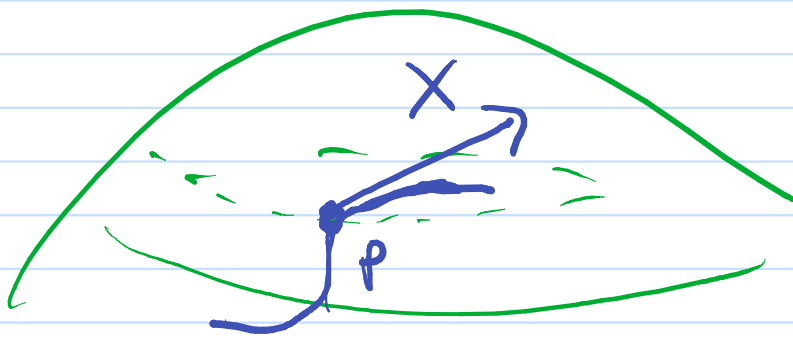
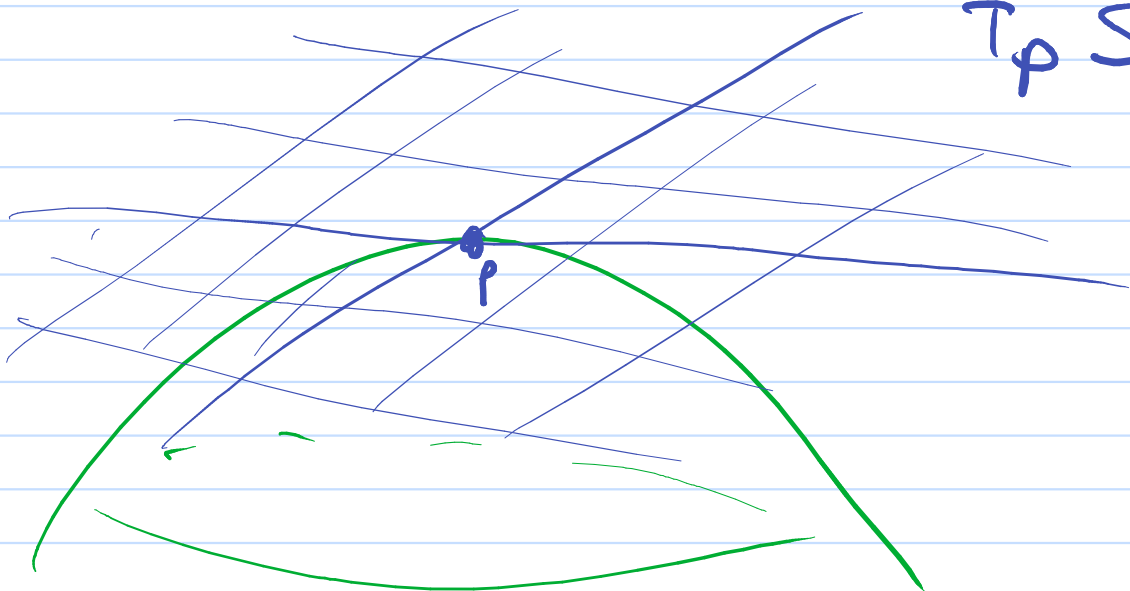


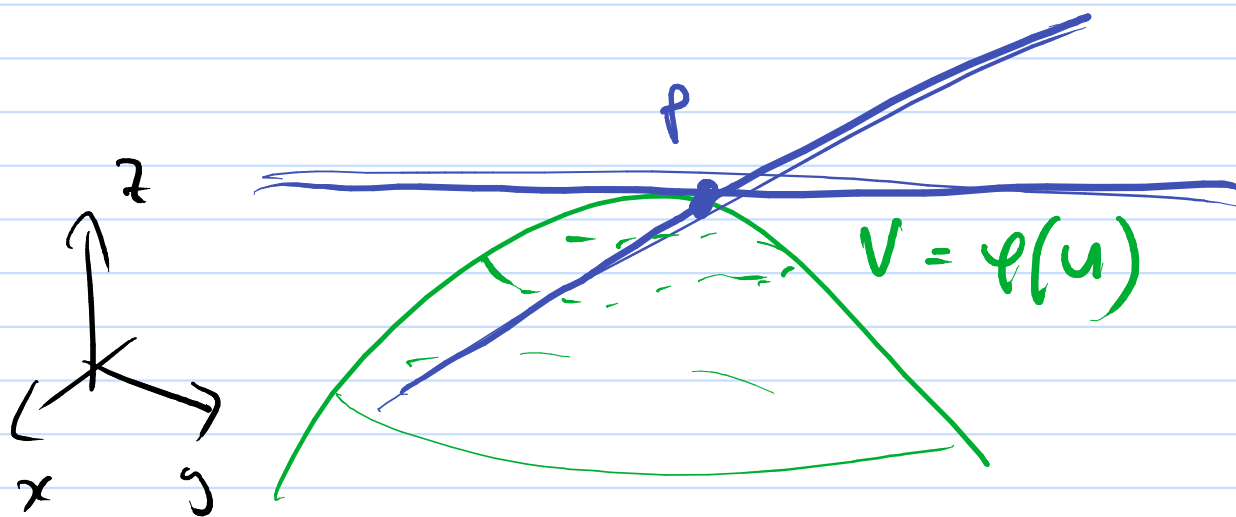
Tangent Vector



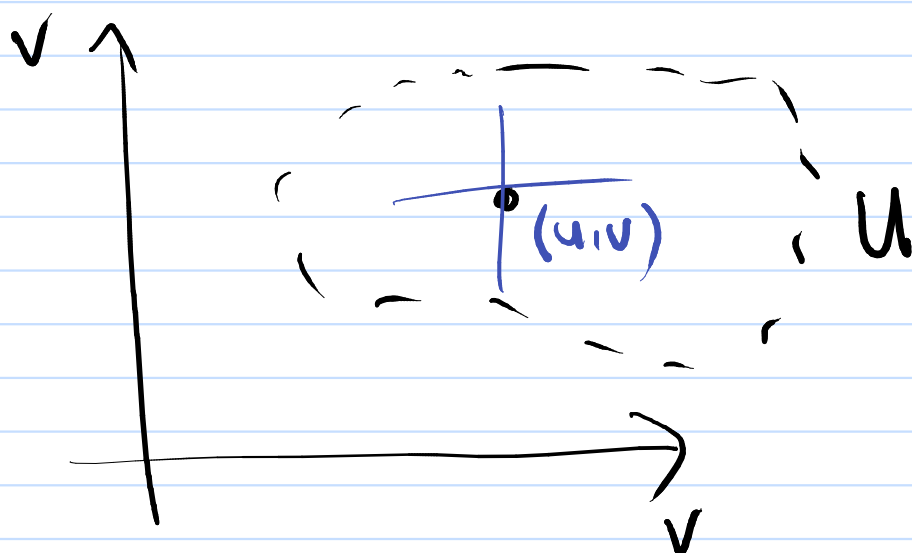
S



$T_p S$



$$\varphi(u, v) = p$$

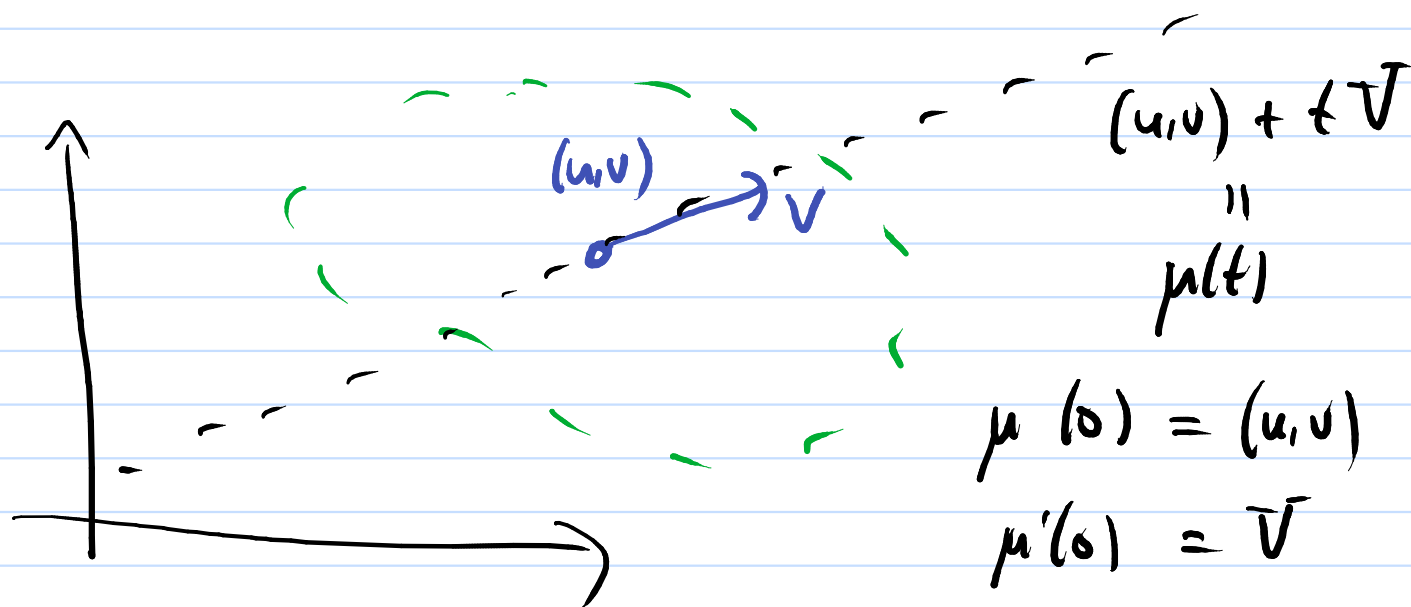
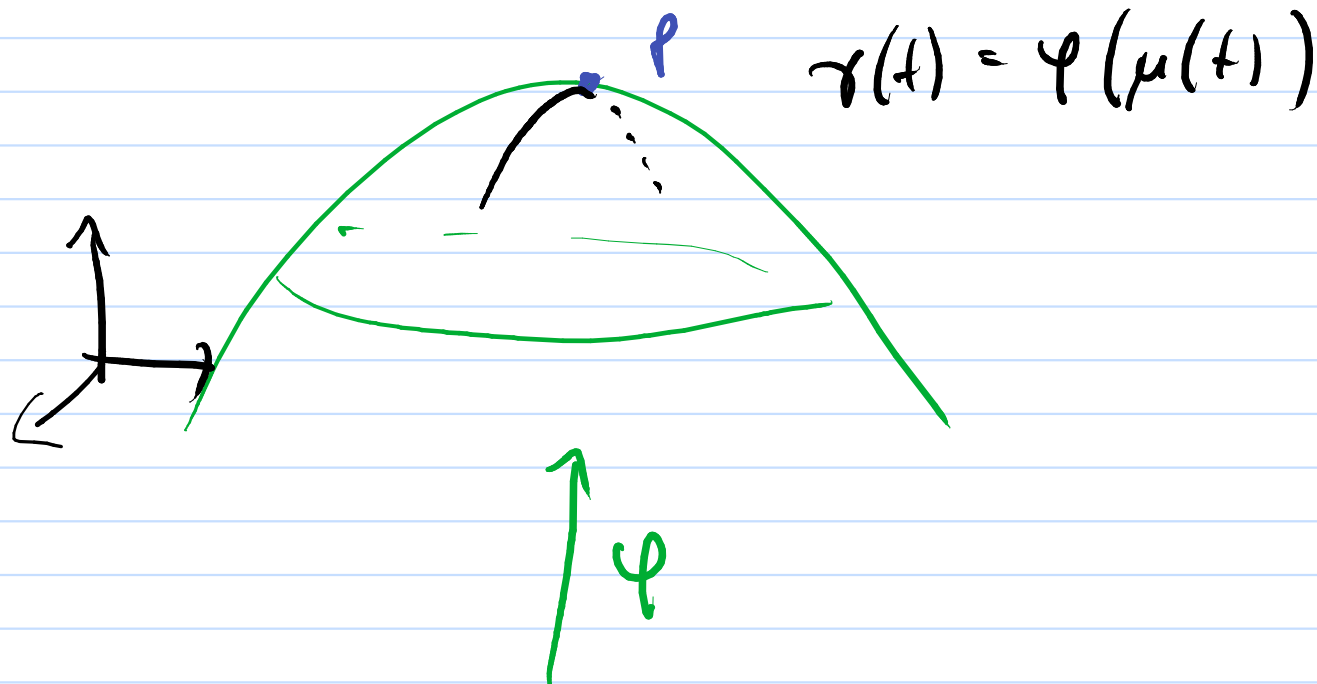


$$T_p S = d\varphi_{(u,v)}(\mathbb{R}^2)$$

$$= \text{Im } d\varphi_{(u,v)}$$

where we think of $\varphi: U \rightarrow \mathbb{R}^3$

Note: $\dim \text{Im } d\varphi_{(u,v)} = 2$ (regular)

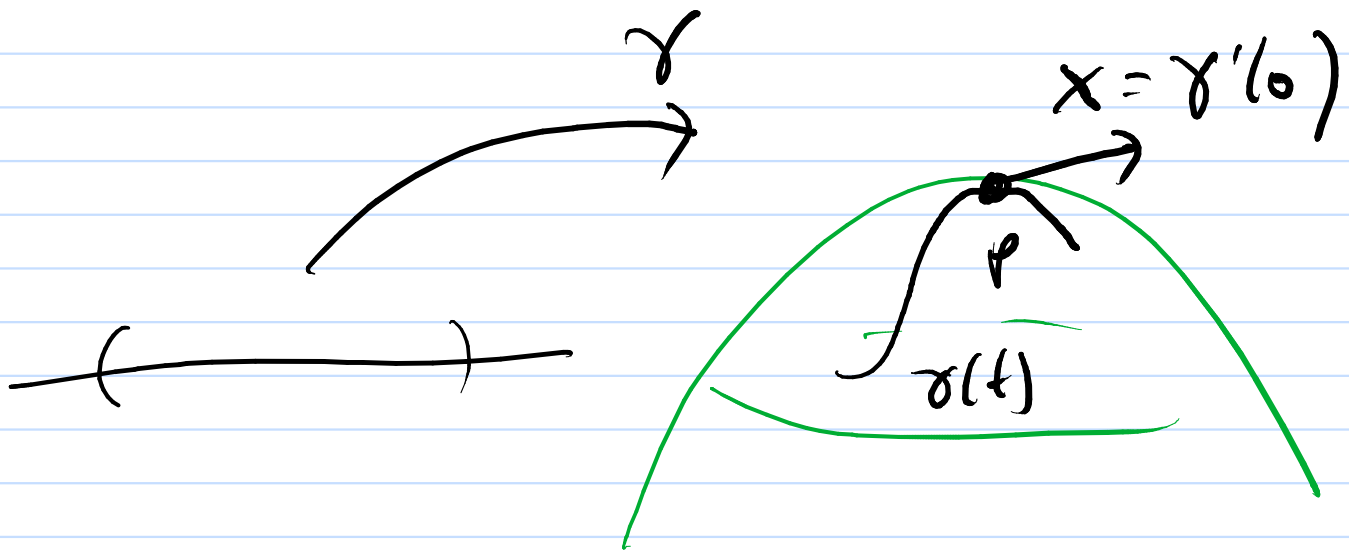


$$\boxed{d\varphi_{(u,v)}(\bar{V})} = \frac{d}{dt} \Big|_{t=0} \varphi(\mu(t))$$

$$\uparrow = \gamma'(0) \in T_p S$$

Im $d\varphi_{(u,v)}$

$$\therefore d\varphi_{(u,v)}(\bar{V}) \in T_p S \implies \text{Im } d\varphi_{(u,v)} \subseteq T_p S$$

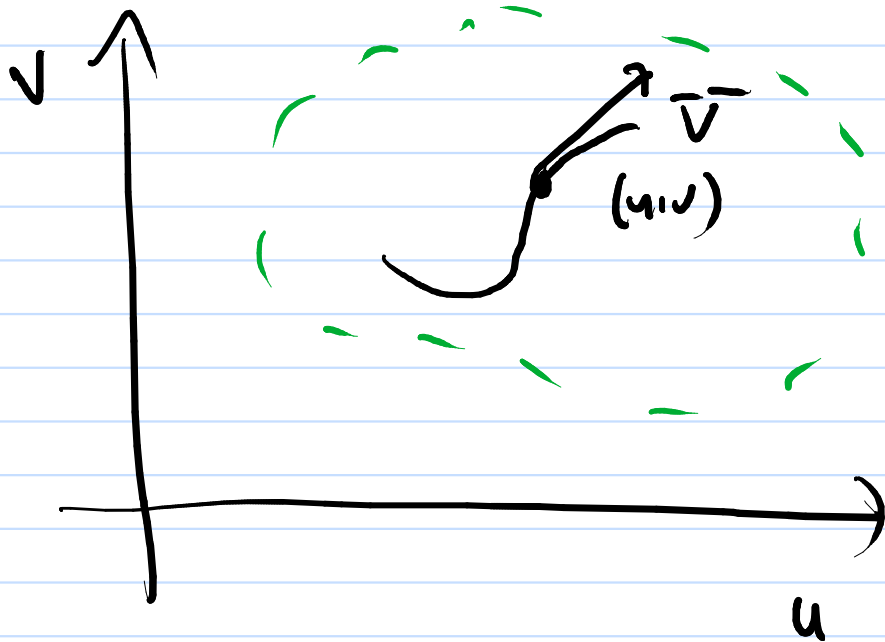


Need to show $X = \gamma'(0) = d\phi_{(u,v)}(\bar{V})$

for $\bar{V} \in \mathbb{R}^2$

$$\dagger \quad (u,v) = \phi^{-1}(p)$$

u



$$\mu(t) = \phi^{-1}(\gamma(t))$$

$$\bar{V} = \mu'(0)$$

if ϕ^{-1} is $C^\infty \Rightarrow \mu$ is C^∞

$$\dagger \quad d\phi(\bar{V}) = \frac{d}{dt}\bigg|_{t=0} (\phi \circ \underbrace{\phi^{-1} \circ \gamma}_{\mu}) = \gamma'(0) = X$$

$$IFT \Rightarrow \exists \underset{\text{(locally)}}{\Phi} : \mathbb{R}^3 \rightarrow \mathbb{R}^3$$

s.t. Φ is C^∞

$$\exists \Phi^{-1}|_S = \varphi^{-1}$$

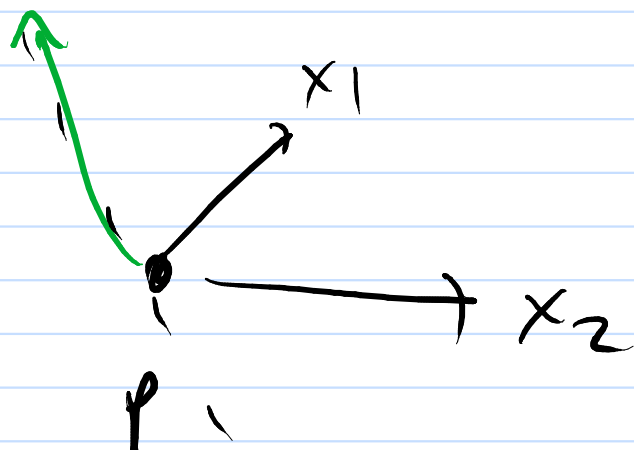
$$\Phi|_{\{\omega=0\}} = \varphi$$

$$\parallel \\ \varphi \circ \iota_{\{\omega=0\}}$$

$$\therefore \mu(t) = \varphi^{-1} \circ \gamma(t)$$

$$= \pi_{\{\omega=0\}} \circ \Phi^{-1} \circ \gamma \text{ is } C^\infty.$$

$$c_1 x_1 + c_2 x_2$$



$\gamma(t)$

$$p + t \underbrace{(c_1 x_1 + c_2 x_2)}_{\gamma'}$$

$\gamma(t) \notin S$ in general

Vector Space Structure

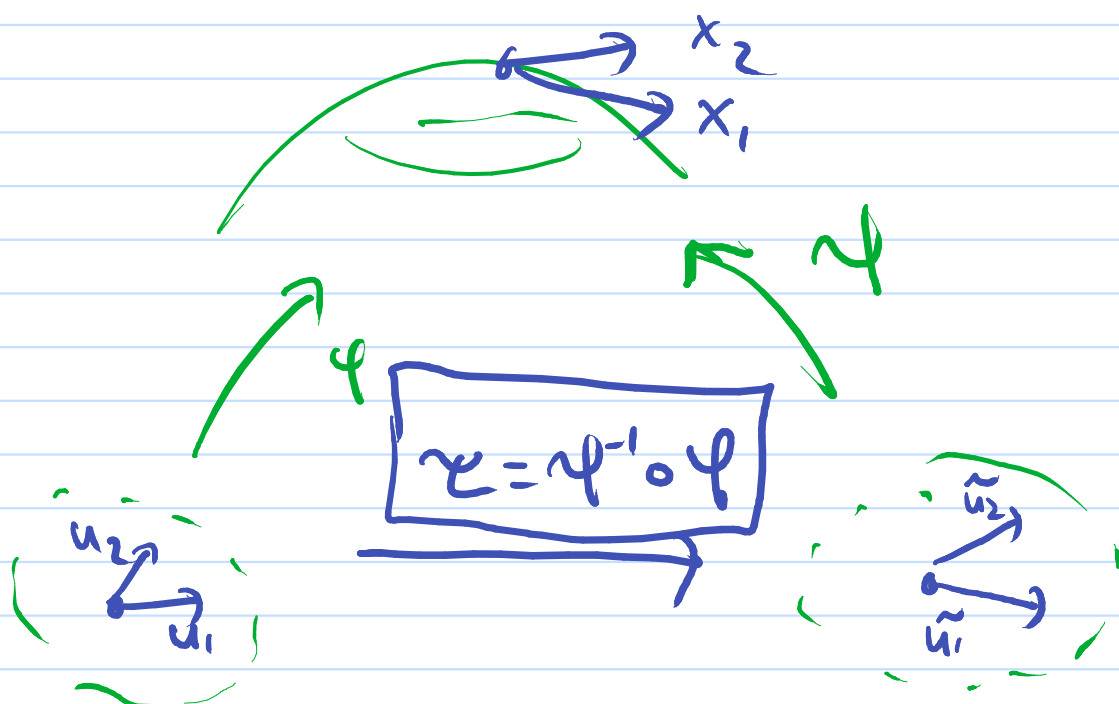
Given $X \in T_p S$

$$\exists ! V \in \mathbb{R}^2 \text{ s.t. } d\varphi(V) = X$$

↑
showed
already
in lemma

↑
 $d\varphi$ injective.

$\therefore c^1 X_1 + c^2 X_2$ is well defined
up to choosing parametrisation φ



CLAIM: $d\varphi(c^1 u_1 + c^2 u_2) = d\varphi(c^1 \tilde{u}_1 + c^2 \tilde{u}_2)$

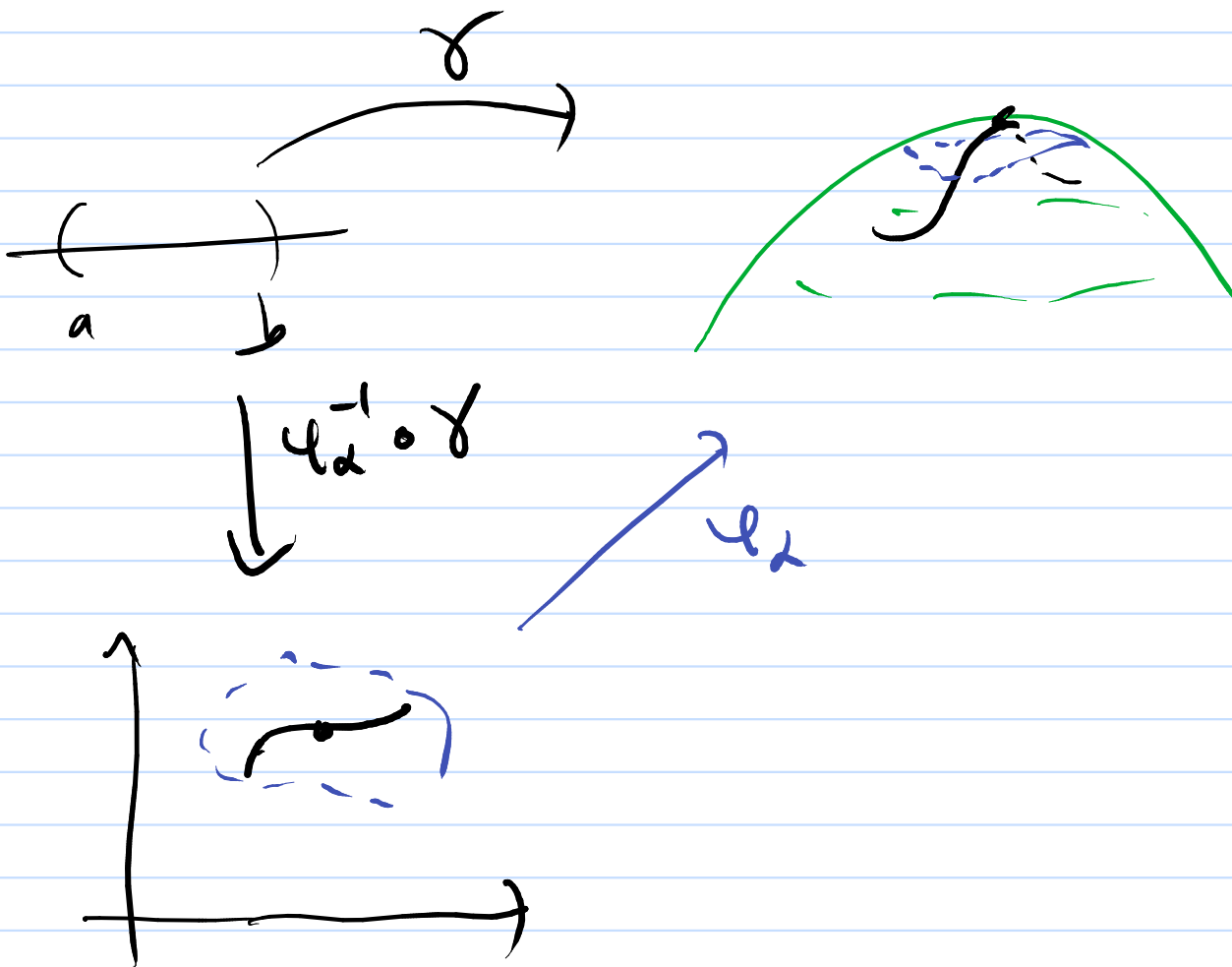
$$\gamma : (a,b) \rightarrow S \text{ is } C^\infty$$



$$c \circ \gamma : (a,b) \rightarrow \mathbb{R}^3 \text{ is } C^\infty$$

$$\text{where } c : S \xrightarrow{\subseteq} \mathbb{R}^3$$

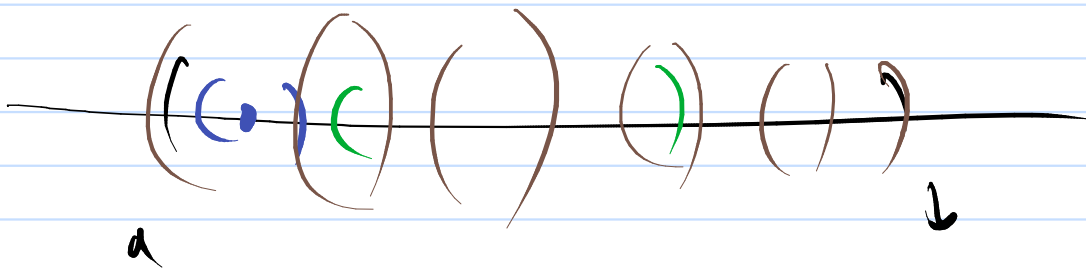
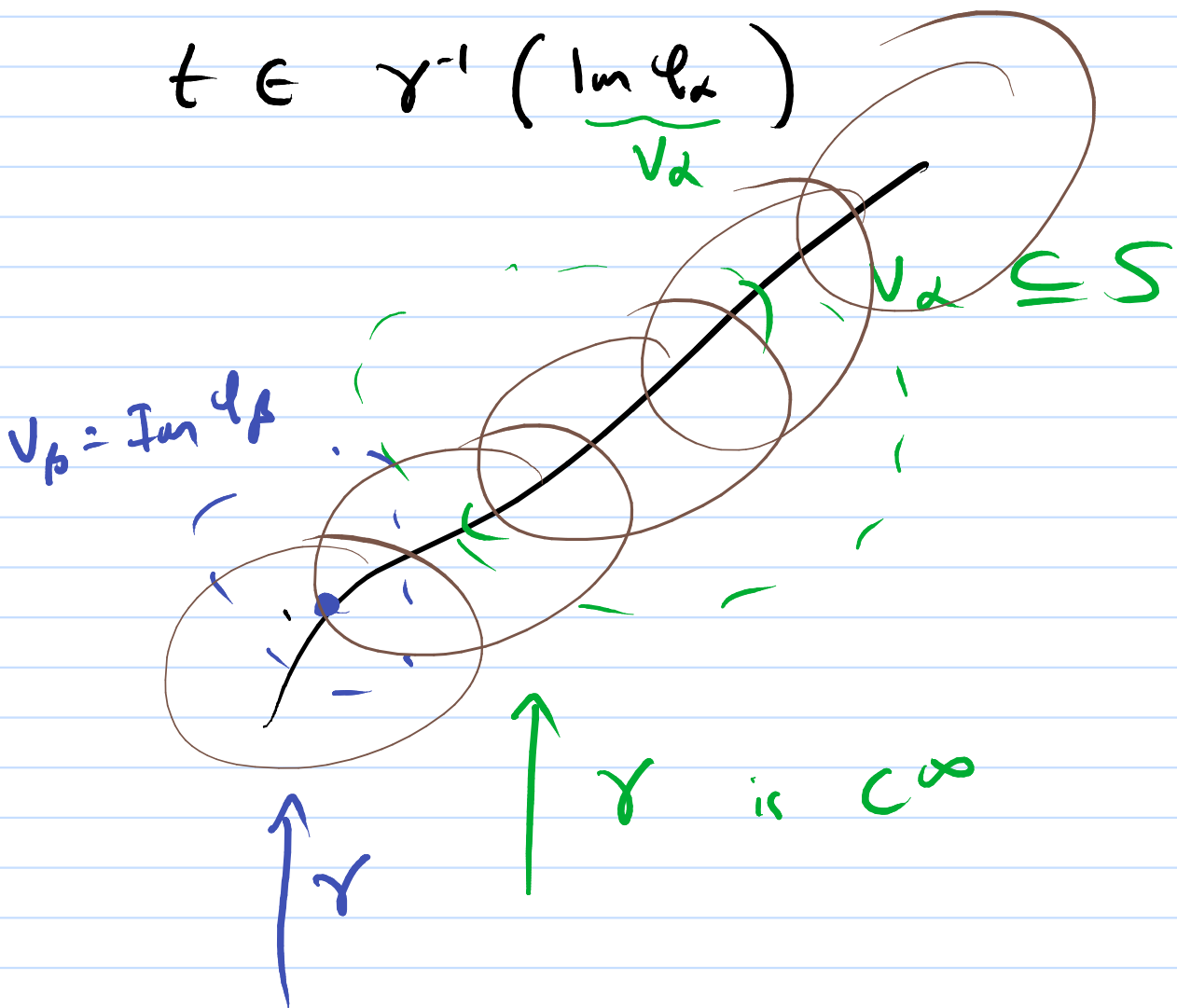
is the inclusion.

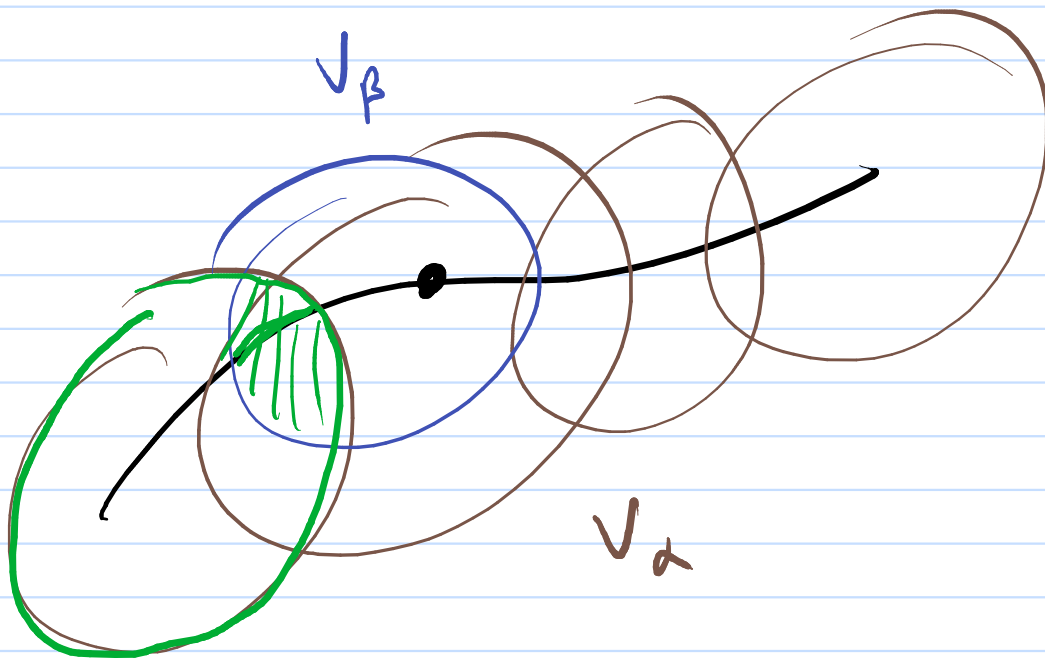


$\varphi_\alpha^{-1} \circ \gamma$ is C^∞

$\Rightarrow \gamma$ is C^∞ for

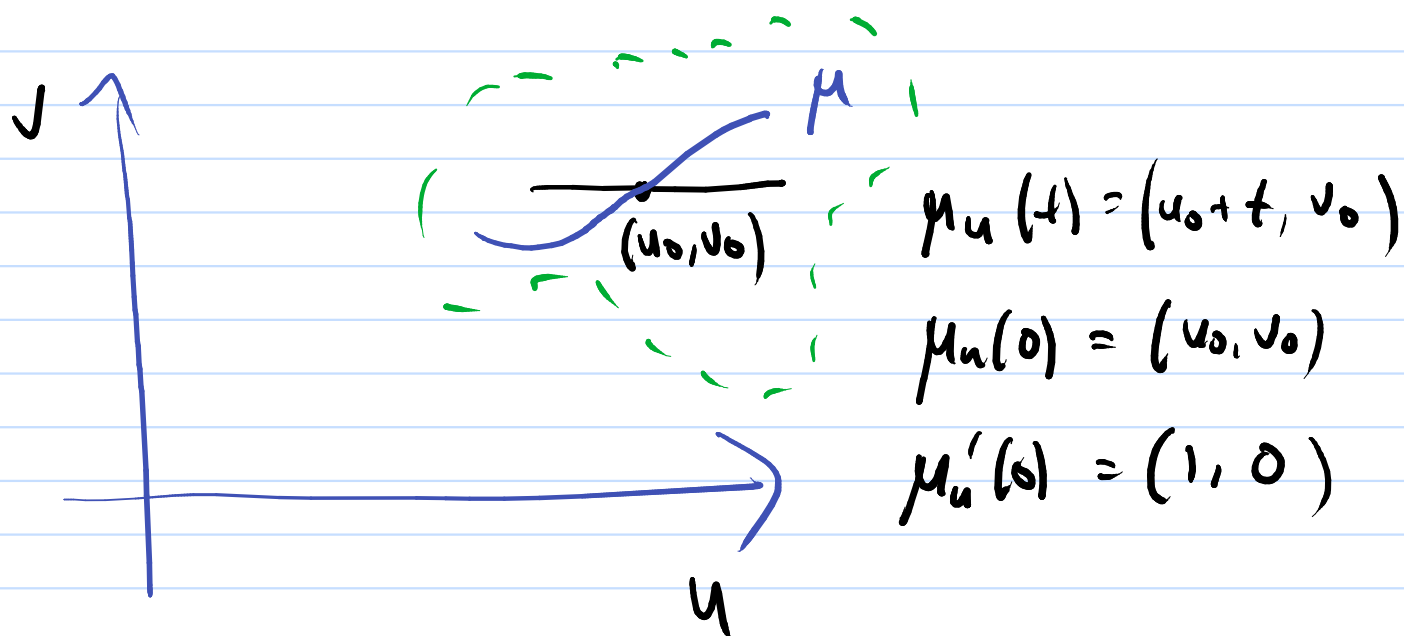
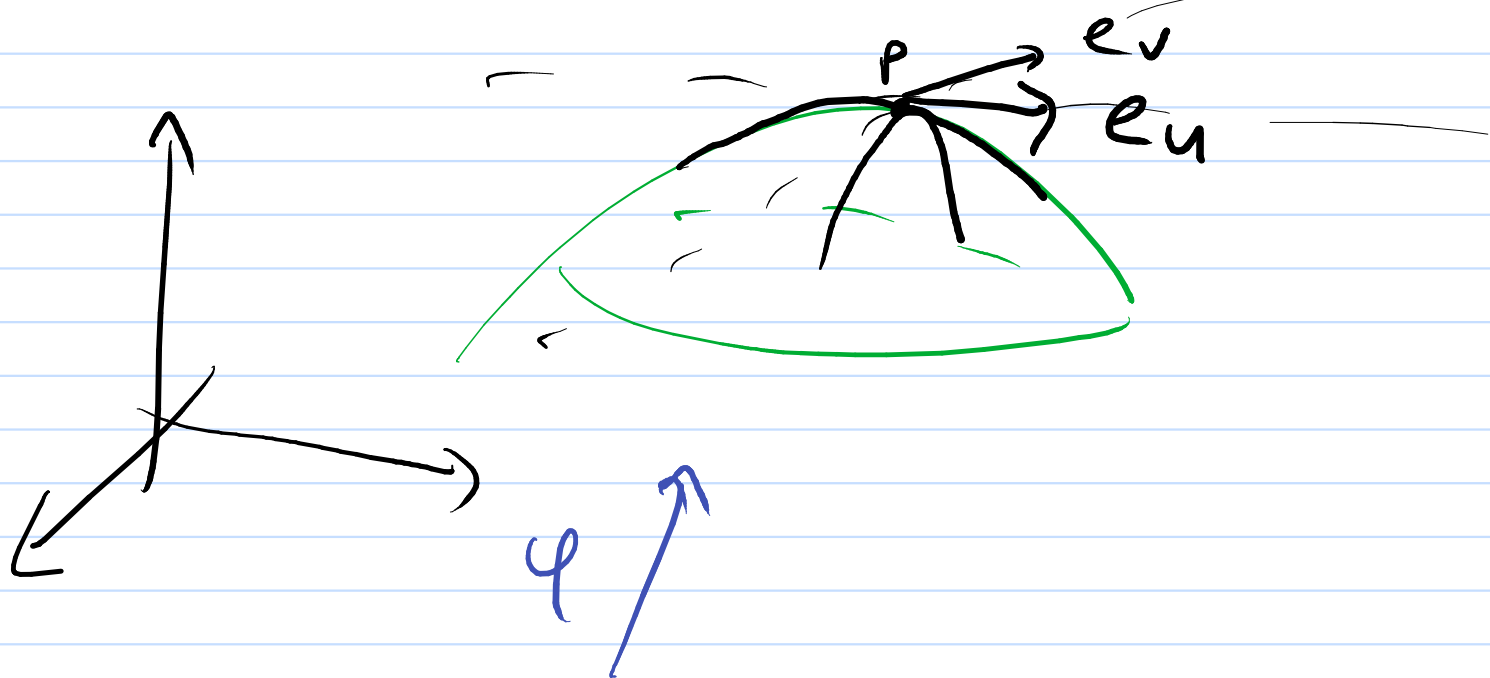
$$t \in \gamma^{-1}(\underbrace{\text{Im } \varphi_\alpha}_{V_\alpha})$$





If $\varphi_{\alpha}^{-1} \circ \gamma$ is C^{∞} for
 the cover, then for
 any V_{β} , $\varphi_{\beta}^{-1} \circ \gamma$ is C^{∞} .

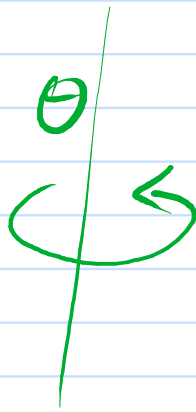
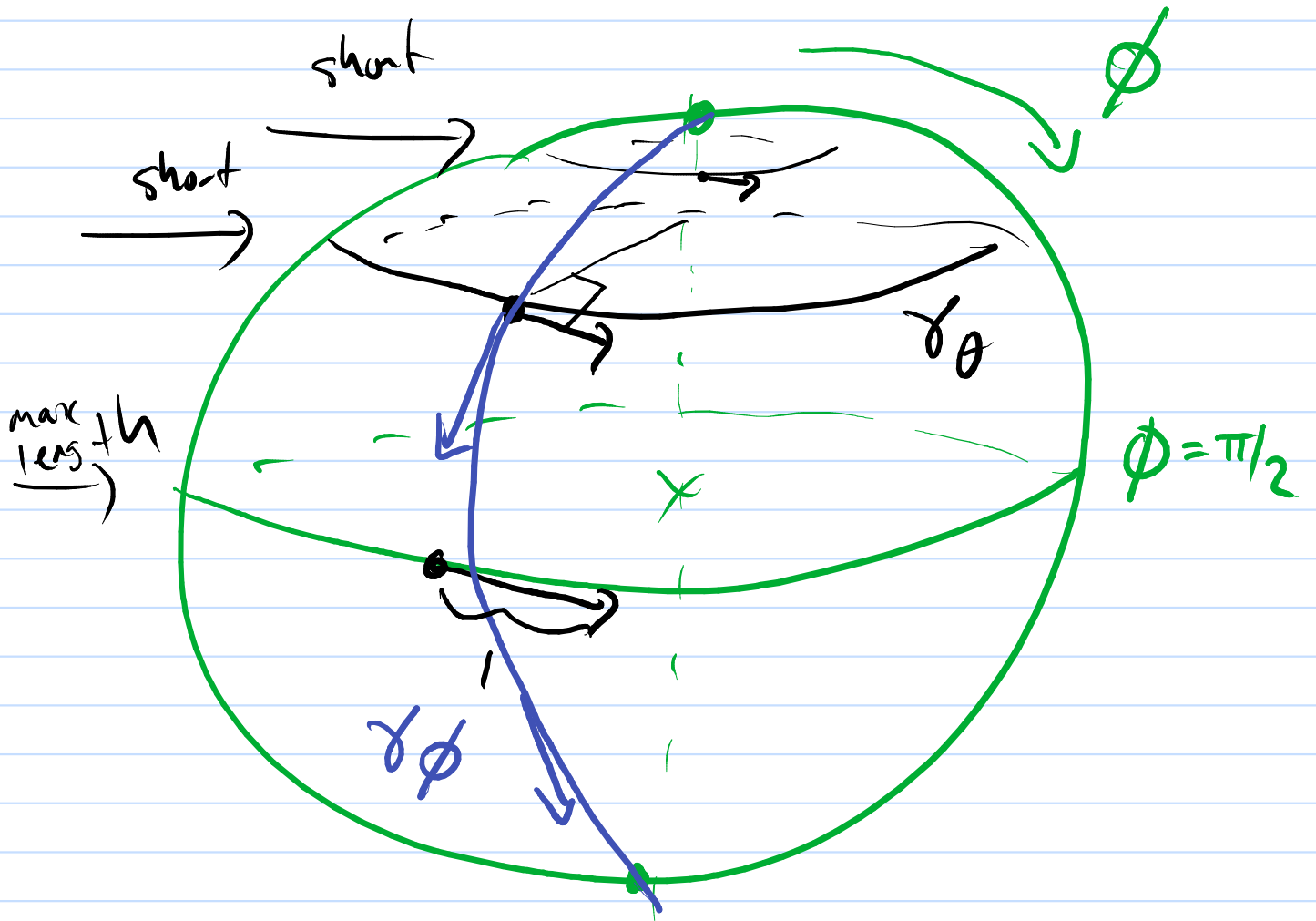
$$\underbrace{\text{Im } \gamma \cap V_{\beta}} = \bigcup_{\alpha} V_{\beta} \cap (V_{\alpha} \cap \text{Im } \gamma)$$



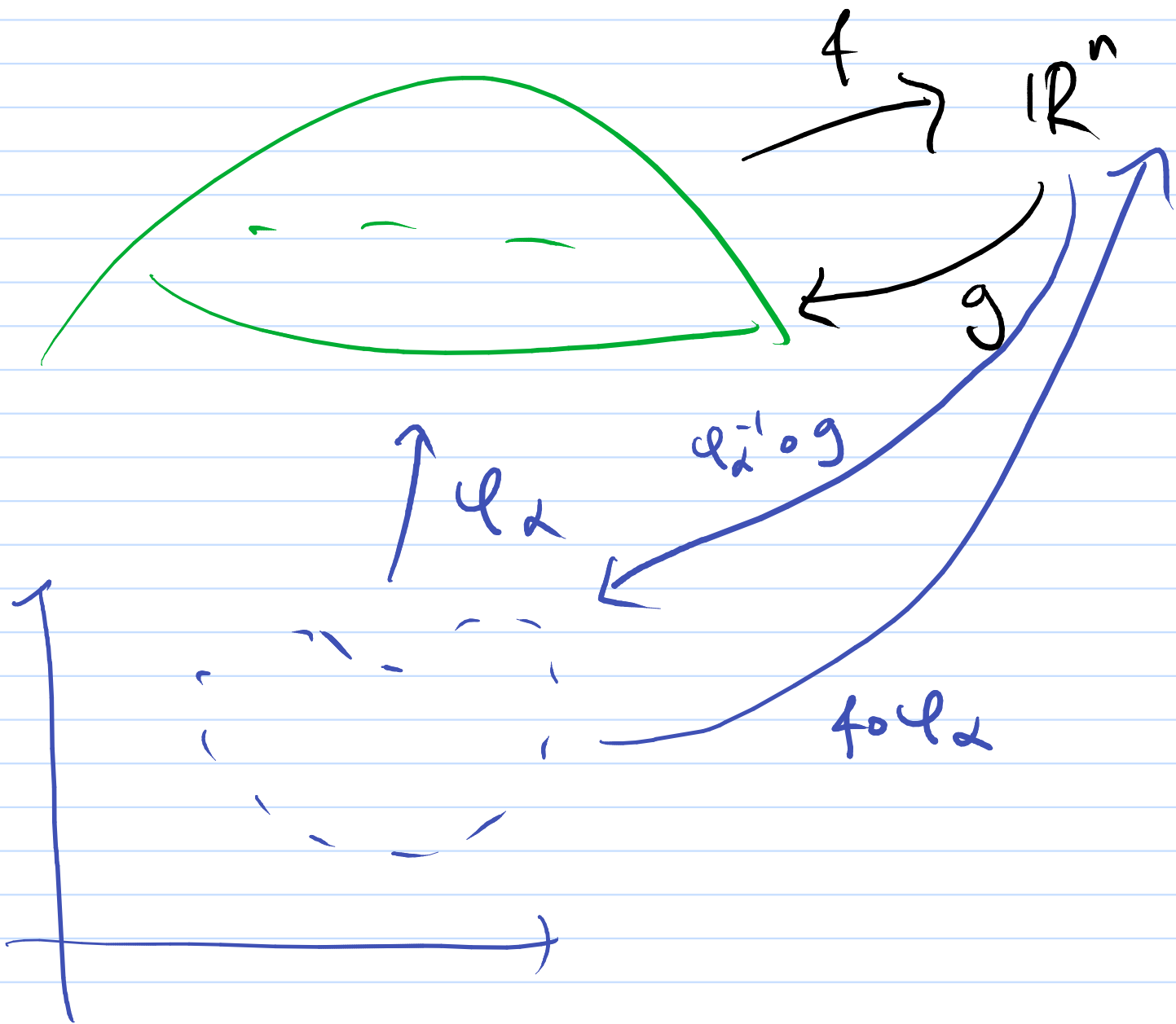
$$\gamma_u = \varphi \circ \mu_u$$

$$\gamma_v = \varphi \circ \mu_v$$

$$e_u = \gamma'_u(0) \quad e_v = \gamma'_v(0)$$

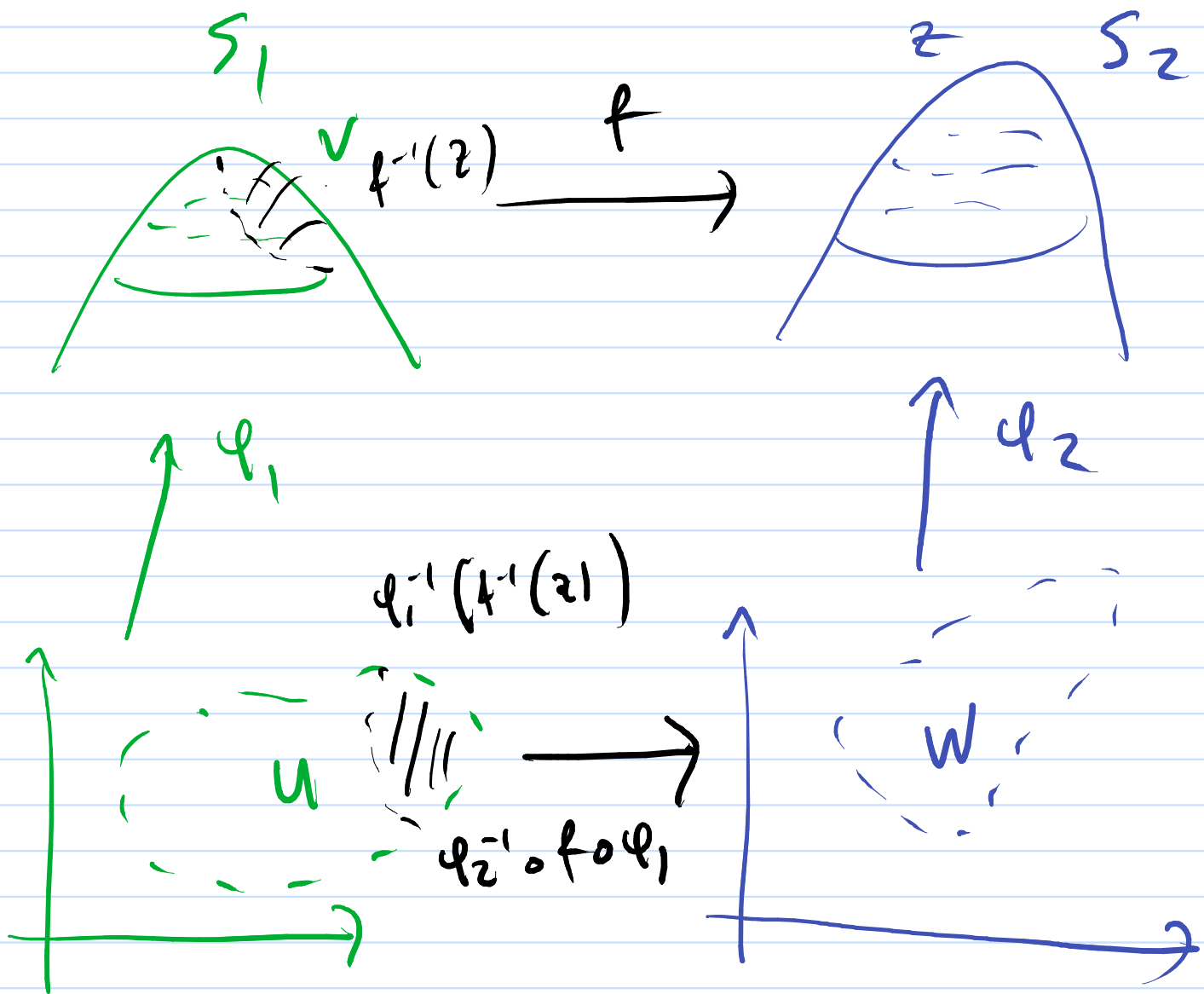


SMOOTH MAPS



Defn $f: S \rightarrow \mathbb{R}^n$ is C^∞ if $\underbrace{f \circ \phi_\alpha}_{\mathbb{R}^2 \rightarrow \mathbb{R}^n}$ is C^∞

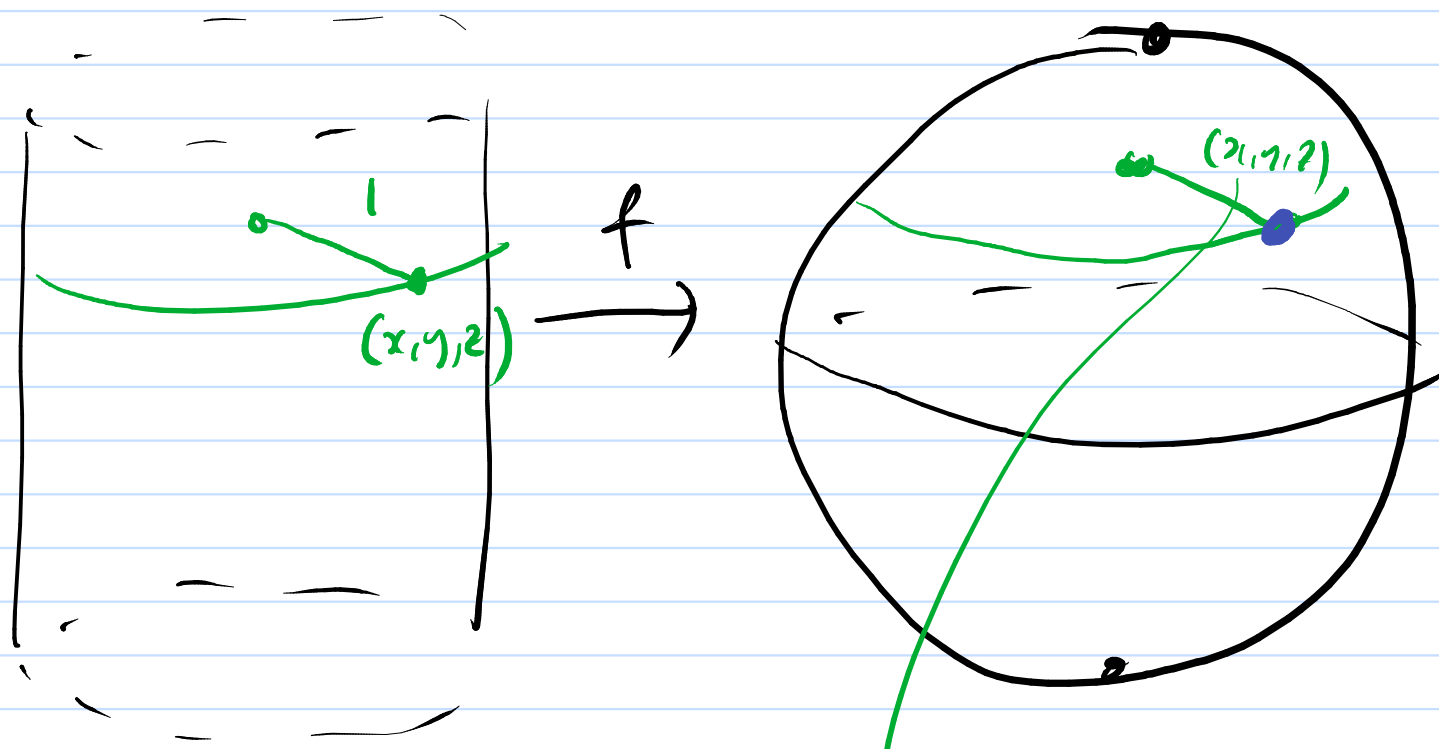
$g: \mathbb{R}^n \rightarrow S$ is C^∞ if $\underbrace{\phi_\alpha^{-1} \circ g}_{\mathbb{R}^n \rightarrow \mathbb{R}^2}$ is C^∞



$$\phi_1^{-1}(f^{-1}(z) \cap v)$$

$$S^1 \xrightarrow{g} S^2 \xrightarrow{f} S^3$$

$$\begin{array}{ccccc}
 & & \uparrow \varphi_2 & & \uparrow \varphi_3 \\
 \varphi_1 \uparrow & & & & \\
 \mathbb{R}^2 & \xrightarrow{\varphi_2^{-1} \circ f \circ \varphi_1} & \mathbb{R}^2 & \xrightarrow{\varphi_3^{-1} \circ g \circ \varphi_2} & \mathbb{R}^2 \\
 & \searrow \varphi_3^{-1} \circ (f \circ g) \circ \varphi_1 & & &
 \end{array}$$



$$x^2 + y^2 + z^2 = 1$$

φ_C

$$(r, \theta) \mapsto (\cos \theta, \sin \theta, r)$$

$$\theta \in (0, 2\pi)$$

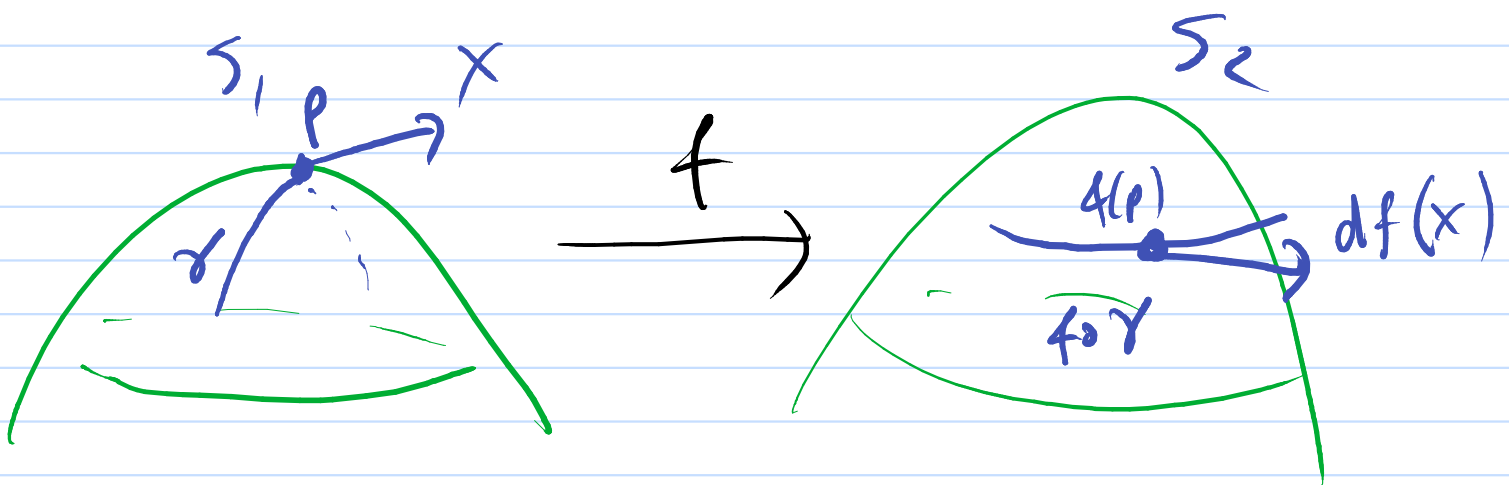
$$r \in (-1, 1)$$

φ_{S^2}

$$(r, \theta)$$

$$\mapsto (\sqrt{1-r^2} \cos \theta, \sqrt{1-r^2} \sin \theta, r)$$

$$\varphi_B^{-1} \circ f \circ \varphi_C(r, \theta) = (r, \theta)$$



if γ is a curve on S_1

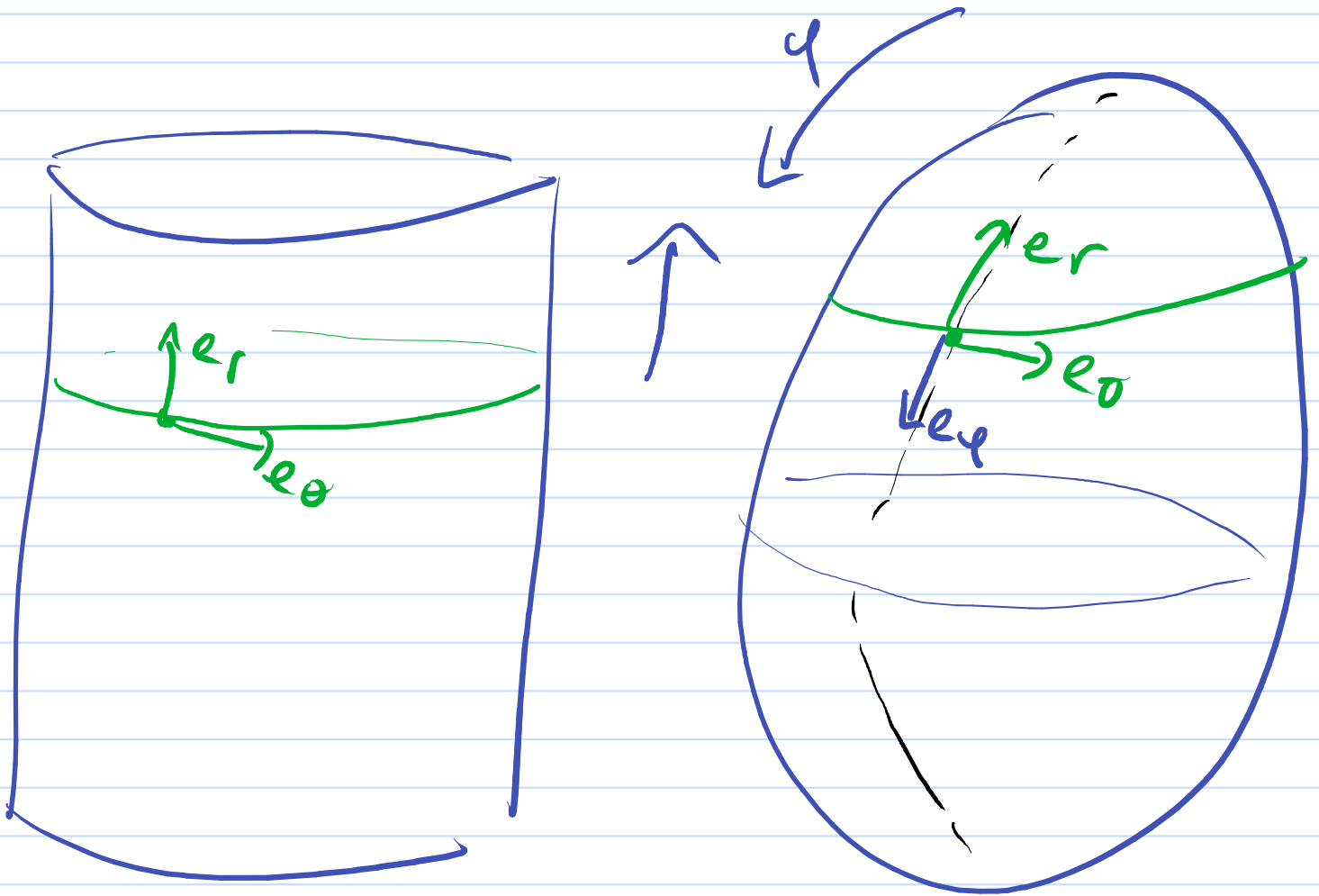
then $f \circ \gamma$ is a curve on S_2

$$\therefore (f \circ \gamma)'(0) \in T_{f(p)} S_2$$

$$\underbrace{f \circ \gamma}_{\uparrow S_2} = \underbrace{L_2 \circ (f \circ \gamma)}_{\uparrow \mathbb{R}^3}$$

$$\begin{array}{ccc}
 S_1 & \xrightarrow{f} & S_2 \\
 \uparrow \varphi_1 & & \uparrow \varphi_2 \\
 \mathbb{R}^2 & \xrightarrow{\varphi_2^{-1} \circ f \circ \varphi_1 = F} & \mathbb{R}^2
 \end{array}$$

$$F(u, v) = (F_1(u, v), F_2(u, v))$$



$$|e_\theta| = |e_r| = 1$$

$$z = \cos \phi \Rightarrow |\vec{s} \cdot \hat{n}| = \sqrt{1 - z^2}$$

||
 $\vec{s} \cdot \hat{n} = \phi \quad \phi \in (0, \pi)$

$$d\mathbf{f} = \begin{pmatrix} 1 & 0 \\ 0 & -\frac{1}{\sqrt{1-z^2}} \end{pmatrix}$$

$$\begin{array}{ccc} (e_0, e_r) & \longrightarrow & (e_0, e_\varphi) \\ TC & & T\mathbb{S}^2 \end{array}$$

Use change of basis

$$\begin{array}{ccc} (e_0, e_r) & \longrightarrow & (e_0, e_\varphi) \\ T\mathbb{S}^2 & & T\mathbb{S}^2 \end{array}$$