

Computer Science 112

Data Structures

Lecture 20:

Graphs:

Representations

Depth First Search

Announcements

- **Midterm Exam 2**
 - **Sunday April 12**
 - **3:00 – 4:20 pm**
 - **See sakai announcements for rooms**

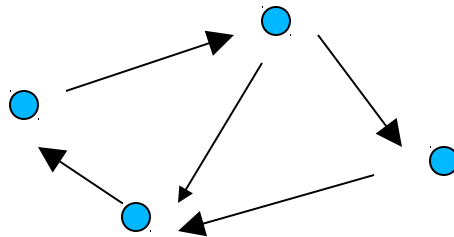
Announcements

- **You should already have watched videos on hashing and on graphs**
 - see sakai announcements
 - **Graph.java and data files website.txt and friendship.txt are on Sakai in Resources > Steinberg > Java > graph**

New: Graphs

Generalization of trees

- **Digraph (Directed Graph)**
 - Like a tree but any vertex can point to any other

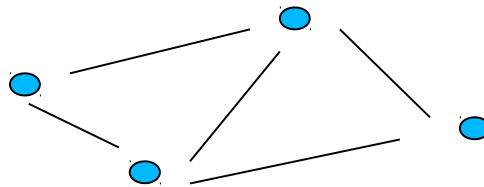


- E.g., Twitter follows relationship

New: Graphs

Generalization of trees

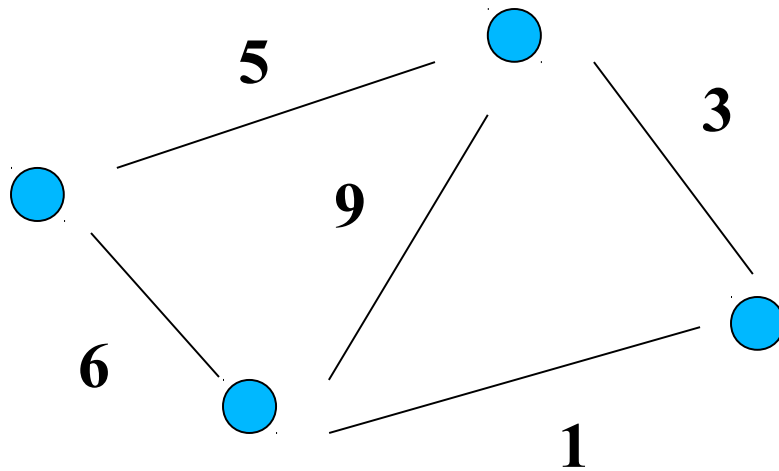
- **Graph**
 - like digraph but arcs have no direction



- **E.g., Facebook friends relationship**

Graphs

- **Weighted Graph**
 - **Positive integer weights on each edge**

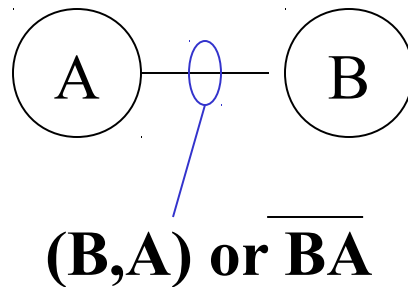


Applications

- **Paths**
 - **On streets (eg Google Maps)**
- **Electrical networks**
 - **Power lines**
- **Constraints**
 - **Ordering constraints on building steps**
eg counters before sinks

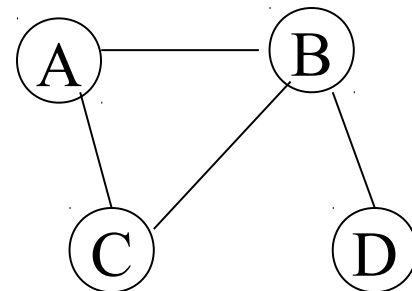
Notation

- **Arcs are named by the vertices they connect**



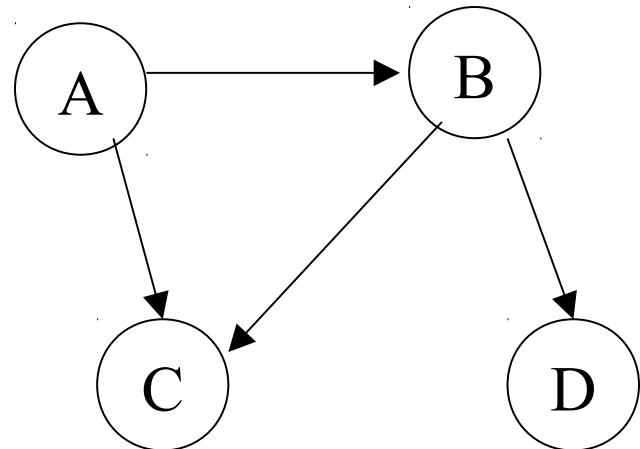
Graph Concepts

- **Neighbors of a vertex:** vertices that it shares an arc with
 - Neighbors of A are B and C
- **Degree of a vertex:** number of neighbors
 - Degree of A is 2, degree of B is 3



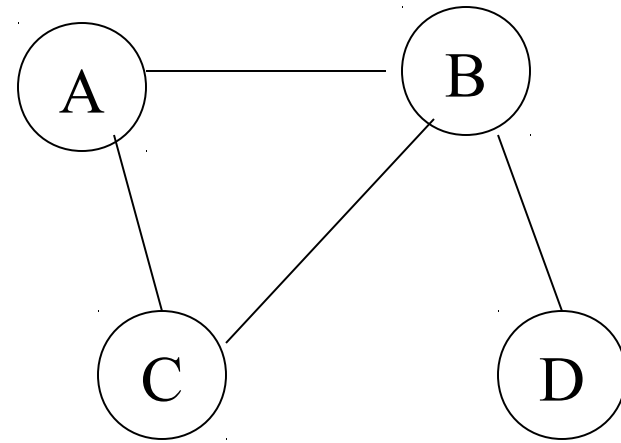
Graph Concepts

- **In degree (in a digraph):** number of vertices that have arcs to this vertex
 - In degree of B is 1
- **Out degree (in a digraph):** number of vertices that have arcs from this vertex
 - Out degree of B is 2



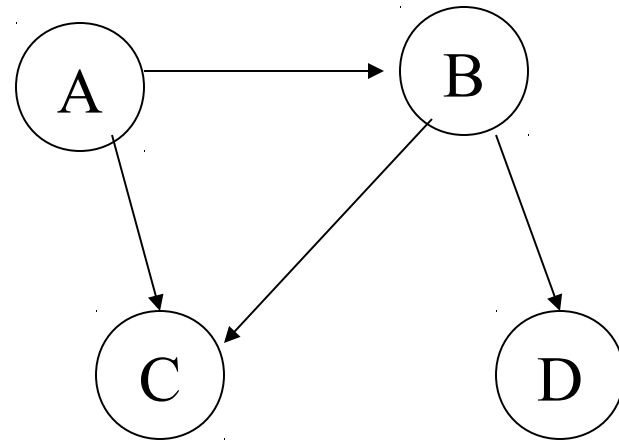
Graph Concepts

- **(Simple) Path**
 - **Sequence of arcs**
 $(A,B),(B,C)$
 - **May not revisit a vertex**
 ~~$(B,A),(A,C),(C,B),(B,D)$~~
 - **Except last vertex may = first**
 $(B,A),(A,C),(C,B)$
- **Vertex A is reachable from B**
if there is a path from B to A



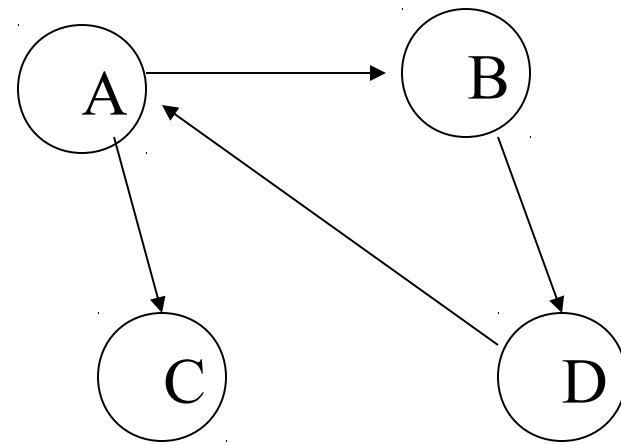
Graph Concepts

- **Path**
 - On digraph must follow arc directions
(A,B),(B,D)
~~(A,C),(C,B)~~



Graph Concepts

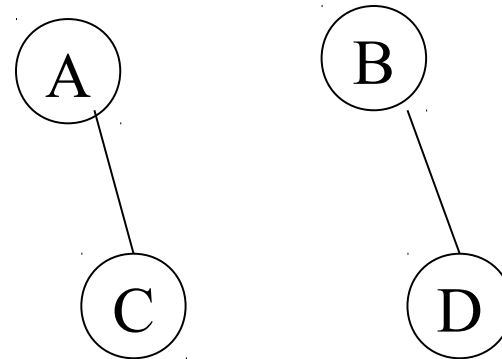
- **A cycle is a path from a node back to itself**
 - (A, B)(B, D)(D, A)
- **A graph with no cycles is called acyclic**



Graph Concepts

- **Connected Graph**

**For any two vertices X and Y
there is a path from X to Y.**

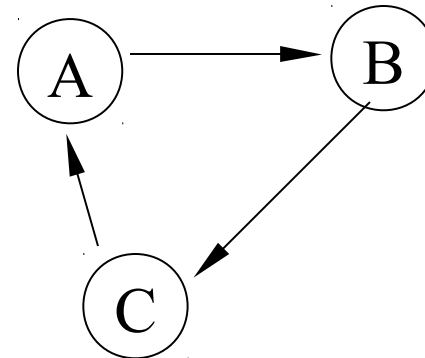


not connected

Graph Concepts

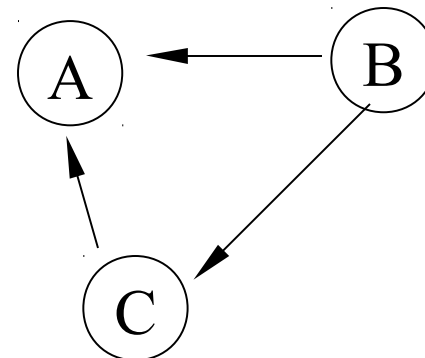
- **Strongly Connected Digraph**

For any two vertices X and Y there is a path from X to Y. (Paths must follow arc directions)



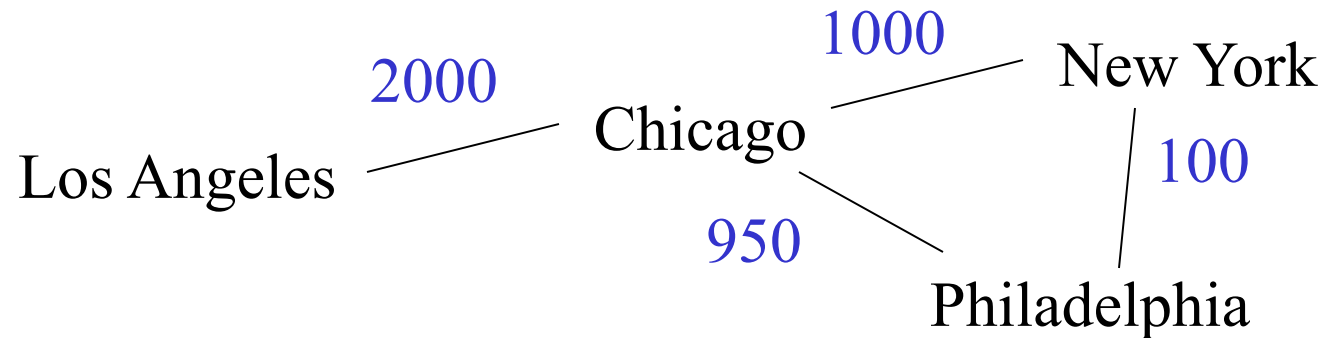
- **Weakly Connected Digraph**

Corresponding graph is connected (i.e., ignoring arc direction)



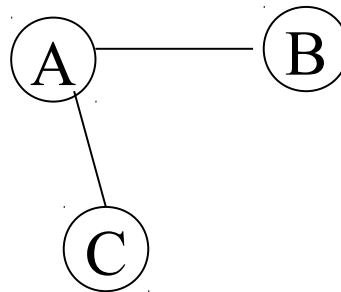
Graph Concepts

- **Weighted graph:** each arc has a numerical weight



Representing Graphs

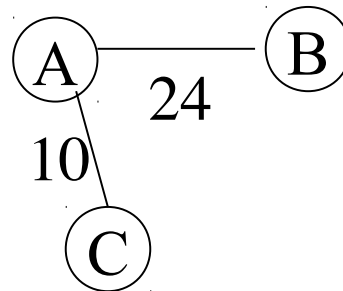
- **Adjacency matrix**
 - **$n \times n$ boolean matrix: is there an arc?**



name				
		0	1	2
0	A	0		
1	B	1	T	T
2	C	2	T	

Representing Graphs

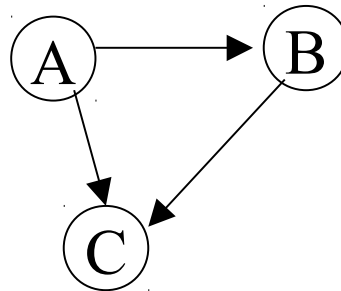
- **Adjacency matrix**
 - **$n \times n$ boolean matrix: is there an arc?**



	name		0	1	2
0	A	0	-1	24	10
1	B	1	24	-1	-1
2	C	2	10	-1	-1

Representing Graphs

- **Adjacency matrix**
 - **$n \times n$ boolean matrix: is there an arc?**

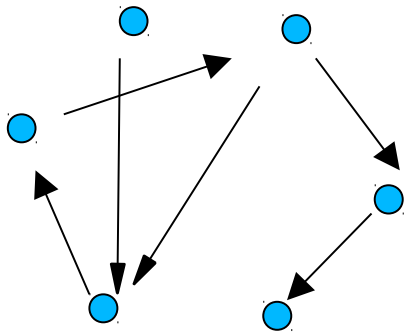


name				
		0	1	2
0	A	0	T	T
1	B	1		T
2	C	2		

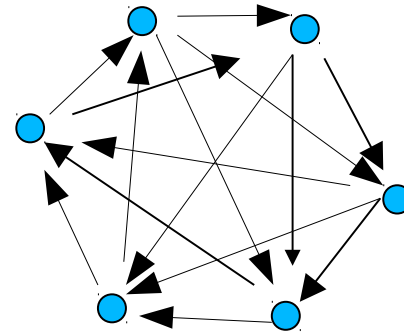
Adjacency Matrix

- Space cost: v^2 booleans where v is number of vertices
- If v is large, v^2 is huge
 - Facebook: $v = 10^9$, $v^2 = 10^{18}$
1,000,000,000,000,000,000
 - An average Facebook user has about 350 friends
 - if e is number of edges, $e = 10^9 * 175$
 - Fraction of Trues in matrix = $1.75 * 10^{-7}$
 $= 1 / 5,000,000$

Sparse vs Dense Graphs



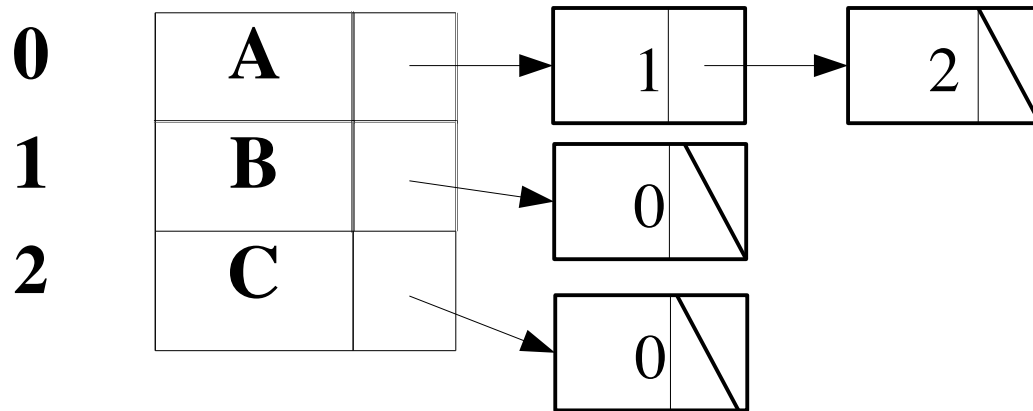
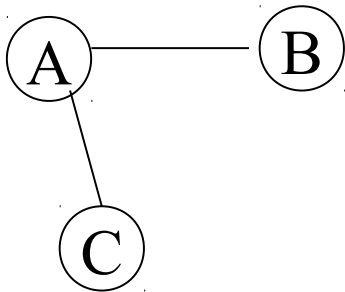
Sparse



Dense

Representing Graphs

- **Adjacency list**
 - **for each node, a linked list of edges that touch it**

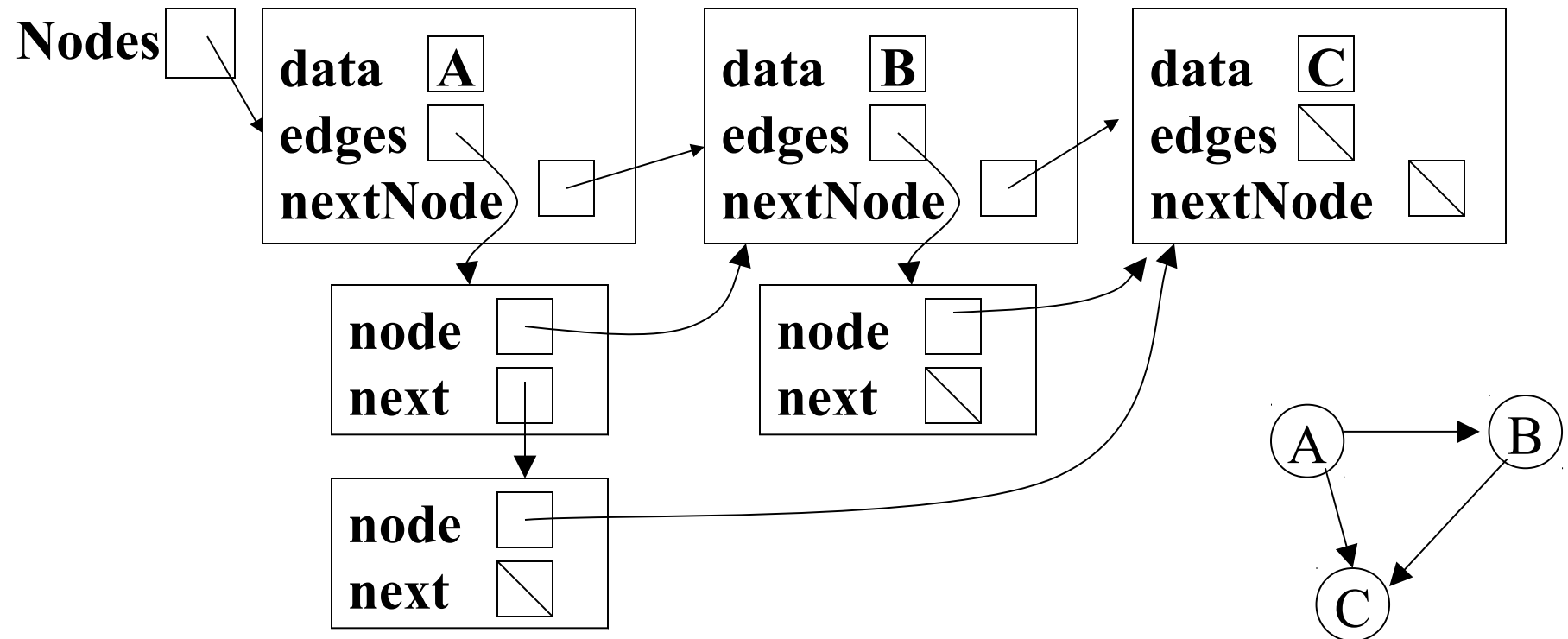


Representing Graphs

- **Adjacency list**
 - **for each node, a linked list of edges that touch it**
 - **Space cost: $v + 2 * 2 * e$**
 - **For Facebook: $10^9 + 4 * 175 * 10^9$
 $= 700 * 10^9$**

Representing Graphs

- **Adjacency list**
 - for each node, linked list of edges



Time costs, Worst case

	Is there an edge from i to j	List the neighbors of i
Adjacency matrix	$O(1)$	$O(v)$
Adjacency list	$O(d)$	$O(d)$

d is degree of i , $d < v$

Exercise

- You write `countEdges()` in class `Graph`

Graph Traversals

- **Need to mark vertices as we see them to prevent infinite loops**
- **Need driver in case not connected**
- **Otherwise like tree traversals**
- **Depth first**

dfsG(v)

if (marked(v)) return;

visit v;

mark v;

for each vn in neighbors(v)

dfsG(vn)

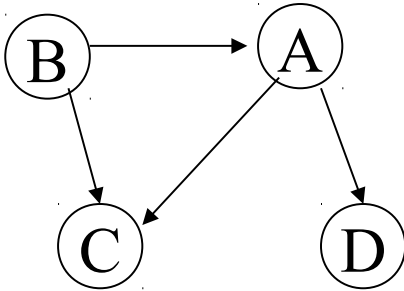
Graph Traversals

- **Need driver in case not connected**
 For v in vertices
 $\text{dfsG}(v)$

DFS Graph Traversal

- **Enters a vertex v**
- **Visits all vertices reachable from v (that have not yet been visited)**
- **Leaves v**

Graph Traversals



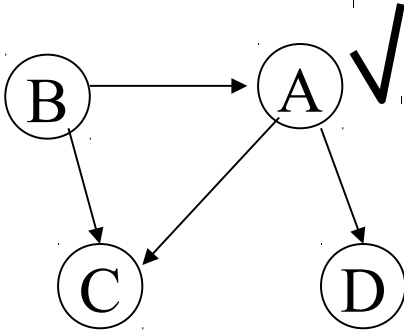
Driver

$\mathbf{v} = \langle \mathbf{A} \rangle$

dfsG

$\mathbf{v} = \langle \mathbf{A} \rangle$

Graph Traversals



Driver

$\mathbf{v} = \langle \mathbf{A} \rangle$

dfsG

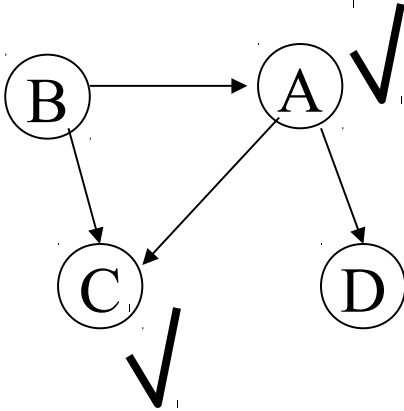
$\mathbf{v} = \langle \mathbf{A} \rangle$

$\mathbf{vn} = \langle \mathbf{C} \rangle$

dfsG

$\mathbf{v} = \langle \mathbf{C} \rangle$

Graph Traversals



Driver

$\mathbf{v} = \langle \mathbf{A} \rangle$

dfsG

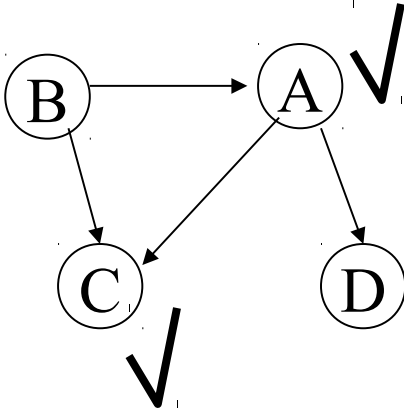
$\mathbf{v} = \langle \mathbf{A} \rangle$

$\mathbf{vn} = \langle \mathbf{C} \rangle$

dfsG

$\mathbf{v} = \langle \mathbf{C} \rangle$

Graph Traversals



Driver

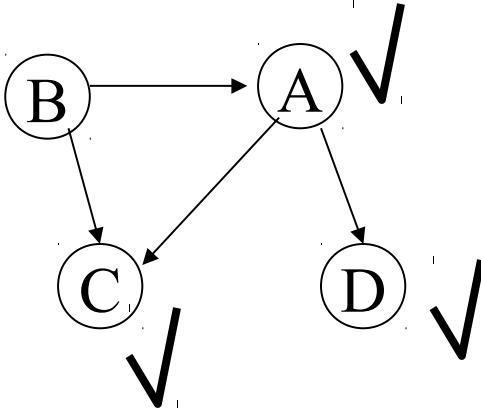
$\mathbf{v} = \langle \mathbf{A} \rangle$

dfsG

$\mathbf{v} = \langle \mathbf{A} \rangle$

$\mathbf{vn} = \langle \mathbf{D} \rangle$

Graph Traversals



Driver

$\mathbf{v} = \langle \mathbf{A} \rangle$

dfsG

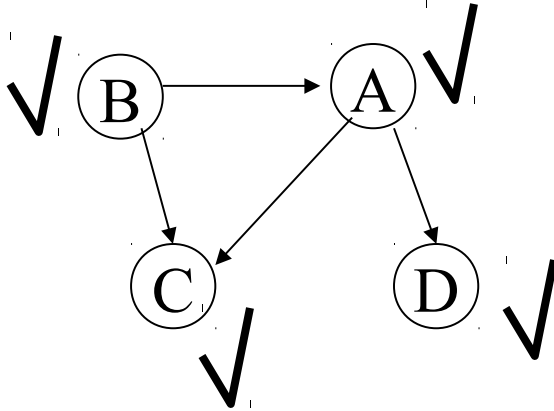
$\mathbf{v} = \langle \mathbf{A} \rangle$

$\mathbf{vn} = \langle \mathbf{D} \rangle$

dfsG

$\mathbf{v} = \langle \mathbf{D} \rangle$

Graph Traversals



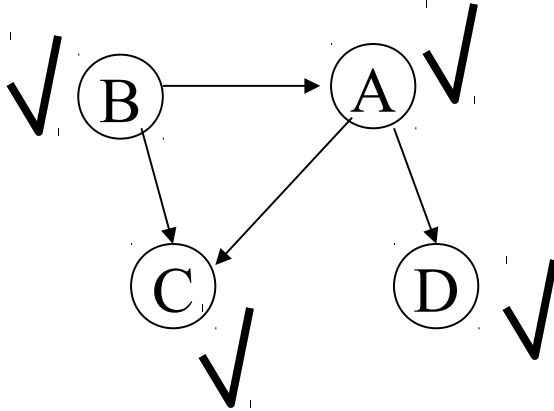
Driver

$\mathbf{v} = \langle \mathbf{B} \rangle$

dfsG

$\mathbf{v} = \langle \mathbf{B} \rangle$

Graph Traversals



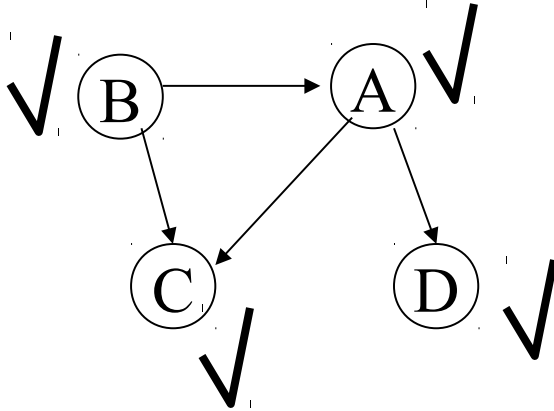
Driver

$v = \langle C \rangle$

dfsG

$v = \langle C \rangle$

Graph Traversals



Driver

$v = \langle D \rangle$

dfsG

$v = \langle D \rangle$

Graph Traversals

- **Time:**
 - Visit each vertex
 - inspect each arc
 - driver
- $O(n + e)$ n vertices, e edges**