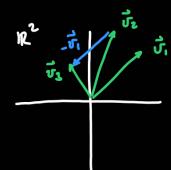
Recall: The vectors it, ..., The form a bosis of V a subspace of IR" when:

- (i) V = span (v, ..., vm) and
- (ii) I, ..., I'm are linearly independent.



$$IR^2 = span (\vec{v}_1, \vec{v}_2, \vec{v}_3) = span (\vec{v}_1, \vec{v}_2) = span (\vec{v}_1, \vec{v}_3)$$

Theorem: Let vi, ..., vim be vectors in V. They form a basis of Vit and only if

every vector in V can be written as a livear combination:

$$\vec{v} = c_1 \cdot \vec{v}_1 + \cdots + c_m \cdot \vec{v}_m$$
 in a unique way.

Coordinates of  $\vec{v}$  with respect to  $\vec{v}_1, \cdots, \vec{v}_m$ 

Theorem: Let it, ,..., in be a basis of V. Them:

(i) Any spanning set of V has at least un vectors.

(ii) Any other basis has un dements.

The number dim (V) of rectors in a basis of V is called the dimension of V.

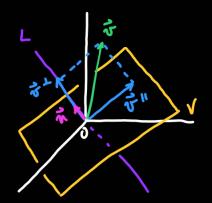
Example: Set 1R3 the ambient space. Let V a subspace of 1R3.

| X2 | V can have at most 3 linearly independent vectors.

Theorem: Let V be a subspace of dimension in = dim(v).

- (i) There are at most in linearly independent vectors in V.
- (ii) We need at least in sectors to span V.
- (iii) If V = span(vi, ..., vim) then vi, ..., vim are linearly independent. (so they form a basis).
- (iv) If  $\vec{w}_1,...,\vec{w}_m$  are linearly independent in v them  $V = \text{span}(\vec{w}_1,...,\vec{w}_m)$ (so they form a basis).

Example: Let  $T: \mathbb{R}^3 \longrightarrow \mathbb{R}^3$  be the orthogonal projection onto V.



im(T) = 
$$V$$
 so  $V = span(\vec{n}_1, \vec{n}_2)$  so  $dim(u) = 2$ .

thus  $uxu - puxu|k|$ 

vectors in  $V$ 

$$V(T) = L$$
so  $L = span(\vec{n}_1)$  so  $dim(L) = 1$ .

 $dim(im(\tau)) + dim(kw(\tau)) = 3$ 

dimension of the Source R3.

Theorem: (Rank-Nullity) let & be an uxu matrix. Thun:

dim (im(4)) + dim (ker (4)) = um.

We call dim (ker (4)) the nullity of 4. Thun:

(rank &) + (nullity of +)= m

Theorem: Let A be an uxm matrix. Thun:

(1) To construct a basis of im(A), pick the columns of A corresponding to

the columns of ref (4) having leading ones.

(ii) To construct a basis of Ker(A1), we can use the columns of A corresponding

to the columns of cref (4) having no leading over.

Example: 
$$A = \begin{bmatrix} 1 & 2 & 0 & 1 & 2 \\ 1 & 2 & 0 & 2 & 3 \\ 1 & 2 & 0 & 3 & 4 \\ 1 & 2 & 0 & 4 & 5 \end{bmatrix}$$

in (4): has basis 
$$\left[\begin{bmatrix} 1\\1\\1 \end{bmatrix}, \begin{bmatrix} 1\\2\\3\\4 \end{bmatrix}\right]$$
.

$$\operatorname{ref}(b) = \begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{array}{c} \uparrow & \uparrow \\ \text{columns with leading mes} \end{array}$$

$$ker(A)$$
: we use columns 2,3,5 in  $A$ :  $ref(A) = \begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ 

$$c_1 \cdot \vec{v}_1 + c_2 \cdot \vec{v}_2 + c_3 \cdot \vec{v}_3 + c_4 \cdot \vec{v}_4 + c_5 \cdot \vec{v}_5 = 0$$

$$columns columns columns columns$$

$$c_1 \cdot \vec{v}_1 + c_2 \cdot \vec{v}_2 + c_3 \cdot \vec{v}_3 + c_4 \cdot \vec{v}_4 + c_5 \cdot \vec{v}_5 = 0$$

$$columns coithant leading to the columns coithant leading to the coithant leading to the columns coithant leading to the coithant leading to t$$

$$\vec{\nabla}_2 = 2 \cdot \vec{\nabla}_1 \qquad \text{So} \qquad -2 \vec{\nabla}_1 + \vec{\nabla}_2 = 0 \qquad \qquad \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} \quad \text{in } \ker(\mathbf{A})$$

$$\vec{\nabla}_3 = 0 \cdot \vec{\nabla}_1 \qquad \text{So} \qquad \vec{\nabla}_3 = 0 \qquad \qquad \mathbf{N}$$

$$\vec{\hat{v}}_{5} = 1 \cdot \vec{\hat{v}}_{1} + 1 \cdot \vec{\hat{v}}_{4}$$
 so  $-\vec{\hat{v}}_{1} - \vec{\hat{v}}_{4} + \vec{\hat{v}}_{5} = 0$   $\sim$   $\begin{bmatrix} -1 \\ 0 \\ -1 \end{bmatrix}$  in  $k\omega(A)$ 

$$T: \mathbb{R}^{n} \longrightarrow \mathbb{R}^{n}$$

$$\downarrow \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad$$

[ ... ] ..L

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