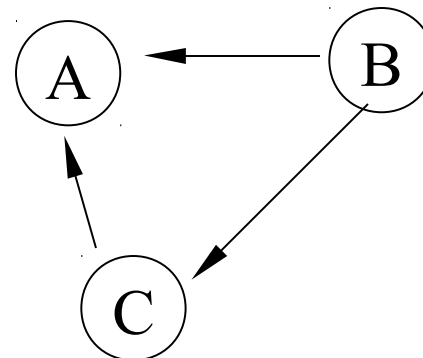
- **Strongly Connected Digraph**

**For any two vertices X and Y there is a path from X to Y. (Paths must follow arc directions)**



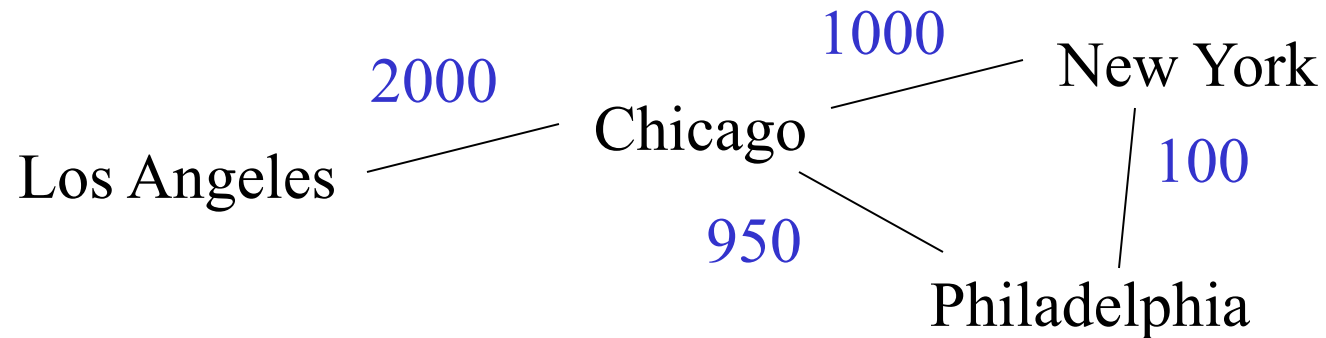
- **Weakly Connected Digraph**

**Corresponding graph is connected (i.e., ignoring arc direction)**

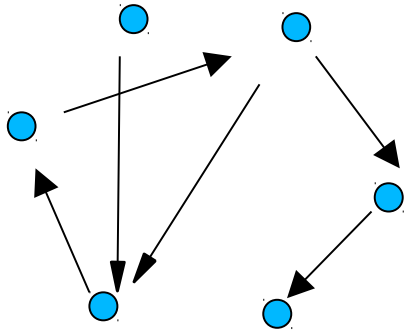


# Graph Concepts

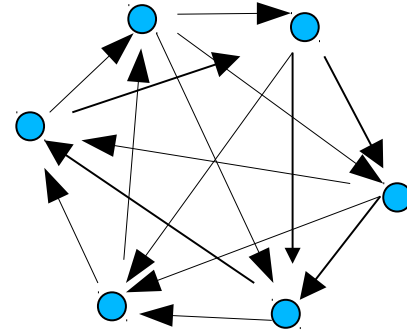
- **Weighted graph:** each arc has a numerical weight



# Sparse vs Dense Graphs



Sparse

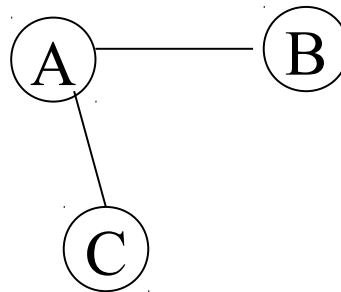


Dense



# Representing Graphs

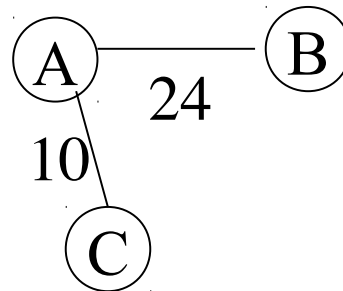
- **Adjacency matrix**
  - **$n \times n$  boolean matrix: is there an arc?**



| name |   | 0 | 1 | 2 |
|------|---|---|---|---|
| 0    | A | 0 | T | T |
| 1    | B | T |   |   |
| 2    | C | T |   |   |

# Representing Graphs

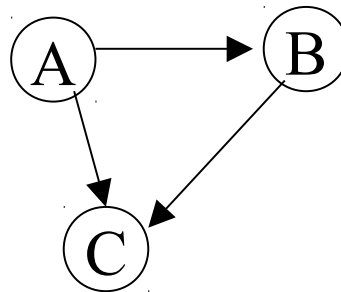
- **Adjacency matrix**
  - **$n \times n$  boolean matrix: is there an arc?**



|   | name |   | 0  | 1  | 2  |
|---|------|---|----|----|----|
| 0 | A    | 0 | -1 | 24 | 10 |
| 1 | B    | 1 | 24 | -1 | -1 |
| 2 | C    | 2 | 10 | -1 | -1 |

# Representing Graphs

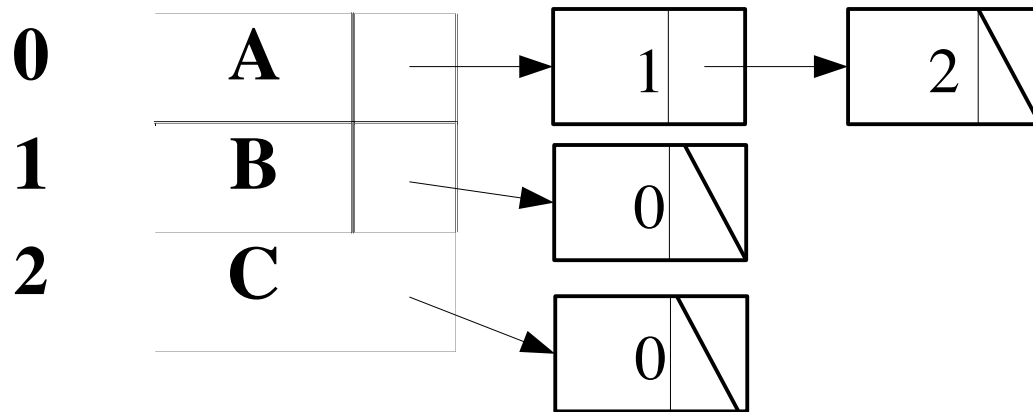
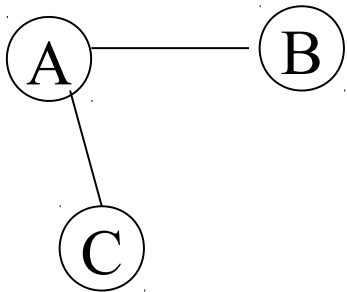
- **Adjacency matrix**
  - **$n \times n$  boolean matrix: is there an arc?**



| name |   | 0 | 1 | 2 |
|------|---|---|---|---|
| 0    | A | 0 | T | T |
| 1    | B | 1 |   | T |
| 2    | C | 2 |   |   |

# Representing Graphs

- **Adjacency list**
  - **for each node, a linked list of edges that touch it**



# Representing Graphs

- **Adjacency list**
  - **for each node, a linked list of edges that touch it**
  - **Space cost:**
    - undirected  $v + 2 * e$**
    - directed  $v + 2 * e$**

# Costs, Worst case

|                  | Space      | Time: Is there<br>and edge from<br>i to j | Time: List the<br>neighbors of i |
|------------------|------------|---|----------------------------------|
| Adjacency matrix | $O(v^2)$   | $O(1)$                                    | $O(v)$                           |
| Adjacency list   | $O(v + e)$ | $O(d)$                                    | $O(d)$                           |

d is degree (i.e., number of  
neighbors) of i  
 $d < v$

# Graph Traversals

- **Need to mark vertices as we see them to prevent infinite loops**
- **Need driver in case not connected**
- **Otherwise like tree traversals**
- **Depth first**

**dfsG(v):**

**if (marked(v)) return;**

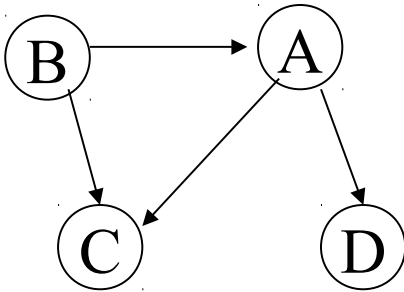
**visit v;**

**mark v;**

**for each vn in neighbors(v)**

**dfsG(vn)**

# Graph Traversals



**Driver**

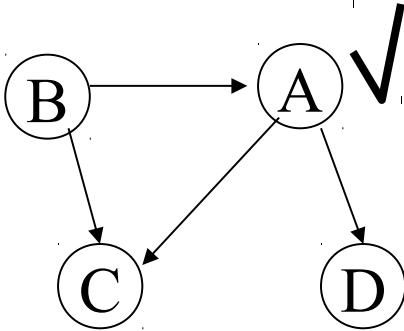
$\mathbf{v} = \langle \mathbf{A} \rangle$

**dfsG**

$\mathbf{v} = \langle \mathbf{A} \rangle$



# Graph Traversals



**Driver**

$\mathbf{v} = \langle \mathbf{A} \rangle$

**dfsG**

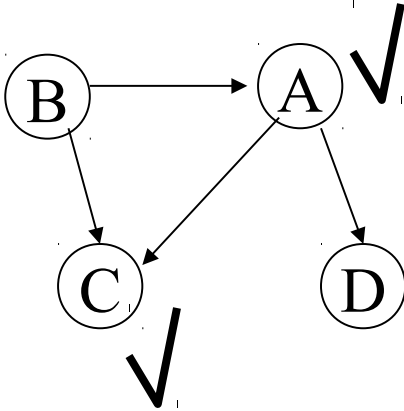
$\mathbf{v} = \langle \mathbf{A} \rangle$

$\mathbf{vn} = \langle \mathbf{C} \rangle$

**dfsG**

$\mathbf{v} = \langle \mathbf{C} \rangle$

# Graph Traversals



**Driver**

$\mathbf{v} = \langle \mathbf{A} \rangle$

**dfsG**

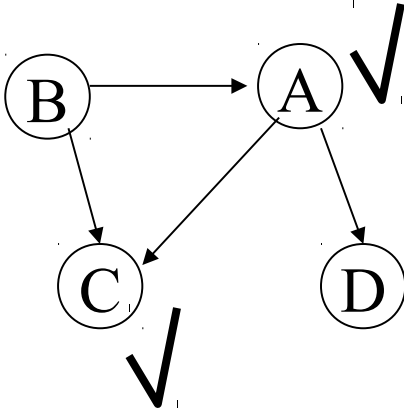
$\mathbf{v} = \langle \mathbf{A} \rangle$

$\mathbf{vn} = \langle \mathbf{C} \rangle$

**dfsG**

$\mathbf{v} = \langle \mathbf{C} \rangle$

# Graph Traversals



**Driver**

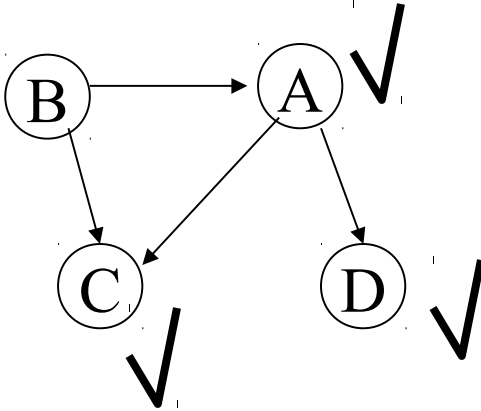
$\mathbf{v} = \langle \mathbf{A} \rangle$

**dfsG**

$\mathbf{v} = \langle \mathbf{A} \rangle$

$\mathbf{vn} = \langle \mathbf{D} \rangle$

# Graph Traversals



**Driver**

$\mathbf{v} = \langle \mathbf{A} \rangle$

**dfsG**

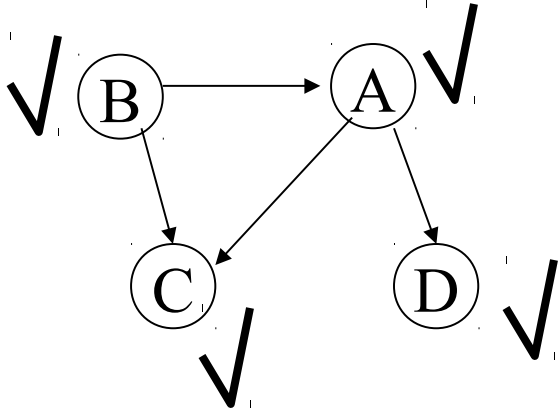
$\mathbf{v} = \langle \mathbf{A} \rangle$

$\mathbf{vn} = \langle \mathbf{D} \rangle$

**dfsG**

$\mathbf{v} = \langle \mathbf{D} \rangle$

# Graph Traversals



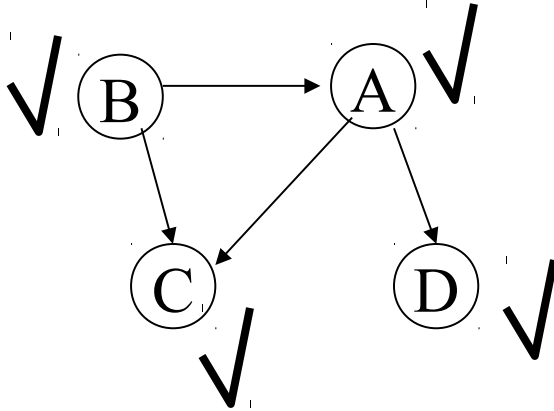
**Driver**

$\mathbf{v} = \langle \mathbf{B} \rangle$

**dfsG**

$\mathbf{v} = \langle \mathbf{B} \rangle$

# Graph Traversals



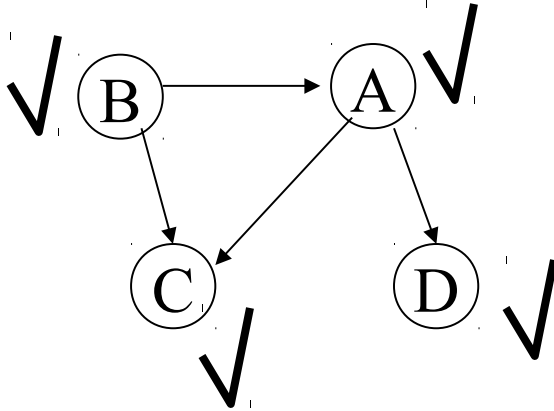
**Driver**

$v = \langle C \rangle$

**dfsG**

$v = \langle C \rangle$

# Graph Traversals



**Driver**

**$v = \langle D \rangle$**

**dfsG**

**$v = \langle D \rangle$**

# Graph Traversals

- **Time:**
  - Visit each vertex
  - inspect each edge **$O(n + e)$   $n$  vertices,  $e$  edges**



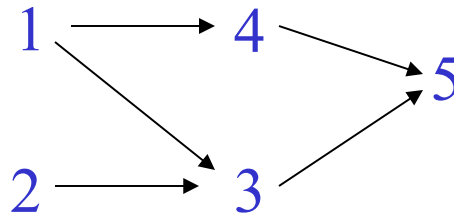
# Uses of DFS Traversal

- **Connected Components**
  - See **GraphCC.java**
- **Topsort**
  - See **GraphTS.java**

# New: Topological Sort

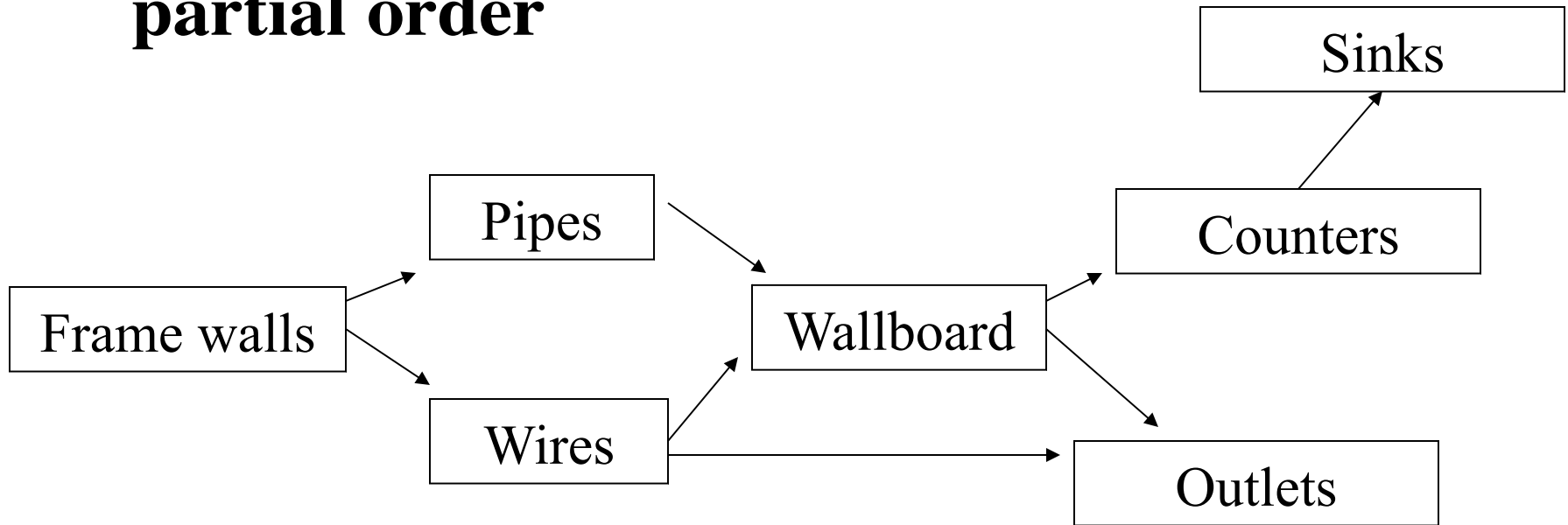
- **Acyclic Digraph  $\Leftrightarrow$  partial order**
- **Topsort: find total order consistent with partial order**

```
1  a=1;  
2  b=2;  
3  c=a*b;  
4  d=a+4  
5  ;  
   c=c+d
```



# Topological Sort

- **Acyclic Digraph  $\Leftrightarrow$  partial order**
- **Topsort: find total order consistent with partial order**



# Topsort Algorithms

- **Most work by assigning numbers to vertices**
  - vertex order = numerical order
- **Depth first**
- **Breadth First**

# DFS Topsort Algorithm

- **Algorithm:**
  - Do DFS
  - Number vertices as you leave them
- **Problem:** leave vertex *after* leave reachable vertices, but needs number *smaller* than reachable vertices
  - **Solution:** number with decreasing numbers
- **See GraphTS.java**