

School of Computer Science and Engineering

Winter Semester 2023-24 Continuous Assessment Test – I

SLOT: B2+TB2

Programme Name & Branch: B.Tech & SCOPE

Course Name & Code: Artificial Intelligence & BCSE306L

Class Number (s): Common to all batches

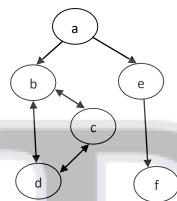
Faculty Name (s): All

Exam Duration: 90 Min. Maximum Marks: 50

Q. No.	Question			$\overline{}$	لللالالا	Max Marks	СО	BL
1.	Design PEAS for the following artificial intelligent agents. i) Taxi driver agent ii) Automated robot in a manufacturing plant. iii) Playing soccer iv) Bidding an item on an auction v) Shopping for used AI books on the Internet				10	CO1	BL2	
Ans wer	Agent	Performance measure	Environment	Actuators	Sensors			
	Playing soccer	Scoring goals, defending, winning, injuries and teamwork	Soccer playground, Players, ball, goals, referee	Player`s legs, head and hands	Camera, orientation sensor, players locator		>	
	Shopping for used AI books on the Internet	Price, authors, book review, interested books, cost minimization	Websites, vendors, shippers	Keyboard, mouse (hands	Camera, price monitor			
	Bidding an item on auction	The winning bid amount	Auctioneer Bidders BiddersItems which are to be bid	Speakers Microphon es Display items Budget	Camera Price monitor, where prices are being displayed.	\		
	Taxi driver agent	Safe Fast Legal	Roads, Traffic, Pedestrians	Steering, Accelerator , Brake,	Cameras, Sonar, Speedometer,			

	Automated robot in a manufacturing	Comfortable trip Maximize profits Percentage of parts correctly manufactured	Conveyor	signal, horn, Jointed arm	GPS, odometer, engine sensors, keyboard Camera, joint angle sensors			
	plant.			hand				
2.	Consider the project developed by Google, codenamed Waymo. Waymo has successfully deployed self-driving cars with advanced sensors and implemented AI-based model algorithms in their decision-making process. These autonomous vehicles navigate the roads, making decisions based on percept history and real-time sensory input — the ability to make informed decisions based on historical data and real-time perceptual input received from the environments. Identify the most suitable model and explain how it fits this scenario where a decision has been made based on the perception of events that happened.				10	CO1	BL3	
Ans wer	A Learning based Agent model may be used and justification for model needed. Architecture -4 marks)			
	To make the overall design more concrete, let us return to the automated taxi example. The performance element consists of whatever collection of knowledge and procedures the taxi has for selecting its driving actions. The taxi goes out on the road and drives, using this performance element. The critic observes the world and passes information along to the learning element. Forexample, afterthe taximakes aquick lefturn across three lanes oftraffic, the critic observes the shocking language used by other drivers. From this experience, the learning element is able to formulate a rule saying this was a bad action, and the performance element is modified by installation of the new rule. The problem generator might identify certain areas of behavior in need of improvement and suggest experiments, such as trying out the brakes on different road surfaces under different conditions. Not Model based agent and others:					3		
	model-based agent literal sense. For ex- telling it to fill up v "driving back hom destination is actual	is that it does not lead to lead that it does not lead that it doe	y be driving bac home unless it aspect of the wo agent's internal	k home, and it has at least hal orld state, the fall state. If you f	t may have a rule If a tank. Although act of the taxi's ind this puzzling,			

BL3



Which sequences of paths are explored by BFS and DFS in this problem? Show the complete intermediate state space for DFS and BFS with a neat sketch. Would you prefer DFS or BFS for this problem? Justify?

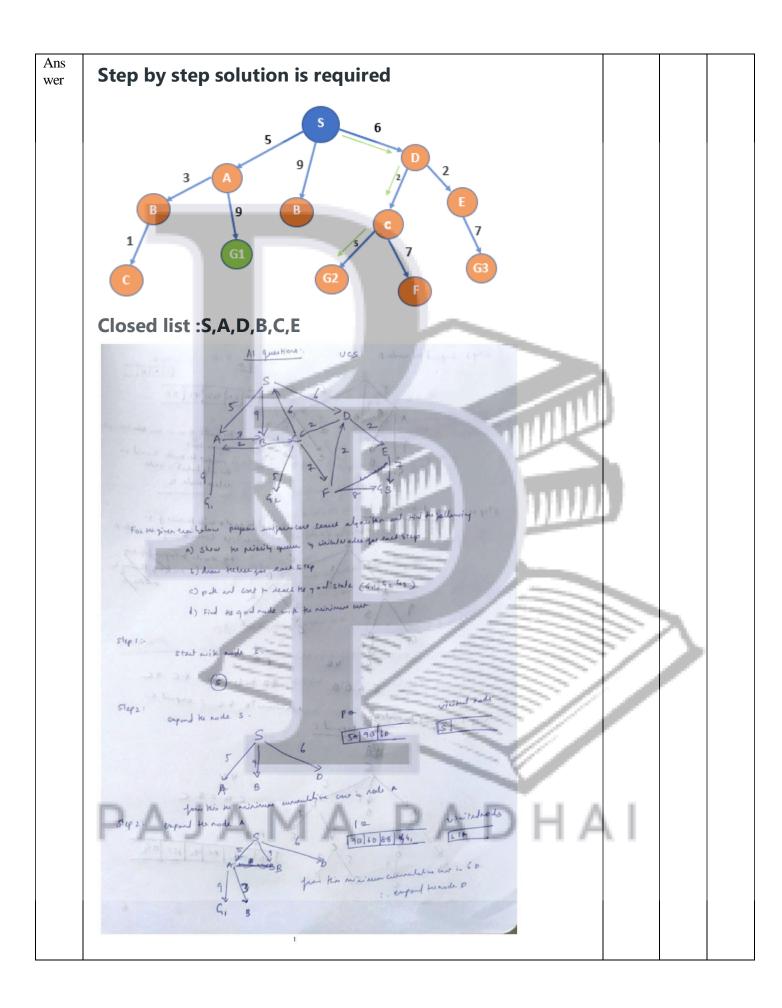
Note: Nodes are revisited as per the direction mentioned.

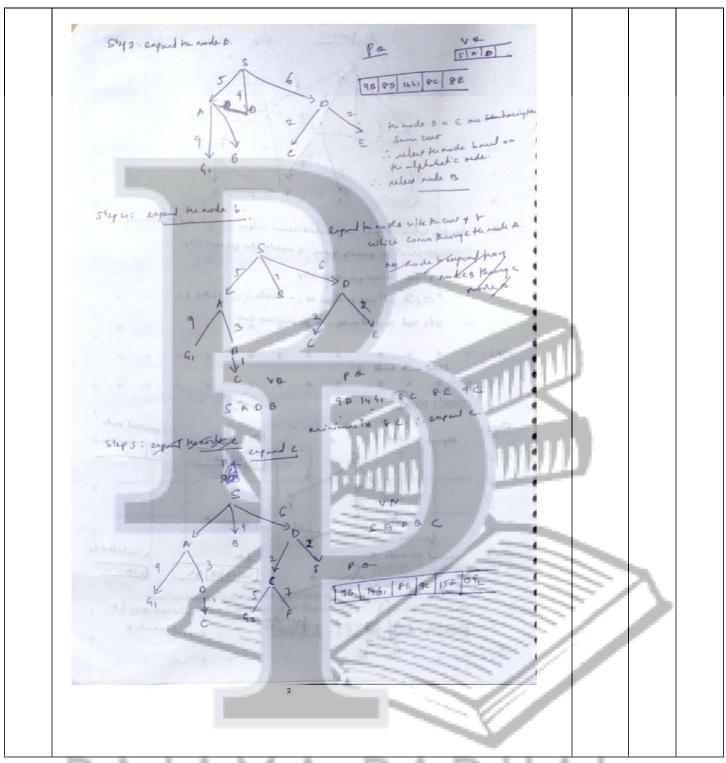
If we were just running vanilla DFS(nopruningor loopchecking) then we would prefer BFS, because DFS could get stuck in an **infiniteloop**. Note that DFS is sensitive to the ordering of the nodes. If it explores to the left first it will get stuck in the loop, whereas if it explores to the right first it will find the goal very quickly.

DFS explores a-->b-->d-->b BFS first adds a-->b and a-->e to the frontier.

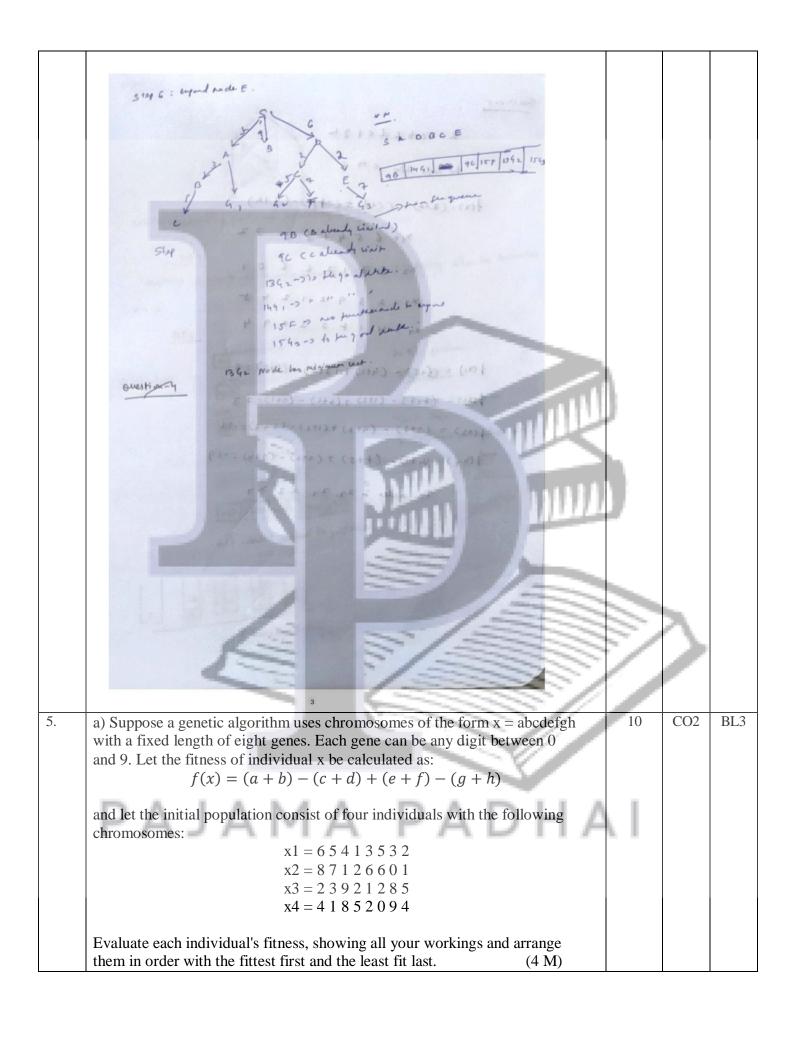
It expands ab and adds abd and abc to the frontier. Path ae is then expanded, adding aef to the frontier. Path abd is selected and removed from the frontier, and expanded so that abdb and abdc are added to the frontier. Path abc is selected and expanded, adding abcb and abcd to the frontier.

Ans	255					
wer	explains a - b -> d -> b -> d meens oscillating blow the two miles					
	explans a -> 6 -> a -> 6 -> a					
	bg d.					
	BFS_					
	for this public					
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	ode aet abdbabde					
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	aet abd abd abd abcb					
	act whether the god mode					
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	b de de					
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4.	For the given directed graph (start node is S), perform the Uniform Cost 10 CO2 BL3					
4.	1 of the grant discount from the control of the con					
	Search (UCS). Expand the node based on the alphabetic order if the nodes have the same cumulative cost.					
	1. Show the priority queue and visited nodes for each step (4M)					
	2. Draw the tree for each step 3. Path and cost to reach the goal states (G1, G2, G3) 4. Find the goal node which has the minimum cost. (4M) (3M) (2M)					
	I mo mo gom no mo mammum cosm					
	6					
	5					
	5 D 2					
	9 2					
	A 3 1 (E)					
	(B) (C)					
	7 2					
	2					
	9 4 4 4 5					
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	8					
	$\left(\begin{array}{c}G1\end{array}\right) \left(\begin{array}{c}G2\end{array}\right)$					





PAJAMA PADHAI



b) With a neat sketch of the hill-climbing algorithm's state-space landscape, explain why the hill-climbing search gets struck. List the variants of the hill climbing algorithm and describe how they overcome this problem. (6 M) Ans wer Questions: f(2) = (2+6) - (c+d) + (e +(21) = (6+5) - (4+1) + (3+5) - (3

