

```

1  """
2  Solution to the one-way tunnel
3  """
4  import time
5  import random
6  from multiprocessing import Lock, Condition, Process, Manager
7
8  SOUTH = 0
9  NORTH = 1
10
11  NCARS = 5
12
13  class Monitor():
14      def __init__(self):
15          self.manager = Manager()
16          self.mutex = Lock()
17          self.inTunnel = self.manager.list([0,0])
18          self.semaphore = Condition(self.mutex)
19          self.carDir = None
20
21      def car_dir(self, car_direction):
22          self.carDir = car_direction
23
24      def validTunnel(self):
25          return (self.inTunnel[(self.carDir + 1)%2] == 0)
26
27      def wants_enter(self, car_direction):
28          self.mutex.acquire()
29          self.car_dir(car_direction)
30          self.semaphore.wait_for(self.validTunnel)
31          self.inTunnel[car_direction] += 1
32          self.mutex.release()
33
34      def leaves_tunnel(self, car_direction):
35          self.mutex.acquire()
36          self.inTunnel[car_direction] -= 1
37          self.semaphore.notify()
38          self.mutex.release()
39
40      def delay(n=3):
41          time.sleep(random.random()*n)
42
43      def car(cid, direction, monitor):
44          print(f"car {cid} direction {direction} created")
45          delay(6)
46          print(f"car {cid} heading {direction} wants to enter")
47          monitor.wants_enter(direction)
48          print(f"car {cid} heading {direction} enters the tunnel")
49          delay(3)
50          print(f"car {cid} heading {direction} leaving the tunnel")
51          monitor.leaves_tunnel(direction)
52          print(f"car {cid} heading {direction} out of the tunnel")
53
54      def main():
55          monitor = Monitor()
56          cid = 0
57          cars=[]
58          for _ in range(NCARS):
59              direction = NORTH if random.randint(0,1)==1 else SOUTH
60              cid += 1
61              p = Process(target=car, args=(cid, direction, monitor))
62              p.start()
63              cars.append(p)
64              time.sleep(random.expovariate(1/0.5)) # a new car enters each 0.5s
65
66          for c in cars:
67              c.join()
68
69      if __name__ == "__main__":
70          main()

```

INVARIANTE

Self.inTunnel = [a,b] ; a,b>=0 and (Si a>0 -> b=0) and (si b>0 -> a=0)

Wants enter:
Supongamos que se cumple el invariante y tomamos car_direction =1 (análogo para car_direction = 0).
Si cumple validTunnel -> inTunnel = [0,b] con b>=0
Entonces inTunnel = [0,b+1]
Y se sigue cumpliendo el invariante
Leaves tunnel:
Renombramos b' = b+1
Supongamos b' >0
Cuando sale el coche ¿b'-1 >0? Si porque b'-1 = b+1-1 = b>0 y esto es cierto por el invariante (b>=0)
Entre wants enter y leaves tunnel se puede haber actualizado la b' pero siempre cumpliendo el invariante (b>=0)