

jointAnklePositionTask.joint
AnklePositionTask.atualizeLenghts
AndVelocity



```
graph LR; A[jointAnklePositionTask.joint  
AnklePositionTask.atualizeLenghts  
AndVelocity] --> B[jointAnklePositionTask.joint  
AnklePositionTask.dLdt]; B --> C[jointAnklePositionTask.joint  
AnklePositionTask.computeAcceleration];
```

The diagram consists of three rectangular boxes arranged horizontally, connected by blue arrows pointing from left to right. The first box on the left has a light gray background and contains the text 'jointAnklePositionTask.joint', 'AnklePositionTask.atualizeLenghts', and 'AndVelocity'. The middle box has a white background and contains 'jointAnklePositionTask.joint' and 'AnklePositionTask.dLdt'. The third box on the right also has a white background and contains 'jointAnklePositionTask.joint' and 'AnklePositionTask.computeAcceleration'.

jointAnklePositionTask.joint
AnklePositionTask.dLdt

jointAnklePositionTask.joint
AnklePositionTask.computeAcceleration