view_frames Result Recorded at time: 1685959159.94 base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.0 Average rate: 10000.0 Average rate: 10000.0 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 patient base_link_inertia base Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.204 Average rate: 10000.0 Buffer length: 4.9 Buffer length: 0.0 Most recent transform: 1685959159.91 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 1685959155.01 shoulder_link camera Broadcaster: /robot_state_publisher Average rate: 10.204 Buffer length: 4.9 Most recent transform: 1685959159.91 Oldest transform: 1685959155.01 upper_arm_link Broadcaster: /robot_state_publisher Average rate: 10.204 Buffer length: 4.9 Most recent transform: 1685959159.91 Oldest transform: 1685959155.01 forearm_link Broadcaster: /robot_state_publisher Average rate: 10.204 Buffer length: 4.9 Most recent transform: 1685959159.91 Oldest transform: 1685959155.01 wrist_1_link Broadcaster: /robot_state_publisher Average rate: 10.204 Buffer length: 4.9 Most recent transform: 1685959159.91 Oldest transform: 1685959155.01 wrist_2_link Broadcaster: /robot_state_publisher Average rate: 10.204 Buffer length: 4.9 Most recent transform: 1685959159.91 Oldest transform: 1685959155.01 wrist_3_link Broadcaster: /robot_state_publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 flange Broadcaster: /robot_state_publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 tool0