

MATH 115A - SPRING 2022

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I. Fields and vector spaces

For the non-mathematician, linear algebra is the study of linear equations and linear transformations. For us, linear algebra will be the study of linear maps between vector spaces.

We should think of vector spaces as abstract objects with special structure that behaves nicely with respect to scalars, and linear maps are functions that preserve this special structure.

Definition: A field \mathbb{F} is a set with two operations

$$+ : \mathbb{F} \times \mathbb{F} \longrightarrow \mathbb{F} \quad \text{and} \quad \cdot : \mathbb{F} \times \mathbb{F} \longrightarrow \mathbb{F}$$

$$(a, b) \longmapsto a+b \qquad (a, b) \longmapsto a \cdot b$$

called sum and product respectively, such that for all $a, b, c \in \mathbb{F}$ we have:

(1) Commutativity: $a+b=b+a$ and $a \cdot b=b \cdot a$.

(2) Associativity: $(a+b)+c=a+(b+c)$ and $(a \cdot b) \cdot c=a \cdot (b \cdot c)$.

(3) Identity: there exist $0, 1 \in \mathbb{F}$ with $a+0=a$ and $a \cdot 1=a$.

(4) Inverses: when $a \neq 0$ there exist $-a, a^{-1} \in \mathbb{F}$ with $a+(-a)=0$ and $a \cdot a^{-1}=1$.

(5) Distributivity: $a \cdot (b+c)=a \cdot b+a \cdot c$.

The elements of a field are called scalars.

Example:

1. Some number sets are fields: \mathbb{Q} , \mathbb{R} , \mathbb{C} .
2. Some number sets are not fields: \mathbb{N} , \mathbb{Z} . (why?)
3. There are weird fields:

$$\mathbb{Q}[\sqrt{2}] = \{a + b\sqrt{2} \mid a, b \in \mathbb{Q}\}$$

$\mathbb{Z}_2 = \{[0], [1]\}$ is the field of integers mod 2, having:

$$0+1=1, \quad 0+0=0, \quad 1+1=0, \quad 0 \cdot 1=0, \quad 1 \cdot 1=1.$$

We can think of \mathbb{Z}_2 as \mathbb{Z} where we have declared that all even numbers are the same, and also that all odd numbers are the same:

$$2k \equiv 0 \quad \text{and} \quad 2k+1 \equiv 0 \quad \text{for all } k \in \mathbb{Z}.$$

$\mathbb{Z}_p = \{[0], [1], \dots, [p-1]\}$ for $p \in \mathbb{N}$ prime is the field of integers mod p .

We can think of \mathbb{Z}_p as \mathbb{Z} where we declare that two numbers are equal if and only if they have the same remainder when divided by p :

$$p \cdot k + j \equiv j \quad \text{for all } 0 \leq j < p \text{ and all } k \in \mathbb{Z}, \text{ so}$$

$[j] = \{ \text{integers with remainder } j \text{ upon division by } p \}$.

Definition: A vector space V over a field \mathbb{F} is a set with two operations:

$$+: V \times V \longrightarrow V \quad \text{and} \quad \cdot : F \times V \longrightarrow V$$

$$(x, y) \longmapsto x+y \quad (a, x) \longmapsto a \cdot x$$

called addition and scalar multiplication respectively, such that for all $x, y, z \in V$ and $a, b \in F$:

(1) Commutativity of addition: $x+y = y+x$.

(2) Associativity of addition: $(x+y)+z = x+(y+z)$.

(3) Identity in V : there exists $\vec{0} \in V$ with $x+\vec{0}=\vec{0}$.

(4) Inverses in V : there exists $-x \in V$ with $x+(-x)=\vec{0}$.

(5) Scalar identity: $1 \cdot x = x$. (do we have multiplicative inverses x^{-1} in V ?)

(6) Associativity of scalar multiplication: $a \cdot (b \cdot x) = (a \cdot b) \cdot x$.

(7) Distributivity of scalar multiplication over addition: $a \cdot (x+y) = a \cdot x + a \cdot y$.

(8) Distributivity of the sum over scalar multiplication: $(a+b) \cdot x = a \cdot x + b \cdot x$.

These properties are saying that the addition and multiplication by scalars in V behave

well with respect to the sum and product in F .

Remark: Alternatively, we could say that a vector space is a commutative group under

addition with associative and distributive scalar multiplication.

In particular, vector spaces are closed under finite sums and scalar multiplication: if

$x_1, \dots, x_n \in V$ and $a_1, \dots, a_n \in F$, then $a_1 x_1 + \dots + a_n x_n \in V$.

When $\mathbb{F} = \mathbb{R}$, we say that V is a real vector space. When $\mathbb{F} = \mathbb{C}$ we say that V is a complex vector space.

Examples:

1. $\mathbb{R}^n = \mathbb{R} \times \cdots \times \mathbb{R}$ is called the real n-space.

The elements in \mathbb{R}^n are n -tuples (r_1, \dots, r_n) with $r_1, \dots, r_n \in \mathbb{R}$.

The vector addition is done componentwise:

$$(r_1, \dots, r_n) + (s_1, \dots, s_n) = (r_1 + s_1, \dots, r_n + s_n)$$

The scalar multiplication is done componentwise:

$$\alpha \cdot (r_1, \dots, r_n) = (\alpha \cdot r_1, \dots, \alpha \cdot r_n)$$

Remark: Here we could replace the field \mathbb{R} by \mathbb{Q} , and everything would still make

sense. It is important to specify over which field we are working.

In fact, if we replace \mathbb{R} by \mathbb{Z} , things still make sense. When we work over

a ring instead of a field, we generalize vector spaces to the notion of modules.

2. Let \mathbb{F} be a field, let S be a set, let V be the set of functions from S to \mathbb{F} .

Namely elements $f \in V$ are functions of sets $f: S \rightarrow \mathbb{F}$.

The scalar multiplication $\alpha \cdot f$ is the function satisfying $(\alpha \cdot f)(x) = \alpha \cdot f(x)$.

The addition $f+g$ is the function satisfying $(f+g)(x) = f(x) + g(x)$.

$$\begin{aligned} a \cdot f : S &\longrightarrow \text{IF} \\ x &\longmapsto a \cdot f(x) \end{aligned}$$

$$\begin{aligned} f+g : S &\longrightarrow \text{IF} \\ x &\longmapsto f(x) + g(x) \end{aligned}$$

Many important examples arise in this way.

2.1. Let V be the set of continuous functions over \mathbb{R} or over \mathbb{C} , denoted $C(\mathbb{R})$ or $C(\mathbb{C})$.

2.2. Let V be the set of polynomials with coefficients in IF , denoted $\text{IF}[x]$. Recall that

$p(x) \in \text{IF}[x]$ has the form $p(x) = a_n x^n + \dots + a_1 x + a_0$ for $a_n, \dots, a_0 \in \text{IF}$.

2.3. Let V be the set of symmetric polynomials in n -variables, denoted $\text{Sym}_n(\text{IF})$.

The elements are polynomials in the variables x_1, \dots, x_n such that:

$$p(x_1, \dots, x_i, \dots, x_j, \dots, x_n) = p(x_1, \dots, x_j, \dots, x_i, \dots, x_n) \quad \text{for all } i, j \in \{1, \dots, n\}.$$

That is, exchanging two variables does not change the polynomial.

Fix $n=3$, then:

$$p(x_1, x_2, x_3) = x_1 + x_2 + x_3 \text{ is symmetric,}$$

$$q(x_1, x_2, x_3) = x_1 + x_2 \text{ is not symmetric since } q(x_1, x_3, x_2) = x_1 + x_3 \neq q(x_1, x_2, x_3).$$

$$r(x_1, x_2, x_3) = x_1 x_2 + 2x_1 x_3 + x_2 x_3 \text{ is not symmetric,}$$

$$S(x_1, x_2, x_3) = x_1x_2 + x_1x_3 + x_2x_3 \text{ is symmetric.}$$

3. Let \mathbb{F} be a field, let V be the set of $n \times n$ matrices with entries in \mathbb{F} , denoted $M_{n \times n}(\mathbb{F})$.

The matrix addition and scalar multiplication are both defined componentwise.

$$\begin{bmatrix} a_{11} & \dots & a_{1m} \\ \vdots & \ddots & \vdots \\ a_{m1} & \dots & a_{mm} \end{bmatrix} + \begin{bmatrix} b_{11} & \dots & b_{1m} \\ \vdots & \ddots & \vdots \\ b_{m1} & \dots & b_{mm} \end{bmatrix} = \begin{bmatrix} a_{11} + b_{11} & \dots & a_{1m} + b_{1m} \\ \vdots & & \vdots \\ a_{m1} + b_{m1} & \dots & a_{mm} + b_{mm} \end{bmatrix}$$

$$a \cdot \begin{bmatrix} a_{11} & \dots & a_{1m} \\ \vdots & \ddots & \vdots \\ a_{m1} & \dots & a_{mm} \end{bmatrix} = \begin{bmatrix} a \cdot a_{11} & \dots & a \cdot a_{1m} \\ \vdots & & \vdots \\ a \cdot a_{m1} & \dots & a \cdot a_{mm} \end{bmatrix}$$

The zero vector is the zero matrix.

$$\begin{bmatrix} 0 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & 0 \end{bmatrix}$$

In general, $M_{n \times n}(\mathbb{F})$ is not a field since we cannot multiply two $n \times n$ matrices.

4. Let V be the field of rational functions over \mathbb{F} , denoted $\mathbb{F}(x)$. Elements in $\mathbb{F}(x)$

are fractions of polynomials, namely $\frac{p(x)}{q(x)}$ with $p(x), q(x) \in \mathbb{F}[x]$. Now $\mathbb{F}[x]$ is a

vector space over \mathbb{F} , and $\mathbb{F}[x]$ is also a field on its own.

The vector addition is:

$$p(x) - q(x) = p(x)S(x) + q(x)T(x)$$

$$\frac{f(x)}{g(x)} + \frac{s(x)}{h(x)} = \frac{f(x)s(x) + g(x)h(x)}{g(x)h(x)}.$$

The scalar multiplication is:

$$a \cdot \frac{f(x)}{g(x)} = \frac{a \cdot f(x)}{g(x)}.$$

With these two operations, $\mathbb{F}(x)$ is a vector space over \mathbb{F} . Consider the sum:

$$\frac{p(x)}{q(x)} + \frac{r(x)}{s(x)} = \frac{p(x)s(x) + q(x)r(x)}{q(x)s(x)}$$

and the product:

$$\frac{p(x)}{q(x)} \cdot \frac{r(x)}{s(x)} = \frac{p(x)r(x)}{q(x)s(x)}.$$

With these two operations, $\mathbb{F}(x)$ is a field. The identities of $\mathbb{F}(x)$ are:

$$z(x) = 0 \text{ the zero, and } e(x) = 1 \text{ the one.}$$

Note that $\mathbb{F}(x)$ is closed since the sum and product give rational functions.

In fact, $\mathbb{F}(x)$ is also a vector space over $\mathbb{F}(x)$. The difference is that here

the scalars have changed from \mathbb{F} to $\mathbb{F}(x)$.

* Small aside on proof techniques:

We will mainly be using four techniques:

1. Induction: this is useful when proving something for all natural numbers.

Example: Prove that $\sum_{i=1}^n i = \frac{n(n+1)}{2}$.

This is true for $n=1$ since $1 = \frac{1 \cdot (1+1)}{2}$.

Suppose this is true for n . We now prove it for $n+1$:

$$\begin{aligned}\sum_{i=1}^{n+1} i &= \sum_{i=1}^n i + (n+1) = \frac{n \cdot (n+1)}{2} + (n+1) = \frac{n \cdot (n+1) + 2 \cdot (n+1)}{2} = \\ &= \frac{(n+1) \cdot (n+2)}{2} = \frac{(n+1) \cdot ((n+1)+1)}{2}.\end{aligned}\quad \square.$$

2. Using the definition: this is useful when we do not know much.

Example: Prove that \mathbb{Z}_2 is a field. We only have to check that all the axioms hold true.

3. Using theorems and other results: this is useful when we know a lot.

Example: Prove that every $p(x) \in \mathbb{C}[x]$ factors into linear terms.

Let n be the degree of $p(x)$. If $n=0, 1$ we are done. If $n \neq 0, 1$, by

the Fundamental Theorem of Algebra $p(x)$ has one root $a_1 \in \mathbb{C}$. Then

$x-a_1$ divides $p(x)$ so $p(x) = (x-a_1) \cdot q(x)$ with $q(x)$ of degree $n-1$. If

$n-1=1$ then $q(x) = x-a_2$ so $p(x) = (x-a_1)(x-a_2)$ and we are done. If

$n-1 \neq 1$, apply the Fundamental Theorem of Algebra again. Since at

every step we are lowering the degree by 1, we will repeat this exactly

n times, so we will have $p(x) = (x-a_1) \dots (x-a_n)$. Thus $p(x)$ factors

into linear terms, as desired. □.

4. Follow your nose: when we are given several hypothesis and we are asked to verify that a statement holds, often we have to "put all the hypothesis in a box, shake it up a bit, and our desired conclusion will fall out."

Example: Prove that $\sqrt{2}$ is not a rational number.

Suppose that $\sqrt{2}$ is rational. We could then write $\sqrt{2} = \frac{a}{b}$ for $a, b \in \mathbb{Z}$.

Then squaring this we obtain $2 = \frac{a^2}{b^2}$ so $2b^2 = a^2$. Thus a^2 is even.

Since even times even is even, and odd times odd is odd, a is even.

Hence there exists $k \in \mathbb{Z}$ with $a = 2k$, so $2b^2 = (2k)^2 = 4k^2$. This

means that $b^2 = 2k^2$, so as before b is even. All in all, we proved

that if $\sqrt{2} = \frac{a}{b}$ then a and b are both even. However, rational

numbers can be written in an irreducible way, that is, if $\sqrt{2} \in \mathbb{Q}$ then

there are $p, q \in \mathbb{Z}$ such that p and q do not share any divisors

and $\sqrt{2} = \frac{p}{q}$. This is a contradiction with what we just proved: p

and q both should be divisible by 2. Thus $\sqrt{2} \notin \mathbb{Q}$. □.

End of the aside. *

We now prove some properties of vector spaces.

Theorem 1: Let V be a vector space. If $x, y, z \in V$ and $x+z=y+z$ then $x=y$.

Proof: Since $z \in V$, by axiom 4 there is $-z \in V$ with $z+(-z)=0$. Hence:

$$x+z=y+z \Rightarrow (x+z)+(-z)=(y+z)+(-z)$$

Associativity (2) $\Rightarrow x+(z+(-z))=y+(z+(-z))$

Inverses (4) $\Rightarrow x+0=y+0$

Identity (3) $\Rightarrow x=y$.

□.

Corollary 2: Let V be a vector space. The vector $\vec{0} \in V$ is unique.

Proof: Suppose that there is a vector $\vec{0}' \in V$ such that $z+\vec{0}'=z$ for all $z \in V$.

Now $z+\vec{0}=z=z+\vec{0}'$ so by Theorem 1 we have $\vec{0}=\vec{0}'$. Every vector in

V that satisfies axiom 3 is equal to $\vec{0}$, so $\vec{0}$ is unique.

□.

Corollary 3: Let V be a vector space, fix $x \in V$. Then $-x \in V$ is unique.

Proof: Analogous to the above.

Given a mathematical object with structure, we always look at how that structure

reappears in mathematical objects inside the original one. For sets, these are subsets. For

vector spaces, we look at vector subspaces.

Definition: Let V be a vector space over IF . A vector subspace W of V is a subset of V

that is also a vector space with the addition and multiplication by scalars
inherited from V .

Example:

1. Over \mathbb{Q} we have $\mathbb{Q}^n \subsetneq \mathbb{R}^n \subsetneq \mathbb{C}^n$ are all subspaces of \mathbb{C}^n .
2. Over \mathbb{Q} we have $\mathbb{Q}[x] \subsetneq \mathbb{R}[x] \subsetneq \mathbb{C}[x]$ are all subspaces of $\mathbb{C}[x]$.
3. Over \mathbb{Q} we have $\text{Muxun}(\mathbb{Q}) \subsetneq \text{Muxun}(\mathbb{R}) \subsetneq \text{Muxun}(\mathbb{C})$ are all subspaces of $\text{Muxun}(\mathbb{C})$.
4. The symmetric polynomials in n variables $\text{Sym}_n(\text{IF})$ are a subspace of the vector space of all the polynomials in n variables $\text{IF}[x_1, \dots, x_n]$.

Theorem 4: Let V be a vector space. A subset W of V is a subspace of V if and only if

all the following hold:

(1) $\vec{0} \in W$.

(2) $x+y \in W$ for all $x, y \in W$.

(3) $a \cdot x \in W$ for all $a \in \text{IF}$.

Proof: (\Rightarrow) Suppose that W is a subspace of V . We want to show that (1), (2), (3)

hold. Since W is a vector space, there is $\vec{0}' \in W$ such that $w + \vec{0}' = w$ for

all $w \in W$. Since W is a subset of V then $w \in V$ so $w + \vec{0} = w$. Now by

Theorem 1 we have $\vec{0}' = \vec{0}$, so (1) holds. Since W is a vector space, (2) and

(3) hold by definition.

(\Leftarrow) Suppose that (1), (2), (3) hold. We have to verify that the following hold.

1. Commutativity of addition: it already is, $+$ is closed by (2).

2. Associativity of addition: it already is.

3. Identity in W : $\vec{0} \in W$ by (1).

4. Inverses in W : let $w \in W$, now $(-1) \cdot w \in W$ by (3), and $\underbrace{-w = (-1) \cdot w}_{\text{why? Prove it!}}$

5. Scalar identity: let $w \in W$, since $w \in V$ then $1 \cdot w = w$, and by (3) we

have $1 \cdot w \in W$, so $1 \cdot w = w$ is an equality in W .

6. Associativity of scalar multiplication: it already is.

7. Distributivity of scalar multiplication over addition: it already is.

8. Distributivity of the sum over scalar multiplication: it already is. \square .

This emphasizes that W needs to be a subset of V that is closed under the same addition

and multiplication by scalars as ν .

A particularly important vector space is $M_{n \times n}(\mathbb{F})$. We now recall some definitions:

1. Column vectors: $\begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} \in \mathbb{F}^n$ with $a_1, \dots, a_n \in \mathbb{F}$.

2. Row vectors: $(a_1, \dots, a_n) \in \mathbb{F}^n$ with $a_1, \dots, a_n \in \mathbb{F}$.

3. Square matrices: $M_{n \times n}(\mathbb{F})$, also denoted $M_n(\mathbb{F})$.

4. Diagonal matrices: $\begin{bmatrix} a_{11} & 0 \\ \vdots & \ddots \\ 0 & a_{nn} \end{bmatrix} \in M_{n \times n}(\mathbb{F})$ with $a_{ij}=0$ for $i \neq j$.

5. Upper triangular matrices: $\begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ 0 & a_{22} & a_{23} & \cdots & a_{2n} \\ 0 & 0 & a_{33} & \cdots & a_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & a_{nn} \end{bmatrix} \in M_{n \times n}(\mathbb{F})$ with $a_{ij}=0$ for $i > j$.

Similarly, we have lower triangular matrices.

5.1. Strictly upper triangular matrices: we instead require $a_{ij}=0$ for $i \geq j$, so the diagonal entries are also zero.

Similarly, we have strictly lower triangular matrices.

6. Zero matrix: $\begin{bmatrix} 0 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & 0 \end{bmatrix} \in M_{n \times n}(\mathbb{F})$ with $a_{ij}=0$ for all i, j .

7. Identity matrix: $I = \begin{bmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{bmatrix} \in M_{n \times n}(\mathbb{F})$ the diagonal matrix with $a_{ii}=1$

for all i , and $a_{ij}=0$ for $i \neq j$.

8. The zero matrix $0 = \lim_{\lambda \rightarrow 0} \lambda I$. $0 = \begin{bmatrix} a_{11} & \cdots & a_{1m} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mm} \end{bmatrix} \in M_{m \times n}(\mathbb{F})$ if $m < n$.

8. Transpose of a matrix : let $M = \begin{bmatrix} \vdots & \vdots \\ a_{11} & \cdots & a_{1n} \\ \vdots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix} \in M_{m \times n}(F)$ its transpose is

$$M^t = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \vdots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix} \in M_{n \times m}(F) \text{ the matrix with } a_{ji} \text{ in the } i\text{-th row and } j\text{-th column.}$$

9. Trace of a matrix : let $M = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \vdots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix} \in M_{m \times n}(F)$ its trace is :

$$\text{tr}(M) = \sum_{i=1}^n a_{ii}, \text{ the sum of the diagonal entries.}$$

Examples:

1. Symmetric matrices are a subspace of square matrices.

Recall that a matrix is symmetric when it is equal to its transpose.

Proof: We show that $\{A \in M_n(F) \mid A^t = A\}$ is a subspace of $M_n(F)$.

(1) $0 = 0^t$ so 0 is symmetric.

(2) If A, B are symmetric then :

$$(A + B)^t = A^t + B^t = A + B \text{ so } A + B \text{ is symmetric.}$$

(3) If A is symmetric and $c \in F$ then :

$$(cA)^t = c(A^t) = cA \text{ so } cA \text{ is symmetric. } \square.$$

2. Diagonal matrices are a subspace of square matrices.

3. Upper triangular matrices are a subspace of square matrices.

4. The set of the zero matrix $\{0\}$ is a subspace of $M_{n \times n}(\mathbb{F})$. We call it the

zero subspace, or the trivial subspace, of $M_{n \times n}(\mathbb{F})$.

5. The set of traceless matrices, namely matrices whose trace is zero, is a subspace of square matrices.

6. The set of polynomials with degree less than or equal to n , denoted $P_n(\mathbb{F})$ or $\mathbb{F}[x]$, is a subspace of the vector space of polynomials $\mathbb{F}[x]$. Here we note that the zero polynomial has any degree we want.

7. We have the inclusions of subspaces:

$$\mathbb{R} \subseteq \mathbb{R}_n[x] \subseteq \mathbb{R}[x] \subseteq \mathcal{C}(\mathbb{R}) \subseteq \mathcal{F}(\mathbb{R}, \mathbb{R})$$

Now that we know many examples of vector spaces, we would like to construct new vector subspaces from old ones.

Theorem 5: Let V be a vector space, let U and W be subspaces of V . Then $U \cap W$ is a

subspace of V .

Proof: We show that $U \cap W$ satisfies conditions (1), (2), (3) of Theorem 4.

(1) We want to show $\vec{o} \in U \cap W$. Since U and W are subspaces of V , then

$\vec{o} \in U$ and $\vec{o} \in W$, so $\vec{o} \in U \cap W$.

(2) We want to show $x+y \in U \cap W$ when $x, y \in U \cap W$. Suppose $x, y \in U \cap W$, then

$x, y \in U$ and $x, y \in W$. Since U and W are subspaces then $x+y \in U$ and

$x+y \in W$, so $x+y \in U \cap W$.

(3) We want to show $c \cdot x \in U \cap W$ when $x \in U \cap W$ and $c \in \mathbb{F}$. Suppose $x \in U \cap W$ and

$c \in \mathbb{F}$. Then $x \in U$ and $x \in W$. Since U and W are subspaces then $c \cdot x \in U$

and $c \cdot x \in W$, so $c \cdot x \in U \cap W$.

□.

However, $U \cup W$ is almost never a subspace of V . The correct way of "putting two vector

subspaces together" is by addition.

Definition: Let V be a vector space, let U and W be subspaces of V . The internal sum or

sum of U and W , denoted $U+W$, is:

$$U+W = \{u+w \mid u \in U, w \in W\}.$$

Theorem 6: Let V be a vector space, let U and W be subspaces of V . Then $U+W$ is a

vector subspace of V .

Proof: We show that $U+W$ satisfies conditions (1), (2), (3) of Theorem 4.

(1) Since $\vec{0} \in U$ and $\vec{0} \in W$, then $\vec{0} = \vec{0} + \vec{0} \in U+W$.

(2) Given $u+w, u'+w' \in U+W$ then :

$$(u+w) + (u'+w') = (u+u') + (w+w') \in U+W$$

since $u+u' \in U$ and $w+w' \in W$.

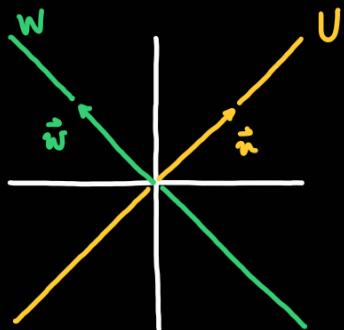
(3) Given $u+w \in U+W$ and $c \in \mathbb{F}$ then:

$$c \cdot (u+w) = c \cdot u + c \cdot w \in U+W$$

since $c \cdot u \in U$ and $c \cdot w \in W$. □.

Example: Let $V = \mathbb{R}^2$, let $\vec{u}, \vec{w} \in V$ be non-zero and non-parallel. Set $U = \{c \cdot \vec{u} \mid c \in \mathbb{R}\}$

and $W = \{c \cdot \vec{w} \mid c \in \mathbb{R}\}$, these are vector subspaces of V . Now $U+W = V$.



Definition: Let V be a vector space, let U and W be subspaces of V . We say that V is the

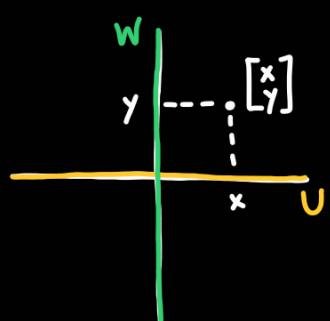
direct sum of U and W , denoted $V = U \oplus W$, when the following hold.

$$(1) \quad V = U+W.$$

$$(2) \quad U \cap W = \{\vec{0}\}.$$

Example:

1. Let $V = \mathbb{R}^2$, let $U = \left\{ \begin{bmatrix} x \\ 0 \end{bmatrix} \mid x \in \mathbb{R} \right\}$, let $W = \left\{ \begin{bmatrix} 0 \\ y \end{bmatrix} \mid y \in \mathbb{R} \right\}$. Then $V = U \oplus W$.



2. We have: $M_n(IF) = U_n(IF) \oplus D_n(IF) \oplus L_n(IF)$ where:

$U_n(IF)$ are the strictly upper triangular matrices,

$D_n(IF)$ are the diagonal matrices.

$L_n(IF)$ are the strictly lower triangular matrices,

because any square matrix $A \in M_n(IF)$ can be decomposed as:

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} & a_{2n} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{n-1,1} & a_{n-1,2} & \dots & a_{n-1,n} & a_{n-1,n} \\ a_{nn} & a_{nn} & \dots & a_{nn} & a_{nn} \end{bmatrix} = \begin{bmatrix} 0 & a_{12} & \dots & a_{1n} & a_{1n} \\ 0 & 0 & \dots & a_{2n} & a_{2n} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 0 & a_{nn} \\ 0 & 0 & \dots & 0 & 0 \end{bmatrix} +$$

$$+ \begin{bmatrix} a_{11} & 0 & \dots & 0 & 0 \\ 0 & a_{22} & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & a_{nn} & 0 \\ 0 & 0 & \dots & 0 & a_{nn} \end{bmatrix} + \begin{bmatrix} 0 & 0 & \dots & 0 & 0 \\ a_{21} & 0 & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{n-1,1} & a_{n-1,2} & \dots & 0 & 0 \\ a_{nn} & a_{nn} & \dots & a_{nn} & 0 \end{bmatrix}.$$

There is also a way of constructing a vector subspace from a collection of vectors.

Definition: Let V be a vector space. A vector $v \in V$ is said to be a linear combination of

the vectors $v_1, \dots, v_m \in V$ if there exist scalars $a_1, \dots, a_m \in F$ such that:

$$v = a_1 v_1 + \dots + a_m v_m.$$

The scalars $a_1, \dots, a_m \in F$ are also called coefficients.

Example: Let $V = \mathbb{Q}[x]$. Since: $3x^5 + 2x - 1 = (5x^6 + 3x^5 - 2) + 2 \cdot (x^6 + x) - (7x^6 + 1)$

then $v = 3x^5 + 2x - 1$ is a linear combination of $v_1 = 5x^6 + 3x^5 - 2$, $v_2 = x^6 + x$,

$v_3 = 7x^6 - 1$ with coefficients $a_1 = 1$, $a_2 = 2$, $a_3 = -1$.

Also: $3x^5 + 2x + 1 = 3 \cdot (x^5) + 2 \cdot (x) - (1)$ so $v = 3x^5 + 2x - 1$ is also a linear

combination of $w_1 = x^5$, $w_2 = x$, $w_3 = 1$ with coefficients $b_1 = 3$, $b_2 = 2$, $b_3 = -1$.

Definition: Let V be a vector space, let $\{v_1, v_2, \dots\} \subseteq V$ be a (possibly infinite) subset of V .

The span of this subset, denoted $\text{Span}\{v_1, v_2, \dots\}$, is the set of all linear combinations of $\{v_1, v_2, \dots\}$.

$$\text{Span}\{v_1, v_2, \dots\} = \{a_{11}v_1 + \dots + a_{1m}v_m \mid a_{11}, \dots, a_{1m} \in F\}.$$

Theorem 7: Let V be a vector space, let $\{v_1, v_2, \dots\} \subseteq V$ be a subset of V . Then

$\text{Span}\{v_1, v_2, \dots\}$ is a vector subspace of V .

Proof: We show that $\text{Span}\{v_1, v_2, \dots\}$ satisfies conditions (1), (2), (3) of Theorem 4.

(1) Note: $\vec{0} = 0 \cdot v_i \in \text{Span}\{v_1, v_2, \dots\}$.

(2) Given $u, v \in \text{Span}\{v_1, v_2, \dots\}$ then there exist scalars $a_{i1}, \dots, a_{in}, b_{j1}, \dots, b_{jn} \in F$

such that $u = \sum_{k=1}^n a_{ik} v_{ik}$ and $v = \sum_{k=1}^m b_{jk} v_{jk}$. Suppose that the

sets $\{v_{i1}, \dots, v_{in}\}$ and $\{v_{j1}, \dots, v_{jn}\}$ have common elements, without loss of generality we may assume that $v_{il} = v_{jl}, \dots, v_{il} = v_{jl}$ for some l .

Then:

$$\begin{aligned} u+v &= \sum_{k=1}^n a_{ik} v_{ik} + \sum_{k=1}^m b_{jk} v_{jk} = \\ &= \sum_{k=1}^l a_{ik} v_{ik} + \sum_{k=l+1}^n a_{ik} v_{ik} + \sum_{k=1}^l b_{jk} v_{jk} + \sum_{k=l+1}^m b_{jk} v_{jk} = \\ &= \sum_{k=1}^l (a_{ik} + b_{jk}) \cdot v_{ik} + \sum_{k=l+1}^n a_{ik} v_{ik} + \sum_{k=l+1}^m b_{jk} v_{jk} \end{aligned}$$

is a linear combination of $v_{i1}, \dots, v_{in}, v_{jl+1}, \dots, v_{jn}$, so $u+v \in \text{Span}\{v_1, v_2, \dots\}$.

(3) Given $u \in \text{Span}\{v_1, v_2, \dots\}$ and $c \in F$ then there exist scalars $a_{i1}, \dots, a_{in} \in F$

such that $u = \sum_{k=1}^n a_{ik} v_{ik}$. Then:

$$c \cdot u = c \cdot \left(\sum_{k=1}^n a_{ik} v_{ik} \right) = \sum_{k=1}^n c \cdot (a_{ik} v_{ik}) = \sum_{k=1}^n (c \cdot a_{ik}) \cdot v_{ik}$$

is a linear combination of v_{i1}, \dots, v_{in} , so $c \cdot u \in \text{Span}\{v_1, v_2, \dots\}$. \square

Definition: Let V be a vector space, let $\{v_1, v_2, \dots\} \subseteq V$ be a (possibly infinite) subset of V .

When $V = \text{Span}\{v_1, v_2, \dots\}$ we say that $\{v_1, v_2, \dots\}$ generate or span V . We call the

elements in $\{v_1, v_2, \dots\}$ the generators of V .

Example: Let $V = \mathbb{R}^3$ and $v_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, v_2 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, v_3 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$. Since any vector $\begin{bmatrix} a \\ b \\ c \end{bmatrix} \in \mathbb{R}^3$ can be expressed as:

$$\begin{bmatrix} a \\ b \\ c \end{bmatrix} = \frac{1}{2}(a+b-c)\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + \frac{1}{2}(a-b+c)\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + \frac{1}{2}(-a+b+c)\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

then $\mathbb{R}^3 = \text{Span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right\}$.

Definition: Let V be a vector space, let $v_1, \dots, v_n \in V$. We say that v_1, \dots, v_n are linearly

dependent if there exist scalars $a_1, \dots, a_n \in F$, at least one of them non-zero,

such that $a_1 v_1 + \dots + a_n v_n = \vec{0}$.

Example: Let $V = \mathbb{R}^3$ and $v_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, v_2 = \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix}, v_3 = \begin{bmatrix} 0 \\ 1/2 \\ 0 \end{bmatrix}$. Now:

$$v_2 - 2v_1 = \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix} - 2 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = 2v_3 \quad \text{so} \quad v_3 = \frac{1}{2}(v_2 - 2v_1) = \frac{1}{2}v_2 - v_1$$

and thus $-v_1 + \frac{1}{2}v_2 - v_3 = \vec{0}$, so v_1, v_2, v_3 are linearly dependent.

Definition: Let V be a vector space, let $v_1, \dots, v_n \in V$. We say that v_1, \dots, v_n are linearly

independent if they are not linearly dependent.

Remark: The vectors v_1, \dots, v_n are linearly independent if and only if when a linear

combination $a_1 v_1 + \dots + a_n v_n = \vec{0}$ in V then $a_1 = \dots = a_n = 0$ in F .

Example: Let V be a vector space, let $v \in V$, let $a \in F$.

1. The empty set is linearly independent.
2. A single vector $\{v\}$ is linearly independent if and only if $v \neq \vec{0}$.
3. A vector and a scalar multiple of that vector $\{v, av\}$ are linearly dependent.

Theorem 8: Let $v_1, \dots, v_n \in \mathbb{R}^n$. The vectors v_1, \dots, v_n are linearly independent if and only if

the matrix $\begin{bmatrix} 1 & & & 1 \\ v_1 & \dots & v_n \\ 1 & & & 1 \end{bmatrix}$ can be row reduced to the identity matrix.

Theorem 9: Let V be a vector space, let $\{v_1, \dots, v_n\} \subset V$ be a linearly independent subset,

let $v_{n+1} \in V$. The set $\{v_1, \dots, v_n, v_{n+1}\}$ is linearly independent if and only if

$$v_{n+1} \notin \text{Span}\{v_1, \dots, v_n\}.$$

Proof: (\Rightarrow) Suppose that $\{v_1, \dots, v_n, v_{n+1}\}$ is linearly independent. Additionally, assume

that $v_{n+1} \in \text{Span}\{v_1, \dots, v_n\}$, we want to achieve a contradiction. Since

$v_{n+1} \in \text{Span}\{v_1, \dots, v_n\}$ then there are scalars $a_1, \dots, a_n \in \mathbb{F}$, at least one of them

not zero, such that $v_{n+1} = a_1 v_1 + \dots + a_n v_n$. Thus $a_1 v_1 + \dots + a_n v_n + (-1) \cdot v_{n+1} = \vec{0}$

is a linear combination of elements in $\{v_1, \dots, v_{n+1}\}$ with at least one of the

coefficients non-zero. This means that $\{v_1, \dots, v_{n+1}\}$ is linearly dependent, a

contradiction. Since we reached a contradiction, our additional assumption of

$v_{n+1} \in \text{Span}\{v_1, \dots, v_n\}$ is false, and thus $v_{n+1} \notin \text{Span}\{v_1, \dots, v_n\}$.

(\Leftarrow) Suppose that $v_{n+1} \notin \text{Span}\{v_1, \dots, v_n\}$. Additionally, assume that $\{v_1, \dots, v_n, v_{n+1}\}$ is

linearly dependent, we want to achieve a contradiction. Since $\{v_1, \dots, v_n, v_{n+1}\}$ is

linearly dependent, then there are scalars $a_1, \dots, a_{n+1} \in \mathbb{F}$, at least one of them

not zero, such that $a_1 v_1 + \dots + a_n v_n + a_{n+1} v_{n+1} = \vec{0}$. If $a_{n+1} = 0$ then

$a_1 v_1 + \dots + a_n v_n = \vec{0}$ is a linear combination of elements in $\{v_1, \dots, v_n\}$ with at

least one non-zero coefficient, meaning that $\{v_1, \dots, v_n\}$ is linearly dependent.

However, $\{v_1, \dots, v_n\}$ is linearly independent by hypothesis, yielding a contradiction.

Thus $a_{n+1} = 0$ is not possible. If $a_{n+1} \neq 0$ then it has a multiplicative

inverse $\frac{1}{a_{n+1}}$ in \mathbb{F} , so we can rewrite $a_1 v_1 + \dots + a_n v_n + a_{n+1} v_{n+1} = \vec{0}$ as

$a_{n+1} v_{n+1} = -a_1 v_1 - \dots - a_n v_n$ and thus $v_{n+1} = \frac{-a_1}{a_{n+1}} v_1 + \dots + \frac{-a_n}{a_{n+1}} v_n$ where

at least one of $\frac{-a_1}{a_{n+1}}, \dots, \frac{-a_n}{a_{n+1}}$ is not zero. Thus $v_{n+1} \in \text{Span}\{v_1, \dots, v_n\}$,

a contradiction. Since we reached a contradiction both when $a_{n+1} = 0$ and

when $a_{n+1} \neq 0$, our original assumption of $\{v_1, \dots, v_n, v_{n+1}\}$ being linearly

dependent is false, and thus $\{v_1, \dots, v_n, v_{n+1}\}$ is linearly independent. \square .

Corollary 10: Let V be a vector space, let $S \subset V$ be a (not necessarily finite) set of

linearly independent vectors, let $v \in V$. Then the set $S \cup \{v\}$ is linearly independent if and only if $v \notin \text{Span}(S)$.

Examples:

1. Let $V = \mathbb{R}^n$, let e_i be the vector with a 1 in the i -th entry and 0 in all other

entries, so for $i=1, \dots, n$ we have $e_1 = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \dots, e_n = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{bmatrix}$. Then e_1, \dots, e_n are

linearly independent and $\mathbb{R}^n = \text{Span}\{e_1, \dots, e_n\}$. These e_1, \dots, e_n are known as the

standard generators of \mathbb{R}^n .

2. Let $V = M_2(\mathbb{C})$, $M_1 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ and $M_2 = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$. Then M_1 and M_2 are linearly

independent, since having scalars $a, b \in \mathbb{C}$ with $aM_1 + bM_2 = \vec{0}$ means:

$$a \cdot \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + b \cdot \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}, \text{ namely } \begin{bmatrix} a+b & 0 \\ 0 & a-b \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

hence $a+b=0$ and $a-b=0$, so $a=b=0$.

3. Let $V = \mathbb{R}[x]$. Then $\{1, x, x^2, \dots\}$ is a linearly independent set. This can be proven

by induction: suppose that there are exponents $n \in \mathbb{N}$ with x^n being a linear

combination of monomials of lower degree, namely $x^n \in \text{Span}\{1, x, \dots, x^{n-1}\}$.

First, if $n=1$, this would mean $x \in \text{Span}\{1\}$. Thus $x=a \cdot 1$ for some

non-zero coefficient $a \in \mathbb{R}$. Evaluating at $x=0$ this gives $0=a$, a contradiction.

Hence $x \notin \text{Span}\{1\}$ and thus by Theorem 9 the set $\{1, x\}$ is linearly independent.

Suppose the statement is true for $n-1$, namely the set $\{1, x, \dots, x^{n-1}\}$ is

linearly independent. We now prove the statement for n .

Suppose that $x^n \in \text{Span}\{1, x, \dots, x^{n-1}\}$. Then for some non-zero coefficients

$a_0, \dots, a_{n-1} \in \mathbb{R}$ we have $x^n = a_0 \cdot 1 + a_1 \cdot x + \dots + a_{n-1} \cdot x^{n-1}$. Evaluating at $x=0$

this gives $0 = a_0$, so in fact we have $x^n = a_1 \cdot x + \dots + a_{n-1} \cdot x^{n-1}$. This yields

$x \cdot x^{n-1} = x \cdot (a_1 + \dots + a_{n-1} \cdot x^{n-2})$ and thus $x^{n-1} = a_1 + \dots + a_{n-1} \cdot x^{n-2}$. Hence

$x^{n-1} \in \text{Span}\{1, x, \dots, x^{n-2}\}$, so by Theorem 9 the set $\{1, x, \dots, x^{n-1}\}$ is linearly

dependent. This is a contradiction with the induction hypothesis, which was

that $\{1, x, \dots, x^{n-1}\}$ is linearly independent. Thus our original assumption

of $x^n \in \text{Span}\{1, x, \dots, x^{n-1}\}$ is false, meaning that $x^n \notin \text{Span}\{1, x, \dots, x^{n-1}\}$.

Hence by Theorem 9 the set $\{1, x, \dots, x^n\}$ is linearly independent.

To finish the reasoning, suppose that $\{1, x, x^2, \dots\}$ is linearly dependent,

we want to achieve a contradiction. Then there are non-zero coefficients

$a_{i_1}, \dots, a_{i_m} \in \mathbb{R}$ such that $a_{i_1} \cdot x^{i_1} + \dots + a_{i_m} \cdot x^{i_m} = 0$, which can be rearranged

as $x = \frac{a_1}{a_{in}} \cdot x^1 + \dots + \frac{a_n}{a_{in}} \cdot x^n$. Hence $x \in \text{Span}\{x^1, \dots, x^n\}$, in

particular $x^{in} \in \text{Span}\{1, x, \dots, x^{in-1}\}$, so by Theorem 9 the set $\{1, x, \dots, x^{in-1}, x^{in}\}$

is linearly dependent, so the set $\{1, x, \dots, x^{in-1}, x^{in-1+1}, \dots, x^{in}\}$ is linearly

dependent. This is a contradiction, since we just proved that the set

$\{1, x, \dots, x^n\}$ is linearly independent for all $n \in \mathbb{N}$. Thus our assumption that

the set $\{1, x, x^2, \dots\}$ is linearly dependent is false, meaning that the set

$\{1, x, x^2, \dots\}$ is linearly independent.

4. The vectors $\{(-2, 0, 3), (1, 3, 0), (2, 4, -1)\}$ are linearly dependent. We consider the

matrix with columns $(-2, 0, 3), (1, 3, 0), (2, 4, -1)$, we row reduce, and we obtain:

$$\begin{bmatrix} -2 & 1 & 2 \\ 0 & 3 & 4 \\ 3 & 0 & 1 \end{bmatrix} \xrightarrow{R_1 + R_3} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 3 & 4 \\ 3 & 0 & -1 \end{bmatrix} \xrightarrow{R_3 - 3R_1} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 3 & 4 \\ 0 & -3 & -4 \end{bmatrix} \xrightarrow{R_3 + R_2} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 3 & 4 \\ 0 & 0 & 0 \end{bmatrix}$$

This matrix in row-reduced echelon form is not the identity matrix, so the vectors

$(-2, 0, 3), (1, 3, 0), (2, 4, -1)$ are not linearly independent by Theorem 8.

5. Solve the system of linear equations:

$$3x_1 - 7x_2 + 4x_3 = 10$$

$$x_1 - 2x_2 + x_3 = 3$$

$$2x_1 - x_2 - 2x_3 = 6.$$

We can rewrite this system as an equation of matrices:

$$\begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix}x_1 + \begin{bmatrix} -7 \\ -1 \\ -2 \end{bmatrix}x_2 + \begin{bmatrix} 4 \\ 1 \\ -2 \end{bmatrix}x_3 = \begin{bmatrix} 10 \\ 3 \\ 6 \end{bmatrix} \quad \text{equivalently} \quad \begin{bmatrix} 3 & -7 & 4 \\ 1 & -2 & 1 \\ 2 & -1 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 10 \\ 3 \\ 6 \end{bmatrix}.$$

This system will have a unique solution if and only if the vectors $(3, 1, 2)$, $(-7, -1, -2)$, $(4, 1, 2)$ are linearly independent. We use row reduction to find it.

$$\left[\begin{array}{ccc|c} 3 & -7 & 4 & 10 \\ 1 & -2 & 1 & 3 \\ 2 & -1 & -2 & 6 \end{array} \right] \xrightarrow{\substack{R_3 - 2R_2 \\ R_1 - R_3}} \left[\begin{array}{ccc|c} 1 & -6 & 6 & 4 \\ 1 & -2 & 1 & 3 \\ 0 & 3 & -4 & 0 \end{array} \right] \xrightarrow{R_2 - R_1} \left[\begin{array}{ccc|c} 1 & -6 & 6 & 4 \\ 0 & 4 & -5 & -1 \\ 0 & 3 & -4 & 0 \end{array} \right] \xrightarrow{\substack{R_1 + 2R_3 \\ R_2 - R_3}} \left[\begin{array}{ccc|c} 1 & 0 & -2 & 4 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 0 \end{array} \right].$$

$$\left[\begin{array}{ccc|c} 1 & 0 & -2 & 4 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 0 \end{array} \right] \xrightarrow{\substack{R_3 - 3R_2 \\ -R_3}} \left[\begin{array}{ccc|c} 1 & 0 & -2 & 4 \\ 0 & 1 & -1 & -1 \\ 0 & 0 & 1 & -3 \end{array} \right] \xrightarrow{\substack{R_1 + 2R_3 \\ R_2 + R_3}} \left[\begin{array}{ccc|c} 1 & 0 & 0 & -2 \\ 0 & 1 & 0 & -4 \\ 0 & 0 & 1 & -3 \end{array} \right].$$

Hence $x_1 = -2$, $x_2 = -4$, $x_3 = -3$.

In fact, we always have $V = \text{Span}(V)$ for all vector spaces V . The question to

ask is whether there is a subset $S \subset V$ such that $V = \text{Span}(S)$ and such

that S has the minimum possible number of elements. We call those subsets a

basis of the vector space V .

Definition: Let V be a vector space. A subset $\{v_1, v_2, \dots\} \subset V$ is called a basis of V

when $V = \text{Span}\{v_1, v_2, \dots\}$ and $\{v_1, v_2, \dots\}$ is linearly independent.

Examples:

1. Let $V = \mathbb{F}^n$, let e_i be the vector with a 1 in the i -th entry and 0 in all other

entries, so for $i=1, \dots, n$ we have $e_1 = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \dots, e_n = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{bmatrix}$. Then e_1, \dots, e_n are

linearly independent and $\text{IF}^n = \text{Span}\{e_1, \dots, e_n\}$, so $\{e_1, \dots, e_n\}$ is a basis of IF^n .

2. Let $V = \text{IF}[x]$, the set $\{1, x, x^2, \dots\}$ is a basis of $\text{IF}[x]$.

3. Let $V = \text{IF}_n[x]$ be the vector space of polynomials of degree at most n ,

the set $\{1, x, \dots, x^n\}$ is a basis of $\text{IF}_n[x]$.

4. Let $V = M_{n \times n}(\text{IF})$, let E_{ij} be the matrix with a 1 in the ij -th entry

and 0 in all other entries. The set $\{E_{ij}\}_{\substack{1 \leq j \leq n \\ 1 \leq i \leq n}}$ is a basis of $M_{n \times n}(\text{IF})$.

Theorem 11: Let V be a vector space. Let β be a finite set that is also a basis

of V . Let β' be another basis of V . Then β and β' have the same

number of elements, namely $|\beta| = |\beta'|$.

The above result is a consequence of the Replacement Theorem and of Theorem 9.

In fact, Theorem 11 also holds when β is infinite. This enables the following

definition.

Definition: Let V be a vector space, let β be a basis of V . The dimension of V ,

denoted $\dim_{\text{IF}}(V)$, is the number of elements in β .

A vector space can be finite dimensional or infinite dimensional.

Examples:

1. $\dim_{\mathbb{R}}(\mathbb{R}^n) = n$.

2. $\dim_{\mathbb{R}}(\mathbb{C}^n) = 2n, \dim_{\mathbb{C}}(\mathbb{C}^n) = n$.

3. $\dim_{\mathbb{F}}(\text{Mat}_{m,n}(\mathbb{F})) = n \cdot m$.

4. $\dim_{\mathbb{F}}(\mathbb{F}[x]) = |\mathbb{N}|$.

Theorem 12: Let V be a vector space. The set $\{v_1, \dots, v_n\}$ is a basis of V if and

only if every $v \in V$ can be expressed as a linear combination $v = a_1v_1 + \dots + a_nv_n$

with $a_1, \dots, a_n \in \mathbb{F}$ in an unique way. Namely if $a_1v_1 + \dots + a_nv_n = b_1v_1 + \dots + b_nv_n$

for $a_1, \dots, a_n, b_1, \dots, b_n \in \mathbb{F}$ then $a_1 = b_1, \dots, a_n = b_n$.

We can now answer the question of the existence of basis: every vector space has

a basis.

Theorem 13: Let V be a vector space, $V = \text{Span}\{v_1, \dots, v_n\}$. Then there exists

a subset $\beta \subseteq \{v_1, \dots, v_n\}$ that is a basis of V .

Proof: We prove this by starting with the empty set, and adding one vector at a time.

Let n be the number of vectors spanning V , namely $V = \text{Span}\{v_1, \dots, v_n\}$. If $n=0$

then $V = \text{Span}\{\}$. Now $v=0$ and $\beta=\{\}$ is a basis. If $n=1$ then $V = \text{Span}\{v_1\}$.

Now if $v_i = \vec{0}$ then $V = 0$ and $\beta = \{\}$ is a basis, and if $v_i \neq \vec{0}$ then $V \neq 0$ and

$\beta = \{v_i\}$ is a basis. If $n \neq 0, 1$ then $V = \text{Span}\{v_1, \dots, v_n\}$. Consider $\text{Span}\{v_i\} \subseteq V$, if

$\text{Span}\{v_i\} = V$ then $\beta = \{v_i\}$ is a basis. If $\text{Span}\{v_i\} \neq V$ check whether v_2 is in

$\text{Span}\{v_i\}$. If $v_2 \notin \text{Span}\{v_i\}$ then consider $\text{Span}\{v_i, v_2\} \subseteq V$ with $\beta = \{v_i, v_2\}$ as

potential basis. If $v_2 \in \text{Span}\{v_i\}$ check whether v_3 is in $\text{Span}\{v_i\}$.

Repeating this process, we obtain at every step a subset $\{v_{i_1}, v_{i_2}, \dots, v_{i_k}\} \subseteq \{v_1, \dots, v_n\}$

that is linearly independent. Moreover since at every step we always have that the

vectors omitted in the candidate basis are in the span of the candidate basis,

$\text{Span}\{v_{i_1}, \dots, v_{i_k}\} \supseteq \text{Span}\{v_1, \dots, v_n\} = V$ and thus $V = \text{Span}\{v_{i_1}, \dots, v_{i_k}\}$ so

$\beta = \{v_{i_1}, \dots, v_{i_k}\}$ is a basis of V . Since we are only checking a finite number of

conditions, because $\{v_1, \dots, v_n\}$ is finite, this process terminates. \square .

This proves that a finitely generated vector space has a basis. It does not say that

infinitely generated vector spaces have a basis; although that statement is true, it requires

a different proof.

Remark: There are several important results related to Theorem 13.

1. Any finite spanning set can be reduced to a basis.

2. Any spanning set with more vectors than $\dim_{\mathbb{R}}(V)$ is not a basis.

3. Any set with fewer vectors than $\dim_{\mathbb{R}}(V)$ does not span V .

Example: Let $V = \mathbb{R}^3$, let $S = \{(2, -3, 5), (8, -12, 20), (1, 0, -2), (0, 2, -1), (7, 2, 0)\}$. Check if

we can extract a basis of V from S , and do so.

Since \mathbb{R}^3 has dimension 3, a basis for \mathbb{R}^3 has exactly 3 vectors. To build a basis,

we follow the proof of Theorem 13:

Step 1: Pick two vectors in S that are not linearly dependent.

Since $(2, -3, 5) \neq a \cdot (1, 0, -2)$ for all $a \in \mathbb{R}$, these are enough.

Step 2: Pick one vector in S that is not in $\text{Span}\{(2, -3, 5), (1, 0, -2)\}$. We can

simplify this a bit further using row reduction:

$$\left[\begin{array}{ccc} 2 & -3 & 5 \\ 1 & 0 & -2 \end{array} \right] \xrightarrow{R_1 - 2R_2} \left[\begin{array}{ccc} 0 & -3 & 9 \\ 1 & 0 & -2 \end{array} \right] \xrightarrow{\frac{-1}{3}R_1} \left[\begin{array}{ccc} 0 & 1 & -3 \\ 1 & 0 & -2 \end{array} \right]$$

and thus $\text{Span}\{(2, -3, 5), (1, 0, -2)\} = \text{Span}\{(0, 1, -3), (1, 0, -2)\}$ so we

immediately see that:

$$(8, -12, 20) \in \text{Span}\{(0, 1, -3), (1, 0, -2)\},$$

$$(0, 2, -1), (7, 2, 0) \notin \text{Span} \{(0, 1, -3), (1, 0, -2)\}.$$

Thus $P = \{(2, -3, 5), (1, 0, -2), (0, 2, -1)\}$ and $P' = \{(2, -3, 5), (1, 0, -2), (7, 2, 0)\}$ are basis of \mathbb{R}^3 .

* Aside on cosets.

A fundamental construction in mathematics is the concept of equivalence, which gives relations between objects. One of the embodiments of equivalence relations are cosets.

Definition: Let V be a vector space, let $W \subseteq V$ be a vector subspace, let $v \in V$. The set

$v + W = \{v + w \mid w \in W\}$ is called a coset.

In general cosets are not vector subspaces of V , just subsets.

Definition: Let V be a vector space, let $W \subseteq V$ be a vector subspace. The set formed

by the sets $v + W$ for $v \in V$ is called the quotient space of V modulo W ,

denoted $\frac{V}{W}$. Namely, $\frac{V}{W} = \{v + W \mid v \in V\}$.

Theorem 14: Let V be a vector space, let $W \subseteq V$ be a vector subspace. The set $\frac{V}{W}$ is

a vector space over \mathbb{F} with the operations:

$$+ : \frac{V}{W} \times \frac{V}{W} \longrightarrow \frac{V}{W} \quad \text{and} \quad \cdot : \mathbb{F} \times \frac{V}{W} \longrightarrow \frac{V}{W} .$$

$$(v_1 + W, v_2 + W) \mapsto (v_1 + v_2) + W \quad (a, v + W) \mapsto (a \cdot v) + W$$

Example: Let $V = \mathbb{R}^3$, let $W = \text{Span} \left\{ \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\} = \left\{ \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \mid r \in \mathbb{R} \right\}$. We know that any vector v

in \mathbb{R}^3 has the form $\begin{bmatrix} a \\ b \\ c \end{bmatrix}$ with $a, b, c \in \mathbb{R}$, so such a vector is in W if and only if $b = c = 0$. Now:

$$v + W = \left\{ \begin{bmatrix} a \\ b \\ c \end{bmatrix} + \begin{bmatrix} r \\ 0 \\ 0 \end{bmatrix} \mid r \in \mathbb{R} \right\} = \left\{ \begin{bmatrix} a+r \\ b \\ c \end{bmatrix} \mid r \in \mathbb{R} \right\}.$$

In particular if $v \in W$ then it has the form $\begin{bmatrix} a \\ 0 \\ 0 \end{bmatrix}$ for some $a \in \mathbb{R}$, hence:

$$v + W = \left\{ \begin{bmatrix} a \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} r \\ 0 \\ 0 \end{bmatrix} \mid r \in \mathbb{R} \right\} = \left\{ \begin{bmatrix} a+r \\ 0 \\ 0 \end{bmatrix} \mid r \in \mathbb{R} \right\} = \left\{ \begin{bmatrix} s \\ 0 \\ 0 \end{bmatrix} \mid s \in \mathbb{R} \right\} = W.$$

The space \mathbb{V}/W is formed by the sets:

$$\begin{bmatrix} 0 \\ b \\ c \end{bmatrix} + W = \left\{ \begin{bmatrix} r \\ b \\ c \end{bmatrix} \mid r \in \mathbb{R} \right\} \quad \text{for each choice of } b, c \in \mathbb{R}.$$

Now \mathbb{V}/W is spanned by the two sets $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + W$ and $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} + W$, and they are linearly

independent since for all $s \in \mathbb{R}$:

$$s \cdot \left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + W \right) = \left(s \cdot \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right) + W = \begin{bmatrix} 0 \\ s \\ 0 \end{bmatrix} + W \quad \text{is different to } \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} + W.$$

Hence $\left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + W, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} + W \right\}$ is a basis of \mathbb{V}/W .

Moreover, the set W is the zero vector in \mathbb{V}/W .

End of the aside. *

Theorem 15: (Replacement Theorem). Let V be a vector space, $V = \text{Span}\{v_1, \dots, v_n\}$,

let $\{u_1, \dots, u_m\} \subset V$ be linearly independent. Then:

1) The cardinality of $\{u_1, \dots, u_m\}$ is, at most, the cardinality of $\{v_1, \dots, v_n\}$.

Namely $m \leq n$.

2) There is a subset $\{v_{i_1}, \dots, v_{i_{n-m}}\} \subseteq \{v_1, \dots, v_n\}$ containing $n-m$ vectors

such that $V = \text{Span}\{u_1, \dots, u_m, v_{i_1}, \dots, v_{i_{n-m}}\}$.

Proof: We use induction on m . Suppose first that $m=0$, now $0 \leq n$ and setting

$v_{i_j} = v_j$ for $j=1, \dots, n$ then $V = \text{Span}\{v_1, \dots, v_n\} = \text{Span}\{v_{i_1}, \dots, v_{i_{n-0}}\}$, as

desired. Suppose second that the statement holds for $m-1$, namely given any

linearly independent set with $m-1$ elements $\{w_1, \dots, w_{m-1}\}$ then $m-1 \leq n$ and

there is a subset $\{v_{i_1}, \dots, v_{i_{n-(m-1)}}\} \subseteq \{v_1, \dots, v_n\}$ such that

$V = \text{Span}\{w_1, \dots, w_{m-1}, v_{i_1}, \dots, v_{i_{n-(m-1)}}\}$. We now prove that the statement

holds for m . Let $\{u_1, \dots, u_m\} \subset V$ be linearly independent, then $\{u_1, \dots, u_{m-1}\}$

is linearly independent, so by induction hypothesis we have $m-1 \leq n$ and

a subset $\{v_{i_1}, \dots, v_{i_{n-m+1}}\} \subseteq \{v_1, \dots, v_n\}$ with

$V = \text{Span}\{u_1, \dots, u_{m-1}, v_{i_1}, \dots, v_{i_{n-m+1}}\}$. Since $u_m \in V$, we can write:

$$u_m = a_1 u_1 + \dots + a_{m-1} u_{m-1} + a_m v_{ij} + \dots + a_n v_{i,n-m+1}$$

where $a_1, \dots, a_m \in \mathbb{F}$, at least one of them is not zero. If $n=m-1$ then

this can be simplified to $u_m = a_1 u_1 + \dots + a_{m-1} u_{m-1}$, where at least one

of the coefficients is not zero. Thus $u_m \in \text{Span}\{u_1, \dots, u_{m-1}\}$ so by

Theorem 9 then $\{u_1, \dots, u_{m-1}, u_m\}$ is linearly dependent, a contradiction.

If $n \neq m-1$, since we know $m-1 \leq n$, then $m-1 < n$ so $m \leq n$, giving

the first part of the result. Moreover if all the coefficients a_m, \dots, a_n

are zero then $u_m = a_1 u_1 + \dots + a_{m-1} u_{m-1}$, where at least one of the

coefficients is not zero, giving a contradiction as before. Thus at least one

of the coefficients a_m, \dots, a_n is not zero, say $a_j \neq 0$ for $m \leq j \leq n$. Thus

we can rearrange $u_m = a_1 u_1 + \dots + a_{m-1} u_{m-1} + a_m v_{ij} + \dots + a_n v_{i,n-m+1}$ as:

$$v_{ij} = -\frac{a_1}{a_j} u_1 - \dots - \frac{a_{m-1}}{a_j} u_{m-1} + \frac{1}{a_j} u_m$$

$$- \frac{a_m}{a_j} v_{ij} - \dots - \frac{a_{(m-1)+(j-1)}}{a_j} v_{ij-1} - \frac{a_{(m-1)+(j+1)}}{a_j} v_{ij+1} - \dots - \frac{a_n}{a_j} v_{i,n-m+1}.$$

Hence $v_{ij} \in \text{Span}\{u_1, \dots, u_m, v_{ij}, \dots, v_{ij-1}, v_{ij+1}, \dots, v_{i,n-m+1}\}$, meaning that

$\{u_1, \dots, u_m, v_{ij}, \dots, v_{i,n-m+1}\} \subset \text{Span}\{u_1, \dots, u_m, v_{ij}, \dots, v_{ij-1}, v_{ij+1}, \dots, v_{i,n-m+1}\}$, so

$\sqrt{\cdot} = \text{Span}\{u_1, \dots, u_m, v_{ij}, \dots, v_{i,n-m+1}\} \subset \text{Span}\{u_1, \dots, u_m, v_{ij}, \dots, v_{ij-1}, v_{ij+1}, \dots, v_{i,n-m+1}\}$

and of course $\text{Span}\{u_1, \dots, u_m, v_{i_1}, \dots, v_{i_{j-1}}, v_{i_{j+1}}, \dots, v_{n-m+1}\} \subseteq V$, whence

$V = \text{Span}\{u_1, \dots, u_m, v_{i_1}, \dots, v_{i_{j-1}}, v_{i_{j+1}}, \dots, v_{n-m+1}\}$. Since the set

$\{v_{i_1}, \dots, v_{i_{j-1}}, v_{i_{j+1}}, \dots, v_{n-m+1}\}$ has $(n-m+1)-1 = n-m$ elements and is a subset

of $\{v_1, \dots, v_n\}$, this yields the second part of the result. \square .

Examples:

1. Let $V = \mathbb{R}^3$, note that $V = \text{Span}\left\{\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right\}$. The set $\left\{\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}\right\}$ is

linearly independent. Now Theorem 15 says that we can find a subset of

$\left\{\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right\}$ that complements $\left\{\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}\right\}$, that is, two of the vectors

$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ together with $\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$ span \mathbb{R}^3 . There is more than one choice:

$$(a) \quad \mathbb{R}^3 \neq \text{Span}\left\{\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}\right\}.$$

$$(b) \quad \mathbb{R}^3 = \text{Span}\left\{\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}\right\}.$$

$$(c) \quad \mathbb{R}^3 = \text{Span}\left\{\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}\right\}.$$

2. Let $V = M_{2 \times 2}(\mathbb{Z}_3)$ be the vector space of 2 by 2 matrices with entries in \mathbb{Z}_3 . Now $V = \text{Span}\left\{\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}\right\}$. The set

$\left\{\begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 2 & 0 \end{bmatrix}\right\}$ is linearly independent, and there are two subsets of the

original generating set that complement it:

$$(a) M_{2 \times 2}(\mathbb{F}) = \text{Span} \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 2 & 0 \end{bmatrix} \right\}.$$

$$(b) M_{2 \times 2}(\mathbb{F}) = \text{Span} \left\{ \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 2 & 0 \end{bmatrix} \right\}.$$

Corollary 16: (Theorem 11) Let V be a vector space. Let β be a finite set that is

also a basis of V . Let β' be another basis of V . Then β and β' have the same number of elements, namely $|\beta| = |\beta'|$.

Proof: Since β is a basis then $V = \text{Span}(\beta)$, since β' is a basis then β' is

linearly independent, so by Theorem 15 then $|\beta'| \leq |\beta|$. Exchanging the roles of

β and β' gives $|\beta| \leq |\beta'|$. Thus $|\beta| = |\beta'|$. □.

Remark: Given a vector space V of dimension $n \in \mathbb{N}$, then:

1. A basis β of V has exactly n elements.

2. A subset of V spanning V has at least n elements.

3. A linearly independent subset of V has at most n elements.

In particular any spanning set of V with exactly n vectors is a basis of V .

Examples:

1. $\dim_{\mathbb{R}}(\mathbb{R}^n) = n$ with basis $\beta = \{e_i = (0, \dots, \overset{i}{1}, \dots, 0) \mid 1 \leq i \leq n\}$.

2.1. $\dim_{\mathbb{C}}(\mathbb{C}^n) = n$ with basis $\beta = \{e_i = (0, \dots, \overset{i}{1}, \dots, 0) \mid 1 \leq i \leq n\}$.

2.2. $\dim_{\mathbb{R}}(\mathbb{C}^n) = 2n$ with basis

$$\beta = \{e_i = (0, \dots, \overset{i}{1}, \dots, 0) \mid 1 \leq i \leq n\} \cup \{f_j = (0, \dots, \overset{j}{1}, \dots, 0) \mid 1 \leq j \leq n\}.$$

3. $\dim_{\mathbb{F}}(\text{Mat}_{m \times n}(\mathbb{F})) = mn$ with basis $\beta = \{E_{ij} \mid 1 \leq i \leq n, 1 \leq j \leq m\}$.

4. $\dim_{\mathbb{F}}(\mathbb{F}[x]) = |\mathbb{N}|$ with basis $\beta = \{x^i \mid i \in \mathbb{N}\}$.

5. $\dim_{\mathbb{F}}(\mathbb{F}_n[x]) = n+1$ with basis $\beta = \{x^i \mid 0 \leq i \leq n\}$.

A vector subspace W of a vector space V is a vector space on its own, so it will have a basis and a dimension. However, our options will be restricted by what is a basis in V , and by the dimension of V .

Theorem 17: Let V be a finite dimensional vector space, $W \subseteq V$ a vector subspace. Then :

(1) $\dim_{\mathbb{F}}(W) \leq \dim_{\mathbb{F}}(V)$,

(2) $\dim_{\mathbb{F}}(W) = \dim_{\mathbb{F}}(V)$ if and only if $V = W$.

In particular, W is finite dimensional.

Proof: (1) Let β be a basis of W . Since β is linearly independent in W it is also

linearly independent in V . Now V can be generated with $\dim_{\mathbb{F}}(V)$ vectors, so

by Theorem 15 then $\dim_{\mathbb{F}}(W) = |\beta| \leq \dim_{\mathbb{F}}(V)$.

(2) We want to prove that $\dim_{\mathbb{F}}(W) = \dim_{\mathbb{F}}(V)$ if and only if $V=W$.

(\Leftarrow) Suppose $V=W$, then $\dim_{\mathbb{F}}(V) = \dim_{\mathbb{F}}(W)$.

(\Rightarrow) Suppose $\dim_{\mathbb{F}}(W) = \dim_{\mathbb{F}}(V)$, let p be a basis of W , let γ be a basis of V .

By Theorem 15 there is a subset S of γ containing $\dim_{\mathbb{F}}(V) - \dim_{\mathbb{F}}(W)$

vectors such that $V = \text{Span}(p \cup S)$. Since $\dim_{\mathbb{F}}(W) = \dim_{\mathbb{F}}(V)$ then S

contains zero vectors, so $S = \emptyset$ and $p \cup S = p$. Hence $V = \text{Span}(p) = W$. \square .

Thus finite dimensional vector spaces can only have finite dimensional subspaces.

Inspecting the proof of Theorem 17, we find a corollary of the Replacement Theorem.

Corollary 18: Let V be a finite dimensional vector space, $W \subsetneq V$ a vector subspace with basis

p . Then we can extend p to a basis of V .

Proof: Let γ be a basis of V . By Theorem 15 there is a subset S of γ containing

$\dim_{\mathbb{F}}(V) - \dim_{\mathbb{F}}(W)$ vectors such that $V = \text{Span}(p \cup S)$. Note that $S \neq \emptyset$

since $W \neq V$. Now $p \cup S$ is a set with at most $\dim_{\mathbb{F}}(V)$ elements that

generates V . By the Remark after Corollary 16 then $p \cup S$ has exactly $\dim_{\mathbb{F}}(V)$

elements, and thus is a basis of V .

\square .

Remark: If W is a vector subspace of V with basis $\{w_1, \dots, w_k\}$, we can add

vectors v_{k+1}, \dots, v_n to it so that $\{w_1, \dots, w_k, v_{k+1}, \dots, v_n\}$ is a basis of V .

Now setting $W^c = \text{Span}\{v_{k+1}, \dots, v_n\}$ the complement subspace of W we find

$$V = W \oplus W^c.$$

2. Linear transformations.

We have given the structure of a vector space (over a field) to some sets, we now

investigate how different objects with this structure interact. Namely, we are

interested in relations between vector spaces, and in how to obtain information

about one if we know information about another. We will achieve this by using

functions that preserve this vector space structure, the so called linear transformations.

Definition: Let V and W be vector spaces over the same field \mathbb{F} . A linear transformation

is a function $T: V \rightarrow W$ satisfying for all $x, y \in V$ and $a \in \mathbb{F}$:

$$(1) \quad T(x+y) = T(x) + T(y)$$

$$(2) \quad T(ax) = a \cdot T(x).$$

Remark: In particular, a linear transformation $T: V \rightarrow W$ preserves linear

combinations, namely $T\left(\sum_{i=1}^n a_i \cdot v_i\right) = \sum_{i=1}^n a_i \cdot T(v_i)$ for all $v_1, \dots, v_n \in V$ and all

$a_1, \dots, a_n \in \text{IF}$. A linear transformation also sends the zero in V to the zero

in W : $T(\vec{0}) = \vec{0}$.

Theorem 19: Let V and W be vector spaces over the same field IF .

1) Let $T_1: V \rightarrow W$ and $T_2: V \rightarrow W$ be linear transformations, then:

$T_1 + T_2: V \rightarrow W$ is a linear transformation.

$$x \mapsto T_1(x) + T_2(x)$$

2) Let $T: V \rightarrow W$ be a linear transformation and $c \in \text{IF}$, then:

$c \cdot T: V \rightarrow W$ is a linear transformation.

$$x \mapsto c \cdot T(x)$$

3) The set $\mathcal{L}(V, W) = \{T: V \rightarrow W \mid T \text{ is a linear transformation}\}$ is a

vector space over IF with the operations above.

Proof: Straightforward, use the definition for 1) and 2), use Theorem 4 for 3). \square .

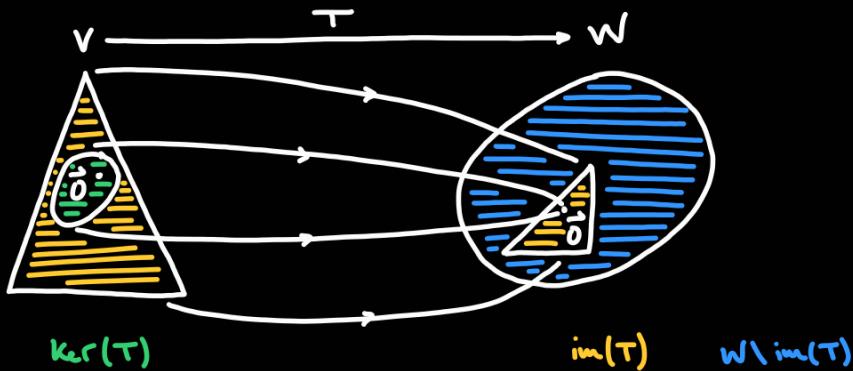
Definition: Let V and W be vector spaces over the same field IF , let $T: V \rightarrow W$ be a

linear transformation. The kernel or null space of T , denoted $\ker(T)$, is the set:

$$\ker(T) = \{x \in V \mid T(x) = \vec{0}\}.$$

The image or range of T , denoted $\text{im}(T)$, is the set:

$$\text{im}(T) = \{y \in W \mid \text{there exists } x \in V \text{ with } T(x) = y\} = \{T(x) \in W \mid x \in V\}.$$



Examples:

1. A function T between a set S and a field \mathbb{F} , namely $T \in \mathcal{F}(S, \mathbb{F})$, that

is a polynomial of degree less than or equal to 1 is a linear transformation

on every vector space structure on S .

2. The function $T: M_{n \times n}(\mathbb{F}) \rightarrow M_{n \times n}(\mathbb{F})$ is a linear transformation since

$$A \mapsto A^t$$

$$T(A+B) = (A+B)^t = A^t + B^t = T(A) + T(B) \text{ and } T(c \cdot A) = (c \cdot A)^t = c \cdot A^t = c \cdot T(A).$$

3. The function $T: \mathbb{F}_n[x] \rightarrow \mathbb{F}_{n-1}[x]$ is a linear transformation since

$$f \mapsto \frac{d}{dx} f$$

$$T(f+g) = \frac{d}{dx}(f+g) = \frac{d}{dx}f + \frac{d}{dx}g = T(f) + T(g) \text{ and}$$

$$T(c \cdot f) = \frac{d}{dx}(c \cdot f) = c \cdot \frac{d}{dx}f = c \cdot T(f).$$

4. The function $T: C(\mathbb{R}, \mathbb{R}) \rightarrow \mathbb{R}$ is a linear transformation.

$$f \mapsto \int_a^b f dx$$

5. The functions from \mathbb{R} to \mathbb{R} given by $T(x) = x^2$, $T(x) = \frac{1}{x}$, $T(x) = e^x$,

$T(x) = \sin(x)$, $T(x) = \cos(x)$, and combinations of these, are not linear

transformations.

Example: Compute the kernel and image of the linear transformation $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$.
 $(x, y, z) \mapsto (x-y, 2z)$

For the kernel, we want $\ker(T) = \{(x, y, z) \mid T(x, y, z) = (0, 0)\}$ so:

$(x, y, z) \in \ker(T)$ if and only if $T(x, y, z) = (0, 0)$, namely $(x-y, 2z) = (0, 0)$

so $x-y=0$ and $2z=0$ so $x=y$ and $z=0$.

Thus (x, y, z) should look like $(x, x, 0)$, and $\ker(T) = \{(x, x, 0) \mid x \in \mathbb{R}\}$.

For the image, we want $\text{im}(T) = \{T(x, y, z) \mid (x, y, z) \in \mathbb{R}^3\}$ so:

$(u, v) \in \text{im}(T)$ if and only if $(u, v) = T(x, y, z) = (x-y, 2z)$,

so $u=x-y$ and $v=2z$.

Now since any real number u can be obtained as a difference of two real numbers $x-y$,

and any real number v can be obtained by doubling another real number z , then

u and v take all the possible real values. Hence $\text{im}(T) = \mathbb{R}^2$.

Theorem 20: Let V and W be vector spaces over the same field \mathbb{F} , let $T: V \rightarrow W$ be a linear transformation. Then:

1) $\ker(T)$ is a subspace of V .

2) $\text{im}(T)$ is a subspace of W .

Proof: We use Theorem 4:

1) Since $T(\vec{0}) = \vec{0}$ then $\vec{0} \in \ker(T)$.

Suppose that $x, y \in \ker(T)$, namely $T(x) = \vec{0} = T(y)$. Then:

$$T(x+y) = T(x) + T(y) = \vec{0} + \vec{0} = \vec{0} \quad \text{so } x+y \in \ker(T).$$

Suppose that $x \in \ker(T)$, so $T(x) = \vec{0}$, and $c \in \mathbb{F}$. Then:

$$T(c \cdot x) = c \cdot T(x) = c \cdot \vec{0} = \vec{0} \quad \text{so } c \cdot x \in \ker(T).$$

2) Since $T(\vec{0}) = \vec{0}$ then $\vec{0} \in \text{im}(T)$.

Suppose that $u, v \in \text{im}(T)$, so there are $x, y \in V$ with $T(x) = u$ and $T(y) = v$.

$$\text{Then } T(x+y) = T(x) + T(y) = u + v \quad \text{so } u+v \in \text{im}(T).$$

Suppose that $u \in \text{im}(T)$, so there is $x \in V$ with $T(x) = u$, and $c \in \mathbb{F}$. Then:

$$T(c \cdot x) = c \cdot T(x) = c \cdot u \quad \text{so } c \cdot u \in \text{im}(T).$$

□.

Theorem 21: Let V and W be vector spaces over the same field \mathbb{F} , let $T: V \rightarrow W$ be a

linear transformation, let $\beta = \{v_1, \dots, v_n\}$ be a basis of V . Then

$$T(\beta) = \{T(v_1), \dots, T(v_n)\} \text{ spans } \text{im}(T), \text{ namely } \text{im}(T) = \text{Span}\{T(v_1), \dots, T(v_n)\}.$$

Proof: We prove the double inclusion of $\text{Span}\{T(v_1), \dots, T(v_n)\}$ in $\text{im}(T)$ and of $\text{im}(T)$

in $\text{Span}\{T(v_1), \dots, T(v_n)\}$.

2) Since $T(v_1), \dots, T(v_n) \in \text{im}(T)$ then $\text{Span}\{T(v_1), \dots, T(v_n)\} \subseteq \text{im}(T)$.

\Leftarrow Let $u \in \text{im}(T)$, then there exists $v \in V$ with $T(v) = u$. Since β is a basis

of V , we can write $v = \sum_{i=1}^n a_i \cdot v_i$ for some coefficients $a_1, \dots, a_n \in \text{IF}$, and thus:

$$u = T(v) = T\left(\sum_{i=1}^n a_i \cdot v_i\right) = \sum_{i=1}^n T(a_i \cdot v_i) = \sum_{i=1}^n a_i \cdot T(v_i).$$

Hence $u \in \text{Span}\{T(v_1), \dots, T(v_n)\}$. Since this holds for all $u \in \text{im}(T)$, we have

that $\text{im}(T) \subseteq \text{Span}\{T(v_1), \dots, T(v_n)\}$. \square

Theorem 22: (Rank-Nullity Theorem) Let V and W be vector spaces over the same field IF ,

with V finite dimensional, and let $T: V \rightarrow W$ be a linear transformation. Then:

$$\dim(V) = \dim(\ker(T)) + \dim(\text{im}(T)).$$

Proof: Since V is finite dimensional, set $n = \dim(V)$. Writing $k = \dim(\ker(T))$, since

$\ker(T)$ is a subspace of V , then $k \leq n$. Given a basis $\{v_1, \dots, v_k\}$ of $\ker(T)$, by

Corollary 18 we can extend it to a basis $\{v_1, \dots, v_k, v_{k+1}, \dots, v_n\}$ of V . As we remarked

this allows us to write $V = \ker(T) \oplus \ker(T)^\perp$ where $\ker(T)^\perp$ has basis $\{v_{k+1}, \dots, v_n\}$.

We now claim that $\{T(v_{k+1}), \dots, T(v_n)\}$ is a basis of $\text{im}(T)$. To prove this, we

have to prove that $\{T(v_{k+1}), \dots, T(v_n)\}$ spans $\text{im}(T)$ and is linearly independent.

To prove spanning, note that since $\{v_1, \dots, v_n\}$ is a basis of V then

$\{T(v_1), \dots, T(v_n)\}$ spans $\text{im}(T)$ by Theorem 21. Now $v_1, \dots, v_k \in \ker(T)$ so

$T(v_1) = \dots = T(v_k) = \vec{0}$, which do not contribute to the span. Thus

$\{T(v_1), \dots, T(v_n)\} \subseteq \text{Span}\{T(v_{k+1}), \dots, T(v_n)\}$ so

$\text{im}(T) = \text{Span}\{T(v_1), \dots, T(v_n)\} \subseteq \text{Span}\{T(v_{k+1}), \dots, T(v_n)\}$. Since

$\text{Span}\{T(v_{k+1}), \dots, T(v_n)\} \subseteq \text{im}(T)$ then $\text{im}(T) = \text{Span}\{T(v_{k+1}), \dots, T(v_n)\}$.

To prove linear independence, we proceed by contradiction. Suppose that the set is

linear dependent, namely there are scalars $a_{k+1}, \dots, a_n \in \mathbb{F}$, at least one non-zero,

such that $a_{k+1}T(v_{k+1}) + \dots + a_nT(v_n) = \vec{0}$. Then $T(a_{k+1}v_{k+1} + \dots + a_nv_n) = \vec{0}$

so $a_{k+1}v_{k+1} + \dots + a_nv_n \in \ker(T)$. Since $\{v_1, \dots, v_k\}$ is a basis of $\ker(T)$ then

$a_{k+1}v_{k+1} + \dots + a_nv_n \in \text{Span}\{v_1, \dots, v_k\}$, so there are scalars $a_1, \dots, a_k \in \mathbb{F}$ such

that $a_{k+1}v_{k+1} + \dots + a_nv_n = a_1v_1 + \dots + a_kv_k$, which we can rewrite as

$-a_1v_1 - \dots - a_kv_k + a_{k+1}v_{k+1} + \dots + a_nv_n = \vec{0}$. This is a linear combination of the

basis $\{v_1, \dots, v_n\}$ of V that is zero, but at least one of the $a_{k+1}, \dots, a_n \in \mathbb{F}$ is

not zero, contradicting the linear independency of the basis. Thus our assumption

that $\{T(v_{k+1}), \dots, T(v_n)\}$ is linear dependent is false, hence it is linearly

independent.

Hence $\{T(v_{k+1}), \dots, T(v_n)\}$ is a basis of $\text{im}(T)$, meaning that $\dim(\text{im}(T)) = n - k$.

Now $\dim(\ker(T)) + \dim(\text{im}(T)) = k + (n - k) = n = \dim(V)$. \square .

Remark: We call $\dim(\ker(T))$ the nullity of T and $\dim(\text{im}(T))$ the rank of T .

Definition: Let V and W be vector spaces over the same field \mathbb{F} , let $T: V \rightarrow W$ be a

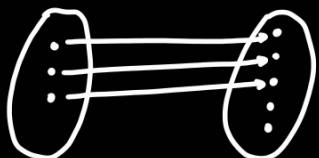
linear transformation. We say that T is injective or one-to-one if $T(x) = T(y)$

implies $x = y$. We say that T is surjective or onto if for every $y \in W$ there is

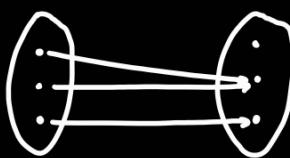
$x \in V$ with $T(x) = y$.

We often write $T: V \hookrightarrow W$ when T is injective, and $T: V \twoheadrightarrow W$ when T is

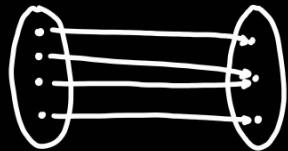
surjective. Pictorially, we have:



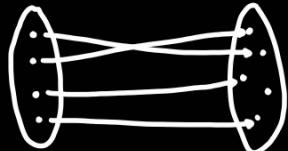
injective, but



not injective, and



surjective, but



not surjective.

Theorem 23: Let V and W be vector spaces over the same field \mathbb{F} , let $T: V \rightarrow W$ be a

linear transformation.

(i) T is injective if and only if $\ker(T) = \{\vec{0}\}$.

(2) T is surjective if and only if $\text{im}(T) = W$.

Proof: (1) (\Rightarrow) Suppose T is injective. We prove $\ker(T) = \{\vec{0}\}$. Let $x \in \ker(T)$, so $T(x) = \vec{0}$.

Now $T(x) = \vec{0} = T(\vec{0})$ so by injectivity of T we have $x = \vec{0}$, the sole element in $\ker(T)$.

(\Leftarrow) Suppose $\ker(T) = \{\vec{0}\}$. We prove T injective. Let $x, y \in V$ such that

$T(x) = T(y)$, then $\vec{0} = T(x) - T(y) = T(x-y)$ so $x-y \in \ker(T)$. Hence

$x-y = \vec{0}$ so $x = y$, and T is injective.

(2) (\Rightarrow) Suppose T is surjective. We prove $\text{im}(T) = W$. Since $\text{im}(T) \subseteq W$, it

suffices to prove $W \subseteq \text{im}(T)$. Let $y \in W$, since T is surjective there is

$x \in V$ with $T(x) = y$, and thus $y \in \text{im}(T)$.

(\Leftarrow) Suppose $W = \text{im}(T)$. We prove T surjective. Let $y \in W$, since $W = \text{im}(T)$

then $y \in \text{im}(T)$, so there is $x \in V$ with $T(x) = y$. Thus T is surjective. \square .

The concepts of injectivity and surjectivity are different in general, but sometimes they coincide.

Theorem 24: Let V and W be vector spaces over the same field \mathbb{F} , let $T: V \rightarrow W$ be a linear transformation, let $\dim(V) = \dim(W)$ be a finite natural number. Then

following are equivalent:

(1) T is injective.

(2) T is surjective.

(3) The dimension of $\text{im}(T)$ equals the dimension of V .

Proof: We have to prove that (1) holds if and only if (2) holds if and only if

(3) holds. It is enough to prove the equivalence between (1) and (3), and

the equivalence between (2) and (3).

(1) \Rightarrow (3) Suppose T is injective. Using Theorem 23 we know that

$\ker(T) = \{\vec{0}\}$. Since $\dim(\ker(T)) = \dim(\{\vec{0}\}) = 0$ by Theorem 22 then

$$\dim(V) = \dim(\text{im}(T)).$$

(3) \Rightarrow (1) Suppose $\dim(V) = \dim(\text{im}(T))$. Since by Theorem 22 then

$\dim(V) = \dim(\text{im}(T)) + \dim(\ker(T))$, we have $\dim(\ker(T)) = 0$ and thus

$\ker(T) = \text{Span}\{\vec{0}\} = \{\vec{0}\}$. Now by Theorem 23 we have T injective.

(2) \Rightarrow (3) Suppose T is surjective. Using Theorem 23 we know that

$$\text{im}(T) = W, \text{ so } \dim(V) = \dim(W) = \dim(\text{im}(T)).$$

(5) \Rightarrow (2) Suppose $\dim(V) = \dim(\text{im}(T))$. Now $\text{im}(T)$ is a vector subspace of W by Theorem 20, and since $\dim(W) = \dim(V) = \dim(\text{im}(T))$, by Theorem 17

then $W = \text{im}(T)$. Now by Theorem 23 then T is surjective. \square .

Given a linear transformation $T: V \rightarrow W$, often it is more convenient to compute

the dimensions of $\ker(T)$ and $\text{im}(T)$ than to compute the dimensions of V and W .

Using Theorem 22 and Theorem 24, we can often determine what we want from

just knowing $\ker(T)$ and $\text{im}(T)$.

We will now see that a linear map $T: V \rightarrow W$ is completely determined by where it

sends a basis of V . This means that to check a characteristic of a linear

transformation, such as checking whether T is linear or compute its kernel and image,

it suffices to work with a basis of V .

Theorem 25: Let V and W be vector spaces over the same field \mathbb{F} , let $\beta = \{v_1, \dots, v_n\}$ be

a basis of V , let $\gamma = \{w_1, \dots, w_m\}$ be a basis of W . Then the function defined

by $T: V \longrightarrow W$ is a linear transformation, and it is unique.

$$\sum_{i=1}^n a_i \cdot v_i \mapsto \sum_{i=1}^m a_i \cdot w_i$$

Proof: We first prove that $T: V \rightarrow W$ is linear. Let $x, y \in V$, since β is a basis

of V we can write $x = \sum_{i=1}^n a_i \cdot v_i$ and $y = \sum_{i=1}^m b_i \cdot v_i$ for some scalars

$a_1, \dots, a_n, b_1, \dots, b_n \in \mathbb{F}$. Now:

$$\begin{aligned} T(x+y) &= T\left(\sum_{i=1}^n a_i \cdot v_i + \sum_{i=1}^n b_i \cdot v_i\right) = T\left(\sum_{i=1}^n (a_i+b_i) \cdot v_i\right) = \sum_{i=1}^n (a_i+b_i) \cdot w_i = \\ &= \sum_{i=1}^n a_i \cdot w_i + \sum_{i=1}^n b_i \cdot w_i = T(x) + T(y). \end{aligned}$$

Similarly if $a \in \mathbb{F}$ then:

$$\begin{aligned} T(ax) &= T\left(a \cdot \sum_{i=1}^n a_i \cdot v_i\right) = T\left(\sum_{i=1}^n (a \cdot a_i) \cdot v_i\right) = \sum_{i=1}^n (a \cdot a_i) \cdot w_i = \\ &= a \cdot \sum_{i=1}^n a_i \cdot w_i = a \cdot T(x). \end{aligned}$$

Hence $T: V \rightarrow W$ is linear. Suppose that there is another linear transformation

$T': V \rightarrow W$ such that $T'(v_i) = w_i$ for all $i=1, \dots, n$. Since any $v \in V$ can be

written as $v = \sum_{i=1}^n a_i \cdot v_i$ for some $a_1, \dots, a_n \in \mathbb{F}$, then:

$$T(v) = T\left(\sum_{i=1}^n a_i \cdot v_i\right) = \sum_{i=1}^n a_i \cdot T(v_i) = \sum_{i=1}^n a_i \cdot T'(v_i) = T'\left(\sum_{i=1}^n a_i \cdot v_i\right) = T'(v).$$

Hence $T(v) = T'(v)$ for all $v \in V$, so $T = T'$ and T is unique. \square .

Note that we only used that $T: V \rightarrow W$ is defined on a basis of V , the values

$T(v_1), \dots, T(v_n)$ do not matter. Namely, a linear transformation $T: V \rightarrow W$ is uniquely

determined by its image on a basis of V .

Example: Consider the function $T: \mathbb{R}_2[x] \rightarrow \mathbb{R}_3[x]$. Is it linear? Is it
 $f(x) \mapsto 2 \cdot f'(x) + \int_0^x 3 \cdot f(t) dt$

injective? Is it surjective?

Note that differentiation and integration are linear transformations, and T is obtained by multiplying linear transformations by scalars, and then adding up the remaining linear transformations. Hence T is indeed a linear transformation.

We now compute the dimensions of the image and kernel of T , using that

$\{1, x, x^2\}$ is a basis of $\mathbb{R}_2[x]$. We obtain:

$$T(1) = 3x, \quad T(x) = 2 + \frac{3}{2}x^2, \quad T(x^2) = 4x + x^3,$$

so $\text{im}(T) = \text{Span}\{3x, 2 + \frac{3}{2}x^2, 4x + x^3\}$. Since $3x, 2 + \frac{3}{2}x^2, 4x + x^3$ all have

different degrees, they are linearly independent and thus $\dim(\text{im}(T)) = 3$.

Since $\mathbb{R}_3[x]$ has basis $\{1, x, x^2, x^3\}$, then $\dim(\mathbb{R}_3[x]) = 4$ and $\text{im}(T) \subsetneq \mathbb{R}_3[x]$,

so T is not surjective. Moreover:

$$3 = \dim(\mathbb{R}_2[x]) = \dim(\text{im}(T)) + \dim(\ker(T)) = 3 + \dim(\ker(T))$$

and thus $\dim(\ker(T)) = 0$ so $\ker(T) = \{\vec{0}\}$ so T is injective.

We are now in a position to justify why "linear transformations are equivalent to matrices". First, we will introduce the notions of coordinate vector. Second, we will use this to define the matrix associated to a linear transformation. Third, we will

explain how these constructions enable us to understand a finite dimensional vector

space V , say of dimension n , in terms of \mathbb{F}^n . In particular, a linear transformation from V to W will be identified with a linear transformation from \mathbb{F}^n to \mathbb{F}^m , where m is the dimension of W , which in turn corresponds to an $m \times n$ matrix.

Definition: Let V be a finite dimensional vector space with basis $\beta = \{v_1, \dots, v_n\}$, let

$v \in V$ be written as $v = \sum_{i=1}^n a_i \cdot v_i$ for some $a_1, \dots, a_n \in \mathbb{F}$. We say that the coordinate vector of v with respect to the basis β is:

$$[v]_{\beta} = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}.$$

Example: Let $V = \mathbb{R}_2[x]$, it has basis $\beta = \{1, x, x^2\}$ and $\gamma = \{1+x, 1-x, 3x^2\}$.

Let $f(x) = 3 - 2x + 4x^2$. We can also write $f(x) = \frac{1}{2}(1+x) + \frac{5}{2}(1-x) + \frac{4}{3} \cdot 3x^2$. Hence:

$$[f(x)]_{\beta} = \begin{bmatrix} 3 \\ -2 \\ 4 \end{bmatrix} \quad \text{and} \quad [f(x)]_{\gamma} = \begin{bmatrix} 1/2 \\ 5/2 \\ 4/3 \end{bmatrix}.$$

Definition: Let V and W be vector spaces over the same field \mathbb{F} , let $\beta = \{v_1, \dots, v_n\}$ be a basis of V , let $\gamma = \{w_1, \dots, w_m\}$ be a basis of W , let $T: V \rightarrow W$ be a linear

transformation. Write $T(v_j) = \sum_{i=1}^m a_{ij} \cdot w_i$ with $a_{ij} \in \mathbb{F}$ for each $i=1, \dots, m$ and

$j=1, \dots, n$. The matrix associated to T with respect to the basis β and γ is:

$$[T]_{\beta}^{\gamma} = \begin{bmatrix} a_{11} & \cdots & a_{1m} \\ \vdots & & \vdots \\ a_{m1} & \cdots & a_{mm} \end{bmatrix} = \begin{bmatrix} [T(v_1)]_{\gamma} & \cdots & [T(v_n)]_{\gamma} \end{bmatrix}.$$

We should think of $[v]_{\beta}$ and $[T]_{\beta}^{\gamma}$ as just notation for the linear combinations

$$v = \sum_{i=1}^n a_{ij} \cdot v_i \quad \text{and} \quad T(v_j) = \sum_{i=1}^m a_{ij} \cdot w_i \quad \text{for } j=1, \dots, n. \quad \text{These vectors and matrices}$$

encode all the information about v and T . Since we understand matrices well, it

will be useful to have access to a matrix containing all the information

required to work with abstract v and T .

Theorem 26: Let V and W be vector spaces over the same field \mathbb{F} , let $\beta = \{v_1, \dots, v_n\}$ be

a basis of V , let $\gamma = \{w_1, \dots, w_m\}$ be a basis of W . Let $T: V \rightarrow W$ and

$T': V \rightarrow W$ be linear transformations, let $c \in \mathbb{F}$. Then:

$$1) \quad [T+T']_{\beta}^{\gamma} = [T]_{\beta}^{\gamma} + [T']_{\beta}^{\gamma} \quad \text{and}$$

$$2) \quad [c \cdot T]_{\beta}^{\gamma} = c \cdot [T]_{\beta}^{\gamma}.$$

Proof: We first establish the notation we will use. Suppose:

$$T(v_j) = \sum_{i=1}^n a_{ij} \cdot w_i, \quad T'(v_j) = \sum_{i=1}^m b_{ij} \cdot w_i, \quad (T+T')(v_j) = \sum_{i=1}^m c_{ij} \cdot w_i,$$

$$\text{and} \quad (c \cdot T)(v_j) = \sum_{i=1}^n d_{ij} \cdot w_i, \quad \text{now:}$$

$$(T+T')(v_j) = T(v_j) + T'(v_j) = \sum_{i=1}^n a_{ij} \cdot w_i + \sum_{i=1}^m b_{ij} \cdot w_i = \sum_{i=1}^n (a_{ij} + b_{ij}) \cdot w_i$$

$$(c \cdot T)(v_j) = c \cdot T(v_j) = c \cdot \sum_{i=1}^m a_{ij} \cdot w_i = \sum_{i=1}^m (c \cdot a_{ij}) \cdot w_i$$

and thus $c_{ij} = a_{ij} + b_{ij}$ and $d_{ij} = c \cdot a_{ij}$ by Theorem 12. Then:

$$1) ([T+T']_{\beta}^{\gamma})_{ij} = c_{ij} = a_{ij} + b_{ij} = ([T]_{\beta}^{\gamma})_{ij} + ([T']_{\beta}^{\gamma})_{ij} \text{ for all } i=1, \dots, m$$

$$\text{and } j=1, \dots, n. \text{ Thus } [T+T']_{\beta}^{\gamma} = [T]_{\beta}^{\gamma} + [T']_{\beta}^{\gamma}.$$

$$2) ([c \cdot T]_{\beta}^{\gamma})_{ij} = d_{ij} = c \cdot a_{ij} = c \cdot ([T]_{\beta}^{\gamma})_{ij} \text{ for all } i=1, \dots, m \text{ and } j=1, \dots, n.$$

$$\text{Thus } [c \cdot T]_{\beta}^{\gamma} = c \cdot [T]_{\beta}^{\gamma}.$$

□.

Theorem 27: Let V, W, X be vector spaces over the same field \mathbb{F} , let $\alpha = \{v_1, \dots, v_m\}$,

$\beta = \{w_1, \dots, w_n\}$, $\gamma = \{x_1, \dots, x_p\}$ be basis of V, W, X . Let $T: V \rightarrow W$ and

$T': W \rightarrow X$ be linear transformations. Then $T' \circ T: V \rightarrow X$ is a linear

transformation and $[T' \circ T]_{\alpha}^{\gamma} = [T']_{\beta}^{\gamma} \cdot [T]_{\alpha}^{\beta}$.

Proof: Let $c \in \mathbb{F}$, $x, y \in V$, then:

$$(T' \circ T)(x+y) = T'(T(x+y)) = T'(T(x) + T(y)) = T'(T(x)) + T'(T(y)) =$$

$$(T' \circ T)(x) + (T' \circ T)(y),$$

$$(T' \circ T)(cx) = T'(T(cx)) = T'(c \cdot T(x)) = c \cdot T'(T(x)) = c \cdot (T' \circ T)(x).$$

Hence $T' \circ T$ is indeed linear. We now establish the notation we will use. Suppose:

$$T(v_j) = \sum_{k=1}^n b_{kj} \cdot w_k \quad \text{and} \quad T'(w_k) = \sum_{i=1}^p a_{ik} \cdot x_i, \text{ now:}$$

$$\begin{aligned}
 (\tau' \circ \tau)(v_j) &= \tau'(\tau(v_j)) = \tau'\left(\sum_{k=1}^m b_{kj} \cdot w_k\right) = \sum_{k=1}^m b_{kj} \cdot \tau'(w_k) = \\
 &= \sum_{k=1}^m b_{kj} \cdot \left(\sum_{i=1}^p a_{ik} \cdot x_i\right) = \sum_{i=1}^p \left(\sum_{k=1}^m a_{ik} \cdot b_{kj}\right) \cdot x_i.
 \end{aligned}$$

$$\text{Thus } ([\tau' \circ \tau]_\alpha^\gamma)_{ij} = \sum_{k=1}^m a_{ik} \cdot b_{kj} = \sum_{k=1}^m ([\tau']_\beta^\gamma)_{ik} \cdot ([\tau]_\alpha^p)_{kj} = ([\tau']_\beta^\gamma \cdot [\tau]_\alpha^p)_{ij}$$

$$\text{so } [\tau' \circ \tau]_\alpha^\gamma = [\tau']_\beta^\gamma \cdot [\tau]_\alpha^p.$$

□.

Theorem 28: Let V and W be vector spaces over the same field \mathbb{F} , let $\beta = \{v_1, \dots, v_n\}$ be

a basis of V , let $\delta = \{w_1, \dots, w_m\}$ be a basis of W . Let $T: V \rightarrow W$ be a linear

transformation. Then $[\tau(v)]_\delta = [\tau]_\beta^\delta [v]_\beta$ for all $v \in V$.

Proof: We first establish the notation we will use. Suppose:

$$T(v_j) = \sum_{i=1}^m b_{ij} \cdot w_i \quad \text{and} \quad v = \sum_{j=1}^n a_j \cdot v_j, \quad \text{now:}$$

$$T(v) = T\left(\sum_{j=1}^n a_j \cdot v_j\right) = \sum_{j=1}^n a_j \cdot T(v_j) = \sum_{j=1}^n a_j \cdot \left(\sum_{i=1}^m b_{ij} \cdot w_i\right) = \sum_{i=1}^m \left(\sum_{j=1}^n b_{ij} \cdot a_j\right) \cdot w_i.$$

$$\text{Hence } ([\tau(v)]_\delta)_i = \sum_{j=1}^n b_{ij} \cdot a_j = \sum_{j=1}^n ([\tau]_\beta^\delta)_{ij} \cdot ([v]_\beta)_j = ([\tau]_\beta^\delta \cdot [v]_\beta)_i, \text{ and thus}$$

$$[\tau(v)]_\delta = [\tau]_\beta^\delta \cdot [v]_\beta.$$

□.

Example: Let $T: \mathbb{R}_2[x] \rightarrow \mathbb{R}_3[x]$, consider $\beta = \{1, x, x^2\}$ a basis of $\mathbb{R}_2[x]$ and
 $f(x) \mapsto \int_0^x f(t) dt$

$\gamma = \{1, x, x^2, x^3\}$ a basis of $\mathbb{R}_3[x]$. Now:

$$T(1) = x, \quad T(x) = \frac{x^2}{2}, \quad T(x^2) = \frac{x^3}{3}.$$

Hence:

$$[\tau]_{\beta}^{\gamma} = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1/2 & 0 \\ 0 & 0 & 1/3 \end{bmatrix}. \text{ Note that } [1]_{\beta} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, [\tau(1)]_{\gamma} = [x]_{\gamma} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \text{ and}$$
$$[\tau]_{\beta}^{\gamma} \cdot [1]_{\beta} = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1/2 & 0 \\ 0 & 0 & 1/3 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = [\tau(1)]_{\gamma}.$$

Consider $\tilde{\tau}: \mathbb{R}_3[x] \rightarrow \mathbb{R}_2[x]$, we have:

$$f(x) \longmapsto f'(x)$$
$$\tilde{\tau}(1) = 0, \quad \tilde{\tau}(x) = 1, \quad \tilde{\tau}(x^2) = 2x, \quad \tilde{\tau}(x^3) = 3x^2.$$

Hence:

$$[\tilde{\tau}]_{\gamma}^{\beta} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{bmatrix}.$$

Moreover:

$$\tilde{\tau} \circ \tau(1) = 1, \quad \tilde{\tau} \circ \tau(x) = x, \quad \tilde{\tau} \circ \tau(x^2) = x^2, \text{ so } [\tilde{\tau} \circ \tau]_{\beta}^{\beta} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

Now:

$$[\tilde{\tau}]_{\gamma}^{\beta} \cdot [\tau]_{\beta}^{\gamma} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1/2 & 0 \\ 0 & 0 & 1/3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = [\tau \circ \tilde{\tau}]_{\beta}^{\beta}.$$

Our approach to the statement "linear transformations are equivalent to matrices"

requires us to make this statement formal for \mathbb{F}^n and \mathbb{F}^m . The following proves

that the function $M_{m \times n}(\mathbb{F}) \rightarrow L(\mathbb{F}^n, \mathbb{F}^m)$ is a linear transformation, injective,

$$A \longmapsto T_A$$

and surjective.

Definition: Let $A \in M_{m \times n}(\mathbb{F})$, we say that the linear transformation $T_A: \mathbb{F}^n \rightarrow \mathbb{F}^m$

$$x \longmapsto Ax$$

is the left-multiplication by A .

Theorem 29: Let $A \in M_{n \times n}(IF)$, then $T_A: IF^n \rightarrow IF^n$ is a linear transformation and:

1) $[T_A]_{\mathcal{O}_n}^{\mathcal{O}_n} = A$, where \mathcal{O}_n and \mathcal{O}_n are the standard basis of IF^n and IF^n .

2) Let $B \in M_{n \times n}(IF)$, then $T_A = T_B$ if and only if $A = B$.

3) Let $B \in M_{n \times p}(IF)$, then $T_{A+B} = T_A + T_B$.

4) Let $c \in IF$, then $T_{c \cdot A} = c \cdot T_A$.

5) Let $B \in M_{n \times p}(IF)$, then $T_{A \cdot B} = T_A \circ T_B$.

6) Let $I_{dn} \in M_{n \times n}(IF)$ be the identity matrix, then $T_{I_{dn}} = id_{IF^n}$, where

id_{IF^n} is the identity function on IF^n (namely $id_{IF^n}(x) = x$ for all $x \in IF^n$).

Proof: It follows from the definitions of matrix operations, but only basic facts

are used, and a straightforward computation suffices. \square .

Remark: Let V be a vector space, the identity function on V is the linear transformation

that sends every element in V to itself: $id_V: V \rightarrow V$.

$$v \mapsto v$$

To further formalize the notion of "equivalence", we will use invertible functions.

Definition: Let V and W be vector spaces, let $T: V \rightarrow W$ be a linear transformation.

We say that a linear transformation $S: W \rightarrow V$ is the inverse of T when

$S \circ T = \text{id}_V$ and $T \circ S = \text{id}_W$. We denote the inverse of T by $T^{-1}: W \rightarrow V$.

When T has an inverse, we say that T is invertible.

Theorem 30: Let V, W, X be vector spaces over the same field \mathbb{F} , let $T: V \rightarrow W$ and

$U: W \rightarrow X$ be invertible linear transformations. Then :

1) The inverse of T is unique.

2) The inverse of $U \circ T$ is $T^{-1} \circ U^{-1}$, namely $(U \circ T)^{-1} = T^{-1} \circ U^{-1}$

3) The inverse of the inverse of T is T , namely $(T^{-1})^{-1} = T$.

Proof: Straightforward using the definitions. \square .

Theorem 31: Let V and W be vector spaces over the same field \mathbb{F} , let $T: V \rightarrow W$ be a

linear transformation. Then T is invertible if and only if T is injective and

surjective.

Proof: (\Rightarrow) Suppose that T is invertible. Then there is a linear transformation

$T^{-1}: W \rightarrow V$ with $T^{-1} \circ T = \text{id}_V$ and $T \circ T^{-1} = \text{id}_W$. Suppose that $x, y \in V$ with

$T(x) = T(y)$, then :

$$x = \text{id}_V(x) = T^{-1} \circ T(x) = T^{-1}(T(x)) = T^{-1}(T(y)) = T^{-1} \circ T(y) = \text{id}_V(y) = y$$

so T is injective. Suppose that $z \in W$, then $T^{-1}(z) \in V$ and :

$$T(T^{-1}(z)) = T \circ T^{-1}(z) = \text{id}_W(z) = z$$

so setting $x = T^{-1}(z)$ we found an element $x \in V$ such that $T(x) = z$, so T

is surjective.

(\Leftarrow) Suppose that T is injective and surjective. Consider the function of

sets $S: W \rightarrow V$ defined by $S(y) = x$ if and only if $T(x) = y$. This is
 $y \mapsto x$

indeed a function of sets: if $y \in W$ then since T is surjective there is

an element $x \in V$ such that $T(x) = y$, and such element x is unique

because if there is another $x' \in V$ such that $T(x') = y$ then since T is

injective and $T(x) = y = T(x')$ we have $x = x'$. Thus S is well defined, and

it is our candidate for the inverse of T : by definition $S \circ T = \text{id}_V$ and

$T \circ S = \text{id}_W$. It only remains to prove that S is a linear transformation.

Let $x, y \in W$ and $c \in F$, then:

$$T(S(x+y)) = T \circ S(x+y) = \text{id}_W(x+y) = x+y = \text{id}_W(x) + \text{id}_W(y) =$$

$$T \circ S(x) + T \circ S(y) = T(S(x)) + T(S(y)) = T(S(x) + S(y)),$$

$$T(S(cx)) = T \circ S(cx) = c \cdot x = c \cdot \text{id}_W(x) = c \cdot (T \circ S)(x) = c \cdot T(S(x)) =$$

$$= T(c \cdot S(x)),$$

hence $S(x+y) = S(x) + S(y)$ and $S(cx) = c \cdot S(x)$ because T is injective.

Thus $S: W \rightarrow V$ is a linear transformation with $S \circ T = \text{id}_V$ and $T \circ S = \text{id}_W$,

so T is invertible. □.

Corollary 32: Let V and W be vector spaces over the same field \mathbb{F} , let $T: V \rightarrow W$ be a

linear transformation, let $\dim(V) = \dim(W)$ be finite. Then T is invertible if and

only if $\text{rank}(T) = \dim(W)$.

Proof: Since $\text{rank}(T) = \dim(\text{im}(T))$, we have to prove that T is invertible if

and only if $\dim(\text{im}(T)) = \dim(W)$.

(\Rightarrow) Suppose T is invertible. Then T is surjective by Theorem 31, and $\text{im}(T) = W$ by

Theorem 23, so $\dim(\text{im}(T)) = \dim(W)$.

(\Leftarrow) Suppose $\dim(\text{im}(T)) = \dim(W)$. Since $\dim(V) = \dim(W) = \dim(\text{im}(T))$ then

T is injective and surjective by Theorem 24, so T is invertible by Theorem 31. □.

Although an invertible linear transformation $T: V \rightarrow W$ requires the inverse $T^{-1}: W \rightarrow V$

to also be a linear transformation, if $T: V \rightarrow W$ is just injective and surjective then

the candidate inverse can be proven to be linear.

Corollary 33: Let V and W be vector spaces over the same field \mathbb{F} , let $T: V \rightarrow W$ be a

linear transformation that is injective and surjective. Then the function of sets

$S: W \rightarrow V$ defined by $S(y) = x$ if and only if $T(x) = y$ is the inverse of T .

This was proven for Theorem 31, and essentially states that linearity could be removed

from the definition of invertibility. In general, however, this cannot be done.

Theorem 34: Let V and W be vector spaces over the same field \mathbb{F} , let $T: V \rightarrow W$ be

an invertible linear transformation. Then V is finite dimensional if and only if

W is finite dimensional.

Proof: (\Rightarrow) Suppose that $T: V \rightarrow W$ is invertible, so by Theorem 31 then T is

injective and surjective. Suppose that V is finite dimensional, let $\beta = \{v_1, \dots, v_n\}$

be a basis of V . Consider $T(\beta) = \{T(v_1), \dots, T(v_n)\}$, we want to prove that

this is a basis of W . Suppose that $T(\beta)$ is not linearly independent, then

there are scalars $a_1, \dots, a_n \in \mathbb{F}$, at least one different from zero, such that

$$a_1 \cdot T(v_1) + \dots + a_n \cdot T(v_n) = 0. \text{ Then since } T \text{ is linear } T(a_1 \cdot v_1 + \dots + a_n \cdot v_n) = 0.$$

Since T is injective then $a_1 \cdot v_1 + \dots + a_n \cdot v_n = 0$, which is a linear

combination of β with at least one coefficient different from zero, and

thus β is linearly dependent. This contradicts that β is a basis of V ,

and thus $T(\beta) = \{T(v_1), \dots, T(v_n)\}$ is linearly independent. Moreover since

$T(\beta) \subset W$ then $\text{Span}(T(\beta)) \subseteq W$, we now prove $W \subseteq \text{Span}(T(\beta))$. Let

$w \in W$, since T is surjective there is a $v \in V$ such that $T(v) = w$. Since

β is a basis of V , we can write $v = \sum_{i=1}^n a_i \cdot v_i$ for some $a_1, \dots, a_n \in F$,

and thus $w = T(v) = T\left(\sum_{i=1}^n a_i \cdot v_i\right) = \sum_{i=1}^n a_i \cdot T(v_i)$, so $w \in \text{Span}(T(\beta))$.

Hence $W \subseteq \text{Span}(T(\beta))$, so $W = \text{Span}(T(\beta))$. Since $T(\beta)$ is a linearly

independent set that generates W , it is a basis of W . Since

$T(\beta) = \{T(v_1), \dots, T(v_n)\}$ has the same number of elements as $\beta = \{v_1, \dots, v_n\}$,

then the dimension of W coincides with the dimension of V .

(\Leftarrow) Suppose that $T: V \rightarrow W$ is invertible. Then there exists $T^{-1}: W \rightarrow V$ the

inverse of T . Now by Theorem 31 then T^{-1} is injective and surjective.

Suppose that W is finite dimensional, let $\gamma = \{w_1, \dots, w_m\}$ be a basis of W . An

analogous reasoning as above proves that $T^{-1}(\gamma) = \{T^{-1}(w_1), \dots, T^{-1}(w_m)\}$ is a basis of

V , and indeed the dimension of V coincides with the dimension of W . \square .

Theorem 35: Let V and W be finite dimensional vector spaces over the same field \mathbb{F} , let

$\beta = \{v_1, \dots, v_n\}$ and $\gamma = \{w_1, \dots, w_m\}$ be basis of V and W respectively, let

$T: V \rightarrow W$ and $T': V \rightarrow W$ be linear transformations such that $[T]_{\beta}^{\gamma} = [T']_{\beta}^{\gamma}$.

Then $T = T'$ as linear transformations.

Proof: Write $T(v_j) = \sum_{i=1}^m a_{ij} \cdot w_i$ and $T'(v_j) = \sum_{i=1}^m b_{ij} \cdot w_i$ for all $j=1, \dots, n$, so

that $([T]_{\beta}^{\gamma})_{ij} = a_{ij}$ and $([T']_{\beta}^{\gamma})_{ij} = b_{ij}$ for all $i=1, \dots, m$ and $j=1, \dots, n$.

Since $[T]_{\beta}^{\gamma} = [T']_{\beta}^{\gamma}$, then $a_{ij} = ([T]_{\beta}^{\gamma})_{ij} = ([T']_{\beta}^{\gamma})_{ij} = b_{ij}$ for all $i=1, \dots, m$

and $j=1, \dots, n$. Hence $T(v_j) = T'(v_j)$ for all $j=1, \dots, n$, and thus $T = T'$ by

Theorem 25. □.

Theorem 36: Let V and W be finite dimensional vector spaces over the same field \mathbb{F} , let

$\beta = \{v_1, \dots, v_n\}$ and $\gamma = \{w_1, \dots, w_m\}$ be basis of V and W respectively, let

$T: V \rightarrow W$ be a linear transformation. Then:

1) T is invertible if and only if $[T]_{\beta}^{\gamma}$ is invertible.

2) If $[T]_{\beta}^{\gamma}$ is invertible then $([T]_{\beta}^{\gamma})^{-1} = [T^{-1}]_{\gamma}^{\beta}$.

Proof: 1) (\Rightarrow) Suppose T is invertible. Then $n=m$ by Theorem 34 and thus $[T]_{\beta}^{\gamma}$

is an $n \times n$ matrix. Moreover the inverse $T^{-1}: W \rightarrow V$ satisfies $T^{-1}T = \text{id}_V$ and

$\tau\tau^{-1} = \text{id}_W$. Since $\text{id}_V(v_j) = v_j$ and $\text{id}_W(w_j) = w_j$ for all $j=1,\dots,n$, then

$[\text{id}_V]_P^\gamma = \text{Id}_n$ and $[\text{id}_W]_Y^\gamma = \text{Id}_n$ are both the $n \times n$ identity matrix. Using

Theorem 27 then:

$$[\tau^{-1}]_\gamma^P [\tau]_P^\gamma = [\tau^{-1}\tau]_P^\gamma = [\text{id}_V]_P^\gamma = \text{Id}_n,$$

$$[\tau]_P^\gamma [\tau^{-1}]_\gamma^P = [\tau\tau^{-1}]_\gamma^P = [\text{id}_W]_Y^\gamma = \text{Id}_n,$$

so $[\tau]_P^\gamma$ is invertible, with inverse $([\tau]_P^\gamma)^{-1} = [\tau^{-1}]_\gamma^P$.

(\Leftarrow) Suppose that $[\tau]_P^\gamma$ is invertible. Then there exists a matrix $A \in M_{n \times n}(IF)$

such that $[\tau]_P^\gamma A = \text{Id}_n$ and $A [\tau]_P^\gamma = \text{Id}_n$. Consider the function

$S: W \rightarrow V$ defined by $S(w_i) = \sum_{j=1}^n A_{ji} \cdot v_j$ for all $i=1,\dots,n$, where $(A)_{ji} = A_{ji}$

for $i,j=1,\dots,n$ are the entries of the matrix A . The function S is a well

defined linear transformation by Theorem 25, and by construction $[S]_Y^P = A$. Now

using Theorem 27 we have:

$$[\tau S]_Y^P = [\tau]_P^\gamma [S]_Y^P = [\tau]_P^\gamma A = \text{Id}_n = [\text{id}_W]_Y^\gamma,$$

$$[S\tau]_P^\gamma = [S]_Y^P [\tau]_P^\gamma = A [\tau]_P^\gamma = \text{Id}_n = [\text{id}_V]_P^\gamma,$$

and by Theorem 35 then $\tau S = \text{id}_W$ and $S\tau = \text{id}_V$. Hence τ is invertible.

2) Suppose $[\tau]_P^\gamma$ is invertible, then by the above τ is invertible and:

$$[\tau^{-1}]_{\gamma}^{\beta} [\tau]_{\beta}^{\gamma} = [\tau^{-1}\tau]_{\gamma}^{\beta} = [\text{id}_V]_{\gamma}^{\beta} = \text{Id}_W,$$

$$[\tau]_{\beta}^{\gamma} [\tau^{-1}]_{\gamma}^{\beta} = [\tau \tau^{-1}]_{\gamma}^{\beta} = [\text{id}_W]_{\gamma}^{\beta} = \text{Id}_W,$$

so $[\tau]_{\beta}^{\gamma}$ has inverse $([\tau]_{\beta}^{\gamma})^{-1} = [\tau^{-1}]_{\gamma}^{\beta}$.

□.

Corollary 37: Let V be a finite dimensional vector space over the field IF , let

$\beta = \{v_1, \dots, v_n\}$ be a basis of V , let $T: V \rightarrow W$ be a linear transformation. Then

T is invertible if and only if $[\tau]_{\beta}^{\gamma}$ is invertible.

Corollary 38: Let $A \in M_{n \times n}(\text{IF})$. Then A is invertible if and only if $T_A: \text{IF}^n \rightarrow \text{IF}^n$

$$x \mapsto A \cdot x$$

is invertible.

Definition: Let V and W be vector spaces over the field IF . We say that V and W are

isomorphic if there is an invertible linear transformation $T: V \rightarrow W$. Such an

invertible linear transformation is called an isomorphism. We denote this by

writing $V \cong W$.

Example: Consider the linear transformation $T: \text{IF}^n \rightarrow \text{IF}_{n-1}[x]$ given by

$$T \left(\begin{bmatrix} a_0 \\ \vdots \\ a_{n-1} \end{bmatrix} \right) = a_0 + a_1 x + \dots + a_{n-2} x^{n-2} + a_{n-1} x^{n-1}. \text{ Then } T \text{ is invertible with}$$

$$\text{inverse } T^{-1}: \text{IF}_{n-1}[x] \rightarrow \text{IF}^n \text{ given by } T^{-1}(b_0 + b_1 x + \dots + b_{n-1} x^{n-1}) = \begin{bmatrix} b_0 \\ \vdots \\ b_{n-1} \end{bmatrix}.$$

$$\text{Let } \beta = \left\{ \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}, \dots, \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix} \right\} \text{ be the standard basis of } \text{IF}^n. \text{ Let } x = b_0 + b_1 x + \dots + b_{n-1} x^{n-1}.$$

Let $\beta = \left\{ \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}, \dots, \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \right\}$ be the standard basis of \mathbb{F}^n , let $\alpha = 1, x, \dots, x^{n-1}$

be a basis of $\mathbb{F}_{n-1}[x]$. Recall that we often denote the elements of β by e_1, \dots, e_n . Then:

$$T(e_1) = 1, \dots, T(e_i) = x^{i-1}, \dots, T(e_n) = x^{n-1}$$

and thus:

$$[T]_{\beta}^{\gamma} = \begin{bmatrix} 1 & & & 0 \\ & \ddots & & \\ & & \ddots & \\ 0 & & & 1 \end{bmatrix} \text{ is the } nxn \text{ identity matrix.}$$

In particular $\mathbb{F}^n \cong \mathbb{F}_{n-1}[x]$.

Corollary 40: Let V be a vector space over the field \mathbb{F} . If V has dimension $n \in \mathbb{N}$

then V is isomorphic to \mathbb{F}^n .

Theorem 41: Let V and W be finite dimensional vector spaces over the same field \mathbb{F} , let

$\beta = \{v_1, \dots, v_m\}$ and $\gamma = \{w_1, \dots, w_m\}$ be bases of V and W respectively. Then the

function $\Phi: L(V, W) \rightarrow M_{m \times n}(\mathbb{F})$ is an isomorphism.

$$T \longmapsto [T]_{\beta}^{\gamma}$$

Proof: We first prove that Φ is a linear transformation. Given $T, T' \in L(V, W)$

and $c \in \mathbb{F}$, by Theorem 26 we have:

$$\Phi(T + T') = [T + T']_{\beta}^{\gamma} = [T]_{\beta}^{\gamma} + [T']_{\beta}^{\gamma} = \Phi(T) + \Phi(T')$$

$$\Phi(c \cdot T) = [c \cdot T]_{\beta}^{\gamma} = c \cdot [T]_{\beta}^{\gamma} = c \cdot \Phi(T)$$

and thus Φ is a linear transformation. Second, by Theorem 31 it is enough to

prove that Φ is injective and surjective to show that it is an isomorphism. For

injectivity, notice that if $T \in \text{ker}(\Phi)$ then $[T]_{\beta}^{\gamma} = \Phi(T) = 0$ the zero matrix.

Thus $T(v_j) = 0$ for all $j=1, \dots, n$, and thus T is the zero linear transformation,

namely $T(v) = 0$ for all $v \in V$, since $\exists : V \rightarrow W$ has $\exists(v_j) = T(v_j)$ for all $v \mapsto 0$

$j=1, \dots, n$, so $T = \exists$ by Theorem 25. This means that $\text{ker}(\Phi) = \{0\}$, so by

Theorem 23 then Φ is injective. For surjectivity, let $A \in M_{n \times n}(IF)$, and define

$S : V \rightarrow W$ by $S(v_j) = \sum_{i=1}^n A_{ij}w_i$. This is a linear transformation from V to W

by Theorem 25, so $S \in L(V, W)$. Now by construction $A = [S]_{\beta}^{\gamma} = \Phi(S)$ and thus Φ is

surjective. □.

Theorem 42: Let V be a finite dimensional vector space over the field IF , let $\beta = \{v_1, \dots, v_n\}$

be a basis of V . Then the function $\phi : V \rightarrow IF^n$ is an isomorphism.

$$v \mapsto [v]_{\beta}$$

Proof: We first prove that ϕ is a linear transformation. Let $v, v' \in V$ and $c \in IF$, say

$$[v]_{\beta} = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} \text{ and } [v']_{\beta} = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix} \text{ for some } a_1, \dots, a_n, b_1, \dots, b_n \in IF. \text{ Then:}$$

$$v + v' = \left(\sum_{i=1}^n a_i \cdot v_i \right) + \left(\sum_{i=1}^n b_i \cdot v_i \right) = \sum_{i=1}^n (a_i + b_i) \cdot v_i, \text{ and}$$

$$c \cdot v = c \cdot \left(\sum_{i=1}^n a_i \cdot v_i \right) = \sum_{i=1}^n (c \cdot a_i) \cdot v_i$$

hence:

$$[v+v']_{\beta} = \begin{bmatrix} a_1+b_1 \\ \vdots \\ a_n+b_n \end{bmatrix} = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} + \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix} = [v]_{\beta} + [v']_{\beta}, \text{ and}$$

$$[c \cdot v]_{\beta} = \begin{bmatrix} c \cdot a_1 \\ \vdots \\ c \cdot a_n \end{bmatrix} = c \cdot \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} = c \cdot [v]_{\beta},$$

and thus ϕ is a linear transformation. Second, by Theorem 31 it is enough to

prove that ϕ is injective and surjective to show that it is an isomorphism. For

injectivity, notice that if $v \in \ker(\phi)$ then $[v]_{\beta} = \phi(v) = 0$ the zero vector. Thus

$v=0$ and $\ker(\phi)=\{0\}$, so ϕ is injective by Theorem 23. For surjectivity let $\begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} \in F^n$

and define $v = \sum_{i=1}^n a_i \cdot v_i$, so $v \in V$. Now by construction $\begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} = [v]_{\beta} = \phi(v)$, so ϕ is

surjective.

□.

We can now restate Theorem 28 as a commutative diagram. Given V and W finite

dimensional vector spaces over the same field IF , with basis $\beta = \{v_1, \dots, v_n\}$ and

$\gamma = \{w_1, \dots, w_m\}$ respectively, then:

$$\begin{array}{ccc} V & \xrightarrow{T} & W \\ \downarrow \phi & & \downarrow \phi \\ IF^n & \xrightarrow{T[\gamma]_{\beta}} & F^m \end{array} \quad \begin{array}{l} \text{is a commutative diagram, namely:} \\ \phi \circ T = T[\gamma]_{\beta} \circ \phi. \end{array}$$

Equivalently for all $v \in V$ we have:

$$[T(v)]_{\gamma} = \phi(T(v)) = \phi \circ T(v) = T_{[\gamma]}_{\beta} \circ \phi(v) = T_{[\gamma]}_{\beta} \phi(v) = T_{[\gamma]}_{\beta} ([v]_{\beta}) = [T]_{\beta}^{\gamma} [v]_{\beta}.$$

When $V=W$, we can use the identity $\text{id}_V: V \rightarrow V$ to change the basis of V .

Definition: Let V be a finite dimensional vector space over the field \mathbb{F} , let $\beta = \{v_1, \dots, v_n\}$ and

$\gamma = \{w_1, \dots, w_n\}$ be basis of V . The change of basis matrix from β to γ is

$$Q = [\text{id}_V]_{\beta}^{\gamma}.$$

Example: Let $V = \mathbb{R}^2$, let $\beta = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$ and $\gamma = \left\{ \begin{bmatrix} 2 \\ 3 \end{bmatrix}, \begin{bmatrix} -2 \\ 3 \end{bmatrix} \right\}$. Since:

$$\begin{bmatrix} 2 \\ 3 \end{bmatrix} = 3 \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} - 1 \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} -2 \\ 3 \end{bmatrix} = 3 \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} - 5 \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \quad \text{then the change of basis matrix}$$

from γ to β is:

$$Q = [\text{id}_V]_{\gamma}^{\beta} = \left[\begin{bmatrix} 2 \\ 3 \end{bmatrix}_{\beta} \begin{bmatrix} -2 \\ 3 \end{bmatrix}_{\beta} \right] = \begin{bmatrix} -1 & -5 \\ 3 & 3 \end{bmatrix}.$$

Theorem 43: Let V be a finite dimensional vector space over the field \mathbb{F} , let $\beta = \{v_1, \dots, v_n\}$

and $\gamma = \{w_1, \dots, w_n\}$ be basis of V , let Q be the change of basis matrix from β to

γ . Then:

1) Q is invertible with inverse $Q^{-1} = [\text{id}_V]_{\gamma}^{\beta}$.

2) $[v]_{\gamma} = Q \cdot [v]_{\beta}$ for all $v \in V$.

Proof: 1) This is a particular case of Theorem 36.

2) This is a particular case of Theorem 28. □.

When $V=W$, we call linear transformations $T: V \rightarrow V$ operators.

Definition: Let V be a vector space over the field \mathbb{F} . A linear transformation $T: V \rightarrow V$ is

called a linear operator on V .

Theorem 44: Let V be a finite dimensional vector space over the field \mathbb{F} , let $\beta = \{v_1, \dots, v_n\}$

and $\gamma = \{w_1, \dots, w_n\}$ be basis of V , let Q be the change of basis matrix from β to

γ , let $T: V \rightarrow V$ be a linear transformation. Then $[T]_{\gamma}^{\gamma} = Q \cdot [T]_{\beta}^{\beta} \cdot Q^{-1}$.

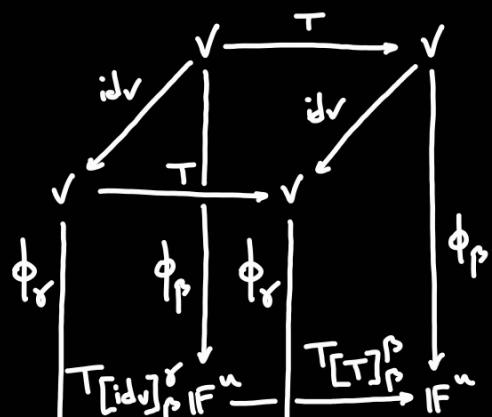
Proof: Note that using Theorem 27 and Theorem 36 we have:

$$\begin{aligned} Q \cdot [T]_{\beta}^{\beta} \cdot Q^{-1} &= [\text{id}_V]_{\beta}^{\gamma} \cdot [T]_{\beta}^{\beta} \cdot ([\text{id}_V]_{\beta}^{\gamma})^{-1} = [\text{id}_V]_{\beta}^{\gamma} \cdot [T]_{\beta}^{\beta} \cdot [\text{id}_V]_{\gamma}^{\beta} = [\text{id}_V]_{\beta}^{\gamma} \cdot [T]_{\beta}^{\beta} \cdot [\text{id}_V]_{\gamma}^{\beta} = \\ &= [\text{id}_{V \circ T \circ \text{id}_V}]_{\gamma}^{\gamma} = [T]_{\gamma}^{\gamma} \end{aligned}$$

as desired. □.

We can rephrase Theorem 44 as a commutative diagram. Given V a finite dimensional

vector space over the field \mathbb{F} , with basis $\beta = \{v_1, \dots, v_n\}$ and $\gamma = \{w_1, \dots, w_n\}$, then:



is a commutative diagram, namely:

$$T[\text{id}_V]_{\beta}^{\gamma} \circ T[T]_{\beta}^{\beta} = T[T]_{\gamma}^{\gamma} \circ T[\text{id}_V]_{\beta}^{\gamma}.$$

$$\begin{array}{ccc} & \downarrow & \downarrow \\ \mathbb{F}^n & \xrightarrow{T[\tau]^\gamma} & \mathbb{F}^n \xrightarrow{T[\text{id}_V]^\beta} \end{array}$$

Remark: When $V = \mathbb{F}^n$, we can use the standard basis $\sigma = \{e_1, \dots, e_n\}$ to handle every

change of basis we may need. Given any other basis $\beta = \{v_1, \dots, v_n\}$ of \mathbb{F}^n , then:

$$Q = [\text{id}_V]_{\beta}^{\sigma} = \left[[\text{id}_V(v_i)]_{\sigma} \cdots [\text{id}_V(v_n)]_{\sigma} \right] = \left[[v_i]_{\sigma} \cdots [v_n]_{\sigma} \right] = \begin{bmatrix} 1 & \dots & 1 \\ v_1 & \dots & v_n \\ 1 & \dots & 1 \end{bmatrix},$$

namely the change of basis matrix from β to σ has the elements of β as columns.

Now given another basis $\gamma = \{w_1, \dots, w_n\}$ of \mathbb{F}^n then by Theorem 27 and Theorem 36:

$$\begin{aligned} Q &= [\text{id}_V]_{\beta}^{\gamma} = [\text{id}_V \circ \text{id}_V]_{\beta}^{\gamma} = [\text{id}_V]_{\gamma}^{\sigma} \cdot [\text{id}_V]_{\beta}^{\sigma} = [\text{id}_V]_{\gamma}^{\sigma} \cdot [\text{id}_V]_{\beta}^{\sigma} = ([\text{id}_V]_{\gamma}^{\sigma})^{-1} \cdot [\text{id}_V]_{\beta}^{\sigma} = \\ &= \begin{bmatrix} 1 & \dots & 1 \\ w_1 & \dots & w_n \\ 1 & \dots & 1 \end{bmatrix}^{-1} \begin{bmatrix} 1 & \dots & 1 \\ v_1 & \dots & v_n \\ 1 & \dots & 1 \end{bmatrix}, \end{aligned}$$

namely any change of basis matrix can be obtained via matrices whose columns are the

vectors of the basis β and γ .

Example: Let $V = \mathbb{R}^3$ with basis $\sigma = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$, $\beta = \left\{ \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right\}$, $\gamma = \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}, \begin{bmatrix} 7 \\ 8 \\ 10 \end{bmatrix} \right\}$.

Since:

$$\begin{aligned} \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix} &= \frac{2}{3} \cdot \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + \frac{4}{3} \cdot \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} + (-1) \cdot \begin{bmatrix} 7 \\ 8 \\ 10 \end{bmatrix}, \\ \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} &= (-2) \cdot \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + 1 \cdot \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} + 0 \cdot \begin{bmatrix} 7 \\ 8 \\ 10 \end{bmatrix}, \\ \begin{bmatrix} 1 \\ -1 \\ -1 \end{bmatrix} &= \frac{-1}{3} \cdot \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + \frac{1}{3} \cdot \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} + 0 \cdot \begin{bmatrix} 7 \\ 8 \\ 10 \end{bmatrix}, \end{aligned}$$

then:

$$[\text{id}_V]_{\beta}^{\gamma} = \begin{bmatrix} 2/3 & -2 & -1/3 \\ 4/3 & 1 & 1/3 \\ -1 & 0 & 0 \end{bmatrix}.$$

Also:

$$[\text{id}_V]_{\beta}^{\gamma} = \begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 10 \end{bmatrix}^{-1} \begin{bmatrix} -1 & 2 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -2/3 & -2/3 & 1 \\ -4/3 & 1/3 & -2 \\ 1 & -2 & 1 \end{bmatrix} \cdot \begin{bmatrix} -1 & 2 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 2/3 & -2 & -1/3 \\ 4/3 & 1 & 1/3 \\ -1 & 0 & 0 \end{bmatrix}.$$

Corollary 45: Let $A \in \text{M}_{n \times n}(\mathbb{F}^n)$, let $\beta = \{v_1, \dots, v_n\}$ be a basis of \mathbb{F}^n , let σ be the

standard basis of \mathbb{F}^n , let Q be the change of basis matrix from β to σ . Then

$$[T_A]_{\beta}^{\sigma} = Q^{-1} A \cdot Q.$$

Proof: This is a particular case of Theorem 44. □.

Definition: Let $A, B \in \text{M}_{n \times n}(\mathbb{F})$. We say that A is similar to B if there is $Q \in \text{M}_{n \times n}(\mathbb{F})$

invertible such that $B = Q^{-1} A \cdot Q$.

Otherwise said, two matrices are similar when they induce the same linear transformation

up to a change of basis. We will see that this is an equivalence relation.

4. Determinants.

Definition: A determinant is a function $\det: \text{M}_{n \times n}(\mathbb{F}) \rightarrow \mathbb{F}$ satisfying:

- It is linear with respect to each column:

$$\det \begin{bmatrix} c_1, \dots, c_i + c_i', \dots, c_n \\ | & | & | & | \end{bmatrix} = \det \begin{bmatrix} c_1, \dots, c_i, \dots, c_n \\ | & | & | & | \end{bmatrix} + \det \begin{bmatrix} c_1, \dots, c_i', \dots, c_n \\ | & | & | & | \end{bmatrix}$$

and:

$$\det \begin{bmatrix} | & | & | \\ c_1, \dots, a \cdot c_i, \dots, c_n \\ | & | & | \end{bmatrix} = a \cdot \det \begin{bmatrix} | & | & | \\ c_1, \dots, c_i, \dots, c_n \\ | & | & | \end{bmatrix}.$$

(ii) It is alternating in the columns:

$$\det \begin{bmatrix} | & | & | & | \\ c_1, \dots, c_i, \dots, c_i, \dots, c_n \\ | & | & | & | \end{bmatrix} = 0.$$

(iii) The determinant of the identity matrix is 1:

$$\det \begin{bmatrix} | & | \\ e_1, \dots, e_n \\ | & | \end{bmatrix} = 1.$$

Theorem 46: Let $n \in \mathbb{N}$, the determinant $\det : M_{n \times n}(\mathbb{F}) \rightarrow \mathbb{F}$ exists and is unique.

Moreover for $A \in M_{n \times n}(\mathbb{F})$ we have:

(i) Column expansion: $\det(A) = \sum_{i=1}^n (-1)^{i+j} \cdot A_{ij} \cdot \det(\hat{A}_{ij})$ for all $j=1, \dots, n$.

(ii) Row expansion: $\det(A) = \sum_{j=1}^n (-1)^{i+j} \cdot A_{ij} \cdot \det(\hat{A}_{ij})$ for all $i=1, \dots, n$.

Where $\hat{A}_{ij} \in M_{(n-1) \times (n-1)}(\mathbb{F})$ is the matrix obtained from A by removing the i -th row

and j -th column. In particular $\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = ad - bc$.

Remark: We have:

i) Let B be the matrix obtained from A by swapping two columns or two rows. Then

$$\det(B) = -\det(A).$$

2) Let B be the matrix obtained from A by multiplying a column or row by a scalar

$c \in \mathbb{F}$. Then $\det(B) = c \cdot \det(A)$.

3) Let B be the matrix obtained from A by adding to the i -th row or column of A

a scalar multiple of the j -th row or column of A , respectively. Then $\det(B) = \det(A)$.

4) If A is a lower or upper triangular matrix then $\det(A) = \prod_{i=1}^n A_{ii}$.

5) The matrix A is invertible if and only if $\det(A) \neq 0$.

6) For $A, B \in M_{n \times n}(\mathbb{F})$ then $\det(AB) = \det(A) \cdot \det(B)$, but in general

$$\det(A+B) \neq \det(A) + \det(B).$$

7) For $A \in M_{n \times n}(\mathbb{F})$ invertible then $\det(A^{-1}) = \frac{1}{\det(A)} = \det(A)^{-1}$.

8) For $A \in M_{n \times n}(\mathbb{F})$ then $\det(A^t) = \det(A)$.

9) If $A, B \in M_{n \times n}(\mathbb{F})$ are similar matrices then $\det(A) = \det(B)$.

