

We know $(\text{im}(A))^\perp = \ker(A^T)$ is always true.

We want a matrix A with $(\text{im}(A))^\perp \neq \ker(A)$. So since $(\text{im}(A))^\perp = \ker(A^T)$,

we want $\ker(A^T) = (\text{im}(A))^\perp \neq \ker(A)$. Now:

$$A: \mathbb{R}^m \longrightarrow \mathbb{R}^n$$

$$A^T: \mathbb{R}^n \longrightarrow \mathbb{R}^m$$

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 \end{bmatrix}$$

For $\ker(A)$:

$$A\vec{x} = \vec{0}, \text{ so } \left[\begin{array}{ccc|c} 1 & 2 & 3 & 0 \end{array} \right] \text{ so } y=t, z=s \text{ are free and}$$

$$\vec{x} = \begin{bmatrix} -2t-3s \\ t \\ s \end{bmatrix} \text{ so } \ker(A) = \text{Span}\left(\begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}\right) \text{ has dimension 2.}$$

For $\ker(A^T)$:

$$A^T \vec{x} = \vec{0}, \text{ so } \left[\begin{array}{c|c} 1 & 0 \\ 2 & 0 \\ 3 & 0 \end{array} \right] \text{ which reduces to } \left[\begin{array}{c|c} 1 & 0 \\ 0 & 0 \\ 0 & 0 \end{array} \right] \text{ so } x=0$$

$$\text{so } \ker(A^T) = \{\vec{0}\}.$$

If A is nxn then: (do we have $\ker(A) = \ker(A^T)$).

$$\dim(\text{im}(A^T)) + \dim(\ker(A^T)) = n \quad , \quad \dim(\text{im}(A^T)) = \text{rank}(A^T)$$

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but $\text{rank}(A) = \text{rank}(A^T)$ so $\dim(\text{im}(A)) = \dim(\text{im}(A^T))$ so:

$$\dim(\ker(A)) = \dim(\ker(A^T)). \quad \underline{\text{No!}} \quad \text{See the end remark.}$$

Problem 5.4.3.: Let $\vec{v}_1, \dots, \vec{v}_p$ be a basis of V , $\vec{w}_1, \dots, \vec{w}_q$ a basis of V^\perp . Is

$\vec{v}_1, \dots, \vec{v}_p, \vec{w}_1, \dots, \vec{w}_q$ a basis of \mathbb{R}^n ?

\mathbb{R}^n is separated into V and V^\perp , so we think yes.

To prove it, we need $\vec{v}_1, \dots, \vec{v}_p, \vec{w}_1, \dots, \vec{w}_q$ to be linearly independent and to span (\mathbb{R}^n) .

1. Suppose we have a sum:

$$c_1 \vec{v}_1 + \dots + c_p \vec{v}_p + d_1 \vec{w}_1 + \dots + d_q \vec{w}_q = 0$$

So:

$$\underbrace{c_1 \vec{v}_1 + \dots + c_p \vec{v}_p}_{\text{in } V} = - \underbrace{(d_1 \vec{w}_1 + \dots + d_q \vec{w}_q)}_{\text{in } V^\perp}$$

So:

$c_1 \vec{v}_1 + \dots + c_p \vec{v}_p$ is in V and V^\perp

$-(d_1 \vec{w}_1 + \dots + d_q \vec{w}_q)$ is in V and V^\perp

But there is only one vector in V and V^\perp , the vector $\vec{0}$:

$c_1 \vec{v}_1 + \dots + c_p \vec{v}_p = 0$ so $c_1 = \dots = c_p = 0$ since $\vec{v}_1, \dots, \vec{v}_p$ are linearly independent

$-(d_1 \vec{w}_1 + \dots + d_q \vec{w}_q) = 0$ so $d_1 \vec{w}_1 + \dots + d_q \vec{w}_q = 0$ so $d_1 = \dots = d_q = 0$

since $\vec{w}_1, \dots, \vec{w}_q$ are linearly independent.

Thus any sum $c_1 \vec{v}_1 + \dots + c_p \vec{v}_p + d_1 \vec{w}_1 + \dots + d_q \vec{w}_q = 0$ always has all coefficients zero, so we cannot have linear dependence.

2. Let \vec{x} be in \mathbb{R}^n , decompose $\vec{x} = \vec{x}'' + \vec{x}'^\perp$, where \vec{x}'' is in V and \vec{x}'^\perp is in V^\perp ,

then \vec{x}'' is in $\text{span}(\vec{v}_1, \dots, \vec{v}_p)$ and \vec{x}'^\perp is in $\text{span}(\vec{w}_1, \dots, \vec{w}_q)$. Thus

\vec{x} is in $\text{span}(\vec{v}_1, \dots, \vec{v}_p, \vec{w}_1, \dots, \vec{w}_q)$. By definition:

$$\mathbb{R}^n = \text{span}(\vec{v}_1, \dots, \vec{v}_p, \vec{w}_1, \dots, \vec{w}_q).$$

Problem 5.3.32.:

a) Let A be $n \times m$ with $A^T A = I_m$, do we have $A A^T = I_n$?

Thought process: Suppose that $m < n$, so $A : \mathbb{R}^m \xrightarrow[A^T]{\quad} \mathbb{R}^n$

$$\mathbb{R}^2 \rightarrow \mathbb{R}^3$$

A will be a 3×2 matrix, $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$.

$$\text{Now: } A^T A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$A A^T = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \text{ which is } \underline{\text{not}} \text{ } I_3.$$

b) Let A be $n \times n$ with $A^T A = I_n$, do we have $A A^{-1} = I_n$?

If $A^T A = I_n$ then A is orthogonal so $A^{-1} = A^T$ so $A A^{-1} = A A^T = I_n$.

Remark: Let A be $n \times n$ with $B A = I_n$, do we have $A B = I_n$?

Yes!

Here A will have $\ker(A) = \{\vec{0}\}$, so it will be invertible, and $A^{-1} = B$.

1. $\ker(A) = \{\vec{0}\}$:

Let $\vec{x} \in \ker(A)$, so $A\vec{x} = 0$. Then :

$$\vec{x} = I_n \vec{x} = (BA)\vec{x} = B(A\vec{x}) = B\vec{0} = \vec{0} \quad \text{so} \quad \vec{x} = \vec{0}.$$

2. $A^{-1} = B$:

Since $BA = I_n$ so multiplying by A^{-1} on the right :

$$B A^{-1} = I_n A^{-1} \quad \text{so} \quad B = A^{-1}.$$

Proof of Cramer's rule: A invertible, $A\vec{x} = \vec{b}$, the solutions are $\vec{x} = \begin{bmatrix} \det(A\vec{b}_1, i) \\ \vdots \\ \det(A\vec{b}_n, i) \\ \vdots \end{bmatrix}$.

We have to prove $x_i = \frac{\det(A\vec{b}_i, i)}{\det(A)}$. Equivalently, we want to prove :

$$\det(A) x_i = \det(A\vec{b}_i, i) \quad \text{when} \quad A = \begin{bmatrix} 1 & \dots & 1 \\ \vec{v}_1 & \dots & \vec{v}_n \\ \vdots & & \vdots \end{bmatrix}$$

$$A\vec{b}_i, i = \begin{bmatrix} 1 & \dots & \vec{v}_{i-1} & \vec{b} & \vec{v}_{i+1} & \dots & \vec{v}_n \\ \vec{v}_1 & \dots & \vec{v}_{i-1} & \vec{b} & \vec{v}_{i+1} & \dots & \vec{v}_n \\ \vdots & & \vdots & & \vdots & & \vdots \end{bmatrix} = \begin{bmatrix} 1 & \dots & 1 & 1 & \vec{b} & 1 & \dots & 1 \\ \vec{v}_1 & \dots & \vec{v}_{i-1} & \vec{b} & \vec{v}_{i+1} & \dots & \vec{v}_n \\ \vdots & & \vdots & & \vdots & & \vdots \end{bmatrix} =$$

$$A\vec{x} = \begin{bmatrix} 1 & \dots & 1 \\ \vec{v}_1 & \dots & \vec{v}_n \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \vec{v}_1 \cdot x_1 + \dots + \vec{v}_n \cdot x_n$$

$$= \begin{bmatrix} 1 & 1 & \dots & 1 \\ \vec{v}_1 & \dots & \vec{v}_{i-1} & \vec{v}_i \cdot x_1 + \dots + \vec{v}_n \cdot x_n & \vec{v}_{i+1} & \dots & \vec{v}_n \\ 1 & 1 & \dots & 1 \end{bmatrix} \text{ so when taking determinants}$$

$$\det(\mathbf{A}_{\vec{t}, :}) = \det \begin{bmatrix} 1 & 1 & \dots & 1 \\ \vec{v}_1 & \dots & \vec{v}_{i-1} & \vec{v}_i \cdot x_1 + \dots + \vec{v}_n \cdot x_n & \vec{v}_{i+1} & \dots & \vec{v}_n \\ 1 & 1 & \dots & 1 \end{bmatrix} =$$

$$= \det \underbrace{\begin{bmatrix} 1 & 1 & \dots & 1 \\ \vec{v}_1 & \dots & \vec{v}_{i-1} & x_i \vec{v}_i & \vec{v}_{i+1} & \dots & \vec{v}_n \\ 1 & 1 & \dots & 1 \end{bmatrix}}_{0} + \dots +$$

$$\det \underbrace{\begin{bmatrix} 1 & 1 & \dots & 1 \\ \vec{v}_1 & \dots & \vec{v}_{i-1} & x_i \vec{v}_i & \vec{v}_{i+1} & \dots & \vec{v}_n \\ 1 & 1 & \dots & 1 \end{bmatrix}}_{0} + \dots + \det \underbrace{\begin{bmatrix} 1 & 1 & \dots & 1 \\ \vec{v}_1 & \dots & \vec{v}_{i-1} & x_n \vec{v}_n & \vec{v}_{i+1} & \dots & \vec{v}_n \\ 1 & 1 & \dots & 1 \end{bmatrix}}_{0} =$$

$$= x_i \det \underbrace{\begin{bmatrix} 1 & 1 & \dots & 1 \\ \vec{v}_1 & \dots & \vec{v}_{i-1} & \vec{v}_i & \vec{v}_{i+1} & \dots & \vec{v}_n \\ 1 & 1 & \dots & 1 \end{bmatrix}}_{A} + \dots +$$

$$x_i \det \underbrace{\begin{bmatrix} 1 & 1 & \dots & 1 \\ \vec{v}_1 & \dots & \vec{v}_{i-1} & \vec{v}_i & \vec{v}_{i+1} & \dots & \vec{v}_n \\ 1 & 1 & \dots & 1 \end{bmatrix}}_{0} + \dots + x_n \det \underbrace{\begin{bmatrix} 1 & 1 & \dots & 1 \\ \vec{v}_1 & \dots & \vec{v}_{i-1} & \vec{v}_n & \vec{v}_{i+1} & \dots & \vec{v}_n \\ 1 & 1 & \dots & 1 \end{bmatrix}}_{0} =$$

So:

$$\det(\mathbf{A}_{\vec{t}, :}) = x_i \cdot \det \underbrace{\begin{bmatrix} 1 & 1 & \dots & 1 \\ \vec{v}_1 & \dots & \vec{v}_{i-1} & \vec{v}_i & \vec{v}_{i+1} & \dots & \vec{v}_n \\ 1 & 1 & \dots & 1 \end{bmatrix}}_{A} = x_i \cdot \det(A)$$

Problem 5.4.25.:

Since A does not have kernel $\vec{0}$, we project \vec{t} onto $\text{im}(A)$ and we solve for

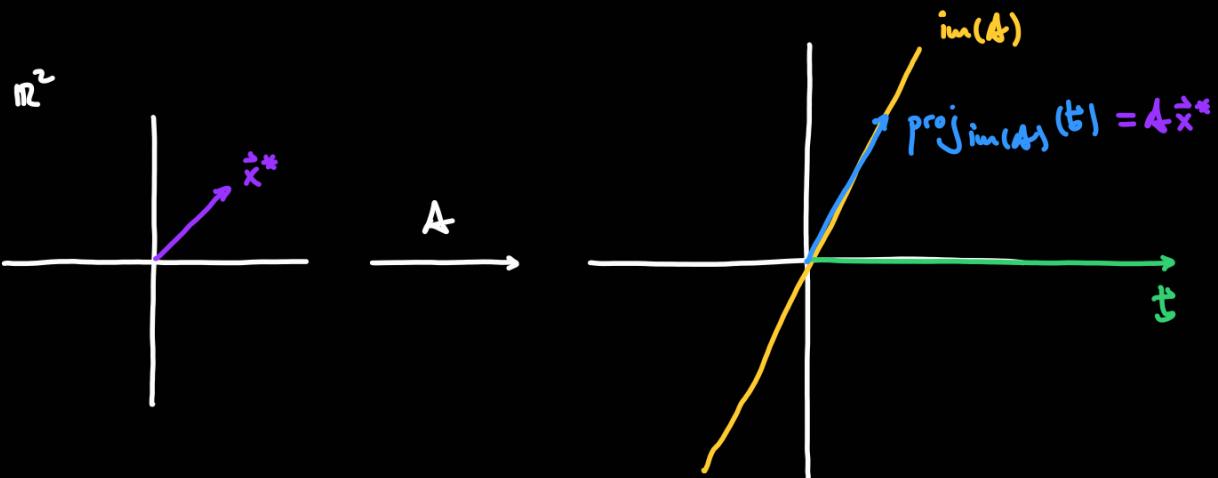
\vec{x}^* in the system $A \vec{x}^* = \text{proj}_{\text{im}(A)}(\vec{t})$.

$$A = \begin{bmatrix} 1 & 3 \\ 2 & 6 \end{bmatrix}, \quad \vec{t} = \begin{bmatrix} 5 \\ 0 \end{bmatrix}$$

$$\text{im}(A) = \text{span} \left(\begin{bmatrix} 1 \\ 2 \end{bmatrix} \right)$$

$$\vec{u} = \frac{1}{\sqrt{5}} \cdot \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

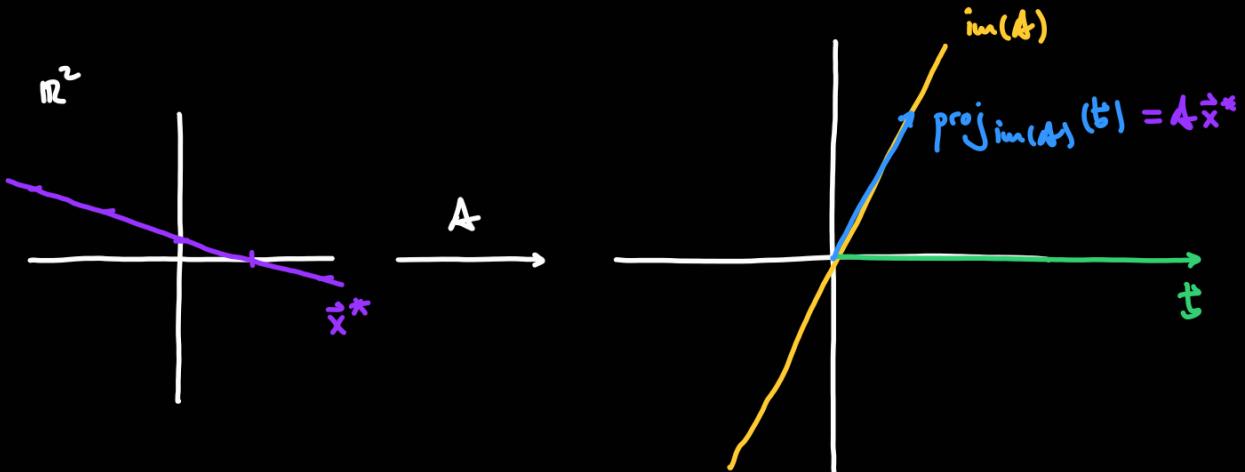
$$\text{proj}_{\text{im}(A)}(\vec{b}) = (\vec{b} \cdot \vec{u}) \vec{u} = \frac{1}{5} \cdot 5 \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$



We want \vec{x}^* in \mathbb{R}^2 such that $A\vec{x}^* = \vec{b}$.

$$\left[\begin{array}{cc|c} 1 & 3 & 1 \\ 2 & 6 & 2 \end{array} \right] \xrightarrow{R_2 - 2R_1} \left[\begin{array}{cc|c} 1 & 3 & 1 \\ 0 & 0 & 0 \end{array} \right] \quad \text{so} \quad x + 3y = 1. \quad y = \frac{-x}{3} + \frac{1}{3}$$

Set $y = t$ free, then $\vec{x}^* = \begin{bmatrix} 1-3t \\ t \end{bmatrix}$.



Remark: In general, if A is $n \times n$, then $\ker(A) \neq \ker(A^T)$.

Let $n=3$ and $A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$. Now:

$$\ker(A) = \left\{ \begin{bmatrix} -2t - 3s \\ t \\ s \end{bmatrix} \text{ for } t, s \text{ in } \mathbb{R} \right\} = \text{span} \left(\begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix} \right),$$

$$\ker(A^T) = \left\{ \begin{bmatrix} 0 \\ t \\ s \end{bmatrix} \text{ for } t, s \text{ in } \mathbb{R} \right\} = \text{span} \left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right).$$