

Amplifier is usually known to be amplifying the input signal. In any amplifier for the given system the properties like amplification, frequency response, input impedance and output impedance are fixed.

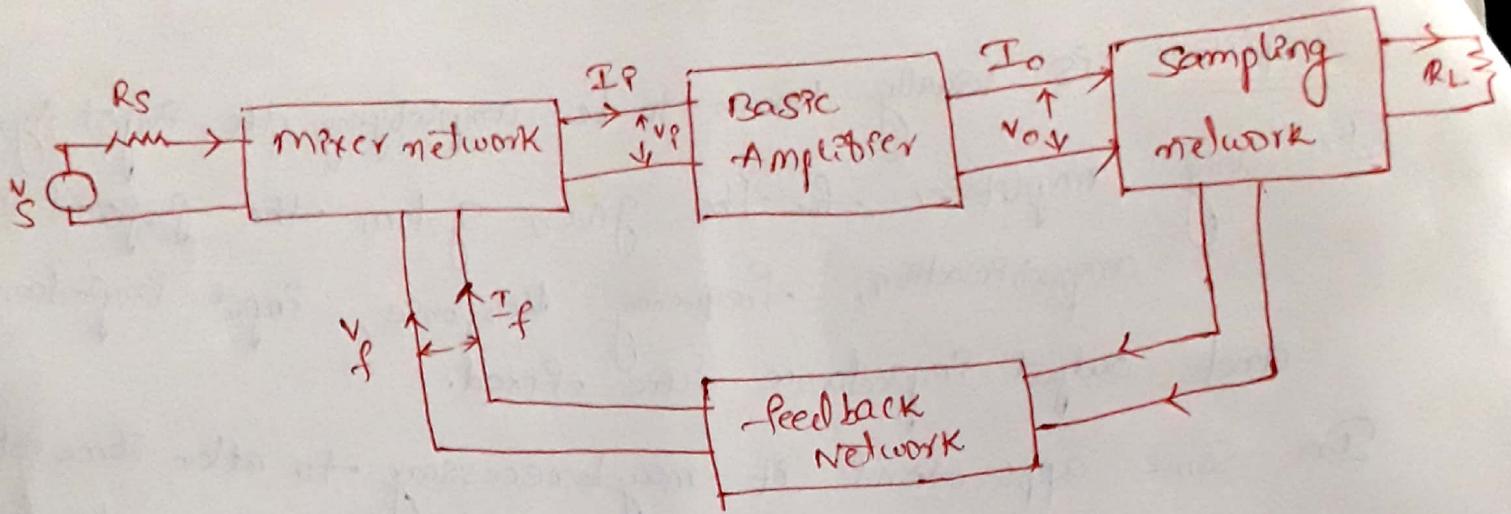
In some applications it may be necessary to alter some of properties of amplifier. Such alterations can be done by the application of feedback technique.

An amplifier is said to be a feedback amplifier if a part of its output is fed back or returned to the input circuit and is combined with the input signal.

Principle of feedback in amplifiers —

A amplifier is one in which a part of the output of the amplifier is fed back to the input.

The block diagram shown here is a consist of a basic amplifier with a gain of A . In its output we have a sampling circuit. From this sampling circuit, we connect a feedback network. The output of the feedback network is given to the input of the amplifier through a mixture network.

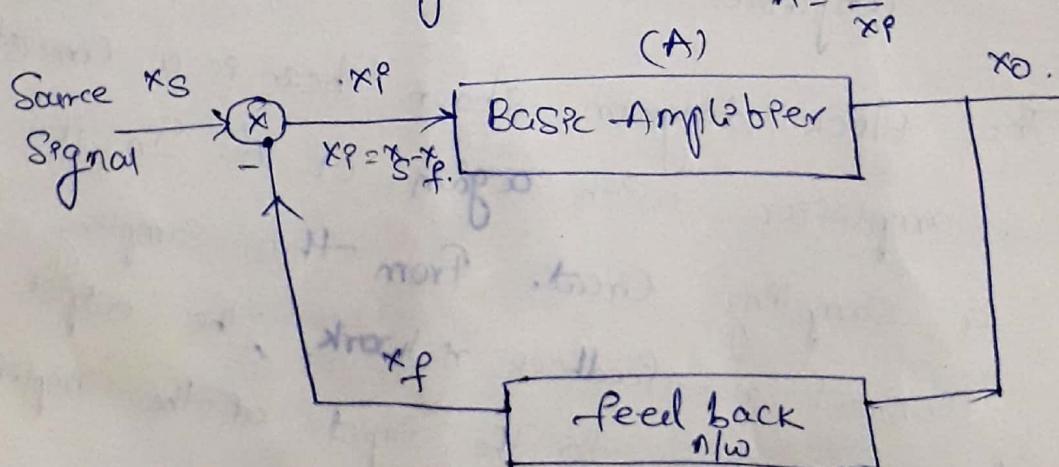


If the feedback signal caused an increase in the output of the amplifier we call it as positive feedback.

If the feedback signal produced a reduction in the output signal from the amplifier then we call the feedback as negative feedback.

Expression for the negative feedback amplifier gains—

Basic Block diagram:



$$A = \frac{v_o}{x_p}$$

$$A_S = \frac{v_o}{v_s}$$

$$A = \frac{v_o}{x_p}$$

$$\beta = \frac{x_p}{v_o}$$

$$A = \frac{v_o}{v_s - \beta v_o} = \frac{v_o}{v_s - \beta v_o}$$

$$A v_s - A \beta v_o = v_o$$

$$A v_s = v_o (1 + A \beta) \Rightarrow$$

$$\frac{v_o}{v_s} = A_S = \frac{A}{1 + A \beta}$$

$$\therefore A_S = \frac{A}{1+AB}$$

The product AB is called the loop gain feedback factor.

(or) loop transmission

Return Ratio

Sampling network :-

1. Sampling system sampled the output voltage by connecting the feedback network in shunt with the output.
2. Sampling system sampled the output current by connecting the feedback network in series with the output.

Mixing Network :-

The feedback voltage may be mixed with single voltage in two basic ways.

1. Series mixing

Feedback circuit is in series with the voltage source. Feedback circuit is in shunt with the current source. This uses output voltage sampling.

1. No Hoge Series feedback :-

and Series mixing at input side.

2. Current Series :-

This uses current sampling at output side and series mixing at input side.

3. Current Shunt :-

This uses current sampling at output side and shunt mixing at input side.

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$$A_f = \frac{A}{1+AB}$$

III. Lin
verifying

Basic Considerations

The following conditions must be met by the feedback circuit in order to tell the above equation is true.

1. The input signal should be transmitted to the output through the internal feedback amplifier 'A' and not through the feedback network.

Thus if 'A' is set to zero by reducing f_{ce} (or) f_m or the transistor to zero, the output must be zero.

When this happens this implied that β network be unilateral. In practice this condition is fully met not met because β is a bilateral network.

2. The feedback signal travels from the output to the input through the β network and not through the amplifier. i.e., Reverse transmission is zero.

3. The Reverse transmission factor β of the network is independent of the load and source resistance.

4. We find that V_d (difference signal) gets multiplied by ' -1 ' in the passing through the basic amplifier is further multiplied by the ' β ' in passing through the feed back network and is multiplied by ' -1 ' in the mixing stage. In this process, the signal has traversed

from the input terminals around the loop formed by the amplifier, feedback network and the mixing of the signal gets multiplied by the $-A\beta$ factor. In the journey along the loop.

The product $-A\beta$ is called the loop gain, return ratio or the loop transmission feedback factor.

The magnitude of feedback introduced into an amplifier is expressed in dB's. (decibels)

$$N = 20 \log \left(\frac{1}{1+A\beta} \right)$$

$$= 20 \log \left(\frac{A_f}{A} \right)$$

A_f = wth. gain

A = gain

Notes

In case of positive feedback, $(1+A\beta) < 1$ so that ab
Equation, 'n' is a positive number.

for negative feedback 'n' is a negative number.

General characteristics of Negative feedback Amplifiers

The negative feedback Reduced the Transfer gain, However
Despite of this Reduction in Transfer gain, negative
feedback is extensively used in amplifiers since
it produced various desirable characteristics.

Some of the Advantages of negative feedback:-

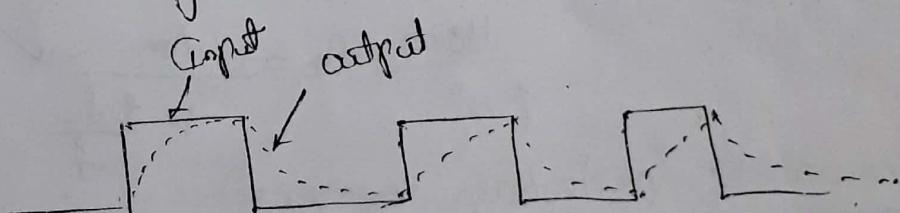
① Frequency distortion:-

In Conventional amplifiers we face the frequency
distortion, this is due to ~~un~~ equal amplification
of different frequencies present in the Input Signal.

In general we will not observe frequency distortion for
Sinusoidal input signals.

But Non-Sinusoidal Signals (L, A, etc) are
Affected by the frequency distortion.

for Example:-



And also, when we use 'pf' (picofarads) Capacitor
at the Input & Output Side it causes high frequency
distortion, and we eliminate the picofarads.

When we use ii farad Capacitor at the Input and Output
Side it caused Tilt problems.

All These Problems are avoided by using feedback Signal.

We make the feedback is output of ph. with the input signal. So we can avoid distortions upto some extent level.

(b) Phase distortion :-

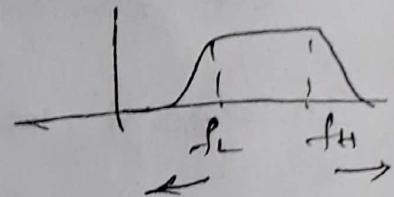
Different frequencies receive the different phase. Phase distortion does not effect the quality of a signal.

(c) Effect on Bandwidth

$$B.W = f_L - f_H$$

B.W is increased in negative feedback amplifiers.

f_L is decreased.



Effect on lower cutoff :-

$$\text{frequency, } f_L \quad A_{Lf} = \frac{A_L}{1 + \beta \cdot A_L}$$

$$\text{Here, } A_L = \frac{Am}{1 - \beta \cdot \frac{f_L}{f}}$$

Here $Am = \underline{\text{Max. Amp}}$

$$\Rightarrow A_{Lf} = \frac{\left(\frac{Am}{1 - \beta \cdot \frac{f_L}{f}} \right)}{1 + \beta \cdot \frac{Am}{\left(1 - \beta \cdot \frac{f_L}{f} \right)}} = \frac{-Am}{1 - \beta \cdot \frac{f_L}{f} + \beta \cdot Am}$$

$$= \frac{-Am}{\left(1 + \beta \cdot Am \right) \left(1 - \frac{\beta \cdot f_L}{f} \right)}$$

$$\boxed{A_{Lf} = \frac{-Am}{1 - \beta \cdot \frac{f_L}{f}} \Bigg| \frac{f}{f(1 + \beta \cdot Am)}}$$

hence above equation proved that lower cut off freq.⁽³⁾ is further decreased by adding the feedback.

Eff

Effect on higher CutOff frequency

-ve feedback increased the higher cut off freq.

$$B_{wp} = f_{hf} - f_{lf}$$

$$\boxed{B_{wp} = (f_h - f_l)(1 + \text{Amp}\beta)} \quad \sim$$

Effect on the frequency distortion

$B_w \uparrow \rightarrow$ frequency distortion \downarrow

$$\% \text{ tilt} = \frac{\Delta f_L}{f_0} \times 100.$$

Variations in f_L cause the tilt changes

$$\downarrow \text{tr} = \frac{0.35}{\Delta f_H \uparrow}$$

frequency distortion is decreased

Effect on the Sensitivity :-

Sensitivity is defined as the

$$\boxed{S = \frac{(dA_f/A_f)}{dn/A}}$$

ability to respond the negative feedback in the circuit.

Tells how the disturbances are influenced by n/w .

$$\text{clear } A_f = \frac{A}{1+AB}.$$

$$\frac{\partial A_f}{\partial A} = \frac{(1+AB) - A\beta}{(1+AB)^2}$$

$$= \frac{1}{(1+AB)} - \frac{\beta}{(1+AB)^2}$$

$$\frac{\partial A_f}{\partial A} = \frac{1+AB - AB}{(1+AB)^2} = \underbrace{\frac{1}{(1+AB)}}_{\text{Ansatz}}$$

$$\Rightarrow \frac{\partial A_f}{\partial A} = \frac{A}{1+AB} \cdot \frac{1}{A} \cdot \frac{1}{(1+AB)}$$

$$\Rightarrow \frac{\partial A_f}{\partial A} = A_f \cdot \frac{1}{A} \cdot \frac{1}{(1+AB)}$$

$$\Rightarrow \frac{\partial A_f}{A_f} = \left(\frac{\partial A}{A}\right) \cdot \frac{1}{(1+AB)}$$

$$\Rightarrow \left(\frac{dA_f}{A_f}\right) = \left(\frac{dA}{A}\right) \cdot \frac{1}{(1+AB)}$$

$$\Rightarrow \text{Sensitivity } \frac{\left(\frac{dA_f}{A_f}\right)}{\frac{dA}{A}} = \frac{1}{1+AB}.$$

$$\Rightarrow \left(S = \frac{1}{1+AB}\right) /$$

$$D = \frac{1}{S} = 1+AB.$$

- Effect on harmonic distortion :-

(4)

D_H distortion w/o F.B.

D_{Hf} distortion with F.B.

\Rightarrow

$$-AB \cdot D_{Hf} + D_H = D_{Hf}$$

\Rightarrow

$$D_{Hf} + BA D_{Hf} = D_H$$

$$D_{Hf} (1 + \beta A) = D_H$$

$$\Rightarrow D_{Hf} = \frac{D_H}{1 + \beta A}$$

clear $D_{Hf} < D_H$.

when O/p is feed back to input, distortion also passes through feed back loop.

$$D_{Hf} < D_H$$

Effect on noise :-

$$N_f = \frac{N}{1 + \beta A}$$

noise also Reduced

④ It is the Ratio of change in overall feedback voltage gain to the differential change in the gain for the amplifier.

$$S = \left(\frac{dA_f}{A_f} \right) / \underbrace{\left(\frac{dA_f}{A_f} \right)}_{\text{for the amplifier}}$$

Problem ①) An amplifier has a open loop gain of $A = 200$. If 5% of output f_L is fed back, f_{Hf} is $20K(1.2)$. If 5% of output is returned to the input in series opposition, Then find
 ① closed loop gain ② f.b. factor ③ An
 of the fb ④ f_{L_n} , f_{H_n}

Solution:-

$$V_f = 5\% V_o$$

$$V_f = 0.05 V_o \quad \text{And given } A = 200$$

$$\Rightarrow \beta = 0.05 ;$$

$$\therefore 1 + AB = 1 + (0.05) \times 200$$

$$= 1 + 10 = 11.$$

$$\textcircled{i} \quad A_f = \frac{A}{1 + AB} = \frac{200}{11}$$

$$\textcircled{ii} \quad \text{f.b. factor } \beta = 0.05$$

$$\textcircled{iii} \quad \text{Amount of the feedback} = \frac{1}{1 + AB}$$

$$= \frac{1}{11}$$

(or)

$$= -20 \log_{10}(1 + AB) \text{ dB}$$

$$= -20 \log_{10}(11) \text{ dB} = 11 \text{ dB}$$

$$\textcircled{iv} \quad f_{L_f} = \frac{f_L}{1 + AB} ; \quad f_{H_f} = f_H (1 + AB)$$

$$= (20f_H) \text{ dB} = 20K (11) \text{ dB} = 20K(1.2) \text{ dB}$$

problem (2) An Amplifier has gain $A = 1000 \pm 100$, (5)
 output. It is desired to have an amp whose gain varied by
 (ii). not more than 0.1% calculate the.

- ① c.L gain ② amount of f.B ③ f.B factor.

Ans :-

$$A = 1000 \pm 100$$

$$= \frac{1000}{100} = 10\%$$

$$\Rightarrow A = 1000 \pm 10\%$$

$$\Rightarrow \frac{\Delta A}{A} = 10\% \quad \text{and given } \frac{\Delta A_f}{A_f} = 0.1\%.$$

we have

$$\frac{\Delta A_f}{A_f} = \frac{\Delta A}{A} \times \frac{1}{1+A_f}$$

$$0.1\% = 10\% \times \frac{1}{1+A_f}$$

$$\Rightarrow \frac{1}{1+A_f} = \frac{0.1}{10} = 0.01$$

$$\therefore \boxed{1+A_f = 100}$$

$$\textcircled{1} \quad \text{c.L gain} \quad A_f = \frac{A}{1+A_f} = \frac{1000}{100} \\ = 10.$$

$$\textcircled{2} \quad \text{Amount of feedback} \quad = \frac{1}{1+A_f} \\ (\text{or}) -20 \log(1+A_f).$$

$$\textcircled{3} \quad \text{f.B factor} \quad 1+A_f = 100 \\ \Rightarrow \beta = \frac{100-1}{1000} = 0.099$$

Problem ③

Intr. Amp. produced an output of 36 Volt with 7% distortion when applied V_P is 28mV. If 1.2% output is returned to the V_P in series opposition calculate ① Output Voltage ② Amount of Distortion.

$$V_O = 36 \text{ V}$$

$$V_P = 28 \text{ mV}$$

$$\therefore A_f = \frac{V_O}{V_P} = \frac{36}{28 \text{ m}} = \underline{\underline{1285}}$$

$$V_f = 1.2\% V_O = \frac{1.2}{100} \times V_O$$

$$V_f = 0.0012 V_O$$

$$\therefore \beta = 0.0012$$

$$\begin{aligned} 1 + A\beta &= 1 + (1285) \times (0.0012) \\ &= 16.42 \end{aligned}$$

$$\Rightarrow A_f = \frac{A}{1 + A\beta} = \frac{1285}{16.42} =$$

$$\textcircled{1} \quad \text{Output Voltage } V_O = ?$$

$$A_f = \frac{V_O}{V_P} \Rightarrow V_O = A_f \cdot V_P$$

$$\textcircled{2} \quad \text{Amount of distortion}$$

$$V_O = \underline{\underline{2.11 \text{ V}}}$$

$$D + V_P = \frac{D_H}{1 + A\beta} = \frac{7}{16.42} = 0.4\%$$

An amplifier with open loop voltage gain of 1000 (6) delivers 10W of power output at 10% second harmonic distortion when input is 10mV. If 40dB negative feedback is applied and output power is to remain at 10W. Determine the required input signal vs and second harmonic distortion with feedback?

$$\text{Ans} \rightarrow A_V = 1000; \quad \text{Output power} = 10W.$$

Input power = 10mV.
Voltage

$$-40 = 20 \log \left(\frac{1}{1 + A\beta} \right)$$

$$\Rightarrow 1 + A\beta = 100.$$

$$A\beta = 99$$

$$\beta = \frac{99}{1000} = 0.099.$$

$$\Rightarrow A_{Vf} = \frac{A_V}{1 + A\beta} = \frac{1000}{1 + 1000 \times (0.099)}$$

$$A_{Vf} = \frac{1000}{1 + 99} = \frac{1000}{100} = 10$$

Now with feedback & without feedback, Amplifier delivers a power of 10W.

$$\Rightarrow A_{Vf} = \frac{V_o}{V_s}$$

\Rightarrow To maintain some output power, we should maintain the same output voltage and also Gain should be constant.

$$A_{Vf} = \frac{V_o}{V_s} = 10.$$

$$\Rightarrow V_s = V_o / 10 = 10 / 10 = 1 \text{ Volt}$$

Second harmonic distortion is reduced by a factor $1 + A\beta$.

$$\Rightarrow D_{2f} = \frac{D_2}{1 + A\beta} = \frac{0.1}{1 + A\beta} = \frac{0.1}{1000} = 0.0001 = 0.1\%$$

- (5) An amplifier with open loop gain of $A = 2000 \pm 150$ is available. It is necessary to have the amplifier whose voltage gain varies by not more than $\pm 0.2\%$. Calculate β and A_f ?

Solution:-

$$\frac{dA_f}{A_f} = \frac{1}{1 + A\beta} \cdot \frac{dA}{A}$$

$$\Rightarrow \frac{0.2}{100} = \frac{1}{1 + (2000)\beta} \times \frac{150}{2000}$$

$$\Rightarrow 1 + 200\beta = 37.5$$

$$200\beta = 36.5$$

$$\beta = 36.5 / 2000 = 1.825\%$$

$$\therefore \beta = 0.01825$$

$$A_f = \frac{A}{1 + A\beta} = \frac{2000}{1 + (2000) \times (0.01825)}$$

$$A_f = 53.33$$

- (6) An amplifier with open loop gain of $A_f \leq 1000 \pm 100$ is available. It is necessary to have an amplifier whose voltage gain varies by no more than $\pm 0.1\%$.

- Find (a) Reverse transmission factor β of the feedback network is used
(b) Find the gain with feedback.

Sol :- (a) we know that $\frac{dA_f}{A_f} = \frac{1}{|1+\beta A|} \cdot \frac{dA}{A}$ (a)

Given $dA = 100$

$A = \underline{1000}$.

$$\Rightarrow \frac{0.1}{100} = \frac{1}{(1+\beta A)} \times \frac{100}{1000}$$

$$1+\beta A = \frac{100}{0.1 \times 10} = 100$$

(b) Gain with feedback =?

$$A_f = \frac{A}{1+\beta A} = \frac{1000}{1+99}$$

= 10

(c) An amplifier without feedback gives a fundamental output of 36V with 2% second harmonic distortion when the input is 0.028V. (a) If 1.2% of the output is fed back into the input negative voltage series feedback circuit. what is the output voltage? (b) If the fundamental output is maintained at a 36V but the second harmonic distortion is reduced to 1%. what is the input voltage?

Solution :-

open loop gain $A = \frac{V_o}{V_p} = \frac{36}{0.028}$

$A = 1285$

$$V_p = 1.2\% \cdot V_o = 0.012 V_o$$

$$V_f = 1.2\% \cdot (36) \Rightarrow \beta = 0.012$$

$$\beta = \frac{V_f}{V_o} \Rightarrow \frac{0.012}{V_o} = \frac{1.2\% \cdot (36)}{V_o}$$

$$A_f = \frac{A}{1+AB}$$

$$= \frac{1285}{1 + 1285 \times 0.012}$$

$$A_f = 78.25$$

$$\Rightarrow A_f = \frac{V_o}{V_S} \Rightarrow V_o = A_f \times V_S \\ = 78.25 \times 0.028$$

$$V_o = 2.19V \quad \rightarrow \text{With feed}$$

(b). Second Harmonic distortion

$$B_{2f} = \frac{B_2}{1+AB} = \frac{B_2}{6}$$

$$1+AB = \frac{B_2}{B_{2f}} = \frac{7}{1}$$

$$= 7 \Rightarrow AB = 6$$

$$\Rightarrow A_f = \frac{V_o}{V_S} = \frac{A}{1+AB}$$

$$= \frac{1285}{6+1} = \frac{1285}{7}$$

$$A_f = 183.57$$

$$\therefore V_S = \frac{V_o}{A_f} = \frac{36}{183.57}$$

$$V_S = 0.196 \text{ Volts}$$

- ⑧ The overall gain of two stage amplifier is 100 and the second stage only has 10% of output voltage applied on negative feedback. If the gain and second harmonic distortion of second stages are -150 and 5% respectively without negative feedback. Find the

⑨ Gain of the first stage ⑩ 2nd harmonic dist. of the circuit.

For the Second stage, gain with feedback is $A_2' = \frac{D_2}{1+A_2\beta}$ (6)

$$A_2' = \frac{150}{1+150+0.1}$$

$$= 9.38$$

The overall gain is $A_1 + A_2' = 100.$

$$A_1 = \frac{100}{9.38} = 10.66$$

A_1 = Gain of the first stage

A_2 = Gain of the second stage.

feedback Identification:-

- ① Identify the input and output nodes.
- ② Identify the feedback Resistor.
- ③ Identify If the output is taken across feedback Resistor then it is called as Voltage Sampling Otherwise it is Current Sampling
- ④ If the feedback signal is connected Input of base transistor then it is said to be a Shunt mixing otherwise Series mixing

Drawbacks of Conventional amplifiers:-

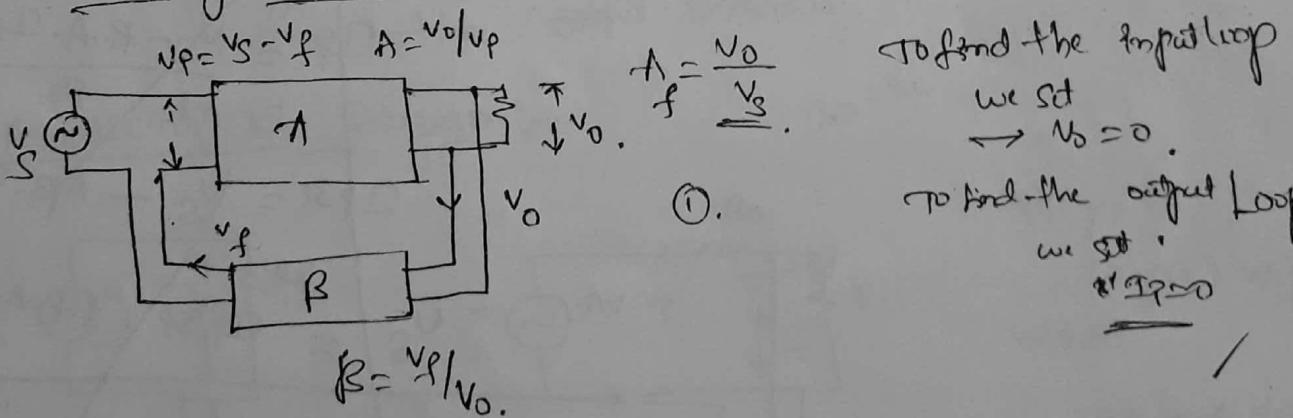
- not
1. Gain is \uparrow constant due to device / Transistor Parameter variations.
 2. Distortion is very high.
 3. Effect of noise is greater.
 4. OIP & OIP Impedances are not as desired values.

There are four ways of connecting a feedback signal.

1. Voltage Sensed feedback signal.
2. Voltage shunt feedback signal.
3. Current Sensed feedback signal.
4. Current Shunt " "

Measurements :- (Avg, Zin, Zout)

① Voltage Sensed feedback Amplifier:-



① Voltage follower (or) Voltage amplifier.

Gain:- $A = \frac{V_O}{V_F} = \frac{V_O}{V_S - V_f} \Rightarrow V_O = A(V_S - V_f)$

$$V_O = A(V_S - BV_O)$$

$$V_O + ABV_O = AV_S$$

$$\Rightarrow \frac{V_O}{V_S} = \frac{-A}{1+AB}$$

(13)

 Z_{outf} :-

$$Z_{\text{outf}} = \frac{V_S}{I_P} = ?$$

clear $I_P = \frac{V_P}{Z_P} = \frac{V_S - V_f}{Z_P} = \frac{V_S - \beta V_O}{Z_P}$

$$I_P = \frac{V_S - \beta(AV_P)}{Z_P} = \frac{V_S - \beta A \cdot I_P \cdot Z_P}{Z_P}$$

$$\Rightarrow I_P Z_P = V_S - \beta A \cdot I_P Z_P.$$

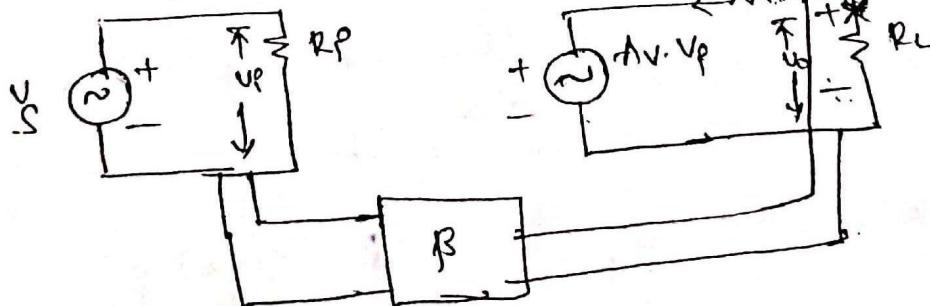
$$I_P Z_P (1 + \beta A) = V_S$$

$$\Rightarrow \boxed{\frac{V_S}{I_P} = Z_{\text{outf}} = Z_P (1 + \beta A)}$$

 Z_{outf} :-

To find Z_{outf} we equate $V_f = 0$, $I_S = 0$

Because Thevenin's / Norton's Impedance looking from the output terminals.

Equivalent circuit Diagram :- $\text{So } V_O = I_O R_O$

apply KVL in loop ② we get
that

$$-V_O + I_O R_O + Av \cdot V_P = 0.$$

$$V_O = I_O R_O + Av \cdot V_P.$$

$$\text{clear } V_P = -V_f$$

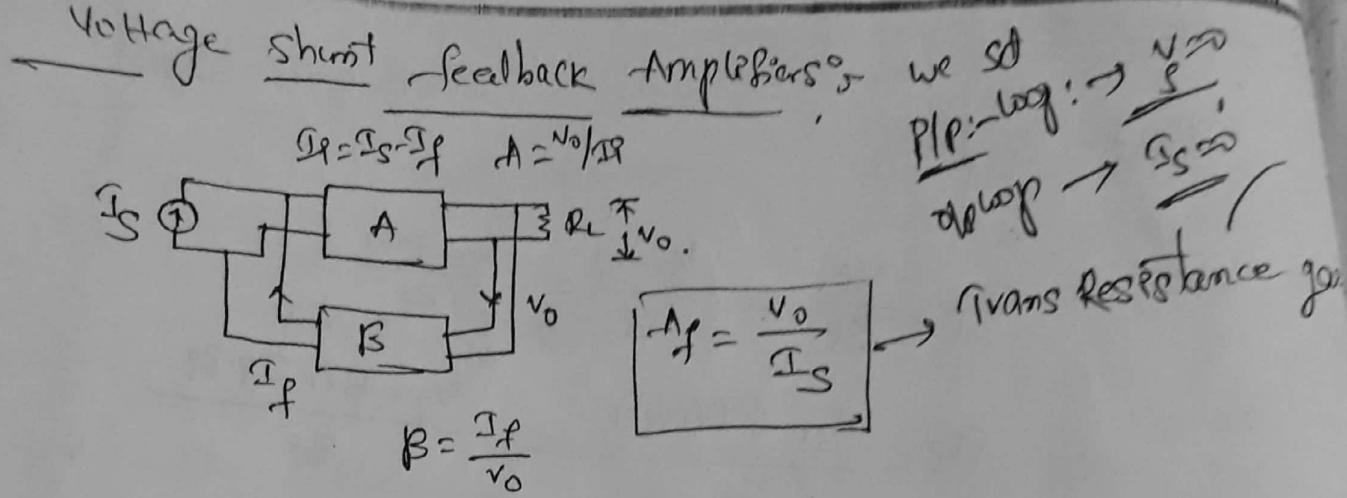
$$\text{Because } V_S = V_P + V_f$$

$$\text{when } V_f = 0 \Rightarrow V_P = -V_f$$

$$\Rightarrow V_O = I_O R_O - Av \cdot V_f$$

$$V_O = I_O R_O - Av \cdot \beta V_O$$

$$\Rightarrow V_O (1 + Av \cdot \beta) = I_O R_O \Rightarrow \boxed{Z_{\text{outf}} = \frac{R_O}{1 + Av \cdot \beta}}$$



1. It is also called TransResistance Amplifier.

Gain :-

$$A = \frac{V_o}{I_f}$$

$$A = \frac{V_o}{I_S - I_f} = \frac{V_o}{I_S - \beta V_o} \Rightarrow V_o = A(I_S - \beta V_o)$$

$$V_o(1 + \beta A) = A I_S$$

From above Trans Resistance gain

$$R_{mf} = \frac{A}{1 + \beta A}$$

$$A_f = \frac{V_o}{I_S} = \frac{A}{1 + \beta A}$$

clear $A = R_m$

Input Impedance :-

$$Z_{inf} = \frac{V_S}{I_S} = \frac{V_p}{I_S}$$

clear $I_S = \frac{V_p}{Z_{inf}} \Rightarrow Z_{inf} = \frac{V_p}{I_p + I_f}$

$$Z_{inf} = \frac{V_p}{I_p + \beta V_o} = \frac{V_p}{I_p + \beta(A \cdot I_p)}$$

$$Z_{inf} = \frac{V_p}{I_p(1 + \beta A)} = \frac{Z_{in}}{(1 + \beta A)}$$

$$\therefore Z_{inf} = \frac{Z_{in}}{1 + \beta A}$$

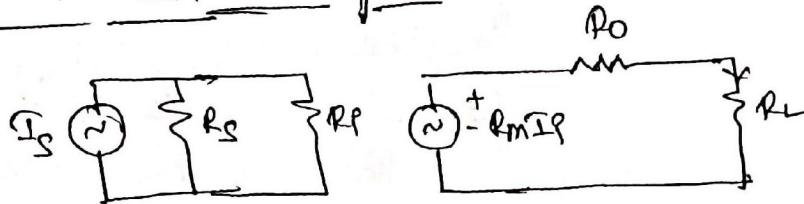
Sat :-

Quade, $\Sigma I_S = 0$.

$$\therefore I_S = I_P + I_F$$

$$\Rightarrow I_P = -I_F.$$

Equivalent Cut Diagram's



$$-V_o + I_o R_o + R_m I_F = 0.$$

$$V_o = I_o R_o + R_m I_F.$$

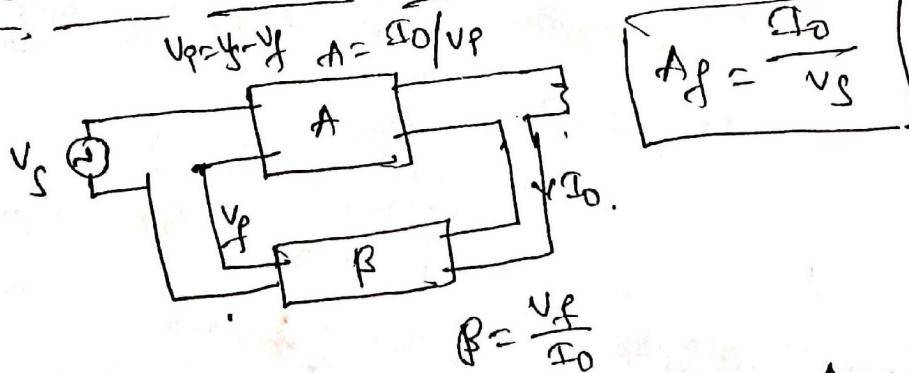
$$V_o = I_o R_o - R_m I_F$$

$$\Rightarrow V_o = I_o R_o - R_m (\beta V_o)$$

$$V_o \left(1 + R_m \beta \right) = I_o R_o.$$

$$\beta_o = \frac{V_o}{I_o} = \frac{R_o}{1 + R_m \beta}$$

Current Series feedback Amplifiers



To find
forward loop
output loop.

$I_o \infty$
output loop.
 $G_{po} \infty$

1. It is a trans conductance amplifier.

Gains :-

$$A = \frac{I_o}{V_p}$$

$$A = \frac{I_o}{V_s - V_f} \Rightarrow I_o = A(V_s - \beta I_o)$$

$$I_o(1 + A\beta) = A \cdot V_s$$

$$\boxed{G_m = \frac{I_o}{V_s} = \frac{A}{1 + A\beta}}$$

∴ $A = G_m$

Slope :-

$$\text{slope} = \frac{V_s}{I_s}$$

$$= \frac{V_s}{I_s} = -\frac{V_s}{I_o}$$

clear $I_o = \frac{V_p}{Z_m} = \frac{V_s - V_f}{Z_m} = \frac{V_s - \beta I_o}{Z_m}$

$$I_o = \frac{V_s - \beta(AV_p)}{Z_m}$$

$$\Rightarrow I_o Z_m = V_s - \beta A \cdot V_p$$

$$I_s Z_m = V_s - A\beta(I_s Z_m)$$

$$\Rightarrow I_s Z_m (1 + A\beta) = V_s$$

$$\Rightarrow \boxed{V_s / I_s = Z_m (1 + A\beta)}$$

Slope :-

Equivalent Circuit

Diagram :-



$$-I_o + \frac{V_o}{R_o} + G_m V_p = 0$$

$$I_o = \frac{V_o}{R_o} + G_m V_p$$

$$I_o = \frac{V_o}{R_o} + G_m(-V_f)$$

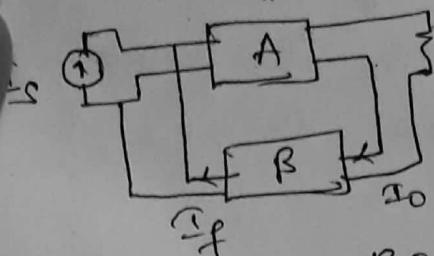
$$\Rightarrow \boxed{\text{slope} = \frac{R_o (1 + G_m \beta)}{1 + G_m}}$$

$$I_o = \frac{V_o}{R_o} - G_m \beta I_o$$

$$\Rightarrow I_o (1 + G_m \beta) = \frac{V_o}{R_o}$$

Current - Shunt Feedback Amplifiers

$A_f = \frac{V_o}{I_S}$



$$(A_f = \frac{V_o}{I_S})$$

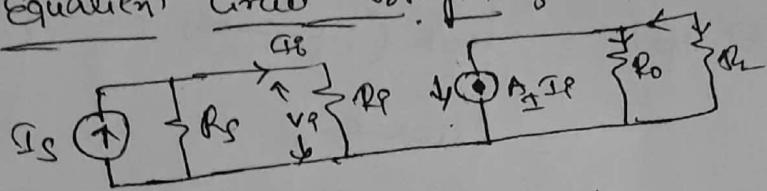
$$\beta = \frac{I_f}{I_O}$$

To find the output loop.

We set $\beta V_S \approx$
at the OP side
we set $I_O \approx$

1. At first a Current Amplifier.

Equivalent Circuit Diagrams



$$\beta_{if} = \frac{V_I}{I_S} = \frac{V_I}{I_f + I_O}$$

$$= \frac{V_I}{I_f + \beta I_O} = \frac{V_I}{I_f + \beta \cdot (A_f I_f)}$$

$$\beta_{if} = \frac{(A_f I_f)}{1 + A_f} = \frac{\beta}{1 + AB}$$

$$\underline{\underline{\beta_{of}}}, \quad \beta_{of} = \frac{V_o}{I_O}$$

$$I_O = \frac{V_o}{Z_0} + A_f I_f$$

$$= \frac{V_o}{Z_0} + A_f (-I_f)$$

$$= \frac{V_o}{Z_0} - A_f \cdot I_f = \frac{V_o}{Z_0} - A_f (B \cdot I_O)$$

$$I_O = \frac{V_o}{Z_0} + (-A_f B \cdot I_O)$$

$$I_O (1 + A_f B) = \frac{V_o}{Z_0}$$

$$\Rightarrow \frac{V_o}{Z_0 \cdot I_O} = (1 + A_f B)$$

$$\therefore \underline{\underline{\beta_{of}}} = Z_0 (1 + A_f B)$$

Problems ① Determine the voltage gain & Input Impedance output impedance with feedback for Voltage Series feedback having $A = -100$, $R_F = 10K\Omega$, $R_o = 20K\Omega$, for β of (a) $\beta = -0.1$, (b) $\beta = -0.5$.

I. (a) $A_{Vf} = \frac{Av}{1 + Av\beta} = \frac{-100}{1 + (-100) \times (-0.1)} = -9.09$.

(b) $Z_{in,f} = Z_{in}(1 + Av\beta) = 10K(1 + (-100) \times (-0.1)) = 110K\Omega$.

(c) $Z_{out,f} = \frac{Z_o}{(1 + Av\beta)} = \frac{20K}{(1 + (-100) \times (-0.1))} = \frac{20K}{(1 + 10)} = \frac{20K}{11} =$

II. (a) $A_{Vf} = \frac{Av}{1 + Av\beta} = \frac{-100}{1 + (-100) \times (-0.5)} = \frac{-100}{1 + 50} = -\frac{100}{51}$

(b) $Z_{in,f} = Z_{in}(1 + Av\beta) = 10K(1 + (-100) \times (-0.5)) = 10K(1 + 50) = 510K\Omega$.

(c) $Z_{out,f} = \frac{Z_o}{(1 + Av\beta)} = \frac{20K}{(1 + (-100) \times (-0.5))} = \frac{20K}{(1 + 50)} = \frac{20K}{51} =$

Problems ②.

An Amplifier has an open loop gain of 100, an input impedance of $1K\Omega$ and an output impedance of 100Ω . A feedback network with a feedback factor of 0.99 is connected to the amplifier in a voltage series feedback mode. The new input impedance and output impedances are respectively?

Given $A = 100$, $\beta_{in} = 1K\Omega$

$$Z_{out} = 100\Omega$$

$$\beta = 0.99$$

Voltage-series feedback mode.

① $\beta_{inf} = \beta_{in} (1 + AB)$

$$= (1K\Omega) (1 + 100 \times 0.99)$$

$$= (1K) (1 + 99) = 100K$$

$$\beta_{inf} = 100K\Omega$$

② $Z_{outf} = Z_{out} / (1 + AB)$

$$= \frac{100}{(1 + 100 \times 0.99)} = \frac{100}{100}$$

$$= 1\Omega$$

③ Calculate the gain of a negative-feedback amplifier having $A = -2000$, $B = -1/10$.

④ Calculate the gain, input, output impedances of a voltage-series feedback amplifier having the gain $A = -300$, $R_p = 1.5K\Omega$, $R_o = 50K\Omega$, $\beta = -1/15$.

① Feedback signal

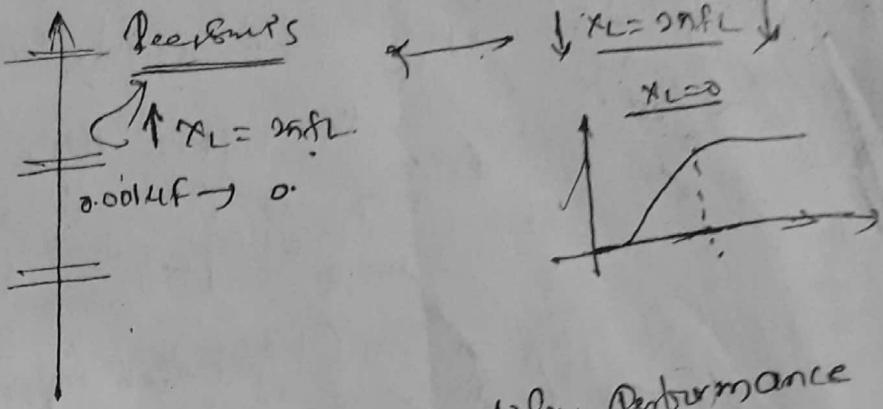
② ^{Sampled} Output signal

③ To find input loop ^{we sd}

④ To find output loop ^{in sd}

⑤ Signal source form.

⑥ $\beta, A_p, D, A_f, R_H, R_{bf}, \underline{R_{sf}}$



Effect of negative feedback on

Amplifier Performance

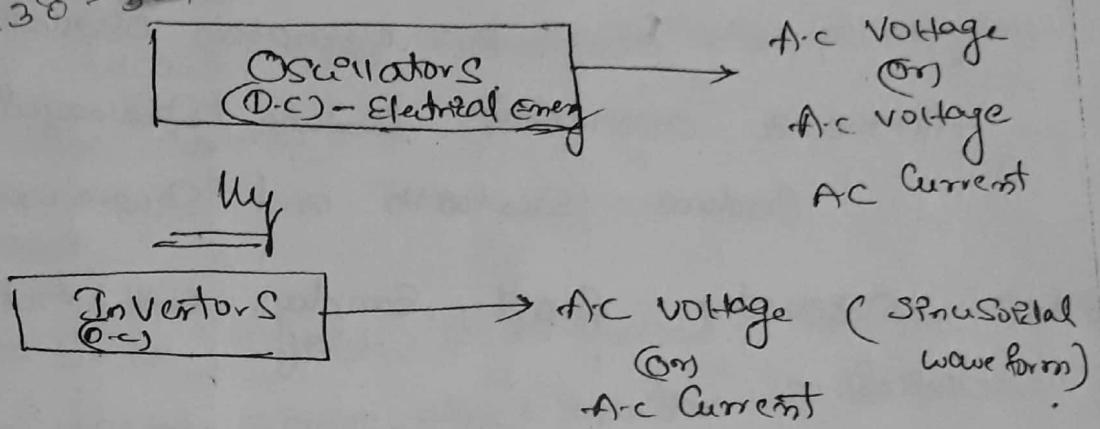
<u>Property</u>	<u>Voltage Series</u>	<u>V/Shunt</u>	<u>Cu-Series</u>	<u>Cu-Shunt</u>
① $\frac{V_o}{V_i}$	Voltage	Current	Voltage \rightarrow Current	Current \rightarrow Current
② $\frac{V_o}{I_o}$	Voltage	Voltage		
③ β	$\frac{V_f/V_o}{V_o}$	$\frac{I_f}{V_o}$	$\frac{N_f}{I_o}$	$\frac{I_f}{I_o}$
④ A	$\frac{V_o/V_f}{V_f}$	$\frac{V_o}{I_f}$	$\frac{I_o}{V_f}$	$\frac{I_o}{I_f}$
⑤ D	$1 + A\beta$	$1 + R_m \beta$	$1 + G_m \beta$	$1 + A\beta$
⑥ A_f	$\frac{A_f}{1 + A_f \beta}$	$\frac{V_o}{I_s}$	$\frac{I_s}{V_s}$	$\frac{G_o}{I_s}$
⑦ R_{if}	increased	decreased.	increased \rightarrow decreased	decreased
⑧ R_{of}	decreased.	decreased	increased \rightarrow decreased	decreased
⑨ To find input loop Parallel $\frac{V_o}{I_s} = 0$	$\frac{V_o}{I_s} = 0 \checkmark$	$V_o = 0 \checkmark$	$I_s = 0 \checkmark$	$V_o = 0 \checkmark$
we set	$I_o = 0$	$I_o = 0$	$I_o = 0$	$I_o = 0$
⑩ To find output loop Series $\frac{V_o}{I_s} = 0$	$\frac{V_o}{I_s} = 0 \cancel{\checkmark}$	$\frac{V_o}{I_s} = 0 \cancel{\checkmark}$	$I_s = 0 \checkmark$	$I_s = 0 \checkmark$
we set	$I_o = 0 \cancel{\checkmark}$	$I_o = 0 \cancel{\checkmark}$	$I_s = 0 \checkmark$	$I_s = 0 \checkmark$
⑪ To find output loop we set	$I_p = 0 \checkmark$	$I_p = 0 \checkmark$	$I_p = 0 \checkmark$	$I_p = 0 \checkmark$

Oscillators:-

4 copies UNIT - III
III - UNIT
LVE Periodic

Oscillator is a source of A.C Voltage (or) A.C Current.
We get A.C Output from the oscillator circuit. In alternator (A.C generators) the thermal energy is converted into Electrical Energy at 50Hz.

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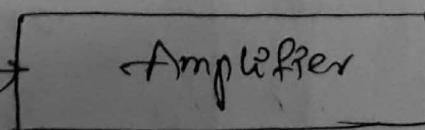


In the oscillator Circuits that we are describing now, Electric Energy is in the form DC is converted into Electrical Energy in the form of A.C.

In the Invertors Electrical Energy DC is converted into A.C. But there only output power is criteria and the actual shape of the waveform.

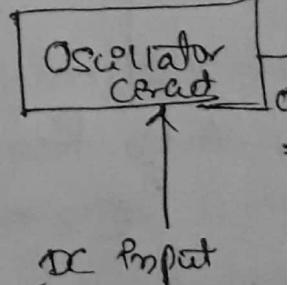
Amplifier Circuit:-

Input



Dc Power

Oscillator Circuit



Oscillator is a circuit which generates the AC output without giving any AC input is called the oscillator.

There are two types of oscillator circuits:

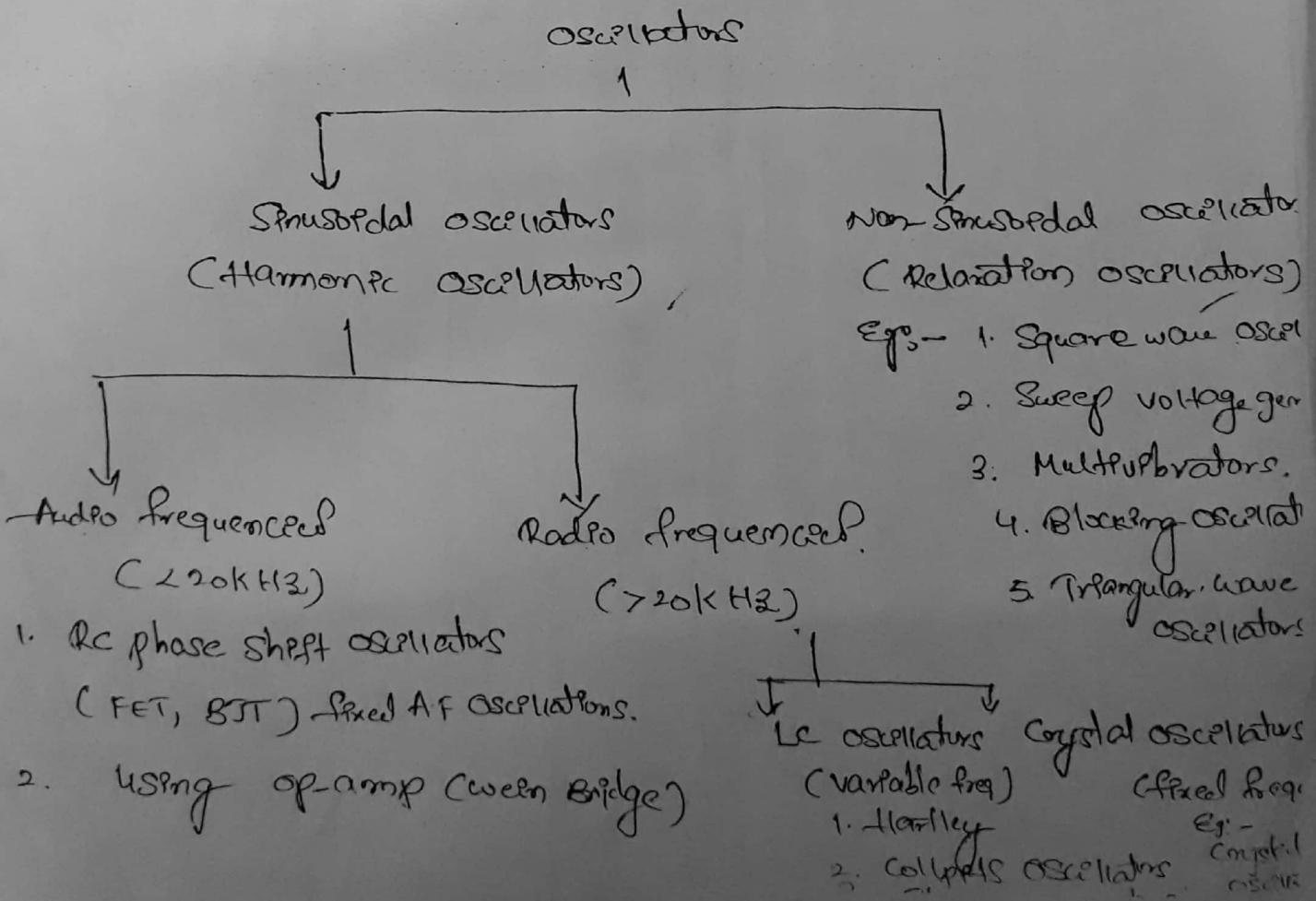
1. Harmonic Oscillators.
2. Relaxation Oscillators.

Harmonic oscillators produce Sine waves. Relaxation oscillator produce Sawtooth and Square waveforms etc.,

Oscillator Circuit Employ Both Active and passive devices.

Active device Components converts the D.C into A.C and passive components determine the frequency of oscillations.

Classification:-

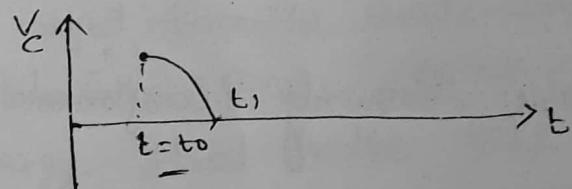


4. Both Capacitor 'C', Inductor 'L' are lossless, ideal devices. So quality factor is infinity.

5. Energy is introduced into the circuit by charging the capacitor to v volts. If switch is open, it cannot be discharged because there is no path for discharging the current to flow.

(N/W) Circuit operation:-

- ① Suppose at $t=t_0$ switch 'S' is closed. Then the current flows. Voltage across the 'L' inductor will be v . At $t=t_1$ the voltage across the 'C' is v volts.
- ② When the switch is closed, current flows. So the charge across the capacitor 'C' decreased.



- ③ The energy stored in the capacitor decreased, the energy stored in the inductor 'L' increased, because current is flowing through the 'L'. Thus the total energy in the circuit remains the same.
- ④ When the v across the capacitor 'C' becomes 0, the current through the inductor is maximum. When the energy in 'C' is 0, energy in 'L' is a maximum. And current in the inductor starts the charging capacitor in the reverse direction.

Performance measured by oscillator circuit.

① Stability :-

This is determined by the passive components. R, L and C determine the frequency of oscillations. If R' changes with T, it changes so stability is affected. Capacitors should be of high quality with low leakage.

So silver and mica ceramic capacitors are widely used.

② Amplitude Stability :-

To get large output voltage, amplification is to be done.

③ Output Power :-

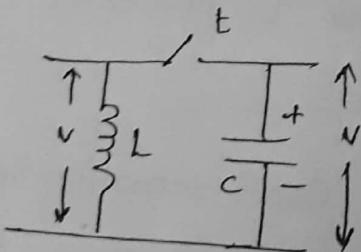
Class A, Class B, Class C operations can be done.

But Class C gives the largest output power but harmonics are more.

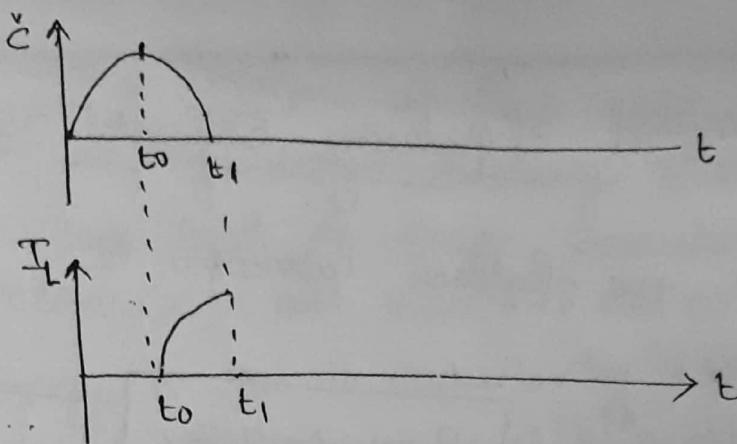
④ Harmonics :-

Un desirable frequency components are called harmonics.

→ Principle of operation :-



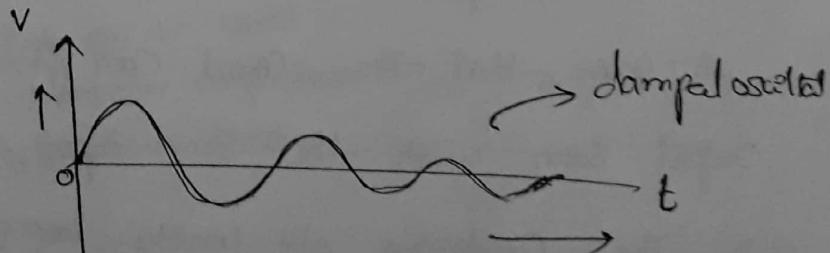
1. In the circuit L, C are Reactive Elements. They store the Energy.
2. The capacitor stores energy in the form of electric field whenever there is a voltage across its plates.
3. The Inductor stores energy in its magnetic field whenever current flows.



So at $t=t_1$, Current in 'L' is maximum and for $t>t_1$ the current starts changing 'i' in the opposite direction. So i across the 'C' becomes the negative as shown in figure. " Then we are getting Sinusoidal variations without giving any one input".

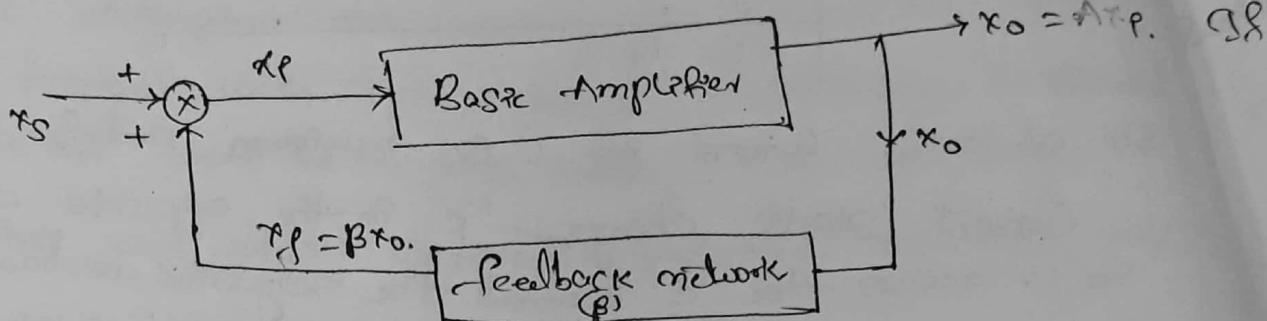
Note:-

- Sinusoidal Function is the only function that satisfies the Conditions governing the Exchange of the Energy in the Circuit.
- But here the circuit is not a practical circuit. Because we have to take output from the circuit; Energy has to be extracted from the circuit. As we draw the energy from circuit, the energy stored in the C & L decreases. So output also decreased or the voltage across the C & L decreased so output also decreased (or) increased the voltage across the C & L decreased so we get damped oscillations.



Another method of producing Sinusoidal oscillation is

They used +ve feedback connection ps:



$$x_F = Bx_O.$$

$$\text{open loop gain ps } A = \frac{x_O}{x_F}.$$

$$A = \frac{x_O}{x_S + x_F} \Rightarrow A = \frac{x_O}{x_S + Bx_O}.$$

$$\Rightarrow Ax_S + Abx_O = x_O.$$

$$\therefore A_F = \frac{x_O}{x_S} = \frac{A}{1+AB}.$$

Overall gain of the amplifier: $A_F = \frac{A}{1+AB}$,

$$\therefore A_F = \frac{A}{1-AB}.$$

If $BA=1$ then the $A_F \rightarrow \infty$.

is gain that the circuit can produce a finite amount of output even with the zero input //

→ The condition ob unity loop gain is called Barkhausen's crit magnitude ob loop gain ps $|AB|=1$.
phase ob loop gain ps 0° (or) 360° . (or) integral multiple ob $\frac{2\pi}{n}$ where $n=0, 1, 2, \dots$

Oscillatory Circuits - A circuit which produces electrical oscillations at any desired frequency is known as oscillatory circuit.

(or) Tank Circuit. A simple oscillatory circuit consists of a capacitor (C) and inductance coil (L) in parallel.

If some energy is given to capacitor by charging it, then this energy will be alternately stored in the electric field of the capacitor (C) and magnetic field in the inductor coil (L).

This interchange of energy between the inductor and capacitor is repeated over and over again, resulting in the production of oscillations. The frequency of oscillations will depend upon the values of L & C .

① An oscillatory circuit itself produces damped oscillations, oscillations whose magnitude decreases gradually. It is because of during each cycle, a small part of energy is used to overcome the resistive and radiation losses in the coil and dielectric losses in the capacitor.

② In practice, we need continuous undamped oscillations, for successful operation of electronic equipment. In order to make the oscillations ~~are more~~ in the tank circuit undamped, it is necessary to supply correct amount of energy to the tank circuit at the proper time to meet the losses.

③ The essential components of oscillator are

- ① A tank or LC circuit
- ② A transistor amplifier.
- ③ A feedback circuit.

Lc oscillators:-

In an Lc oscillator, the oscillations of desired frequency are produced in an oscillatory (LC) circuit. The Transistor and feedback circuit are properly connected to the LC circuit to sustain undamped oscillations.

The following are the most commonly used Lc oscillators.

- ① Tuned Collector oscillator
- ② Hartley oscillator
- ③ Colpitts oscillator.

The major difference b/w these oscillators lies in the method by which the energy is supplied to the tank circuit, to meet the losses.

Rc oscillators:-

In an Rc oscillator, we use a RC network instead of LC circuit. There are two basic types of RC ~~sustained~~ sinusoidal oscillators.

- ① RC phase shift oscillator
- ② Wien bridge oscillator.

① An RC phase shift oscillator essentially consists of a RC phase's network and a transistor amplifier. For a given set of RC values, there is only one frequency at which the RC mlw produces a phase shift of 180° . A further phase shift of 180° introduced in the circuit due to transistor parameters properties.

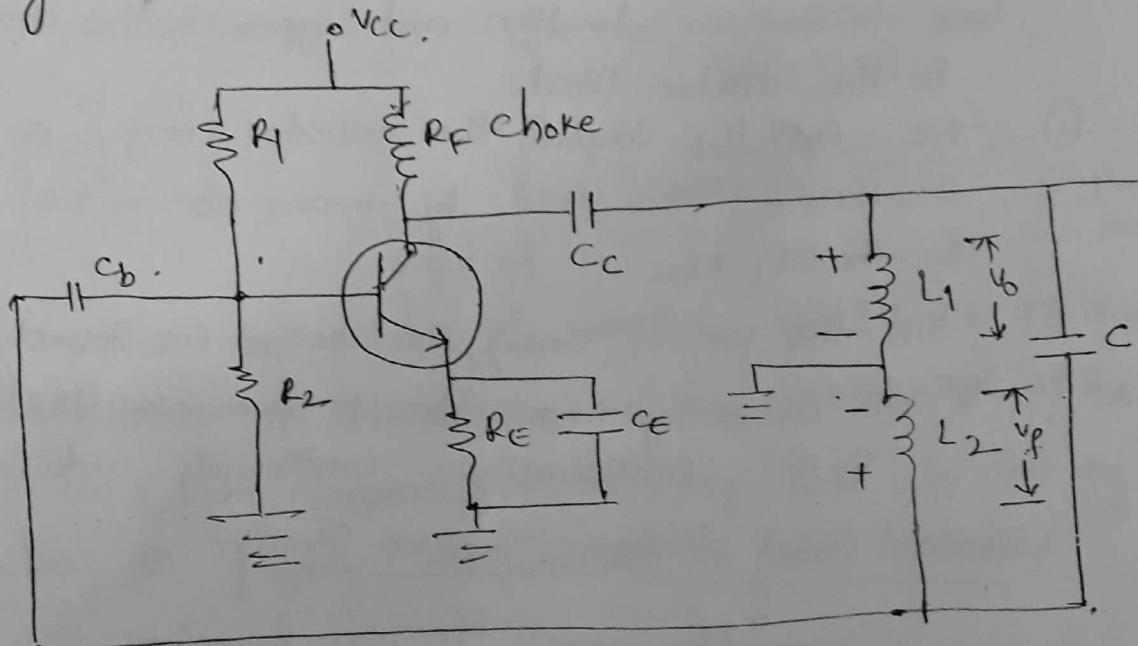
As a result, phase shift around the entire loop is 360° and undamped oscillations are produced.

② In wien bridge oscillator, the phase shift of 180° is determined by wienbridge instead of RC network.

Difference b/w the Alternator and oscillator

Although an alternator produces sinusoidal oscillations of 50Hz, it is fundamentally different from an oscillator. First, an alternator is a mechanical energy device having rotating parts whereas an oscillator is a non-rotating device. Second, an alternator converts mechanical energy into a.c. energy whereas an oscillator converts d.c. energy into a.c. energy. Third, an alternator cannot produce high frequency oscillations whereas an oscillator can produce oscillations ranging from a few Hz to several MHz.

Hartley oscillator



Circuit Details

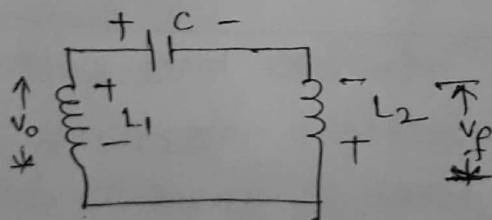
- ① L_1, L_2, C forms a tank circuit. Frequency of oscillations are to be determined with the help of all these 3 parameters.
- ② L_2 is ads like a feed back Inductor and output is taken across the inductor L_1 .
- ③ R_1, R_2 provided necessary biasing, R_E, C_E are provided the necessary gain.

④ L_1 & L_2 are connected with the opposite polarity. (2)

Circuit Operation :-

- ① When the circuit is switched on &, i.e. d.c power supply is applied to Amplifier circuit, Collector current starts rising and charges the capacitor C.
- ② When the capacitor is fully charged, it discharged through the coils L_1 & L_2 .
- ③ The oscillations across the L_2 are applied to the base to Emitter junction and appear in the amplified form in the collector circuit.
- ④ The coil L_1 couples the collector energy (or) Circled Energy into Tank Circuit by means of mutual inductance b/w the L_1 & L_2 .
- ⑤ In this way, energy is being continuously supplied to Tank Circuit by means of to overcome the losses occur in it. Consequently, continuous undamped oscillations

Equivalent Circuit diagram of Tank Circuit



Note :- L_2 produced a waveform of 180° phase shift of whenever the voltage developed across the inductor L_1 .

① Feed back fraction m_V :

The amount of feedback voltage for Hartley oscillator is depends upon the feedback fraction " m_V " of the circuit,

For this circuit

$$\text{Feedback fraction } m_V = \frac{V_f}{V_{\text{out}}} = \frac{x_{L_2}}{x_{L_1}} = \frac{L_2}{L_1}$$

Condition for Sustained oscillations are

$$h_{fe} = \frac{L_1}{L_2}$$

Condition for oscillations is

$$\gamma_1 + \gamma_2 + \gamma_3 = 0.$$

$$3\omega L_1 + 3\omega L_2 + \frac{1}{3\omega C} = 0.$$

$$3\omega L_1 + 3\omega L_2 = -\frac{1}{3\omega C}$$

$$3\omega L_1 + 3\omega L_2 = \frac{8}{\omega C}$$

$$f = \frac{1}{2\pi\sqrt{L_T C}}$$

$$\omega^r (L_1 + L_2) = \frac{1}{C}$$

clear $L_T = L_1 + L_2$

$$\omega^r = \frac{1}{C(L_1 + L_2)}$$

$$f = \frac{1}{2\pi\sqrt{(L_1 + L_2)C}} = \frac{1}{2\pi\sqrt{L_T C}}$$

output of

⑤ Transistor produced \uparrow 180° waveform and C_1, C_2 combination provided further 180° phase shift waveform. Total 360° of the waveform appears at the input side. In this way feedback is properly designed ~~not~~ to produce continuous undamped oscillations.

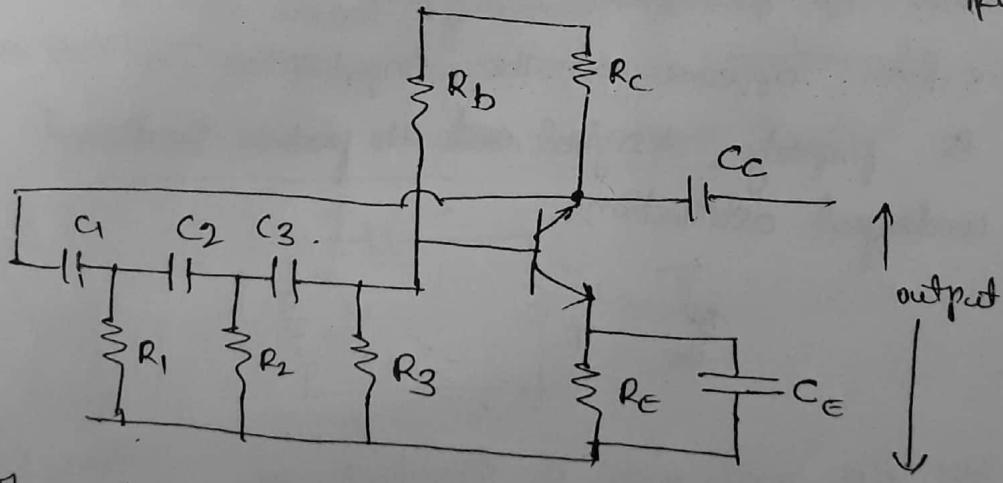
Phase shift oscillator

The oscillator circuits employing L-C elements have the general drawbacks. firstly, they suffer from frequency instability and poor wave form. Secondly, they cannot be used for very low frequencies, because they become too much bulky and expensive.

(Good frequency stability and waveform can be obtained by oscillators employing resistive and capacitive elements. Such amplifiers are called RC phase shift oscillators and the additional advantage that they have can be used for very low frequencies.)

In phase shift oscillators, a phase shift of 180° is obtained with a phase shift circuit instead of inductive and reactive capacitive coupling. A further phase shift of 180° is produced due to transistor properties.

$$RC = R \frac{d\theta + d\phi}{d\theta} \\ = dt \text{ sec.}$$

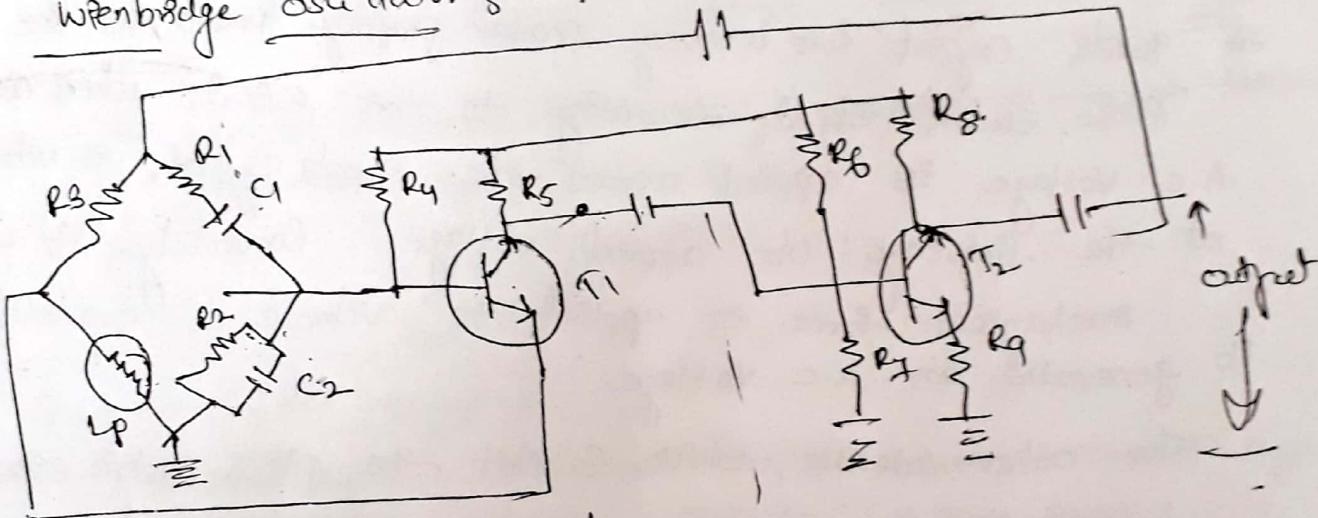


The phase shift m/w consists of a three sections R_1C_1, R_2C_2, R_3C_3 . At some particular frequency f_0 , the phase shift in each RC section is 60° . So that the total phase shift produced by the RC m/w is 180° . The frequency of oscillations is given by $f_0 = \frac{1}{2\pi\sqrt{R}C}$.

where $R_1 = R_2 = R_3 = R$ & $C_1 = C_2 = C_3 = C$.

- ① For Transistor in phase shift oscillator we employed voltage shunt feedback.
- ② FET phase shift oscillator Employed voltage series feedback.
- ③ Input Impedance of BJT is very low compare with FET
So we Employed voltage shunt feedback.
- ④ If we want to design , voltage series feedback ac-phase shift oscillator , we connect a Resistor in shunt with with the feedback network.

Wienbridge oscillator :-



$$f = \frac{1}{2\pi \sqrt{R_1 R_2 C_1 C_2}}$$

~~① $T \uparrow R_A$~~
~~② $I_B \downarrow I_C \downarrow V_C \downarrow$~~
~~③ $T \downarrow R_f \uparrow$~~ \rightarrow original

~~① $T \uparrow R_A$~~
~~② $I_B \downarrow I_C \downarrow V_C \downarrow$~~
~~③ $T \downarrow R_f \uparrow$~~ \rightarrow amplifier
 → constant gain

- ① Gain is constant
- ② Caud would very easily
- ③ over gain is also high.
- ④ no property block noise comp.

Crystal oscillators :-

quartz crystal

Crystal oscillators:-

- ①. The crystal oscillator uses a piezo electric crystal as a tank circuit. The crystal usually, made of quartz or material and provides a high degree of quality, frequency, cry stability and accuracy.

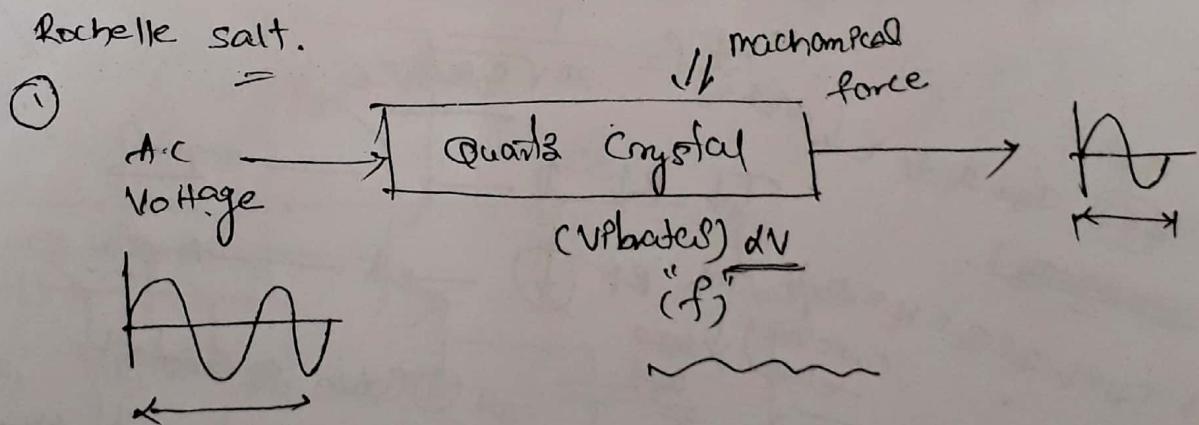
Theradore Crystal oscillators are useful in those applications, where the frequency stability is very essential.

The crystal oscillators are widely used as digital watches and clocks.

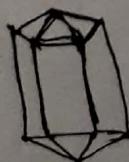
A quartz crystal has a very peculiar property known as the Piezo electric effect. According to this effect, when an A.C voltage is applied across the quartz crystal, it vibrates at the frequency of applied voltage. Conversely, if a mechanical force is applied to vibrate a quartz crystal it generates an A.C voltage.

The other materials, which exhibit the piezo-electric effect?

Rochelle salt.

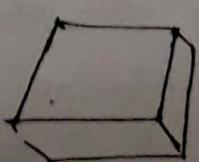


The natural shape of a quartz crystal is a hexagonal prism with pyramids at the ends of ~~the~~ prism.

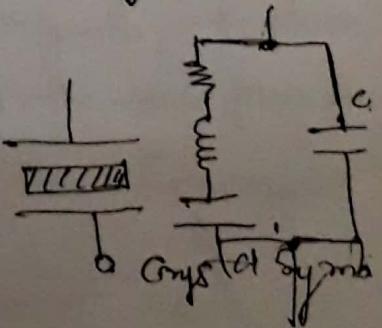


A geometric diagram showing a truncated octahedron, which is a polyhedron with 14 faces: 8 regular hexagonal faces and 6 square faces. It is drawn as a wireframe with vertices at the centers of the faces.

natural shape to
anything



Rectangular Slab



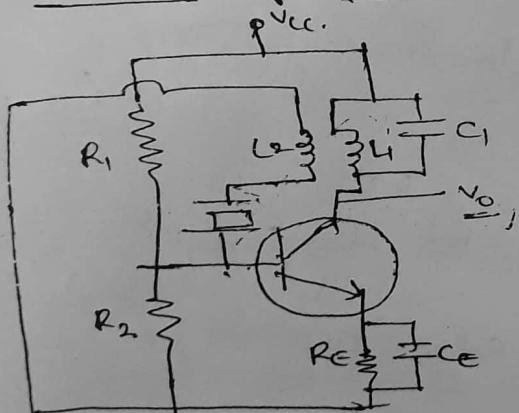
When it is vibrating, there are internal frictional losses which are denoted by a resistance R , while the mass of the crystal, which is vibration of its line of motion represented by an inductance L . In vibrating condition, it is having some stiffness, which is represented by a capacitance C . The mounting capacitance is a shunt capacitance.

It forms a resonating circuit. The expression for the resonance frequency is:

$$f_r = \frac{1}{2\pi\sqrt{LC}} \sqrt{\frac{Qr}{1+Qr}} \rightarrow Q = \frac{WL}{R}$$

The Crystal frequency is inversely proportional to the thickness of the crystal. $\propto \frac{1}{t}$.

Circuit of crystal oscillator



Show the circuit of a transistor crystal oscillator. A tank circuit $L_1 C_1$ is placed in the collector and crystal is connected in the base circuit. Feedback is obtained by coil L_2 which is coupled to coil L_1 . The crystal is connected in series with feedback wind. The natural frequency of L_C circuit is made nearly equal to the natural frequency of crystal.

Circuit operation

When the power is turned on, capacitor C_1 charges. When this capacitor discharged, it sets up oscillations. The voltage across the L_1 is fed to coil L_2 due to mutual induction. The positive feedback produced caused the oscillator to produce oscillations. The frequency of oscillations in the circuit is controlled by the crystal. It is because of the crystal is connected

In the base circuit and hence its influence on the frequency. In the circuit ω is much more than the Lc circuit. Consequently it vibrates at the natural frequency of the crystal.

As the frequency of crystal is independent of temperature & therefore, the circuit generates at a constant frequency.

Advantages

- ① High ^{order} quality of frequency stability
- ② Q is very high. \rightarrow

Disadvantages:

- ① low power circuits.

Advantages of phase shift oscillator and Disadvantages

Advantages-

1. It does not require transistors and indicators.

2. Frequency stability

3. It can produce the good low frequency signals.

Disadvantages-

1. low output power.

2. It is very difficult to start frequency in oscillator.

Advantages and Disadvantages of Wien Bridge oscillator

Advantages

1. It easy to generate the oscillations.

2. Constant output, gain is more.

3. Frequency can also easily change by means of capacitor.

Disadvantages

1. The circuit designing is complex thing.

65, 98, 100, 103, 108, 109, 110, 111, 118 very slab.

2. Frequency range is very slab.