

H-BRS

(Masters In Autonomous Systems)

Foundation Course(Hackathon Topic)

TOPIC:

Robust position control of the arm using velocity interface.

MENTOR:

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DESCRIPTION:

1. Focus of the project is to have robust position control of the robot arm.
2. In order to control position robustly, velocity control and position feedback will be used.
3. The required functionalities will be implemented, keeping in view the theme of the Hackathon so that software can be scalable and integrable.