



(Artificial) Neural Networks: Advanced

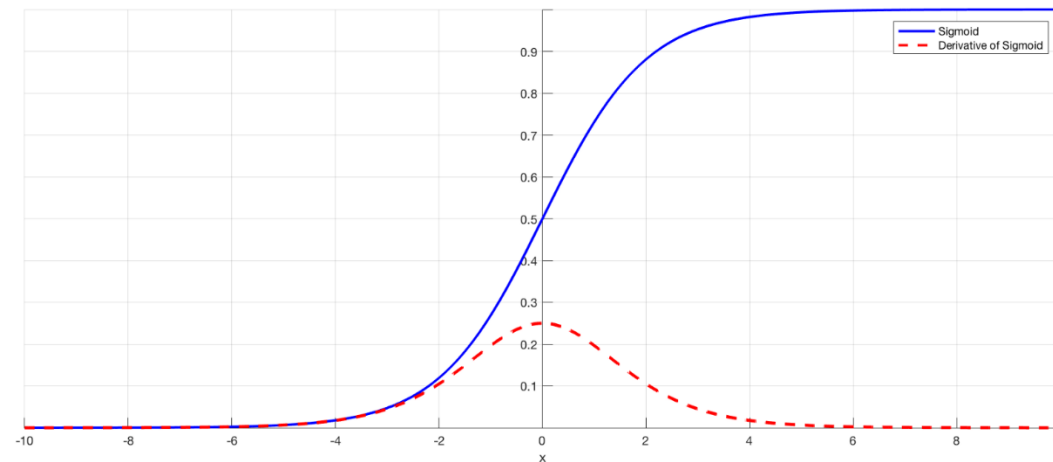
**Industrial AI Lab.
Prof. Seungchul Lee**

Nonlinear Activation Function

The Vanishing Gradient Problem

- As more layers using certain activation functions are added to neural networks, the gradients of the loss function approaches zero, making the network hard to train.
- For example,

$$-\frac{dz}{du} = \frac{dz}{dy} \cdot \frac{dy}{dx} \cdot \frac{dx}{dw} \cdot \frac{dw}{du}$$

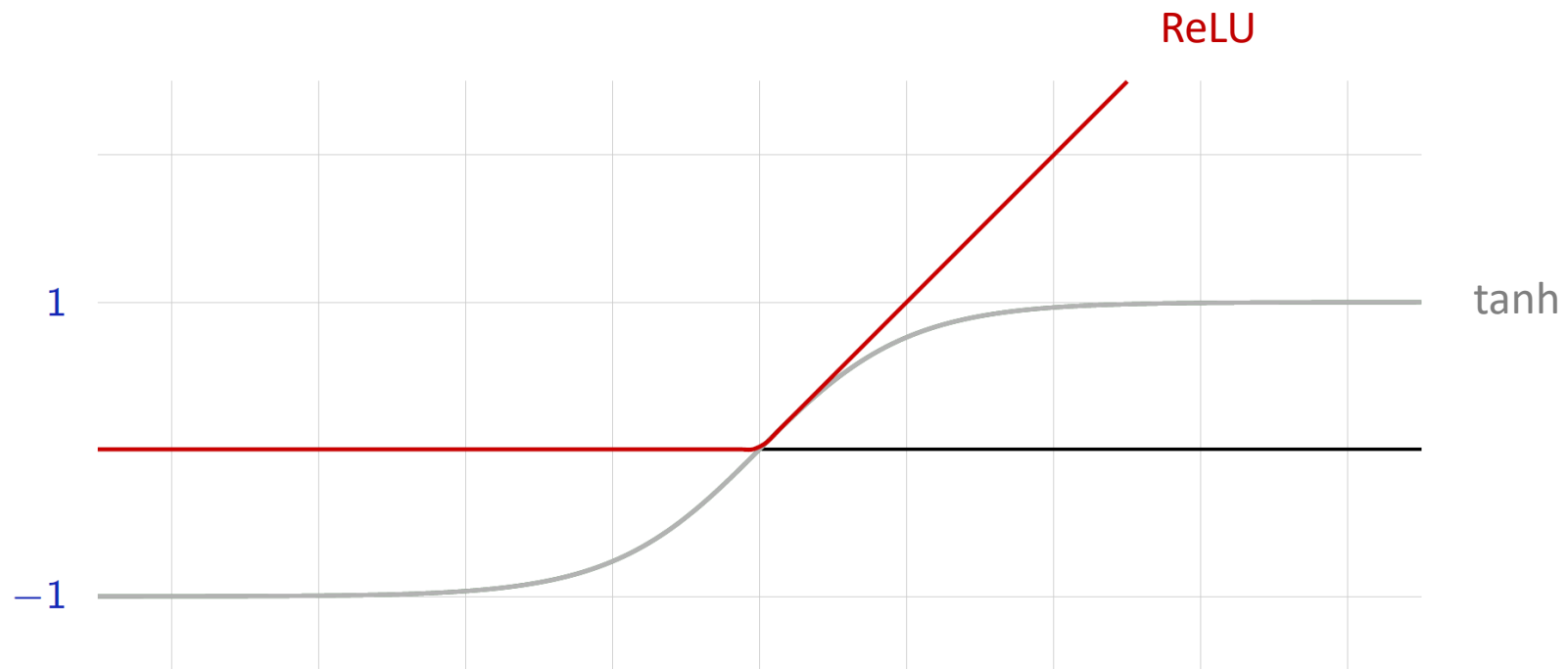


sigmoid

Derivative of sigmoid

Rectifiers

- The use of the **ReLU** activation function was a great improvement compared to the historical tanh.



Rectifiers

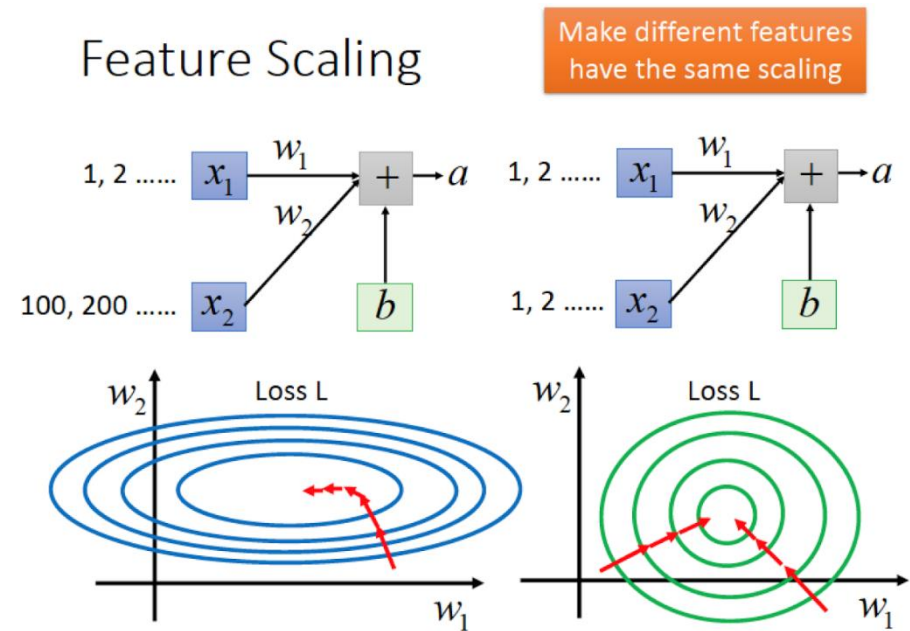
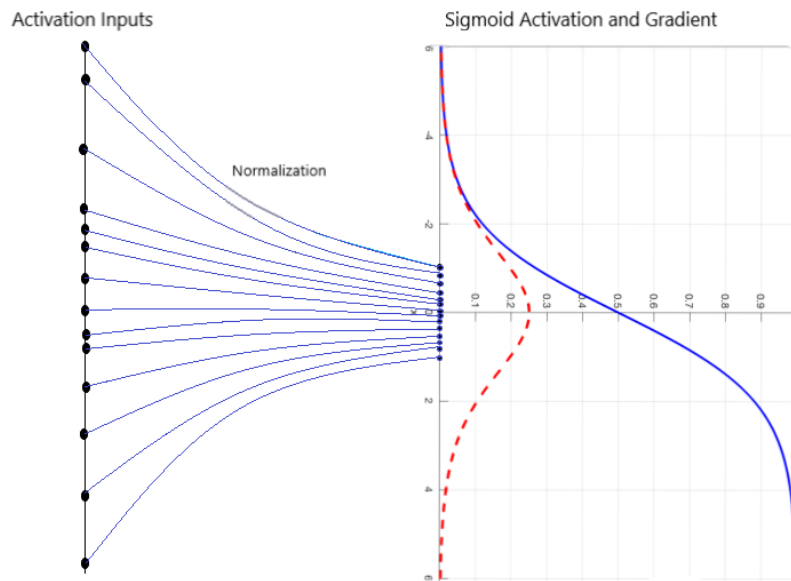
- This can be explained by the derivative of ReLU itself not vanishing, and by the resulting coding being sparse (Glorot et al., 2011).



Batch Normalization

Batch Normalization

- Batch normalization is a technique for improving the performance and stability of artificial neural networks.
- It is used to normalize the input layer by adjusting and scaling the activations.



Batch Normalization

- During training batch normalization shifts and rescales according to the mean and variance estimated on the batch.
- During test, it simply shifts and rescales according to the empirical moments estimated during training.

Input: Values of x over a mini-batch: $\mathcal{B} = \{x_1 \dots x_m\}$;

Parameters to be learned: γ, β

Output: $\{y_i = \text{BN}_{\gamma, \beta}(x_i)\}$

$$\mu_{\mathcal{B}} \leftarrow \frac{1}{m} \sum_{i=1}^m x_i \quad // \text{ mini-batch mean}$$

$$\sigma_{\mathcal{B}}^2 \leftarrow \frac{1}{m} \sum_{i=1}^m (x_i - \mu_{\mathcal{B}})^2 \quad // \text{ mini-batch variance}$$

$$\hat{x}_i \leftarrow \frac{x_i - \mu_{\mathcal{B}}}{\sqrt{\sigma_{\mathcal{B}}^2 + \epsilon}} \quad // \text{ normalize}$$

$$y_i \leftarrow \gamma \hat{x}_i + \beta \equiv \text{BN}_{\gamma, \beta}(x_i) \quad // \text{ scale and shift}$$

Algorithm 1: Batch Normalizing Transform, applied to activation x over a mini-batch.

Dropout as Regularization

Regularization (Shrinkage Methods)

- Often, overfitting associated with very large estimated parameters
- We want to balance
 - how well function fits data
 - magnitude of coefficients

$$\text{Total cost} = \underbrace{\text{measure of fit}}_{RSS(\theta)} + \lambda \cdot \underbrace{\text{measure of magnitude of coefficients}}_{\lambda \cdot \|\theta\|_2^2}$$

$$\implies \min \|\Phi\theta - y\|_2^2 + \lambda \|\theta\|_2^2$$

- multi-objective optimization
- λ is a tuning parameter

Different Regularization Techniques

- Big Data
- Data augmentation
 - The simplest way to reduce overfitting is to increase the size of the training data.

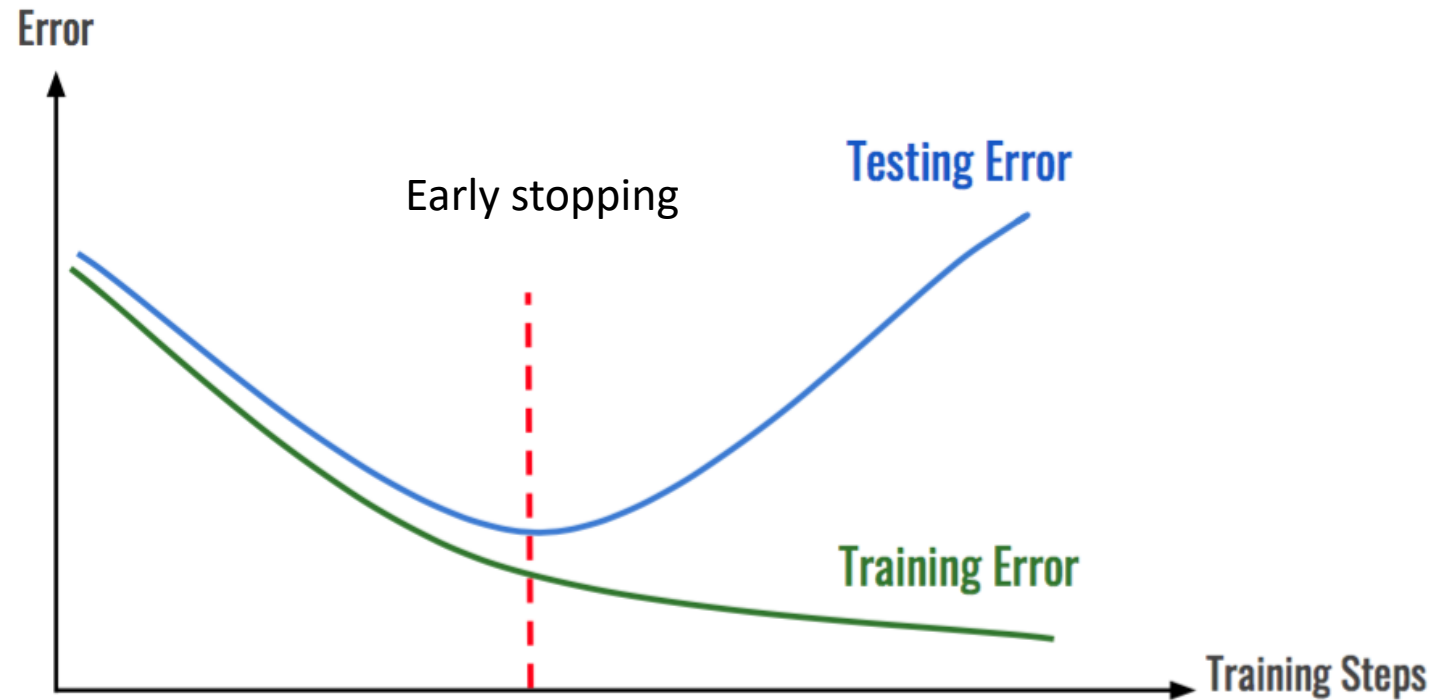


shift shift shear shift & scale rotate & scale



Different Regularization Techniques

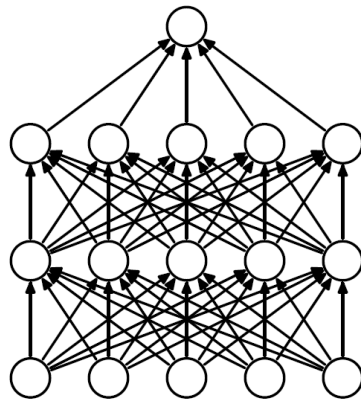
- Early stopping
 - When we see that the performance on the validation set is getting worse, we immediately stop the training on the model.



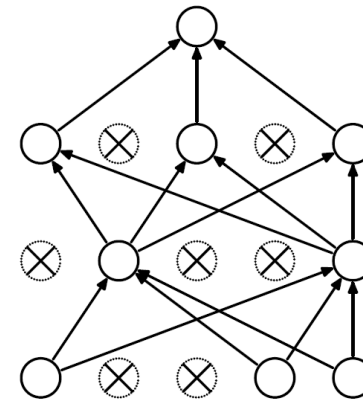
Different Regularization Techniques in Deep Learning

- **Dropout**

- This is the one of the most interesting types of regularization techniques.
- It also produces very good results and is consequently the most frequently used regularization technique in the field of deep learning.
- At every iteration, it **randomly selects some nodes and removes them**.
- It can also be thought of **as an ensemble** technique in machine learning.



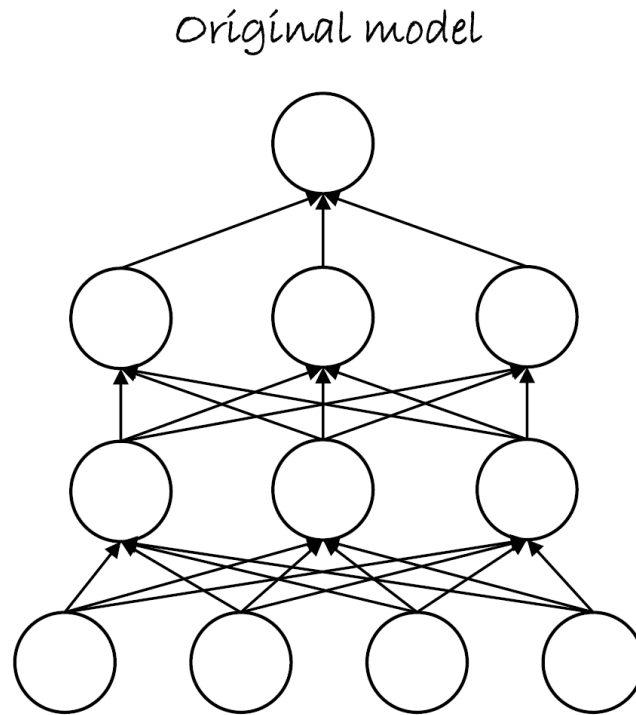
(a) Standard Neural Net



(b) After applying dropout.

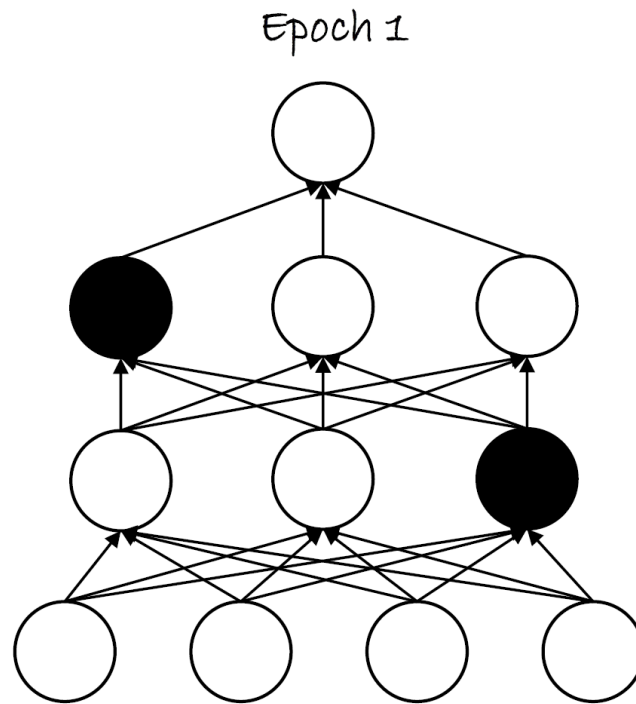
Dropout Illustration

- Effectively, a different architecture at every training epoch
- It can also be thought of as an ensemble technique in machine learning.



Dropout Illustration

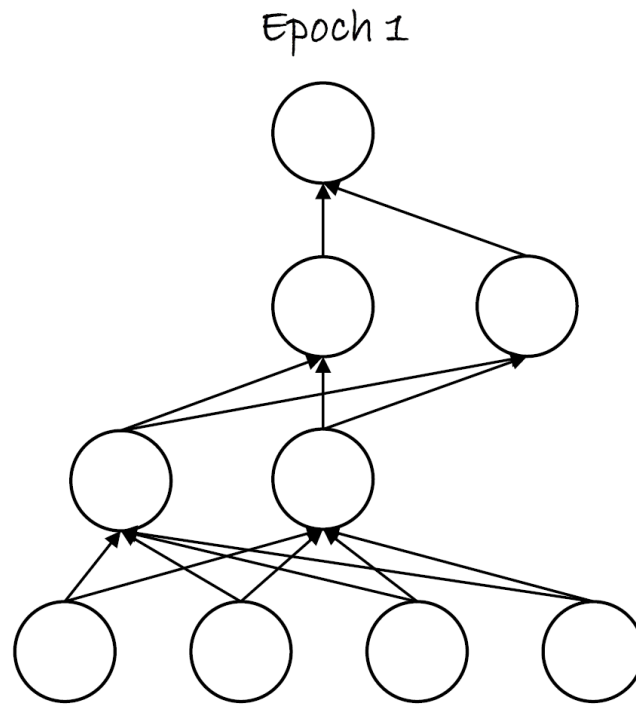
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`tf.nn.dropout(layer, keep_prob = p)`

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