

(Artificial) Neural Networks with TensorFlow

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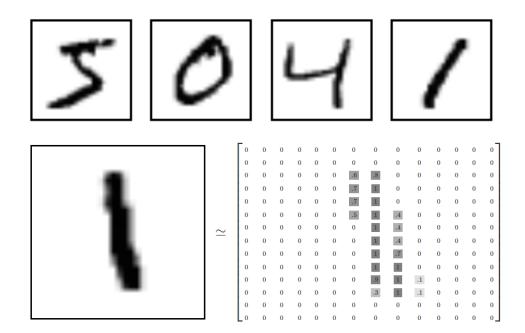


ANN in TensorFlow: MNIST



ANN with MNIST

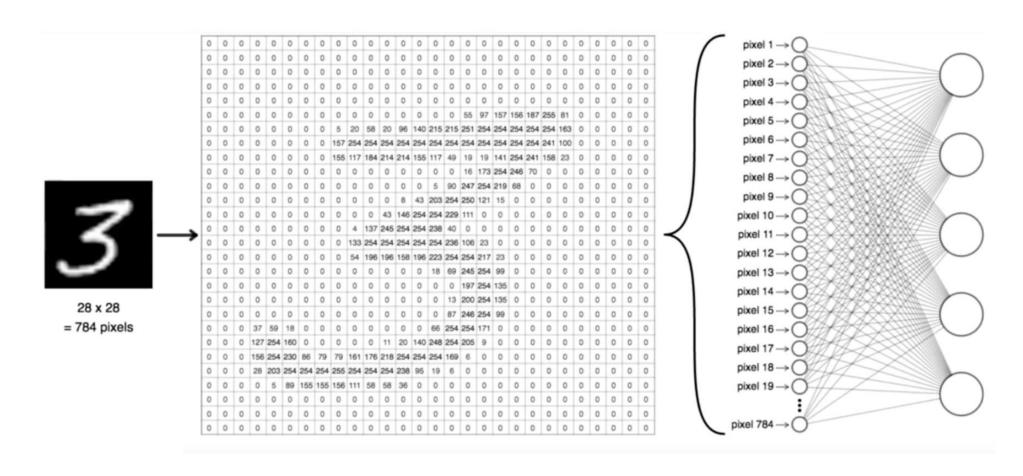
- MNIST database
 - Mixed National Institute of Standards and Technology database
 - Handwritten digit database
 - 28×28 gray scaled image
 - Flattened matrix into a vector of 28×28=784





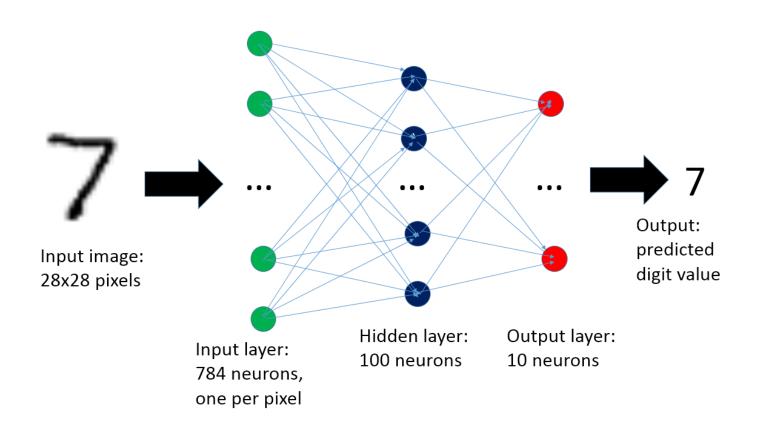
ANN with TensorFlow

Feed a gray image to ANN





Our Network Model



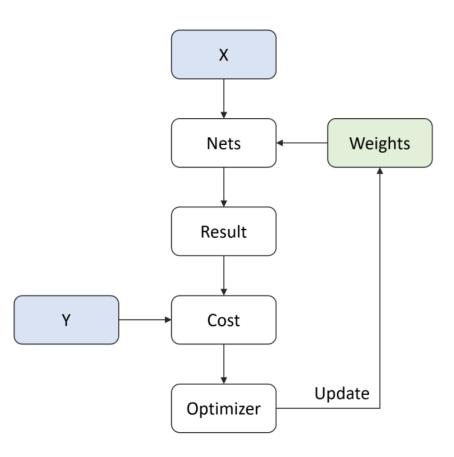


Iterative Optimization

- We will use
 - Mini-batch gradient descent
 - Adam optimizer

$$\min_{ heta} \quad f(heta)$$
 $\mathrm{subject\ to} \quad g_i(heta) \leq 0$

$$heta:= heta-lpha
abla_{ heta}\left(h_{ heta}\left(x^{(i)}
ight),y^{(i)}
ight)$$





ANN with TensorFlow

Import Library

```
# Import Library
import numpy as np
import matplotlib.pyplot as plt
import tensorflow as tf
```

- Load MNIST Data
 - Download MNIST data from TensorFlow tutorial example

```
from tensorflow.examples.tutorials.mnist import input_data
mnist = input_data.read_data_sets("MNIST_data/", one_hot=True)
```



One Hot Encoding

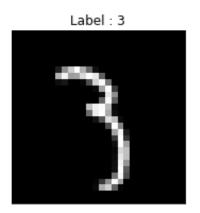
Batch maker

```
train_x, train_y = mnist.train.next_batch(1)
img = train_x[0,:].reshape(28,28)

plt.figure(figsize=(5,3))
plt.imshow(img,'gray')
plt.title("Label : {}".format(np.argmax(train_y[0,:])))
plt.xticks([])
plt.yticks([])
plt.show()
```

One hot encoding

```
print ('Train labels : {}'.format(train_y[0, :]))
Train labels : [0. 0. 0. 1. 0. 0. 0. 0. 0. 0.]
```

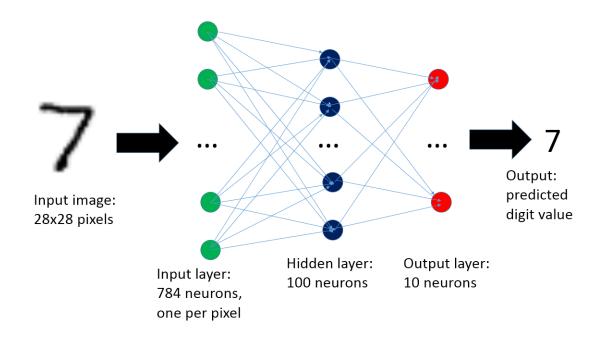




ANN Structure

- Input size
- Hidden layer size
- The number of classes

n_input = 28*28
n_hidden = 100
n_output = 10





Weights & Biases and Placeholder

- Define parameters based on predefined layer size
- Initialize with normal distribution with $\mu=0$ and $\sigma=0.1$

```
weights = {
    'hidden' : tf.Variable(tf.random_normal([n_input, n_hidden], stddev = 0.1)),
    'output' : tf.Variable(tf.random_normal([n_hidden, n_output], stddev = 0.1))
}
biases = {
    'hidden' : tf.Variable(tf.random_normal([n_hidden], stddev = 0.1)),
    'output' : tf.Variable(tf.random_normal([n_output], stddev = 0.1))
}
```

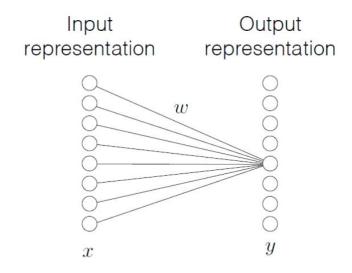
Placeholder

```
x = tf.placeholder(tf.float32, [None, n_input])
y = tf.placeholder(tf.float32, [None, n_output])
```



Build a Model

• First, the layer performs several matrix multiplication to produce a set of linear activations



$$y_j = \left(\sum_i \omega_{ij} x_i
ight) + b_j \ y = \omega^T x + b$$

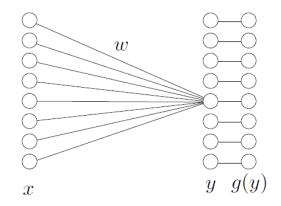
```
# Define Network
def build_model(x, weights, biases):

# first hidden Layer
hidden = tf.add(tf.matmul(x, weights['hidden']), biases['hidden'])
# non-linear activate function
hidden = tf.nn.relu(hidden)

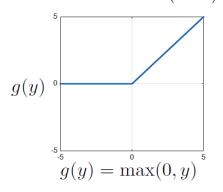
# Output Layer
output = tf.add(tf.matmul(hidden, weights['output']), biases['output'])
return output
```

Build a Model

• Second, each linear activation is running through a nonlinear activation function



Rectified linear unit (ReLU)



```
# Define Network
def build_model(x, weights, biases):

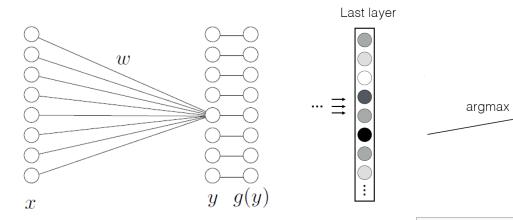
# first hidden layer
hidden = tf.add(tf.matmul(x, weights['hidden']), biases['hidden'])

# non-linear activate function
hidden = tf.nn.relu(hidden)

# Output layer
output = tf.add(tf.matmul(hidden, weights['output']), biases['output'])
return output
```

Build a Model

• Third, predict values with an affine transformation



```
# Define Network
def build_model(x, weights, biases):

# first hidden Layer
hidden = tf.add(tf.matmul(x, weights['hidden']), biases['hidden'])
# non-linear activate function
hidden = tf.nn.relu(hidden)

# Output Layer
output = tf.add(tf.matmul(hidden, weights['output']), biases['output'])
return output
```

Loss and Optimizer

Loss: softmax cross entropy

$$-rac{1}{N} \sum_{i=1}^N y^{(i)} \log(h_ heta\left(x^{(i)}
ight)) + (1-y^{(i)}) \log(1-h_ heta\left(x^{(i)}
ight))$$

- Optimizer
 - AdamOptimizer: the most popular optimizer

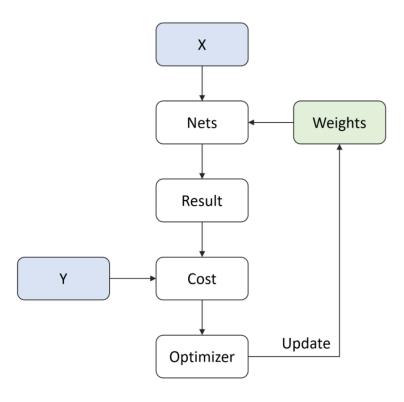
```
# Define Loss
pred = build_model(x, weights, biases)
loss = tf.nn.softmax_cross_entropy_with_logits(logits = pred, labels = y)
loss = tf.reduce_mean(loss)

LR = 0.0001
optm = tf.train.AdamOptimizer(LR).minimize(loss)
```

Iteration Configuration

- Define parameters for training ANN
 - n_batch: batch size for mini-batch gradient descent
 - n_iter: the number of iteration steps
 - n_prt: check loss for every n_prt iteration

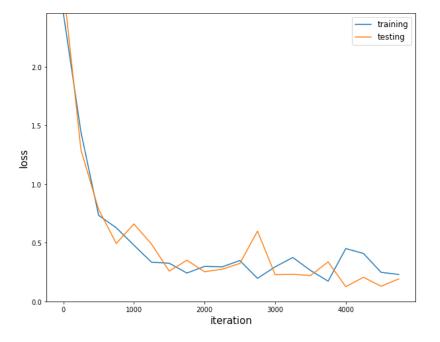
```
n_batch = 50  # Batch Size
n_iter = 5000  # Learning Iteration
n_prt = 250  # Print Cycle
```





Optimization

```
sess = tf.Session()
init = tf.global_variables_initializer()
sess.run(init)
loss record training = []
loss_record_testing = []
for epoch in range(n iter):
   train x, train y = mnist.train.next batch(n batch)
    sess.run(optm, feed dict = {x: train x, y: train y})
    if epoch % n prt == 0:
       test_x, test_y = mnist.test.next_batch(n_batch)
        c1 = sess.run(loss, feed dict = {x: train x, y: train y})
        c2 = sess.run(loss, feed dict = {x: test x, y: test y})
       loss_record_training.append(c1)
       loss record testing.append(c2)
        print ("Iter : {}".format(epoch))
        print ("Cost : {}".format(c1))
plt.figure(figsize=(10,8))
plt.plot(np.arange(len(loss record training))*n prt,
        loss record training, label = 'training')
plt.plot(np.arange(len(loss record testing))*n prt,
        loss record testing, label = 'testing')
plt.xlabel('iteration', fontsize = 15)
plt.ylabel('loss', fontsize = 15)
plt.legend(fontsize = 12)
plt.ylim([0,np.max(loss record training)])
plt.show()
```





Test or Evaluation

```
test_x, test_y = mnist.test.next_batch(100)

my_pred = sess.run(pred, feed_dict = {x : test_x})
my_pred = np.argmax(my_pred, axis = 1)

labels = np.argmax(test_y, axis = 1)

accr = np.mean(np.equal(my_pred, labels))
print("Accuracy : {}%".format(accr*100))
```

```
test_x, test_y = mnist.test.next_batch(1)
logits = sess.run(tf.nn.softmax(pred), feed_dict = {x : test_x})
predict = np.argmax(logits)

plt.imshow(test_x.reshape(28,28), 'gray')
plt.xticks([])
plt.yticks([])
plt.yticks([])
plt.show()

print('Prediction : {}'.format(predict))
np.set_printoptions(precision=2, suppress=True)
print('Probability : {}'.format(logits.ravel()))
```



