

Akshaya Athwale

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OVERVIEW

I'm a research scientist and engineer with a strong background in machine learning, deep learning, and computer vision, specializing in geometric deep learning and wide-angle imagery. I build robust, efficient, and scalable ML systems by integrating geometric priors into neural networks, enabling real-time perception with limited data. With experience bridging academic research and industrial applications, I focus on solutions that generalize well and are ready for deployment in autonomous systems and vision-based products.

PUBLICATIONS

- **A. Athwale, O. Ahmad, J.-F. Lalonde:**
 - “Network-agnostic distortion-invariant projections for wide-angle image understanding”. **Under review**.
- **A. Athwale, I. Shili, Émile Bergeron, O. Ahmad, J.-F. Lalonde:**
 - “DarSwin-Unet: Distortion Aware Encoder-Decoder Architecture”. **IEEE Winter Conference on Applications of Computer Vision (WACV) 2025**.
- **A. Athwale, A. Afrasiyabi, J. Lague, I. Shili, O. Ahmad, J.-F. Lalonde:**
 - “DarSwin: Distortion Aware Radial Swin Transformer”. In **IEEE International Conference on Computer Vision, ICCV 2023**.
- **Y. Hold-Geoffroy, A. Athwale, J.-F. Lalonde:**
 - “Deep Sky Modeling for Single Image Outdoor Lighting Estimation”. In **IEEE Conference on Computer Vision and Pattern Recognition, CVPR 2019**.
- **S. Sengupta, A. Athwale, T. Gulati, V. Lakshminarayanan:**
 - “FunSyn-Net: Enhanced Residual Variational Auto-encoder and Image-to-Image Translation Network for Fundus Image Synthesis”. in **SPIE Medical Imaging Conference 2020**.

EDUCATION

- **Université Laval, Thales digital solution**, Quebec City, Canada 2021 – 2025
Doctorate in Computer Vision and Machine Learning
Thesis: Geometry-Aware Deep Learning for Robust Perception with Wide-Angle Cameras
Research focuses on integrating lens geometry into deep networks for robust perception in autonomous systems.
- **Aalto University**, Espoo, Finland 2019 – 2020
Project Employee
Developed a physics-informed neural network framework grounded in Lagrangian mechanics for energy-consistent catalyst prediction in industrial workflows at Neste.
- **Indian Institute of Technology (IIT-ISM) Dhanbad**, India 2014 – 2019
Integrated Master of Technology in Mathematics and Computing
Thesis: Generative Modeling and Applications
GPA: 8.85 / 10.0

WORK EXPERIENCE

- **Research Intern, Thales Digital Solutions** Quebec City, Canada
Supervised By : Ola Ahmad and Prof. Jean-Francois Lalonde , June 2023 - December 2023
 - **Objective:** Extended our prior geometric distortion-invariant framework to pixel-level tasks, targeting deployment in autonomous obstacle-avoidance drones using wide-angle imagery.
 - Designed a transformer-based encoder-decoder architecture that incorporates lens geometry for robust wide-angle image understanding, with improved depth and segmentation accuracy.
 - Successfully deployed the model real-time on obstacle-avoidance autonomous drones with results on depth estimation accepted at WACV 2025.
- **Project Employee, Aalto University, Neste** Espoo, Finland
Supervised By : Prof. Alexander Ilin, May'20 - August'21
 - Developed a physics-informed neural network (PINN) framework for catalyst prediction, grounded in Lagrangian and Hamiltonian mechanics.
 - Modeled system dynamics by minimizing the action integral and enforcing energy conservation for improved physical consistency.

- Explored integration of the framework within industrial workflows at **Neste**.

● **Arya.ai, Lithasa Technologies**

Mumbai, India

Deep Learning Researcher, May 2017 - July 2017

- **Objective :** Automating reading of trader's documents and capture all documents, including the ones that were not just structured layouts, and make that data actionable with a minimum of human intervention.
- Our first task was to implement a data driven model that can recognize different documents. To build this classifier we implemented a SVM classifier using term frequency document inverse frequency (TFIDF) vectorizer to extract a feature from the document
- Second task was to implement a model that can understand the context such as what an identity number is not and what should (or shouldn't) be around the number, For this we implemented an OCR that can read a text image which was extracted from the document

RESEARCH EXPERIENCE

● **Graduate Research Assistant, Université Laval**

Quebec City, Canada

Supervised By : Prof. Jean-Francois Lalonde and Ola Ahmad, August'21 - Present

- **Project 1: Geometrically Informed Transformer for Wide-Angle Images**
 - * **Objective:** Develop a geometrically informed model to handle wide-angle image distortion and generalize to unseen fisheye lenses.
 - * Proposed the **Radial Transformer Network**, a distortion-equivariant architecture that embeds fisheye lens geometry into the network using angular positional encoding and polar representations.
 - * Leveraged geometric priors to enable distortion-invariant feature learning, allowing the model to generalize across lens types without fine-tuning.
 - * Demonstrated out-of-distribution generalization to novel distortions on classification tasks, outperforming distortion-agnostic baselines.
 - * Published at **ICCV 2023**, establishing the value of distortion-aware, geometry-guided deep learning for robust wide-angle image understanding.
- **Project 2: Distortion-invariant, model-agnostic wide-angle image projection**
 - * **Objective:** Develop a distortion-invariant projection method for wide-angle images that generalizes across architectures for easy deployment.
 - * Proposed a model-agnostic projection approach using square-to-disc mappings from computer graphics, enabling consistent distortion handling with fewer artifacts.
 - * Unlike network-specific methods like the Radial Transformer, this approach supports any architecture, simplifying integration into production systems.
 - * The method is currently **under review** for publication.

● **Mitacs Globalink Research Internship, University Laval**

Quebec City, Canada

Guide : Prof. Jean-Francois Lalonde, May'18 - December'18

- **Objective:** Estimate physically plausible HDR sky environment maps from a single low dynamic range (LDR) image.
- Proposed a three-stage architecture to model HDR skies using complementary datasets: Laval HDR (radiometrically accurate HDR panoramas) and SUN360 (diverse LDR panoramas).
- Learned a latent space of HDR skies from Laval HDR, training the encoder to be robust to white balance, exposure, and occlusions.
- Converted SUN360 LDR panoramas to HDR, extracted representations, and supervised LDR-to-HDR mapping using cropped image pairs.
- Published as a conference paper at **CVPR 2019**.

● **Research Internship, University of Waterloo**

Waterloo, Canada

Guide : Prof. Vasudevan Lakshminarayanan, May'19 - July'19

- **Objective :** Generating synthetic retinal images.
- We proposed a pipeline of two models for generating retinal images and corresponding blood vessel.
- First model outputs the blood vessel using enhanced Residual Variational Auto-Encoder using a random normal vector as input. Second model is image-to-image translation network which takes the generated blood vessel as input to outputs retinal fundus image.
- Results were clinically relevant and our research paper was published in **SPIE Medical Imaging Conference 2020**.

REFERENCES

- **Prof. J. F. Lalonde:** Professor, Department of Electrical and Computer Engineering, University Laval, jflalonde@gel.ulaval.ca
- **Ola Ahmad:** Chief AI Scientist at Thales Canada, ola.ahmad@thalesdigital.io
- **Prof. Alexander Ilin:** Professor, Computer Engineering, Aalto University, +358415014497, alexander.ilin@aalto.fi
- **Prof. Vasudevan Lakshminarayanan:** Professor, Electrical and Computer Engineering, University of Waterloo, vengulak@uwaterloo.ca
- **Deekshith Marla:** Founder & CTO (Featured in Forbes 30 Under 30), Lithasa Technology, Arya.ai, deekshith@arya.ai