

Homework 1 - Thomas Boyko - 30191728

1. (5 points) Define $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$f(x, y) \begin{cases} 0 & (x, y) = (0, 0) \\ \frac{xy^2}{x^2+y^2} & (x, y) \neq (0, 0) \end{cases}.$$

(a) (1 point) Compute the partial derivatives for f at $(0, 0)$.

Use the definition for directional derivatives:

$$\begin{aligned} f_x(x, y) = D_{e_1} f(0, 0) &= \lim_{t \rightarrow 0} \frac{f(t, 0) - f(0, 0)}{t} \\ &= \lim_{t \rightarrow 0} \frac{\frac{0}{t^2} - 0}{t} \\ &= \lim_{t \rightarrow 0} \frac{0}{t} = 0 \end{aligned}$$

And for f_y :

$$\begin{aligned} f_y(x, y) = D_{e_2} f(0, 0) &= \lim_{t \rightarrow 0} \frac{f(0, t) - f(0, 0)}{t} \\ &= \lim_{t \rightarrow 0} \frac{\frac{0}{t^2} - 0}{t} \\ &= 0 \end{aligned}$$

So we see that $f_x(x, y) = f_y(x, y) = 0$.

Note for later that $Df(0, 0) = \begin{bmatrix} 0 & 0 \end{bmatrix}$

(b) (2 point) Determine which directional derivatives exist for f at $(0, 0)$ and compute their value.

Let $\vec{v} = \begin{bmatrix} v_1 & v_2 \end{bmatrix}$, $\vec{v} \in \mathbb{R}^2$ with $\|\vec{v}\| = 1$. Note that $\sqrt{v_1^2 + v_2^2} = 1$ and $v_1^2 + v_2^2 = 1$.

Then the directional derivatives at $(0, 0)$ will exist when the following limit exists.

$$\begin{aligned} D_{\vec{v}} f(x, y) &= \lim_{t \rightarrow 0} \frac{f(v_1 t, v_2 t) - f(0, 0)}{t} \\ &= \lim_{t \rightarrow 0} \frac{\frac{v_1 v_2^2 t^3}{t^2(v_1^2 + v_2^2)} - 0}{t} \\ &= \lim_{t \rightarrow 0} \frac{v_1 v_2^2 t}{t} \\ &= v_1 v_2^2 \end{aligned}$$

So the directional derivative exists for any value of \vec{v} .

(c) (2 points) Is f differentiable at $(0, 0)$? Why or why not?

In order for f to be differentiable at $(0, 0)$, the following limit must be 0, at any path to the origin.

$$\begin{aligned} \lim_{(x, y) \rightarrow (0, 0)} \frac{f(x, y) - f(0, 0) - \begin{bmatrix} 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}}{\sqrt{x^2 + y^2}} &= \lim_{(x, y) \rightarrow (0, 0)} \frac{\frac{xy^2}{x^2 + y^2}}{(x^2 + y^2)^{\frac{1}{2}}} \\ &= \lim_{(x, y) \rightarrow (0, 0)} \frac{xy^2}{(x^2 + y^2)^{\frac{3}{2}}} \end{aligned}$$

Choose the path to the origin where $x = y$ and $x \rightarrow 0^+$.

$$\begin{aligned}\lim_{x \rightarrow 0^+} \frac{x^3}{(2x^2)^{\frac{3}{2}}} &= \lim_{x \rightarrow 0^+} \frac{x^3}{2x^3} \\ &= \frac{1}{2}\end{aligned}$$

Since this limit does not equal 0 for our curve near the origin, the function f is not differentiable at $(0, 0)$.

2. (4 points) Define $f(x, y, z) = e^{x^2+yz}$.

(a) (1 point) Compute the gradient for f at the point $(1, 1, -1)$.

$$\begin{aligned}\nabla f(x, y, z) &= \begin{pmatrix} f_x \\ f_y \\ f_z \end{pmatrix} = \begin{pmatrix} 2xe^{x^2+yz} \\ ze^{x^2+yz} \\ ye^{x^2+yz} \end{pmatrix} \\ \nabla f(1, 1, -1) &= \begin{pmatrix} 2e^0 \\ -e^0 \\ 1e^0 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix}\end{aligned}$$

(b) (1 point) Determine the maximal rate of ascent for f at $(1, 1, -1)$. In which direction does this occur?

The maximal rate of ascent will be given by $\|\nabla f(1, 1, -1)\|$.

$$\|\nabla f(1, 1, -1)\| = \sqrt{2^2 + 1^2 + (-1)^2} = \sqrt{6}$$

The direction in which this occurs will be given by:

$$\frac{\nabla f}{\|\nabla f\|} = \frac{1}{\sqrt{6}} \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix}$$

(c) (1 point) Compute the tangent plane for f at $(1, 1, -1)$.

$$\begin{aligned}\vec{L}(1, 1, -1) &= f(1, 1, -1) + \begin{pmatrix} 2 & -1 & 1 \end{pmatrix} \begin{pmatrix} x-1 \\ y-1 \\ z+1 \end{pmatrix} \\ &= 1 + (2x-2) + (1-y) + z + 1 \\ \vec{L}(1, 1, -1) &= 2x - y + z + 1\end{aligned}$$

(d) (1 point) Estimate the value $f(0.9, 1.1, -0.8)$ using part (c)

$$f(0.9, 1.1, -0.8) \approx 2(0.9) - 1.1 - 0.8 + 1 = 0.9$$

3. (6 points) Define the function $\vec{f}(x, y) = (xy, x^2 + y^2)^T$ on \mathbb{R}^2 .

(a) (3 point) Determine on which set of points in \mathbb{R}^2 the hypotheses of the inverse function theorem is satisfied.

Begin by finding $D\vec{f}(x, y)$.

$$D\vec{f}(x, y) = \begin{bmatrix} y & x \\ 2x & 2y \end{bmatrix}$$

This matrix is invertible whenever $\det(D\vec{f}(x, y)) \neq 0$.

$$\det(D\vec{f}(x, y)) = 2y^2 - 2x^2$$

So $2y^2 - 2x^2 \neq 0$.

So \vec{f} has a local inverse wherever $y \neq \pm x$

- (b) Apply the inverse function theorem to f at the point $(2, 1)$ and use it to find $D\vec{g}(2, 5)$ where g is a local inverse for f at the point $(2, 1)$.

From above, $D\vec{f}(2, 1) = \begin{bmatrix} 1 & 2 \\ 4 & 2 \end{bmatrix}$, and $\det(D\vec{f}(2, 1)) = 2 - 8 = -6$.

So $D\vec{f}^{-1}(2, 1) = D\vec{g}(2, 5) = -\frac{1}{6} \begin{bmatrix} 2 & 2 \\ -4 & 1 \end{bmatrix}$

4. Consider the equations

$$\begin{aligned} x^2 + y + 3z + u + v + 4 &= 0 \\ xy^2 - z + u - v + 3 &= 0 \end{aligned}$$

around the point $(x, y, z, u, v) = (1, 0, -1, -3, 1)$. Let $\vec{F}(x, y, z, u, v) = (x^2 + y + 3z + u + v + 4, xy^2 - z + u - v + 3)^T$. Use the implicit function theorem to show that there is a function $\vec{g}: U \rightarrow \mathbb{R}^2$ where U is an open set containing $(x, z, v) = (1, -1, 1)$, so that $g_1(x, z, v) = y, g_2(x, z, v) = u$ and $\vec{F}(x, g_1(x, z, v), z, g_2(x, z, v), v) = (3, 2)^T$. Find $D\vec{g}(1, 2, 1)$

First we must find $D\vec{F}_{(1,0,-1,-3,1)} = \begin{pmatrix} 2x & 1 & 3 & 1 & 1 \\ y^2 & 2xy & -1 & 1 & -1 \end{pmatrix}_{(1,0,-1,-3,1)}$

Evaluating at our chosen point we get $D\vec{F}_{(1,0,-1,-3,1)} = \begin{pmatrix} 2 & 1 & 3 & 1 & 1 \\ 0 & 0 & -1 & 1 & -1 \end{pmatrix}$.

If an implicit function exists then the matrix $B = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ will be invertible. Clearly this matrix is invertible since it is upper triangular and $\det B = 1$ which is the product of the main diagonal. And the inverse of B is the matrix $B^{-1} = \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix}$.

So now we can take the remaining columns of our large matrix and create the matrix $A = \begin{pmatrix} 2 & 3 & 1 \\ 0 & -1 & -1 \end{pmatrix}$. Finally we can compute the product

$$-B^{-1}A = -\begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 2 & 3 & 1 \\ 0 & -1 & -1 \end{pmatrix} = \begin{pmatrix} -2 & -4 & -2 \\ 0 & 1 & 1 \end{pmatrix}$$

And by the implicit function theorem, $D\vec{g}(1, 2, 1) = \begin{pmatrix} -2 & -4 & -2 \\ 0 & 1 & 1 \end{pmatrix}$.