

Problem Formulation

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1 MILP

$$\min_{P_{EV,a,t}} \sum_{T=1}^{T_{end}} \left| \sum_{t=K(T-1)}^{K*T-1} \left(P_{plan}(T) - P_{BRP}(t) \right) \Delta t \right| \quad (1a)$$

$$P_{BRP}(t) = \sum_a P_a(t) \quad (1b)$$

$$P_{EV,a}(t) = P_{EV,chg,a}(t) - P_{EV,dischg,a}(t) \quad (1c)$$

$$= P_{EV,plan,a}(t) + \Delta P_{EV,a}(t) \quad (1d)$$

$$P_a(t) = P_{grid,a}(t) + P_{PV,a}(t) - P_{load,a}(t) - P_{EV,a}(t) \quad (1e)$$

$$P_a(t) = \sum_b P_{ab}(t) \quad (1f)$$

$$P_{a,min} \leq P_a(t) \leq P_{a,max} \quad (1g)$$

$$SoC_a(t) = SoC_a(t-1) + \frac{P_{EV,chg,a}(t)\Delta t}{E_{bat}} \eta_{chg} - \frac{P_{EV,dischg,a}(t)\Delta t}{E_{bat} \eta_{dischg}} \quad (1h)$$

$$SoC_{a,min} \leq SoC_a(t) \leq SoC_{a,max} \quad (1i)$$

$$\rho(t)P_{EV,a,min} \leq P_{EV,chg,a}(t) \leq \rho(t)P_{EV,a,max} \quad (1j)$$

$$(1 - \rho(t))P_{EV,a,min} \leq P_{EV,dischg,a}(t) \leq (1 - \rho(t))P_{EV,a,max} \quad (1k)$$

2 MPC

Lets consider Δ_t , Δ_T , and t_{sim} respectively as the problem's temporal resolution (in minutes), imbalance length and total horizon with

$$\Delta_T = f(\Delta_t) \quad (2a)$$

$$= \underbrace{15}_{mn} // \Delta_t. \quad (2b)$$

Each instant k_{init} of the problem's horizon is indexed as

$$k_{init} \in \{0, \dots, t_{sim}\}, \quad (3)$$

while each imbalance period is indexed as

$$T'' \in \left\{ 0, \dots, \underbrace{T_{end}}_{t_{sim} // \Delta_T} \right\}. \quad (4)$$

At each instant k_{init} , we consider the MPC horizon that spans from k_{init} to $k_{init} + hor$. Each instant of the MPC's horizon can be defined either as

$$k \in \{k_{init}, \dots, k_{init} + hor\}, \quad (5)$$

or

$$t \in \{0 \dots, hor\}, \text{ with } t = k - k_{init} \quad (6)$$

and the imbalance periods covered by the MPC's horizon are given by

$$T \in \left\{ \underbrace{T_{init}^{hor}}_{k_{init} // \Delta_T} \dots, \underbrace{T_{end}^{hor}}_{(k_{init} + hor) // \Delta_T} \right\} \quad (7)$$

where T_{init}^{hor} and T_{end}^{hor} represent the first (initial) and last imbalance period. Figure 1 resumes all the above mention variables.

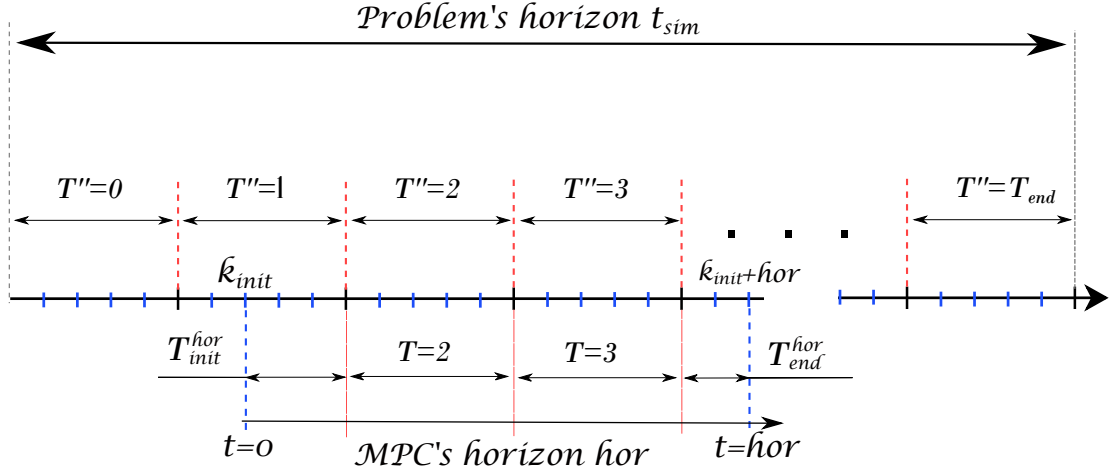


Figure 1: MPC problem variables

2.1 V1G problem formulation

$$\min_{P_{EV,a}(t), SoC_a^{relax}} \left((1 - \alpha)f(P_{EV,a}(t)) + \alpha g(SoC_a^{relax}) \right) \quad (8a)$$

$$\forall t \in \{0, h_{or}\}$$

$$P_{BRP}(t) = \sum_a P_a(t) \quad (8b)$$

$$P_{EV,a}(t) = P_{EV,chg,a}(t) \quad (8c)$$

$$= P_{EV,plan,a}(t) + \Delta P_{EV,a}(t) \quad (8d)$$

$$P_a(t) = P_{grid,a}(t) + P_{PV,a}(t) - P_{load,a}(t) - P_{EV,a}(t) \quad (8e)$$

$$P_a(t) = \sum_b P_{ab}(t) \quad (8f)$$

$$P_{a,min} \leq P_a(t) \leq P_{a,max} \quad (8g)$$

$$SoC_a(t) = SoC_a(t-1) + \frac{P_{EV,chg,a}(t)\Delta_t}{E_{bat}}\eta_{chg} \quad (8h)$$

$$SoC_{a,min} \leq SoC_a(t) \leq SoC_{a,max} \quad (8i)$$

$$P_{EV,a,min} \leq P_{EV,chg,a}(t) \leq P_{EV,a,max} \quad (8j)$$

$$SoC_a(t = t_a^{dep}) \geq SoC_{min}^{dep} - SoC_a^{relax} \quad (8k)$$

$$SoC_a^{relax} \geq 0 \quad (8l)$$

where

$$f(P_{EV,a,t}) = \frac{1}{E_{Mis}^{norm}} \left(\left| \sum_{t=t_{init}(T_{init}^{hor},k)}^{t_{end}(T_{init}^{hor},k)} \left(P_{plan}(T_{init}^{hor}) - P_{BRP}(t) \right) + \mathcal{C}(t) \right| \Delta_t \right. \\ \left. + \sum_{T=T_{init}^{Hor}+1}^{T_{end}^{Hor}} \left| \sum_{t=t_{init}(T,k)}^{t_{end}(T,k)} \left(P_{plan}(T) - P_{BRP}(t) \right) \right| \Delta_t \right), \quad (9)$$

and

$$g(Soc_a^{relax}) = \max_{Soc_a^{relax}} \left\{ \frac{Soc_a^{relax}}{Soc_{min}^{dep} - Soc_{min}} \right\}. \quad (10)$$

In $f(P_{EV,a,k})$

- T_{init}^{hor} and T_{end}^{hor} represent the first (initial) and last imbalance period over the MPC's Horizon;
- $t_{init}(T', k) = \max(0, \Delta T \cdot T' - k)$ and $t_{end}(T', k) = \min(\Delta T \cdot (T' + 1) - k, hor)$ the first and last instant over the imbalance period T' ;
- $\mathcal{C}(t)$ is the already computed energy mismatch of previous instant(s) of the first imbalance period defined as

$$\mathcal{C}(t) = \sum_{k'=0}^{t-1} f(P_{EV,a,k'}). \quad (11)$$

Note that these previous instants are no longer covered by the MPC's horizon however, they are to be considered to compute the total energy mismatch of the first imbalance period;

- the first absolute value is used to compute the first imbalance period energy mismatch;
- the second absolute value is used to compute the remaining imbalance period energy mismatch;