MATH 150A - HW 1

 $\alpha(t_0)$ is the point of the trace closed to the origin implies that $d'(t_0) = 0 \Rightarrow \frac{d}{dt} \left[\alpha(t) \cdot \alpha(t)\right] = 0$ $\Rightarrow \alpha'(t_0) \cdot \alpha(t_0) + \alpha(t_0) \cdot \alpha'(t_0) = 0$

Since $\alpha'(t_0) \neq 0$ and $\alpha(t_0) \neq 0$, we must have that $\alpha'(t_0)$ and $\alpha(t_0)$ are orthogonal.

1.2.3 Using the fundamental theorem of calculus, we have $\alpha''(t) = 0 \Rightarrow \int_{0}^{t} \alpha''(\tau) d\tau = 0$

$$\Rightarrow \int_{0}^{t} \alpha'(x) d\tau - \int_{0}^{t} \alpha'(0) d\tau = 0$$

Then, we see that & is a line.

1.2.5 |x(4) = c => |x(4)|2 = c2

1.3.1
$$\omega(\xi) = (3t, 3\xi^{2}, Z\xi^{3})$$

$$\omega'(\xi) = (3, 6t, 6\xi^{2})$$

$$\omega'(\xi) \cdot (1, 0, 1) = |\omega'(\xi)| \cdot |(1, 0, 1)| \cdot \cos \theta$$

$$\Rightarrow 3 + 6\xi^{2} = \sqrt{9 + 36\xi^{2} + 36\xi^{4}} \cdot \sqrt{2} \cdot \cos \theta$$

$$\Rightarrow 3 + 6\xi^{2} = \sqrt{(3 + 6\xi^{2})^{2}} \cdot \sqrt{2} \cdot \cos \theta$$

$$\Rightarrow \cos \theta = \sqrt{12} \Rightarrow \theta = \sqrt{4}$$

- - (a) In polar coordinates, we have $\kappa(t) = (ae^{bt}; t)$ Then $|d(t)| = ae^{bt} \Rightarrow \lim_{t\to\infty} |d(t)| = 0$ since b<0. Also, a'(+) = (abebt; 1), so a is moving with constant angular velocity, with negative radial velocity, hence, spiralling inward to 0.
 - (abebt cost aebt sint, abebt sint + aebt cost) | u'(+)| = ae bt | b-11 -> 0 as t -> ∞ $\lim_{t\to\infty}\int_{t_0}^{t}|a'(t)|dt\leq\lim_{t\to\infty}\int_{t_0}^{t}a|b-1|e^{bt}dt\leq-\frac{a|b-1|}{b}e^{bt_0}<\infty$

1.3.10 By the Fundamental Theorem of Calculus
$$(q-p). V = \int_{0}^{b} \alpha'(t) dt \cdot V$$

By linearity of the integral (Indeed, by the definition of integration in finite dimensions)

$$= \int_{0}^{b} \alpha'(t) \cdot V dt$$

$$= \int_{0}^{b} |\alpha'(t)| |V| \cos \theta_{t} dt$$

where θ is the angle between $\alpha'(t)$ and V .

$$\leq \int_{0}^{b} |\alpha'(t)| dt$$

(b) This follows immediately from part a, since,
$$|v| = \frac{|q-p|}{|q-p|} = 1$$

and

1.5.1 (a)
$$\alpha(s) = (a\cos\frac{s}{c}, a\sin\frac{s}{c}, b\frac{s}{c})$$

 $\alpha'(s) = (-\frac{a}{c}\sin\frac{s}{c}, \frac{a}{c}\cos\frac{s}{c}, \frac{b}{c}) = t(s)$
 $|\alpha'(s)| = \frac{a^2 + b^2}{c^2} = 1$

(b)
$$a''(s) = (-\frac{a}{c^2}\cos\frac{5}{c}, -\frac{a}{c^2}\sin\frac{5}{c}, 0) = t'(s)$$
 $K(s) = |a''(s)| = \frac{a}{c^2} = |t'(s)|$
 $a''(s) = K(s)n(s) \Rightarrow n(s) = (-\cos\frac{5}{c}, -\sin\frac{5}{c}, 0)$
 $b(s) = t(s)nn(s)$
 $= (\frac{b}{c}\sin\frac{5}{c}, -\frac{b}{c}\cos\frac{5}{c}, \frac{a}{c})$
 $b'(s) = (\frac{b}{c^2}\cos\frac{5}{c}, \frac{b}{c^2}\sin\frac{5}{c}, 0)$

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 $b'(s) = T(s)n(s) \Rightarrow T(s) = -\frac{b}{c^2}$

(d)
$$\Gamma_s(t) = (a\cos\frac{\xi}{2}, a\sin\frac{\xi}{2}, b\frac{\xi}{2}) + t(-\cos\frac{\xi}{2}, -\sin\frac{\xi}{2}, 0)$$

$$\Gamma_s \text{ weets the } \xi \text{ axis at } t = a.$$

$$(-\cos\frac{\xi}{2}, -\sin\frac{\xi}{2}, 0) \cdot (0, 0, 1) = 0 \Rightarrow \Theta = \frac{\pi}{2}$$

$$e + (5) \cdot (0,0,1) = (-\frac{a}{c} \sin \frac{5}{c}, \frac{a}{c} \cos \frac{5}{c}, \frac{b}{c}) \cdot (0,0,1)$$

$$= \frac{b}{c}$$

=> angle is constant. No s-dependence.

1.5.2
$$T(s) \stackrel{?}{=} - \frac{\alpha'(s) \wedge \alpha''(s) \cdot \alpha'''(s)}{|\kappa(s)|^2}$$

We work backwards:

$$= - \frac{\det(\alpha'(s), \alpha''(s), \alpha'''(s))}{|\kappa(s)|^2}$$

$$= - \frac{\det(t(s), \kappa(s)n(s), (\kappa(s)n(s))')}{|\kappa(s)|^2}$$

$$= - \frac{|\kappa(s)|^2}{|\kappa(s)|^2}$$

$$= - \frac{|\kappa(s)|^2}{|\kappa(s)|^2} \det(t(s), \kappa(s), (\kappa(s)n(s)) + \kappa(s), \kappa(s))$$

$$= - \frac{|\kappa(s)|^2}{|\kappa(s)|^2} \det(t(s), \kappa(s), \kappa(s), \kappa(s)$$

$$= - \frac{|\kappa(s)|^2}{|\kappa(s)|^$$

1.5.6 a) | pu| = 1 pu.pu = 1 u.u = |u|

Note; for $0 \le \theta \le \pi$, that ease $\theta \mapsto \cos \theta$ is a bijection. So we show $\cos\theta$ is 'theireuni'

 $\cos \theta_p = \frac{\rho u \cdot \rho v}{|\rho u| |\rho v|} = \frac{u \cdot v}{|u| |v|} = \cos \theta$

(b) We show that (puppy).pw = (upv).w (brivba).bm = gef(briba'bm) = det(p)·det(u,u,w)

To show det(p)=1, consider that

pe: pe; == Si; => pTp=I => 1 = det(I) = det(pTp) = det(p).det(p) \Rightarrow det(p) = ±1

Since we only consider the positive determinant case, det(p)=1, and (purpu).pw = (urv).w.

© First observe that:

 $A(\alpha(s))' = [\alpha(s) + \nu]' = \alpha'(s)$

which shows that differentiation is invariant under translation.

Since are length, curvature and torsion are functions of norms, and inner products and vector products, which are invariant under orthogonal transformations, the result follows.

$$\frac{1.5.11}{9} \underbrace{(a)}_{j=1}^{2} p(b) \cos \theta = p(b) \cos \theta = p(b) \sin \theta = p(b) \cos \theta = p(b) \sin \theta = p(b) \cos \theta = p(b) \sin \theta = p(b) \cos \theta = p$$