

Multimodal classification of birds

Seed-grant proposal

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School of Computing and Electrical Engineering



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- The objective
- The acoustics
- The image/video
- The machine learning
- The budget and other details



Figure: Slaty-headed parakeet. Pic by PPJ.

- Develop algorithms for automatic analysis of avian biodiversity
- Combine information from acoustic and visual data streams
- Sensors: microphones, cameras
- Apply signal processing and machine-learning techniques to collected data
- Tasks: Species identification, species detection

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- Avian diversity: good indicator of ecosystem health in a local area
- Automatic and semi-automatic sensing devices can be utilized
- Large volume of data captured by these devices
- Algorithms to analyse this data would be useful to ecologists
- Our campus location in the lower Himalays: sensitive ecosystem
- Proposed system can be used for long-term ecological monitoring

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The challenges

- Challenges at various levels
- Acoustics:
 - Complex acoustic environment where recordings are made
 - Overlapping vocalizations, intra-species call variability
 - Background sounds (other animals, human-made sounds, river etc.)
- Image/video:
 - Complex visual environment, visual background clutter
 - Overlapping inter-class visual appearances, local variations
 - Intra-class variations: robustness to changes in pose, motion, light conditions.
- Machine-learning:
 - Fixed-length representations and varying-length representations
 - Dynamic kernels for bird data from different modalities
 - Fusion of modalities
 - Combining the representations from acoustic and image/video sources
 - Combining the decisions from the classifiers for the representations from acoustic and image/video sources
 - Bird indexing and retrieval

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 - ▶ Fusion of modalities
 - ▶ Learning the representation space across the modalities and across the classes
 - ▶ Learning the domain adaptation model for the cross-modal classification
 - ▶ Cross-modal retrieval
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- Processing of human speech: techniques can be adapted for birdcalls
- Production mechanisms are different, but have similarities (eg. formant structure)
- Existing techniques include:
 - ▶ spectral representations ¹,
 - ▶ Mel frequency cepstra ²,
 - ▶ hidden Markov models ³,
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- A recording can be represented as a fixed-length vector x
- Can be used for various applications, for eg. removing background sounds before classification:
 - ▶ Project x into a subspace of background sounds, and remove this component from x
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- Detection, segmentation and tracking of birds (relatively unexplored): adapting general object detection, segmentation and tracking methods
- Learning visual guidance: inverse problem to classification
 \Rightarrow Given the classes, find the discriminative features
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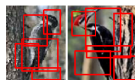
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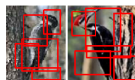
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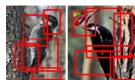
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- ▶ B. Yao et. al., “A codebook-free and annotation-free approach for fine-grained image categorization”, CVPR 2012.
- ▶ L. Xie et. al., “Hierarchical part matching for fine-grained visual categorization”, ICCV 2013.



- Visual guidance: T. Berg and P. Belhumeur, “How do you tell a blackbird from a crow?”, ICCV 2013.
- Detection: D. Song and Y. Xu, “A monocular vision-based low false negative filter for assisting the search for rare bird species using a probable observation data set-based EKF method”, IEEE Trans. Image Processing, 2010.

The visual: existing work

- Fine-grained classification

- ▶ P. Welinder et. al., “Caltech-UCSD Birds 200”, CNS-TR-2010-001. 2010.
- ▶ T. Berg and P. Belhumeur, “POOF: Part-based one-vs-one features for fine-grained categorization, face verification, and attribute estimation”, CVPR 2013.
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- Features and frameworks:
 - ▶ Patch-based features
 - ▶ Body-part features: appearance and geometric relationships
 - ▶ Feature learning: deep neural networks, discriminative features
- Frameworks:
 - ▶ Sparse representation
 - ▶ Markov random fields
 - ▶ Hierarchical classification
- Systems:
 - ▶ Dataset collection
 - ▶ Audio-video systems for monitoring
 - ▶ On-board algorithms: detection, tracking

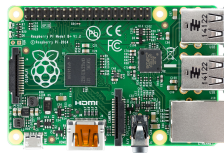
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Example on-field system components

- Data acquisition (audio): rugged, field-deployable recorders
e.g. Song Meter SM3 recorder from Wildlife Acoustics Inc, USA.
- Data acquisition (video): Network cameras
e.g. Panasonic WV-SP302
- Processing: Raspberry Pi, Beagle Bone



The machine learning: tasks

- Bird call identification using fixed-length and varying-length acoustic features
- Bird classification from images and videos
- Bird call indexing and retrieval
- Bird image and video indexing and retrieval
- Combining different modalities for classification, indexing and retrieval tasks

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The machine learning: bird classification

- Classification of birds using SVMs from bird calls and bird images & videos
- The representations for bird call are either fixed-length representation or varying-length representation
- Varying-length representation are either sets of local feature vectors or sequences of local feature vectors
- Dynamic kernel based SVMs for varying-length representation

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- Some of the dynamic kernels are:
 - ▶ GMM-based intermediate matching kernel ⁵,
 - ▶ HMM-based intermediate matching kernel ⁶,
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 - ▶ Spatial pyramid match kernel ⁸

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- Matching and retrieval of birds using bird calls and bird images & videos
 - ▶ Query-by-example (QBE) based retrieval⁹
 - ▶ Query-by-semantics (QBS) based retrieval¹⁰
 - ▶ Query-by-semantic example (QBSE) based retrieval¹¹
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The machine learning: multimodal classification and retrieval

- Classification and retrieval of birds by combining the cues from bird calls and bird images & videos
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 - ▶ Late fusion: Combining the decisions from the different classifiers built for bird calls, bird images and bird videos
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Table: Projected expenses in lakhs INR.

Items	Year 1	Year 2	Year 3	Total
High-end computers (2)	3.0	3.0	0	6.0
Imaging and audio equipment	5.0	3.0	0	8.0
Desktop computers (6)	5.0	0	0	5.0
Contingency	0.5	0.5	1.0	2.0
Travel	0.5	0.5	1.0	2.0
Overall	15.0	8.0	2.0	23.0

- **Proposal to SERB:**

- ▶ *Automatic analysis of avian acoustics.*
- ▶ In collaboration with IIT Madras, NCBS and CDAC.
- ▶ Value: Rs 50 lakhs.
- ▶ **Ready for submission.**

- **Proposal planned:** Camera and acoustic sensor networks for a local area (IIT Mandi campus)

Thank you for your attention.

Table: Equipment budget in thousands INR.

Item	Unit cost	Qty.	Total
Bioacoustic recorder	50	6	300
Network camera	30	5	150
Recorder accessories	15	8	120
DSLR camera and lens	100	1	100
Consumables	50	1	50
Processing hardware	8	5	40
Network access points	3	5	15
Total			775