Pixel space convolution using sparse matrices

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No abstract for now.

1 Objective

Propose a novel way of calculating full-sky convolution of a polarized sky with antenna beams in pixel space.

Note

This section uses the same notation as the paper that describes PISCO.

2 Beams of a Polarization Sensitive Bolometer

A Polarization Sensitive Bolometer (PSB) is a detection device that uses a pair of bolometers to sense both the total intensity (Stokes parameter I) and the degree of linear polarization in incoming light (Stokes parameter Q and U). Denoting each bolometer of the PSB as a and b we can write b

 $^{^{1}\}mathrm{cite}$ Rossett et al and link the calculations that show this formulation is equivalent to O'Dea et al.

$$\tilde{I}_a = |\vec{E}_a|^2 \tag{1}$$

$$\tilde{I}_b = |\vec{E}_b|^2 \tag{2}$$

$$\tilde{Q}_a = |\vec{E}_{a||}|^2 - |\vec{E}_{a\times}|^2$$
 (3)

$$\tilde{Q}_b = |\vec{E}_{b\parallel}|^2 - |\vec{E}_{b\times}|^2$$
 (4)

$$\tilde{U}_a = 2\Re \left(\vec{E}_{a\parallel} \vec{E}_{a\times} \right) \tag{5}$$

$$\tilde{U}_b = 2\Re\left(\vec{E}_{b\parallel}\vec{E}_{b\times}\right) \tag{6}$$

$$\tilde{V}_a = -2\Im\left(\vec{E}_{a\parallel}\vec{E}_{a\times}\right) \tag{7}$$

$$\tilde{V}_b = -2\Im\left(\vec{E}_{b\parallel}\vec{E}_{b\times}\right) , \qquad (8)$$

where \vec{E} denotes the time-averaged electric field density at co-latitude ρ and longitude σ (see 1). Subscript \parallel is used to denote the co-polarized field, while \times is used for the cross-polarized field.

Maybe add a note about polarization efficiency

3 Sky model

The sky can be modeled as a set of 4 scalar fields

$$S^{i} = S^{i}(\theta, \phi) = (I, Q, U, V) \quad , \tag{9}$$

where I, Q, U and V are Stokes parameters² of light coming from co-latitude θ and longitude ϕ in the sky basis.

4 Coupling of sky and PSB beams in pixel space

Note that if the PSB beams and sky are considered discrete quantities, then each pixel k will have an associated pair of coordinates in its corresponding basis. In pixel space, the power (per unit-wavelength) measured by a PSB pointing at \bar{q}_0 becomes

$$d_{\alpha} = \sum_{k=1}^{N_s} {}_k D_{\alpha,i}(\chi, \epsilon, s_{\alpha}) {}_k S^i \quad , \tag{10}$$

where α denotes a and b.

²Note about definition of polarization

The quantity D for detector a is

$$D_{a,i}(\chi,\epsilon,s_a) = \frac{s_a}{2} \Big[\tilde{I}_a + \epsilon \tilde{I}_b,$$

$$\left(\tilde{Q}_a - \epsilon \tilde{Q}_b \right) \cos(2\chi) - \left(\tilde{U}_a - \epsilon \tilde{U}_b \right) \sin(2\chi),$$

$$\left(\tilde{U}_a - \epsilon \tilde{U}_b \right) \cos(2\chi) + \left(\tilde{Q}_a - \epsilon \tilde{Q}_b \right) \sin(2\chi),$$

$$0 \Big] ,$$

$$(11)$$

and the quantity D for detector b

$$D_{b,i}(\chi,\epsilon,s_b) = \frac{s_b}{2} \Big[\tilde{I}_b + \epsilon \tilde{I}_a, \\ -\left(\tilde{Q}_b - \epsilon \tilde{Q}_a\right) \cos(2\chi) + \left(\tilde{U}_b - \epsilon \tilde{U}_a\right) \sin(2\chi), \\ -\left(\tilde{U}_b - \epsilon \tilde{U}_a\right) \cos(2\chi) - \left(\tilde{Q}_b - \epsilon \tilde{Q}_a\right) \sin(2\chi), \\ 0 \Big] ,$$

$$(12)$$

5 Computation of D

In practice, discrete quantities such as sky and PSB beams are represented as vectors. Note that the definition of D is implicitly assuming that the PSB beam is aligned with the sky: more precisely, that pixel k of the beam corresponds to pixel k of the sky. In this sense D hides a rotation of the PSB beams from the beam basis to the sky basis.

Calculating the rotated PSB beam can be represented as a matrix-vector product. For each component (i) of the beam, its rotated counterpart becomes

$$\tilde{X}' = \mathbf{R}\tilde{X}^T \quad , \tag{13}$$

where **R** is an $N_s \times N_b$ sparse matrix with exactly 4 non-zero entries per row³.

In some way, every row of **R** represents the dot-product of 4 pixels from the PSB beam component (North, South, East and West pixels around \bar{q}_0) and their interpolation weights. Denoting S, N, E and W (all integers from 0 to N_b) to neighbor pixels and z_N, z_S, z_E and z_W to the interpolating weights

$$_{k}\tilde{X}' = {}_{k}\mathbf{R}\tilde{X}^{T} = \left[0\cdots z_{N}\cdots z_{S}\cdots z_{E}\cdots z_{W}\cdots 0\right]\cdot\tilde{X}^{T}$$
 (14)

³For bi-linear interpolation

6 Remarks of algorithm

- Formalism is designed for full-sky convolution.
- \bullet Every row of ${f R}$ can be calculated in parallel using already existing libraries (like HEALPix)
- \bullet Matrix ${\bf R}$ is very sparse, and can be represented efficiently using compression techniques (like CSR)
- The (sparse) matrix-vector product can be calculated in accelerators, like a GPU, using existing libraries for Sparse Linear Algebra (like cuSparse from NVIDIA).

References

http://www.xkcd.com/242/