

FLUX INTEGRALS

- Normal Vector
- Flux Integrals

NORMAL VECTOR

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DEFINITION

The **positively oriented unit normal** in a parametrisation is

$$\vec{\mathbf{N}} = \frac{\vec{\mathbf{e}}_u \times \vec{\mathbf{e}}_v}{\left| \vec{\mathbf{e}}_u \times \vec{\mathbf{e}}_v \right|}$$

NORMAL VECTOR

$\vec{\mathbf{N}}$ is perpendicular to \mathcal{S}

$$\vec{\mathbf{N}} \cdot \vec{\mathbf{e}}_u = \vec{\mathbf{N}} \cdot \vec{\mathbf{e}}_v = 0$$

ORIENTATION

DEFINITION

Positive orientation is the right hand rule. Negative orientation is the left hand rule.

ORIENTATION EXAMPLES

- Positive: $(\vec{e}_u, \vec{e}_v, \vec{N}), (\vec{e}_v, \vec{e}_u, -\vec{N})$
- Negative: $(\vec{e}_u, \vec{e}_v, -\vec{N}), (\vec{e}_v, \vec{e}_u, \vec{N})$

EXAMPLE

- Sphere: $\vec{\mathbf{N}}(p) = p$
- xy -plane: $\vec{\mathbf{N}} = \vec{\mathbf{e}}_3$
- Cylinder: $\vec{\mathbf{N}}(x, y, z) = (x, y, 0)$
- Graph $z = f(x, y)$: $\vec{\mathbf{N}} = \frac{\vec{\mathbf{e}}_3 - \nabla f}{\sqrt{1 + |\nabla f|^2}}$

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DEFINITION

The **flux** of a vector field $\vec{\mathbf{F}}$ across a surface S is

$$\begin{aligned}\iint_S \vec{\mathbf{F}} \cdot \vec{\mathbf{N}} dA &= \iint_U \vec{\mathbf{F}} \cdot \frac{\vec{\mathbf{e}}_u \times \vec{\mathbf{e}}_v}{|\vec{\mathbf{e}}_u \times \vec{\mathbf{e}}_v|} |\vec{\mathbf{e}}_u \times \vec{\mathbf{e}}_v| du dv \\ &= \iint_U \vec{\mathbf{F}} \cdot (\vec{\mathbf{e}}_u \times \vec{\mathbf{e}}_v) du dv\end{aligned}$$

FLUX INTEGRALS

- Flux integrals are independent of parametrisation up to orientation
- Change of orientation $\vec{\mathbf{N}} \mapsto -\vec{\mathbf{N}}$ changes the **sign** of the flux integral

EXAMPLE

$$S = \{-1 < x < 1, -1 < y < 1, z = 0\}$$

$$\vec{\mathbf{F}} = (xz^2, e^y, xe^z)$$

EXAMPLE

$$S = \{x^2 + y^2 + z^2 = 1\}$$

$$\overrightarrow{\mathbf{F}}_1 = (x, y, z), \overrightarrow{\mathbf{F}}_2 = (-y, x, 0)$$

EXAMPLE

$$S = \{x^2 + y^2 = 1\}$$

$$\overrightarrow{\mathbf{F}}_1 = (x, y, z), \overrightarrow{\mathbf{F}}_2 = (-y, x, 0)$$