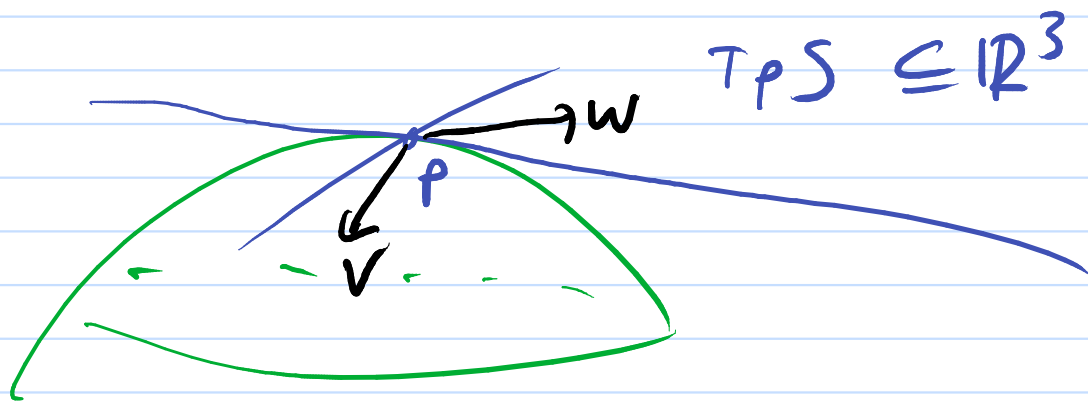
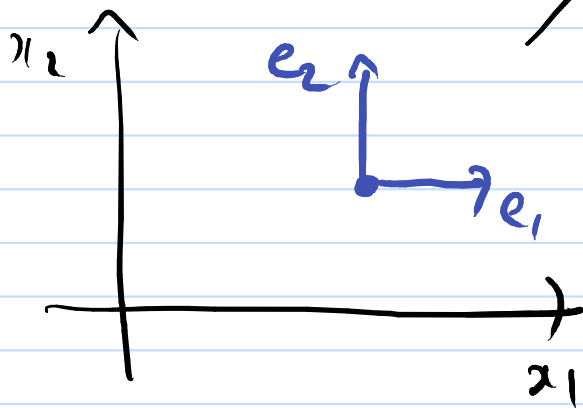
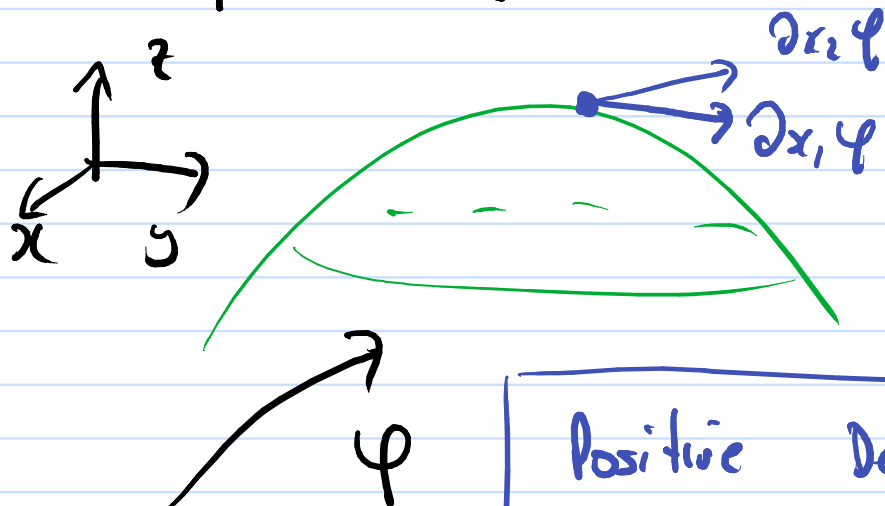


Typo in slide:

$$g_p(v, w) = \langle v, w \rangle_{\mathbb{R}^3}$$



Coordinate Expression of metric



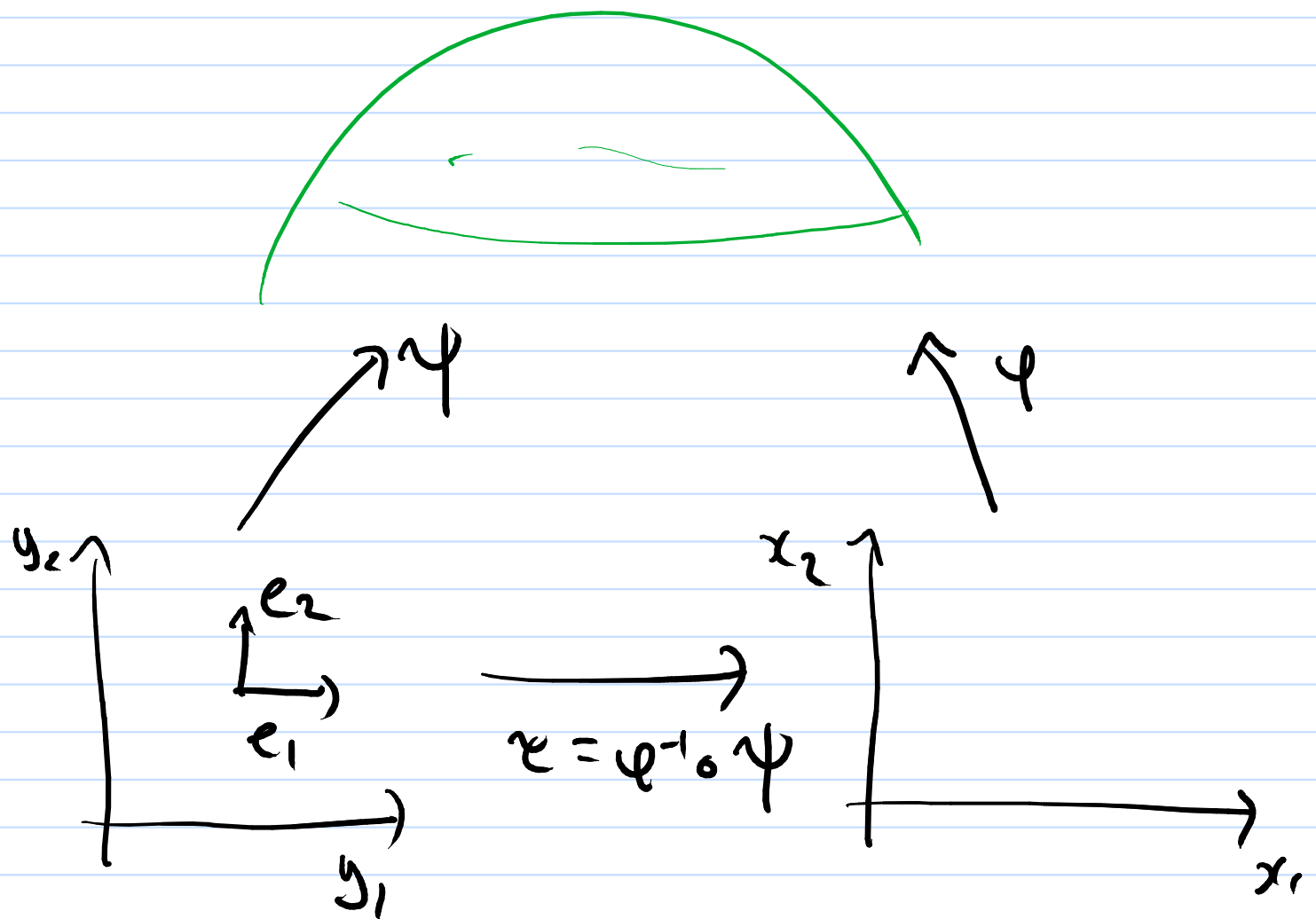
Positive Definite

$$g(v, v) = \langle v, v \rangle_{\mathbb{R}^3}$$

$$= \|v\|_{\mathbb{R}^3}^2 > 0$$

$$\text{if } v \neq 0$$

Change of coords:



$$\begin{aligned} (\partial_{y_a} \psi)^j &= [\partial_{y_a} (\varphi \circ \tau)]^j \\ &= [d\varphi \cdot d\tau(e_a)]^j \\ &= \sum_k \partial_k \varphi^j \partial_a \tau^k \end{aligned}$$

$$d\psi_a^i = \sum_p d\psi_p^i \cdot dx_a^p$$

$$= \sum_p \partial_p \psi^i \partial_a x^p$$

$$(\partial_a \psi)^i = (d\psi \cdot e_a)^i$$

$$e_a = \begin{pmatrix} 1, 0 \\ 0, 1 \end{pmatrix}$$

$$= d\psi_k^i (e_a)$$

$$= d\psi_a^i$$

$$= \sum_p \partial_p \psi^i \partial_a x^p$$

↑
added

$$(AB)^i_j = \sum_p A^i_p B^p_j$$

Change of coords

$$\psi = \varphi \circ \tau$$

$$d\varphi = \begin{pmatrix} \partial_{x^1} \varphi^1 & \partial_{x^2} \varphi^1 \\ \partial_{x^1} \varphi^2 & \partial_{x^2} \varphi^2 \\ \partial_{x^1} \varphi^3 & \partial_{x^2} \varphi^3 \end{pmatrix} \quad \leftarrow$$

$$d\tau = \begin{pmatrix} \partial_{y^1} \tau^1 & \partial_{y^2} \tau^1 \\ \partial_{y^1} \tau^2 & \partial_{y^2} \tau^2 \end{pmatrix}$$

$$d\psi = d\varphi \cdot d\tau$$

$$= \begin{pmatrix} \partial_{x^1} \varphi^1 & \partial_{x^2} \varphi^1 \\ \partial_{x^1} \varphi^2 & \partial_{x^2} \varphi^2 \\ \partial_{x^1} \varphi^3 & \partial_{x^2} \varphi^3 \end{pmatrix} \begin{pmatrix} \partial_{y^1} \tau^1 & \partial_{y^2} \tau^1 \\ \partial_{y^1} \tau^2 & \partial_{y^2} \tau^2 \end{pmatrix}$$

↓ ↓
↓ col 1

$$= \begin{pmatrix} \partial_{x^1} \varphi^1 \partial_{y^1} \tau^1 + \partial_{x^2} \varphi^1 \partial_{y^2} \tau^1 \\ \partial_{x^1} \varphi^2 \partial_{y^1} \tau^1 + \partial_{x^2} \varphi^2 \partial_{y^2} \tau^1 \\ \partial_{x^1} \varphi^3 \partial_{y^1} \tau^1 + \partial_{x^2} \varphi^3 \partial_{y^2} \tau^1 \end{pmatrix} \quad (y^1 \leftrightarrow y^2)$$

row 1 →
 row 2 →
 row 3 →

sum ↖

change of coords

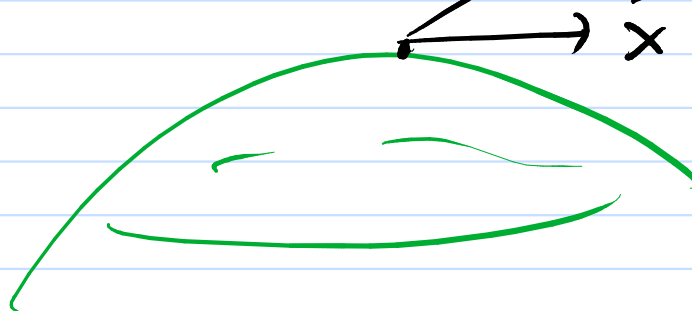
$$g_{ab}^{\psi} = \sum_{i,j} \underbrace{\partial_{y^a} x^i \partial_{y^b} x^j}_{\text{change of basis}} g_{ij}^{\varphi}$$

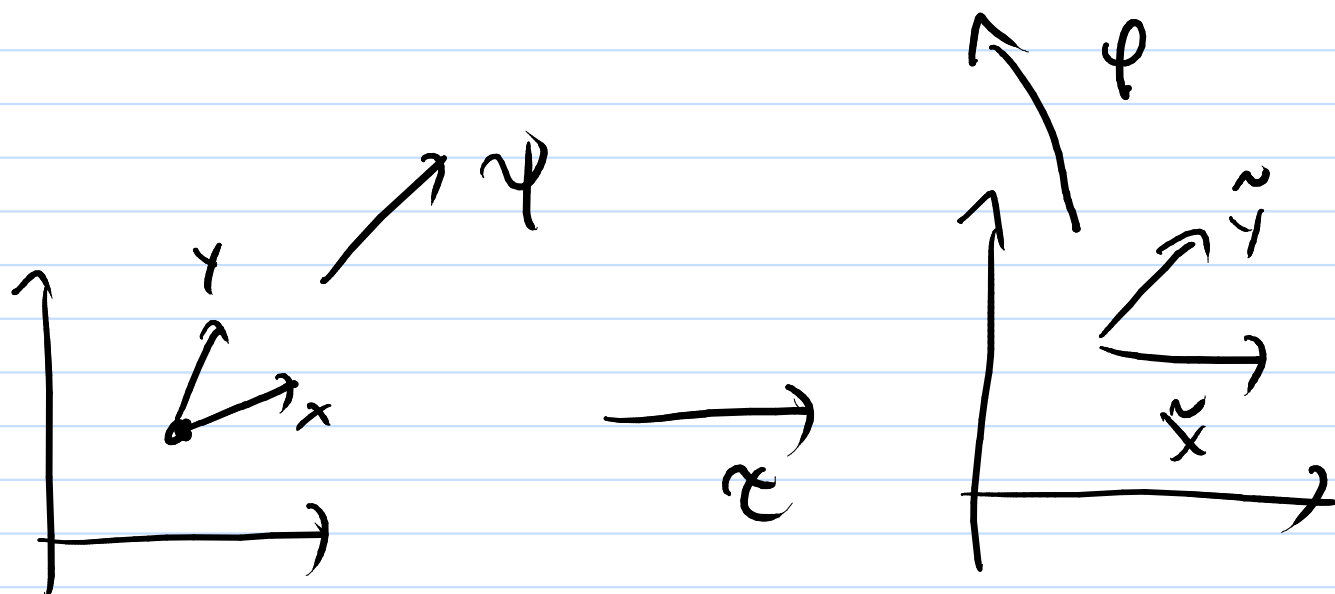
\uparrow
w.r.t. basis
 $\{\partial_1 \psi, \partial_2 \psi\}$

\uparrow
w.r.t. basis
 $\{\partial_1 \varphi, \partial_2 \varphi\}$

change of basis

$$\bar{y} = d\psi \cdot y = d\psi \cdot \tilde{y}$$

$$\bar{x} = d\psi \cdot x = d\psi \cdot \tilde{x}$$




$$g^{\psi}(x, y) = \langle \bar{x}, \bar{y} \rangle = g^{\phi}(\tilde{x}, \tilde{y})$$

$$\tilde{x} = d\tau \cdot x, \quad \tilde{y} = d\tau \cdot y$$

since $\bar{x} = d\psi \cdot x = d\psi \cdot d\tau \cdot x$

$$= d\psi \cdot \tilde{x}$$

equal since $d\psi$ injective.

Matrix change of coords

$$g^{\varphi_0 \tau}(x, y) = g^{\varphi}(d\tau \cdot x, d\tau \cdot y)$$

$$= (d\tau \cdot x)^T g^{\varphi} d\tau \cdot y$$

$$= x^T d\tau^T g^{\varphi} d\tau y$$

$$= x^T \underbrace{(d\tau^T g^{\varphi} d\tau)}_{g^{\varphi_0 \tau}} y$$

$$g(u, v) = u^T g v$$

$$= v^T g u \quad (\text{by symmetry})$$

Euclidean Metric

$$\varphi(\underset{x_1, x_2}{u, v}) = (u, v, 0)$$

$$\begin{cases} \underset{x_1}{\partial_u} \varphi = (1, 0, 0) \overset{e_1}{\text{basis for } T_p S} \\ \underset{x_2}{\partial_v} \varphi = (0, 1, 0) \overset{e_2}{\text{basis for } T_p S} \end{cases}$$

$$g = \begin{pmatrix} \overset{g_{11}}{g_{uu}} & \overset{g_{12}}{g_{uv}} \\ \underset{g_{21}}{g_{vu}} & \underset{g_{22}}{g_{vv}} \end{pmatrix}$$

$$= \begin{pmatrix} \langle \partial_u \varphi, \partial_u \varphi \rangle & \langle \partial_u \varphi, \partial_v \varphi \rangle \\ \langle \partial_v \varphi, \partial_u \varphi \rangle & \langle \partial_v \varphi, \partial_v \varphi \rangle \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\delta_{ij} = \begin{cases} 1, & i = j \\ 0, & i \neq j \end{cases}$$

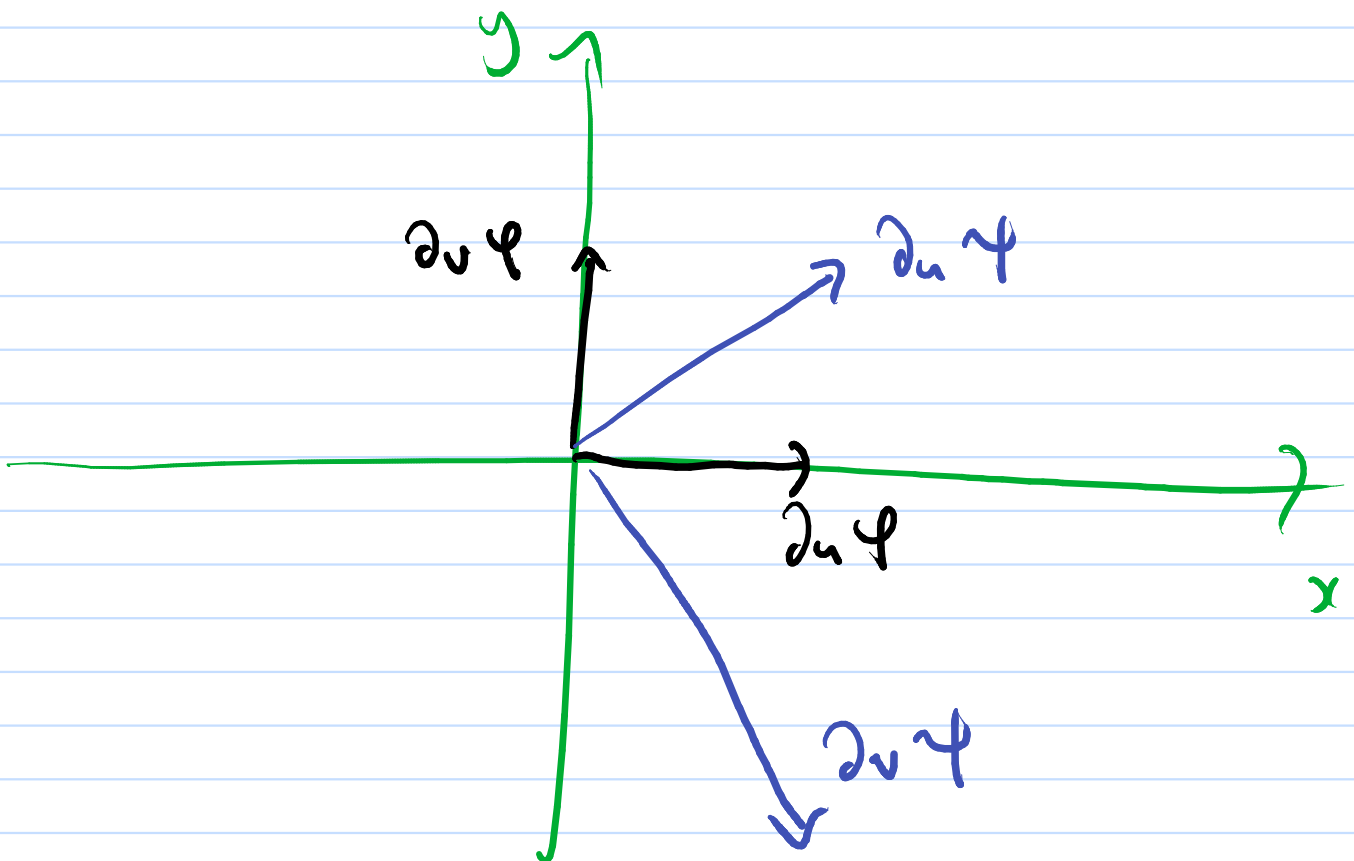
Euclidean metric

$$\psi(u, v) = (u + v, u - 2v, 0)$$

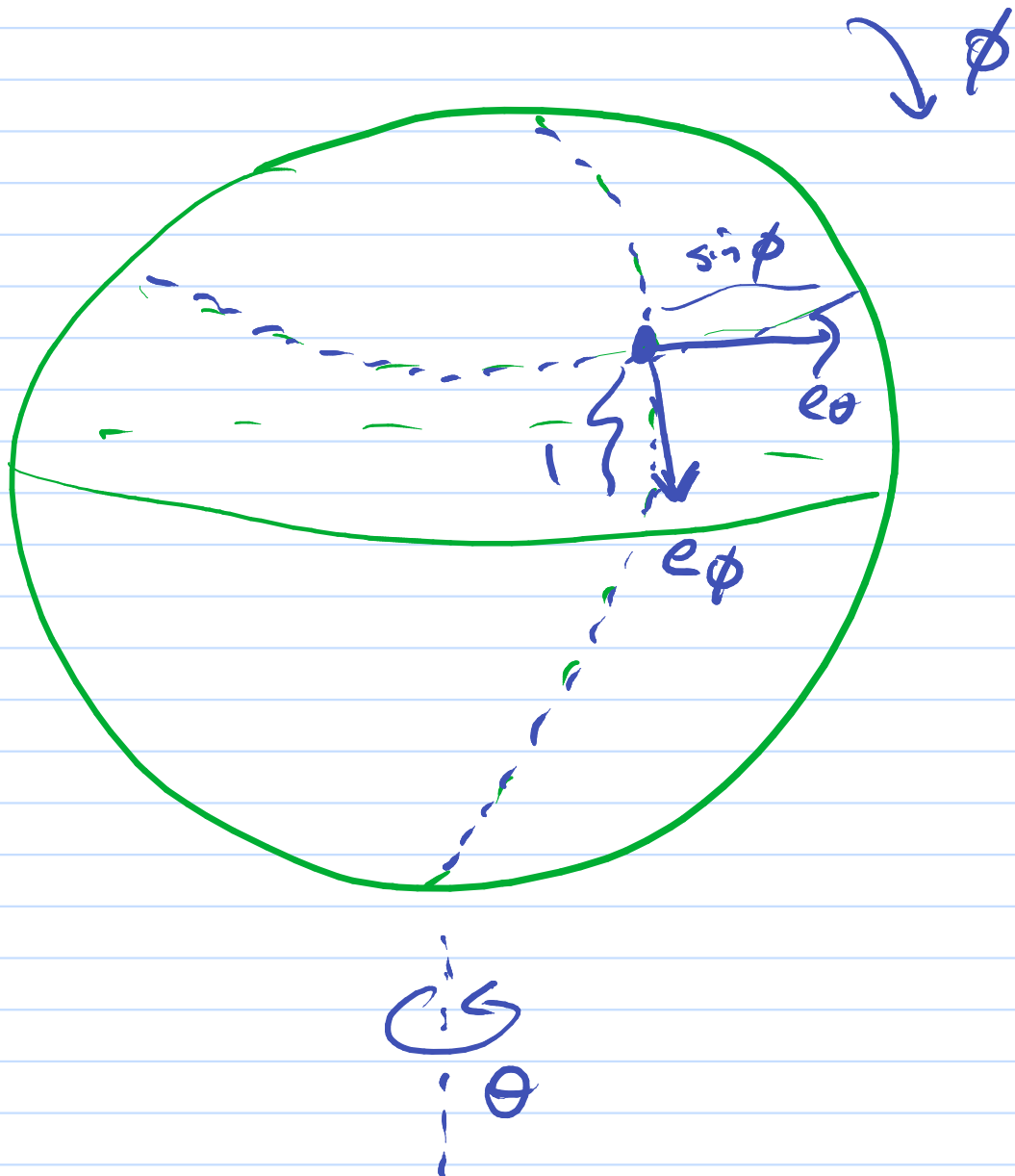
$$\partial_u \psi = (1, 1, 0)$$

$$\partial_v \psi = (1, -2, 0)$$

$$g = \begin{pmatrix} 2 & -1 \\ -1 & 5 \end{pmatrix}$$

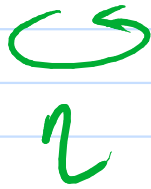
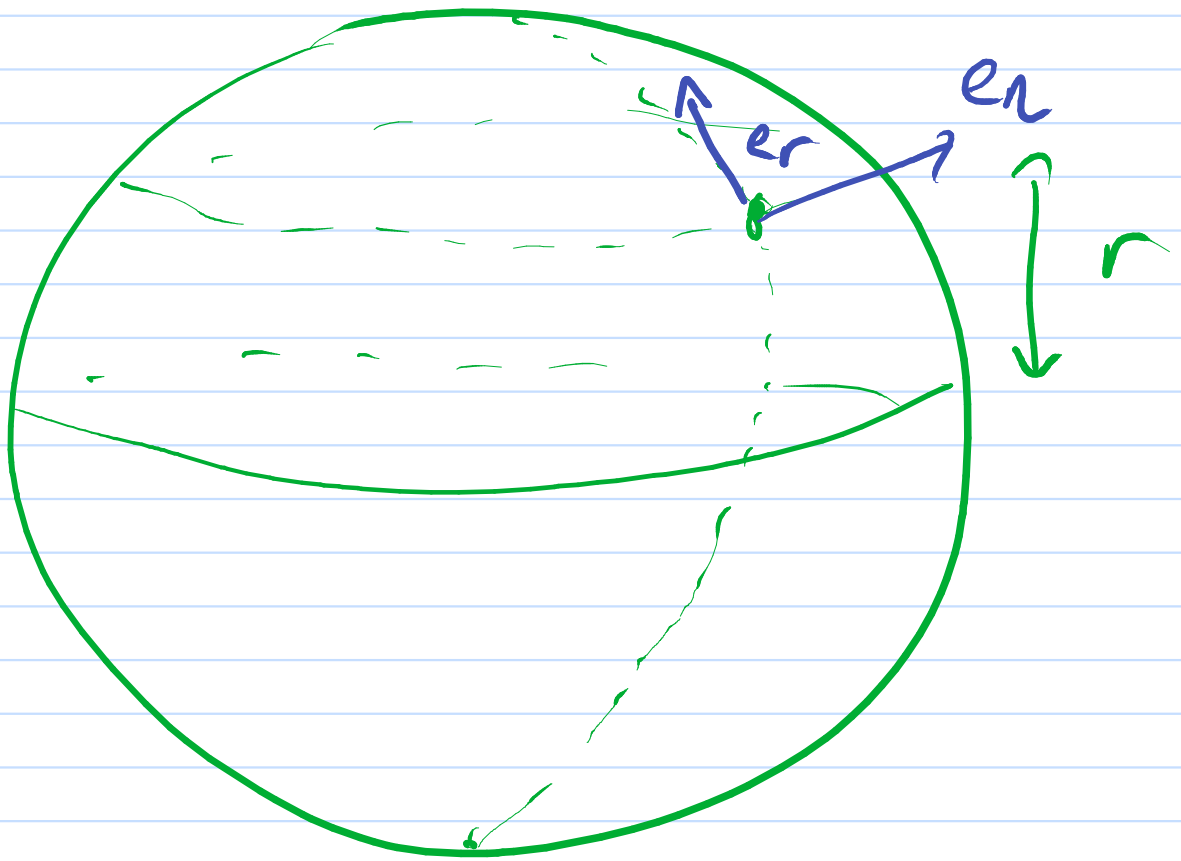


Spherical Polar



$$\begin{aligned}
 \langle \mathbf{e}_\theta, \mathbf{e}_\theta \rangle &= \langle \sin \phi (-\sin \theta, \cos \theta, 0), \sin \phi (-\sin \theta, \cos \theta, 0) \rangle \\
 &= \sin^2 \phi \, |(-\sin \theta, \cos \theta, 0)|^2 \\
 &= \sin^2 \phi (\sin^2 \theta + \cos^2 \theta) \\
 &= \sin^2 \phi
 \end{aligned}$$

Cylindrical Coords



Cylinder to Sphere

$$\left. \begin{aligned} d\tau(e_\eta) &= e_\theta \\ d\tau(e_r) &= \frac{1}{\sqrt{1-r^2}} e_\phi \end{aligned} \right\} \begin{array}{l} \text{last} \\ \text{lecture} \end{array}$$

$$d\tau = \begin{pmatrix} 1 & 0 \\ 0 & -\frac{1}{\sqrt{1-r^2}} \end{pmatrix}$$

$$\psi(\theta, \phi) = (\sin \phi \cos \theta, \sin \phi \sin \theta, \cos \phi)$$

$$\psi(\eta, r) = (\sqrt{1-r^2} \cos \eta, \sqrt{1-r^2} \sin \eta, r)$$

↕ ↗

$$\tau = \psi^{-1} \circ \psi(\eta, r) \mapsto (\underline{\theta}, \phi)$$

$$\phi = \arccos r$$

$$r = \cos \phi \Rightarrow \sin^2 \phi = 1 - \cos^2 \phi = 1 - r^2$$

Find (θ, ϕ) such that $\psi(\theta, \phi) = (\eta, r)$
given (η, r)

