School of Computer Winter Semester 2023-24 Continuous Assessment Test



Science and Engineering

- I - KEY

SLOT: B1+TB1

Programme Name & Branch: B.Tech. & Computer Science & Engineering / SCOPE

Course Name & Code: Artificial Intelligence & BCSE306L

Class Number (s): Common for all batches

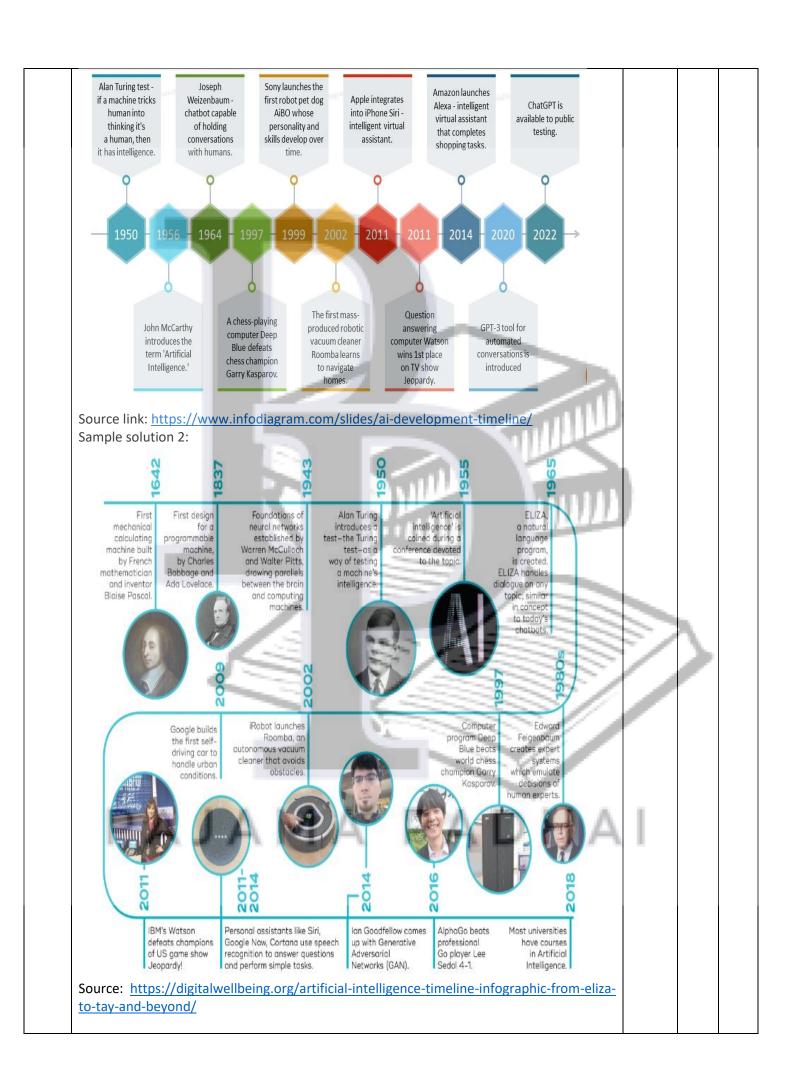
Exam Duration: 90 Min.

Faculty Name (s): All

Maximum Marks: 5*10 = 50

Q. **Question** (Answer all questions) Max CO BL No. Mark a) Describe different approaches to Artificial Intelligence. List the timeline of the evolution 10 1. CO BLof artificial intelligence and briefly describe each period/breakthrough. 3 1 b) Consider an artificial agent learning to play chess, where the agent learns the game's rules and optimal moves through multiple plays and feedback from critics. Which type of agent would be most suitable for a chess-playing agent? Justify your answer. Also, briefly describe the agent architecture with a suitable diagram. [5 M] a) Following are the four different approaches to Artificial Intelligence [2 Marks] Ans 1 Mark for naming four approaches + 1 Mark for brief explanation of each wer category. Thinking Rationally Thinking Humanly The law of thought The cognitive modeling approach approach Four Main Approaches to Artificial Intelligence **Acting Humanly** Acting Rationally The rational agent The Turing Test approach approach Timeline of the evolution of artificial intelligence [3 Marks] **Sample Solution 1:**

PAJAMA PADHAI

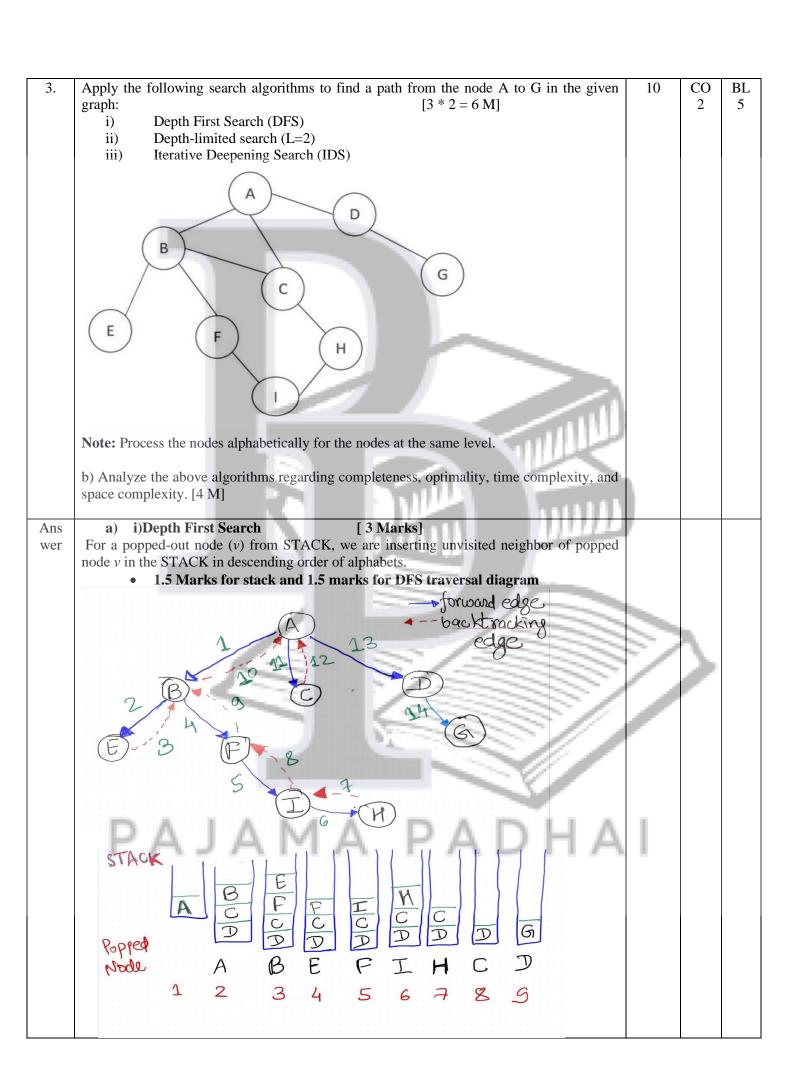


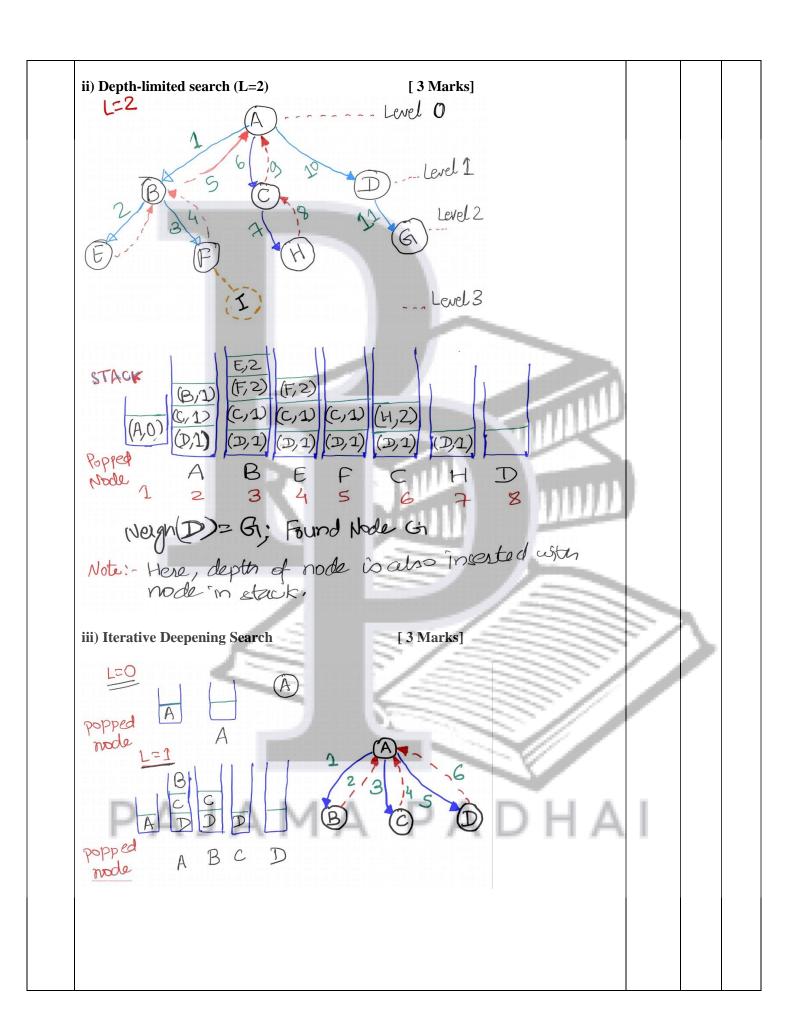
Othe similar timeline: https://www.linkedin.com/pulse/artificial-intelligence-timeline-2021-drmansoor-agha-siddiqui/ https://qbi.uq.edu.au/brain/intelligent-machines/history-artificial-intelligence https://digitalwellbeing.org/artificial-intelligence-timeline-infographic-from-elizato-tay-and-beyond/ b) Learning based Agent is most suitable as the agent is game's rules and optimal moves through multiple plays and feedback from critics. [2 Marks] Architecture of Learning based Agent [2 Marks] Performance standard Critic feedback changes Learning Performance knowledge learning goals Problem generator Agent Following are the major components of Leanring based Agent: [1 Marks] **Learning element** is responsible for making improvements. i. **Performance element** is responsible for selecting external actions. ii. iii. Critic provides feedback on how the agent is doing and determines how the performance element should be modified to do better in the future. **Problem generator** is responsible for suggesting iv. actions that will lead to new and informative experiences. Note: Partial marks may be provided for giving other agent types and its architecture diagram based on justification provided by student. Describe the task environments and their characteristics for the following agents. 2. CO BL. 10 i. Rental Bike/Car booking 4 ii. Cooking Robot iii. Grocery Delivery iv. Playing Chess The characteristics of task environment are as follows: [4*2.5 = 10 M]Ans Task Observable Agent **Deterministic Episodic** Static Discrete wer Environment Dyna i) Rental Partially Multi Non-Episodic Continu mic Bike/Car Deterministic ous booking Deterministic ii) Cooking Fully Single Sequential Static Discrete Robot iii) Grocery **Partially** Multi Non-**Episodic** Dyna Discrete Delivery Deterministic mic Multi iv) Playing Fully Non-Sequential static Discrete

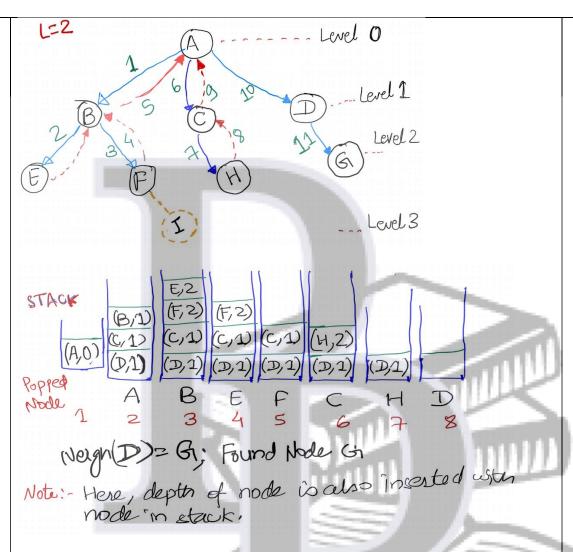
Deterministic

Chess

Observable







b) Anlaysis of Algorithm

Algorithm	Completenes	Optimality	Time	Space Complexity
Name		.77	Complexity	
Depth First	No	No	O(bm)	O(bm)
Search (DFS)				
Depth Limited	No	No	$O(b^l)$	O(bl)
DFS				
Iterative	Yes	Yes	O(bd) when	O(bd) when there is
Deepening			' '	solution
DFS			solution	O(bm) when there is
			O(bm) when	no solution
Ph A	1 4	h // A	there is no	PS II A
$P \Delta$		Δ	solution	Γ Γ Γ Γ Γ

where

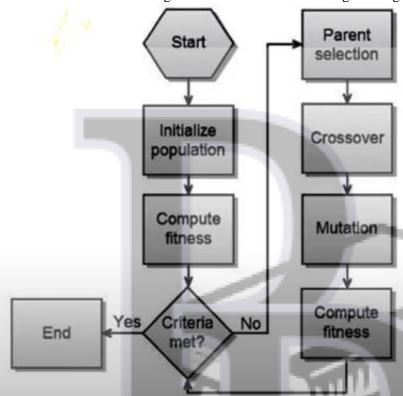
b is branching factor

m is the maximum depth of tree

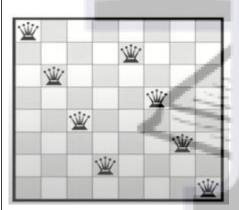
d is the depth where the goal node v is found.

4.	Appl	y A* S	earch algo	rithm to fir	nd the shortes	st path from	a to z using	the fo	llowir	ng graph:	10	СО	BL
			9	b 11	_							2	5
		a	1	/27	e 5								
		21	4	17		Z							
		7	18	12	f 9								
			d	14	8								
	The	hauricti	18	r each nod	le is given be	low							
	N	ode	a	b	c d	e 5	f 8						
	h	(n)	21	14	18 18	5	8						
								_	d	- (1)			
	Was	:11 4		ouk koood	on the f(n)			~	<u> </u>	עוווו			
ns er	Wh	ere f(n))=g(n)+1		on the f(n) = cost to read	ch node n, l	n(n) = heuri	stic co	st to r	each goal			
	from	node n	1			100	Ш		100		1		
	Nodes Extracted node								,				
	S. N	a	b	c	d	e	f	z	No de	f(n)			
		21	∞	∞	∞	∞	∞	∞	a	0			
		0	0+9+14 = 23	0+4+18 = 22	$\begin{vmatrix} 0+7+18 \\ = 25 \end{vmatrix}$	∞	∞	∞	С	0+4	= 7	1	
		0	23	4	25	4+17+5	4+12+8	000	b	0+9			
		U			4	= 26	= 24			= 9			
		0	9	4	25	9+11+5 = 25	24	∞	f	16			
		0	9	4	25	9+11+5 = 25	16	25	Z	25			
		_							4				
	Henc	re nath	cost from 1	node a->z	is 25 and the	nath is a->c	->f->z.	D	-	ΤA			
5.	Expl quee	ain eac n probl	h step of th	e genetic a	lgorithm with examples. Ca	h correct ter	minology ir				10	CO 2	BI 6
					lgorithm is								
	Darv				tion. In Genet lecimal/hexac	tıc algorıthn lecimal/alpl							
ns er													
	popu indiv	lation o idual i	of individ s w.r.t. to	uals. Furtl target goa	ner, we define ls. Using fith eneration of in	e a fitness f ness function	function to n, we selec	estima t the g	te hov	y good an parents to			

The flowchart of Genetic Algorithm can be illustrated using the diagram given below.



8 - Queen problem: Arrange the 8 queens in 8*8 Chess board such that no queens attach each other (horizontally, vertically, or diagonally).



With respect to solving 8 Queen problems using Genetic algorithm, we will demonstrate following steps:

- i. Define Encoding mechanism: Representing an individual.
- ii. Define Fitness Function: to estimate how good an individual of a population is.
- iii. Initialize a population.
- iv. Calculate the Fitness of all individuals of the population using fitness function.
- v. Selection of parent for generating new child.
- vi. Cross of selected parents
- vii. Mutation of selected parents
- viii. Repeat step (iv) to (vii) until the stopping criteria is met.

