#include <kipr/botball.h>

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Code is written to follow a black line with the approximate value of 3000 on a Large Top Hat sensor.

Two sensors, analog ports 1 and 2,  are mounted at the edge of the robot right in front of each wheel.

There are two wheels--0=right; 1=left.

The button sensor is plugged into port analog 4,  and is basically useless.

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void up\_pos();

void down\_pos();

void left();

void right();

int main()

{