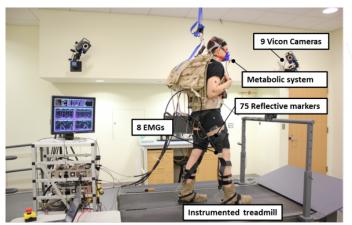
Gait Event Detection Using an LSTM Network 10-701 Project Presentation

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Introduction



from http://biodesign.seas.harvard.edu/soft-exosuits

Goal: Accurately detect gait events (heel strike, toe off) in video-based motion capture data of human walking gait

Introduction

- Problem: Sequence labeling
 - ▶ Input: 3D locus of 18 motion capture markers (54*N reals)
 - ► Output: {Left, Right} × {Heel Strike, Toe Off} (4*N bools)

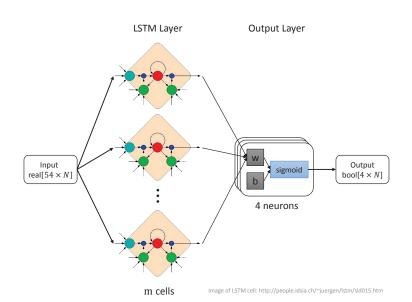
Dataset:

- ▶ 8 subjects × 3 trials × 10 000 samples @ 100 Hz
- Ground truth from force plates on treadmills

Our Approach

- Objectives (by order of priority):
 - 1. Gross mis-predictions should be avoided even with the presence of input noise
 - Number of manually-picked parameters (window size, threshold, filter cutoff, etc.) should be minimal
 - 3. Empirical feature-engineering should be minimal
 - 4. Algorithm should generalize to all (healthy) subjects regardless of training set used
- Proposed solution: LSTM-based RNN
 - Robust recognition of periodic patterns and precise timing
 - Can possibly exploit inter-gait-cycle dependence

Network architecture



Implementation

- ► Torch/Lua on 1 AWS EC2 GPU instance (g2.2xlarge)
- Start with LSTM code example by de Freitas
 - ► Heavily modified to adapt to our problem setup
 - ▶ Problem: Does not converge fast enough out of the box
 - Tweaks: Learning rate, mini-batch, regularization, etc.
- Further work:
 - Explore alternative network configurations
 - Improve time/space invariance
 - Generalize to unhealthy subjects and/or over-ground trials

Results

	devia	tion	mistal	mistake	
	mean	std	mean	std	
Foot velocity	4.84	3.74	2260.2	560.4	
Feed-forward NN	0.85	1.48	211.1	204.5	
LSTM	2.35	3.87	306.6	360.5	

Table 1: Comparison of results for N = 30, T = 2.5 s.

Results

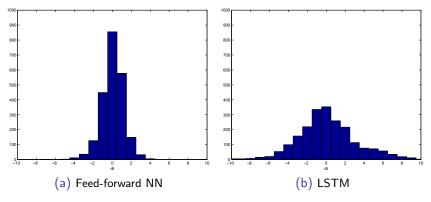


Figure 1: Absolute deviations, N = 30, T = 2.5 s.

Thank you for your attention!

Human Gait Cycle

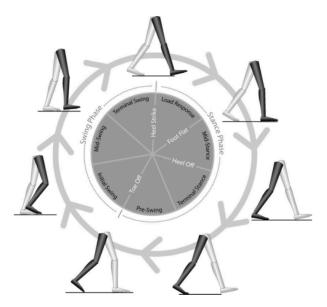


Figure 2: Gait events [Rueterbories et al., 2010] Figure 2: Gait events