

Drones for Infrastructure Inspections and Interactions Research Group (DIII)

Projects: IFD Drones4Energy, H2020 Drones4Safety and Aerial-Core Projects)

Emad Samuel Malki Ebeid

Associate Professor, SDU UAS Center,

Project Coordinator of H2020 [Drones4Safety](#) and IFD [Drones4Energy](#) Projects, [DIII](#) Group leader,

The University of Southern Denmark

esme@mmmi.sdu.dk

<https://www.sdu.dk/diii>

Today's Power line Inspection



HV cable length:

- US \approx 320,000 km
- CA \approx 230,000 km
- EU \approx 200,000 km
- DK \approx 7,000 km

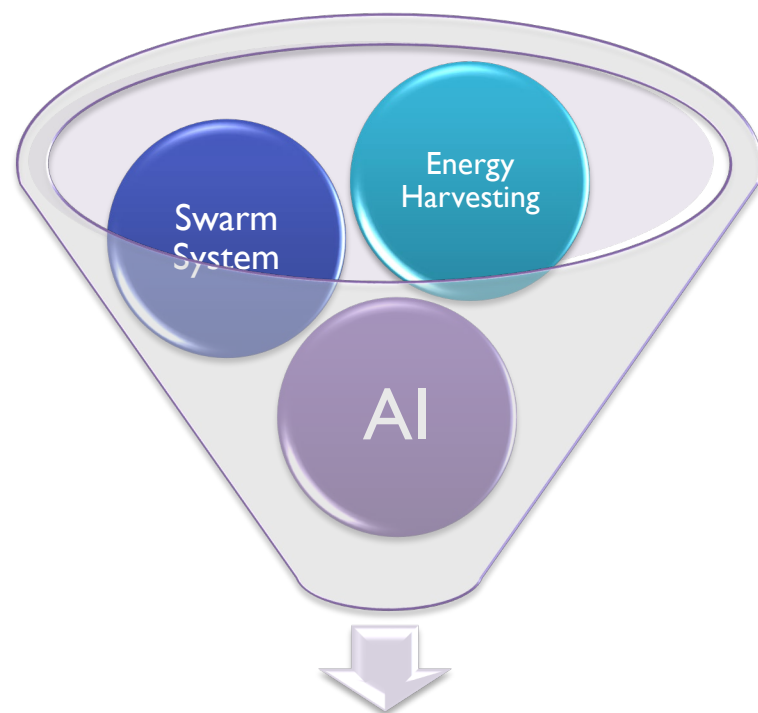
Funding: Innovation Fund Denmark with a grant of DKK 14 million (total budget of DKK 19 million including co-financing) [3M Euro]

Program: Grand Solutions

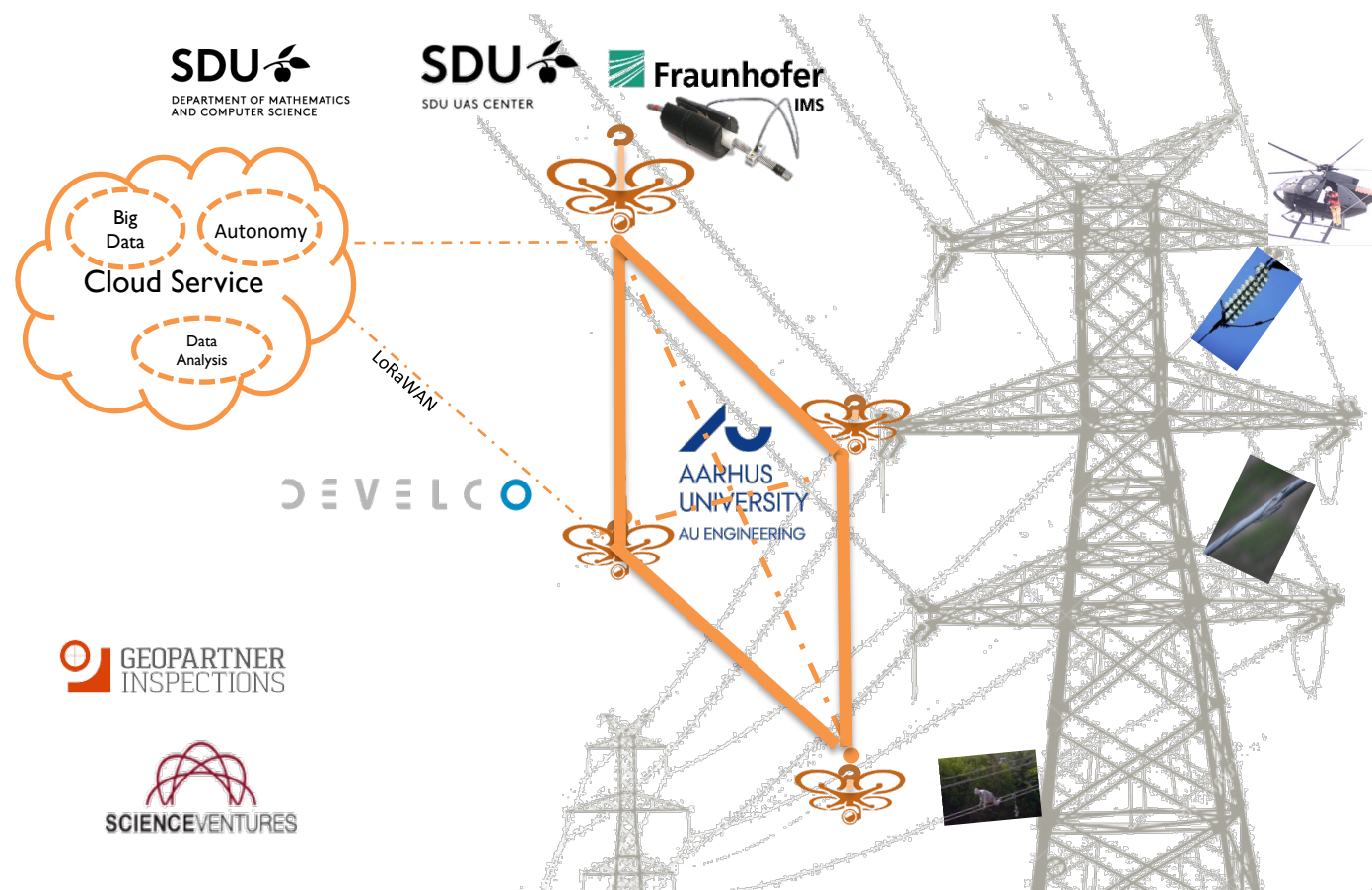
Drones4Energy Project

(<https://drones4energy.dk/>)

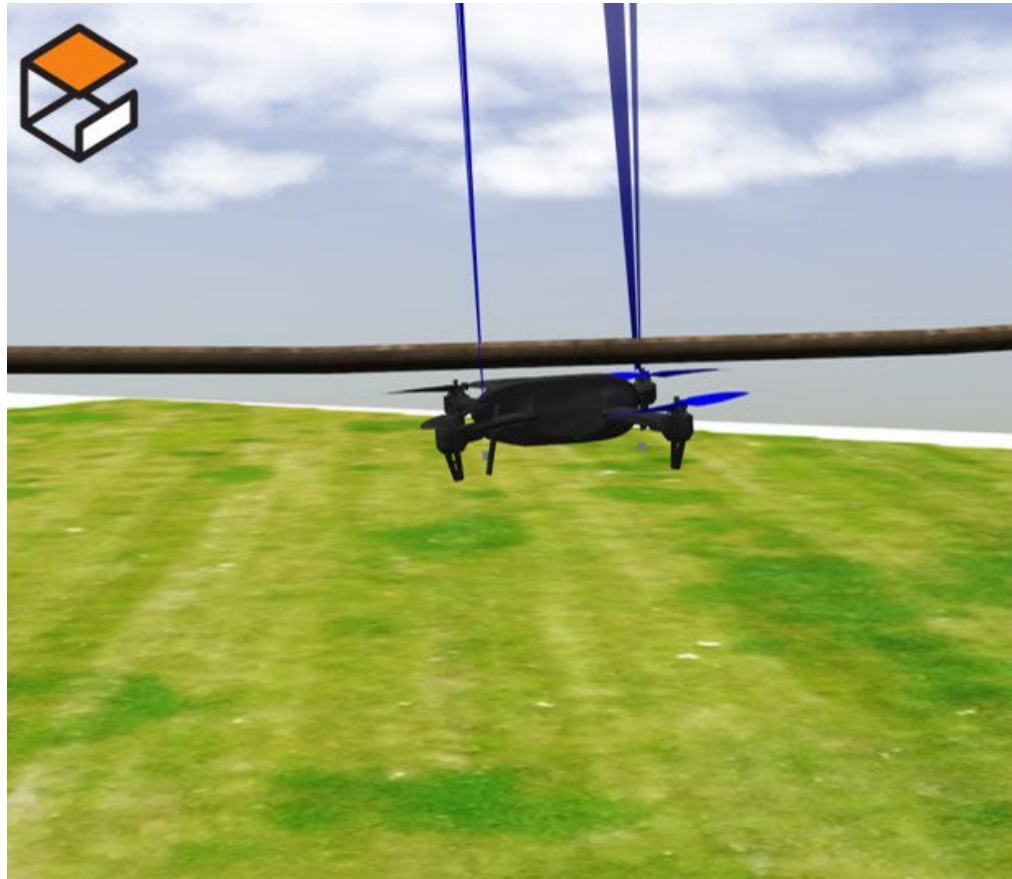
(2019-2022)



Drones4Energy



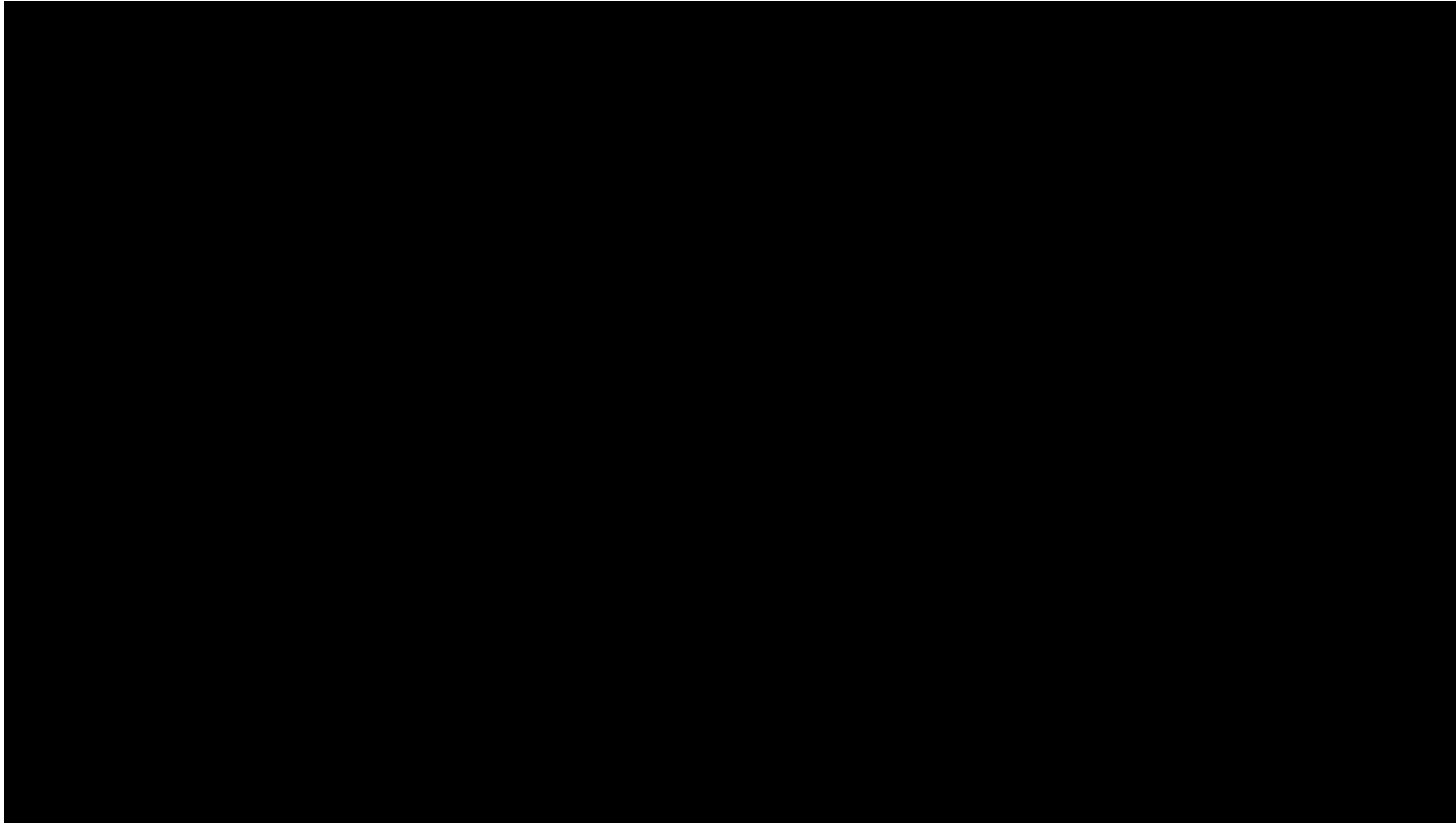
LOCATOR - Lightweight and Low-Cost Autonomous Drone System for Overhead Cable Detection and Soft Grasping



Autonomous Power Line Sensor Unit Deployment (Drones4Energy Drones)



AI Drone for Continuous Inspection



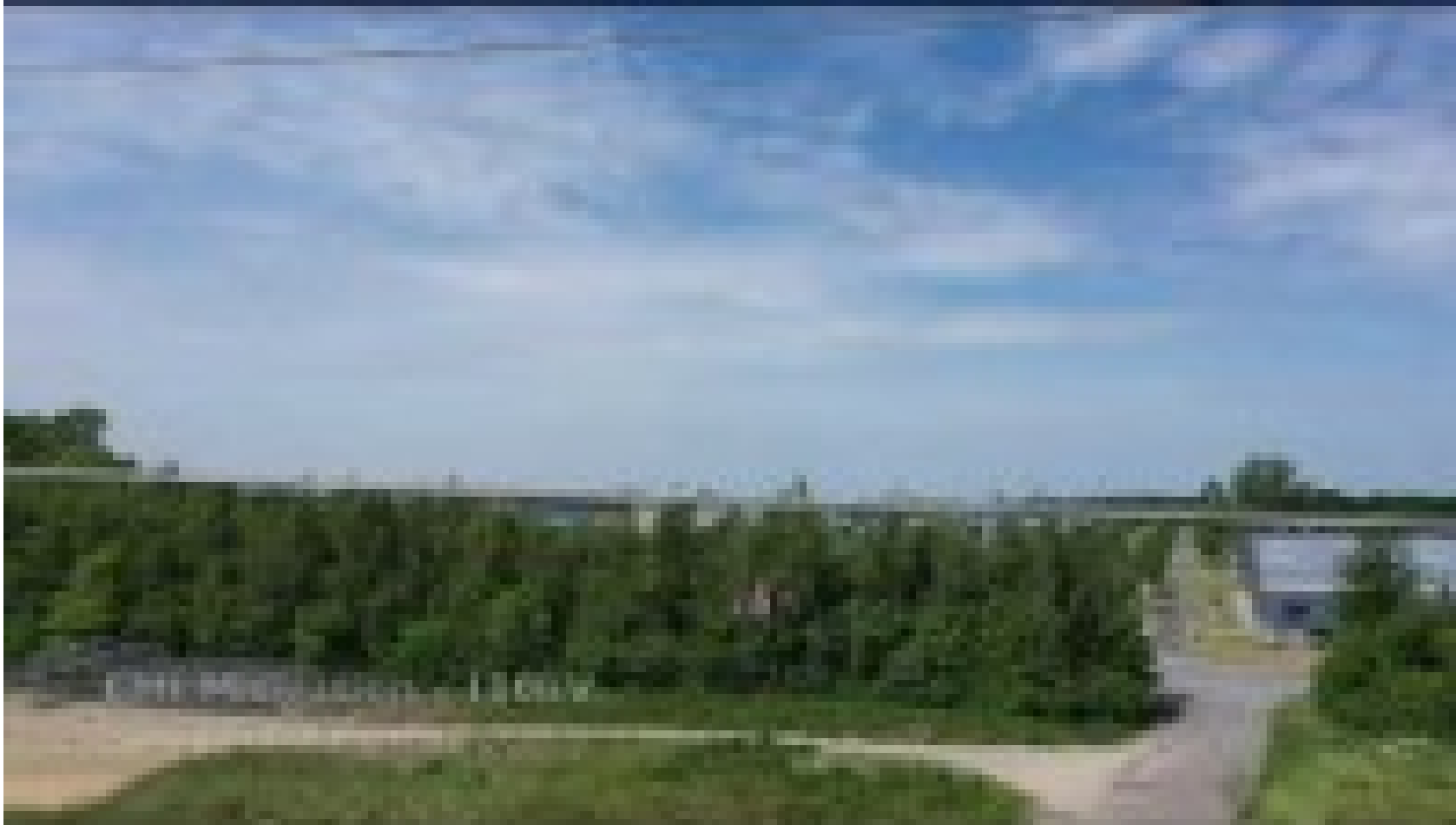
Iversen, Nicolai ; Schofield, Oscar Bowen ; Cousin, Linda ; Ayoub, Naeem ; Vom Bögel, Gerd ; Ebeid, Emad. / **Design, Integration and Implementation of an Intelligent and Self-recharging Drone System for Autonomous Power line Inspection**. 2021 IEEE/RSJ International Conference on Intelligent Robots and Systems. IROS, 2021.

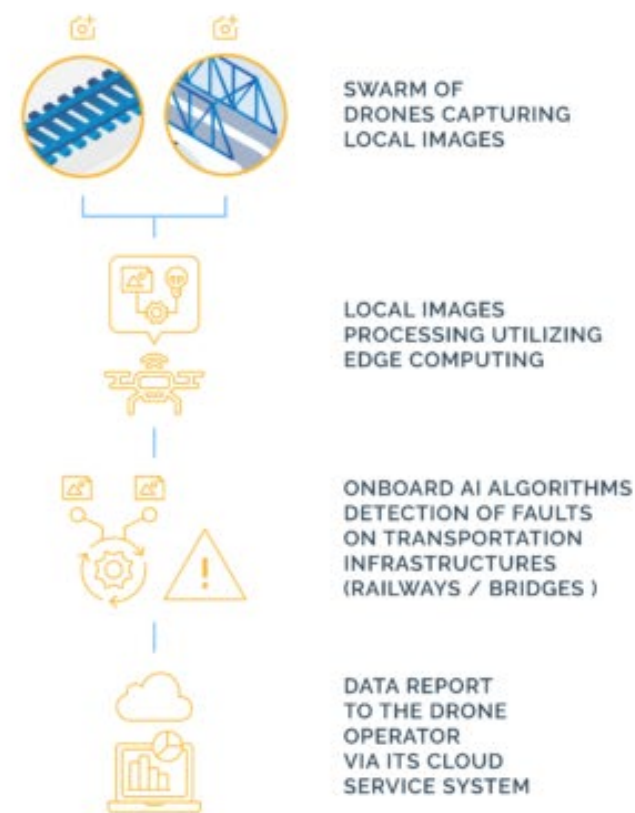
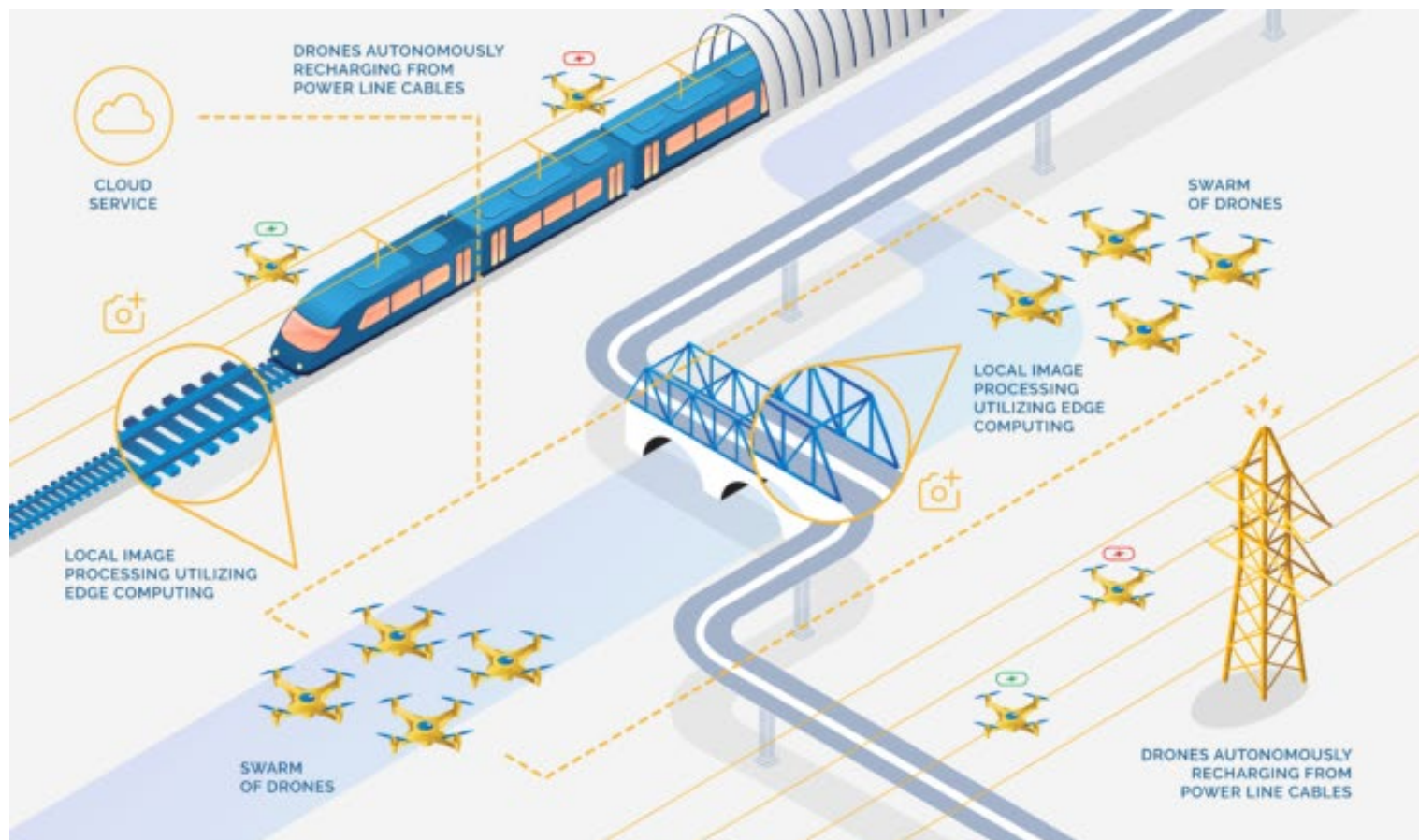
Patent: Emad Ebeid, **Failsafe powerline engagement system for a drone or for an aerial robot**, EP Patent WO2021048201

<https://www.youtube.com/watch?v=RPOxezvIBLk> 



Main Research Activities





Light-weight Sensors for Overhead Cable Detection

Dynamic measurements
from UAV in flight



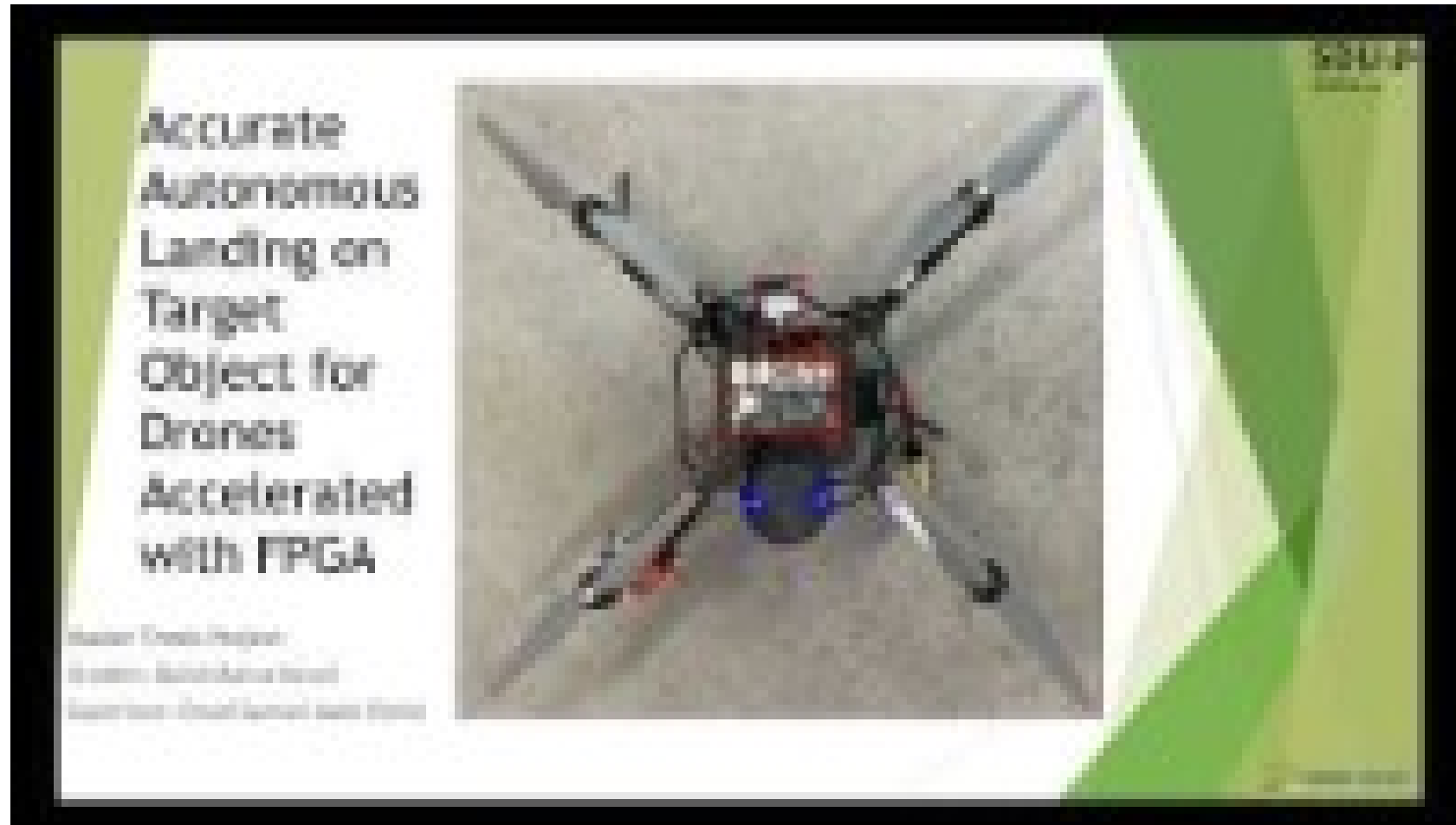
Malle, Nicolaj Haarhoj ; Nyboe, Frederik Falk ; Ebeid, Emad. / **Survey and Evaluation of Sensors for Overhead Cable Detection using UAVs**. 2021 International Conference on Unmanned Aircraft Systems, ICUAS 2021. IEEE, 2021. pp. 361-370 (2021 International Conference on Unmanned Aircraft Systems, ICUAS 2021).

<https://www.youtube.com/watch?v=keq51pOEn0k> 



This project has received funding from European Union's Horizon 2020 Research and Innovation Programme under Grant Agreement No°861111.

Master Thesis: Accurate Autonomous Landing on Target Object for Drones Accelerated with FPGA



Balint Kővári; Ebeid, Emad / **MPDrone: FPGA-based Platform for Intelligent Real-time Autonomous Drone Operations**. 2021 IEEE/RAS SSRR.

<https://youtu.be/halMdOPNrdU> YouTube



This project has received funding from European Union's Horizon 2020 Research and Innovation Programme under Grant Agreement No°861111.

Emad Samuel Malki Ebeid, University of Southern Denmark

Drone Infrastructure Inspection and Interaction Group (DIII)

<https://www.sdu.dk/diii>

Competencies:

- Drone embedded system design and integration
- Autonomous navigation and tracking of cables
- Disturbance rejection and EMI mitigation
- Energy harvesting and recharging from powerlines

Current participation in:

- Coordination of H2020 Drones4Safety project
- Coordination of IFD Drones4Energy project
- Partnering in H2020 Aerial-Core project



Emad Samuel M. Ebeid

Assoc. Prof., SDU
Embedded systems
and Electronics



Frederik Nyboe

PhD fellow, SDU UAS
Drone Design for
disturbance rejection



Nicolaj Malle

PhD fellow, SDU UAS
AI drones for
Autonomous navigation



Oscar Schofield

Research Assistant
Drone System Integration



Nicolai Iverson

Research Assistant
Mechanical Drone
Designer

Thank you

Emad Samuel Malki Ebeid
esme@mmmi.sdu.dk