# **Econometrics in R: Estimation of Gravity Models**

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# Before we begin

# This is about a new R package

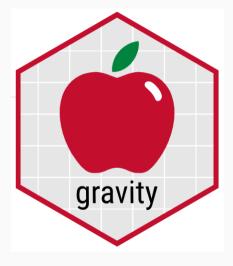


Figure 1: Hex sticker

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#### Question to the audience

Do you understand (a bit) linear algebra?

Have you ever fitted a regression (in R) before today?

5

Let  $y \in \mathbb{R}^n$  be the outcome and  $X \in \mathbb{R}^{n \times p}$  be the design matrix in the context of a general model with intercept:

$$y = X\beta + e$$

Being:

$$\mathbf{y}_{n\times 1} = \begin{pmatrix} y_0 \\ y_1 \\ \vdots \\ y_n \end{pmatrix} \text{ and } \begin{matrix} X \\ n\times p \end{matrix} = \begin{pmatrix} 1 & x_{11} & x_{1p} \\ 1 & x_{21} & x_{2p} \\ & \ddots & \\ 1 & x_{n1} & x_{np} \end{pmatrix} = (\mathbf{1} \mathbf{x}_1 \dots \mathbf{x}_p)$$

In linear models the aim is to minimize the error term by chosing  $\hat{\beta}$ . One possibility is to minimize the squared error by solving this optimization problem:

$$\min_{\beta} S = \|\mathbf{y} - X\beta\|^2 \tag{1}$$

Books such as Baltagi [2011] discuss how to solve (1) and other equivalent approaches that result in this optimal estimator:

$$\hat{\boldsymbol{\beta}} = (X^t X)^{-1} X^t \mathbf{y} \tag{2}$$

With one independent variable and intercept, this is  $y_i = \beta_0 + \beta_1 x_{i1} + e_i$ , equation (2) means:

$$\hat{\beta}_1 = cor(\mathbf{y}, \mathbf{x}) \cdot \frac{sd(\mathbf{y})}{sd(\mathbf{x})} \text{ and } \hat{\beta}_0 = \bar{\mathbf{y}} - \hat{\beta}_1 \bar{\mathbf{x}}$$
 (3)

Consider the model:

$$mpg_i = \beta_1 wt_i + \beta_2 cyl_i + e_i$$

This is how to write that model in R notation:

Or written in matrix form:

```
y <- mtcars$mpg
x0 <- rep(1, length(y))
x1 <- mtcars$wt
x2 <- mtcars$cyl
X <- cbind(x0,x1,x2)</pre>
```

It's the same to use lm or to perform a matrix multiplication because of equation (2):

```
fit <- lm(y ~ x1 + x2)
beta <- solve(t(X)%*%X) %*% (t(X)%*%y)
```

It's the same to use 1m or to perform a matrix multiplication because of equation (2):

```
coefficients(fit)
  (Intercept)
                        x1
                                    x2
##
    39.686261 -3.190972 -1.507795
beta
           [,1]
##
## x0 39.686261
## x1 - 3.190972
## x2 -1.507795
```

# Coding example with Galton dataset

Equation (3) can be verified with R commands:

```
if (!require(pacman)) install.packages("pacman")
p_load(HistData)
y <- Galton$child
x <- Galton$parent
beta1 <- cor(y, x) * sd(y) / sd(x)
beta0 <- mean(y) - beta1 * mean(x)
c(beta0, beta1)
```

**##** [1] 23.9415302 0.6462906

## Coding example with Galton dataset

```
##
## Call:
## lm(formula = y ~ x)
##
## Coefficients:
## (Intercept) x
## 23.9415 0.6463
```

The main reference for this section is Woelwer et al. [2018] and the references therein.

Gravity models in their traditional form are inspired by Newton law of gravitation:

$$F_{ij}=G\frac{M_iM_j}{D_{ij}^2}.$$

The force F between two bodies i and j with  $i \neq j$  is proportional to the masses M of these bodies and inversely proportional to the square of their geographical distance D. G is a constant and as such of no major concern.

The underlying idea of a traditional gravity model, shown for international trade, is equally simple:

$$X_{ij} = G \frac{Y_i^{\beta_1} Y_j^{\beta_2}}{D_{ij}^{\beta_3}}.$$

The trade flow X is explained by  $Y_i$  and  $Y_j$  that are the masses of the exporting and importing country (e.g. the GDP) and  $D_{ij}$  that is the distance between the countries.

This is also used to study urban policies and migration flows!

Dummy variables such as common borders *contig* or regional trade agreements rta can be added to the model. Let  $t_{ij}$  be the transaction cost defined as:

$$t_{ij} = D_{ij} \exp(contig_{ij} + rta_{ij})$$

So that the model with friction becomes:

$$X_{ij}=Grac{Y_i^{eta_1}Y_j^{eta_2}}{t_{ij}^{eta_3}}.$$

A logarithmic operator can be applied to form a log-linear model and use a standard estimation methods such as OLS:

$$\log X_{ij} = \beta_0 \log G + \beta_1 \log Y_i + \beta_2 \log Y_j + \beta_3 \log D_{ij} + \beta_4 contig_{ij} + \beta_5 rta_{ij}$$

Basically the model proposes that the exports  $X_{ij}$  from i to j are determined by the supply factors in i,  $Y_i$ , and the demand factors in j,  $Y_j$ , as well as the transaction costs  $t_{ij}$ .

Next to information on bilateral partners i and j, information on the rest of the world is included in the gravity model with  $Y = \sum_i Y_i = \sum_j Y_j$  that represents the worldwide sum of incomes (e.g. the world's GDP).

In this model  $\sigma$  represents the elasticity of substitution between all goods. A key assumption is to take a fixed value  $\sigma>1$  in order to account for the preference for a variation of goods (e.g. in this model goods can be replaced for other similar goods).

The Multilateral Resistance terms are included via the terms P, Inward Multilateral Resistance, and  $\Pi$ , Outward Multilateral Resistance.

The Inward Multilateral Resistance  $P_i$  is a function of the transaction costs of i to all trade partners j.

The Outward Multilateral Resistance  $\Pi_j$  is a function of the transaction costs of j to all trade partners i and their demand.

The Multilateral Resistance terms dependent on each other. Hence, the estimation of structural gravity models becomes *complex*.



Figure 2: What?

The econometric literature proposes the Multilateral Resistance model defined by the equations:

$$X_{ij} = \frac{Y_i Y_j}{Y} \frac{t_{ij}^{1-\sigma}}{P_j^{1-\sigma} \Pi_i^{1-\sigma}}$$

with

$$P_{i}^{1-\sigma} = \sum_{j} \frac{t_{ij}^{1-\sigma}}{\Pi_{j}^{1-\sigma}} \frac{Y_{j}}{Y}; \ \Pi_{j}^{1-\sigma} = \sum_{i} \frac{t_{ij}^{1-\sigma}}{P_{i}^{1-\sigma}} \frac{Y_{i}}{Y}$$



Figure 3: Again, what?

## **Model estimation**

#### **Model estimation**

To estimate gravity equations you need a square dataset including bilateral flows defined by the argument dependent\_variable, a distance measure defined by the argument distance that is the key regressor, and other potential influences (e.g. contiguity and common currency) given as a vector in additional\_regressors are required.

Some estimation methods require ISO codes or similar of type character variables to compute particular country effects. Make sure the origin and destination codes are of type "character".

#### Model estimation

The rule of thumb for regressors or independent variables consists in:

- All dummy variables should be of type numeric (0/1).
- If an independent variable is defined as a ratio, it should be logged.

The user should perform some data cleaning beforehand to remove observations that contain entries that can distort estimates, notwithstanding the functions provided within gravity package will remove zero flows and distances.

# **Examples**

#### **Double Demeaning**

Double Demeaning subtracts importer and exporter averages on the left and right hand side of the respective gravity equation, and all unilateral influences including the Multilateral Resistance terms vanish.

Therefore, no unilateral variables may be added as independent variables for the estimation.

#### **Double Demeaning**

Our ddm function first logs the dependent variable and the distance variable.

Afterwards, the dependent and independent variables are transformed in the following way (exemplary shown for trade flows,  $X_{ij}$ ):

$$(\log X_{ij})_{\mathsf{DDM}} = (\log X_{ij}) - (\log X_{ij})_{\mathsf{Origin\ Mean}} - (\log X_{ij})_{\mathsf{Destination\ Mean}} + (\log X_{ij})_{\mathsf{Mean}}.$$

#### **Double Demeaning**

One subtracts the mean value for the origin country and the mean value for the destination country and adds the overall mean value to the logged trade flows.

This procedure is repeated for all dependent and independent variables. The transformed variables are then used for the estimation.

An example of how to apply the function ddm to an example dataset in gravity and the resulting output is shown in the following:

```
p_load(gravity)
fit <- ddm(
    dependent variable = "flow",
    distance = "distw".
    additional regressors = c("rta", "comcur", "contig"),
    code origin = "iso o".
    code_destination = "iso_d",
    data = gravity no zeros
```

The package returns Im or glm objects instead of summaries. Doing that allows to use our functions in conjunction with broom or other packages, for example:

```
p_load(dplyr, broom)
tidy(fit)
```

```
## # A tibble: 4 x 5
##
                estimate std.error statistic p.value
    term
##
    <chr>
                   <dbl>
                            <dbl>
                                     <dbl>
                                              <dbl>
## 1 dist log ddm
                  -1.60
                           0.0331
                                     -48.4 0.
                   0.797
                           0.0700
                                     11.4 6.54e-30
## 2 rta ddm
                   0.174
                           0.146
                                      1.19 2.34e- 1
## 3 comcur ddm
## 4 contig ddm
                   1.00
                           0.120
                                      8.36 6.62e-17
```

```
glance(fit) %>% select(matches("squared"))

## # A tibble: 1 x 2

## r.squared adj.r.squared

## * <dbl> <dbl>
## 1 0.254 0.254
```

```
# Checks
 stopifnot(is.data.frame(data))
 stopifnot(is.logical(robust))
. . .
# Transforming data, logging distances
 d <- d %>%
    mutate(
      dist_log = log(!!sym(distance))
```

```
# Transforming data, logging flows
d <- d %>%
    mutate(
        y_log = log(!!sym(dependent_variable))
    )
...
```

```
# Substracting the means
 d <- d %>%
    mutate(
      y_{\log_{10}} ddm = !!sym("y_{\log}"),
      dist log ddm = !!svm("dist log")
    ) %>%
    group_by(!!sym(code_origin), add = FALSE) %>%
    mutate(
      ym1 = mean(!!sym("y log ddm"), na.rm = TRUE),
      dm1 = mean(!!sym("dist log ddm"), na.rm = TRUE)
    ) %>%
```

## **Code and documentation**

#### **Code and documentation**

github.com/pachamaltese/gravity pacha.hk/gravity

# **Questions?**

Questions?

Thanks for your attention!

## References

#### References

Badi H. Baltagi. *Econometrics*. Number 978-3-642-20059-5 in Springer Texts in Business and Economics. Springer, June 2011. doi: 10.1007/978-1-4614-3169-5.

Anna Lenna Woelwer, Jan Pablo Burgard, Joshua Kunst, and Mauricio Vargas. Gravity: Estimation methods for gravity models in r. *Journal of Open Source Software*, 31(3): 1038, 2018. doi: 10.21105/joss.01038.