# Time series modeling

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Time Series Models

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### Basic time Models: AR

# - Auto Regressive (AR)

Current predicted output depends on previous outputs

$$Y(k) = \theta_1 Y(k-1) + \xi(k)$$

$$Y(k) = \theta_1 Y(k-1) + \theta_2 Y(k-2) + \xi(k)$$

$$\vdots$$

$$Y(k) = \sum_{i=1}^{n} \theta_i Y(k-i) + \xi(k)$$

$$AR(1)$$

$$AR(2)$$

$$AR(n)$$

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### Basic time Models: MA

# - Moving Average (MA)

Current predicted output depends on previous estimation errors

$$Y(k) = \phi_1 \xi(k-1) + \xi(k)$$

$$Y(k) = \phi_1 \xi(k-1) + \phi_2 \xi(k-2) + \xi(k)$$

$$\vdots$$

$$Y(k) = \sum_{i=1}^{p} \phi_i \xi(k-j) + \xi(k)$$

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$$MA(p)$$

#### Basic time Models: MA

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 MA(2)

$$Y(k) = \sum_{j=1}^{p} \phi_j \xi(k-j) + \xi(k)$$
  $MA(p)$ 

#### Basic time Models: MA

# Moving Average (MA)

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$$\vdots$$

$$Y(k) = \sum_{i=1}^{p} \phi_i \xi(k-j) + \xi(k) \qquad MA(p)$$

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#### Mixed time models: ARMA

# - Auto Regressive Moving Average (ARMA)

Current predicted output depends on previous outputs and estimation errors

$$Y(k) = \sum_{i=1}^{n} \theta_{i} Y(k-i) + \sum_{j=1}^{p} \phi_{j} \xi(k-j) + \xi(k)$$

- Auto Regressive Integrated Moving Average (ARIMA)
  ARMA with differentiation to remove trends.
- Exponential smoothing ARMA (ESARMA)

Associates to  $\theta_i$  and  $\phi_j$  a decreasing function to give more importance to new information.

- ARMA with Exogenous Regressors (ARMAX)
  - Model includes parallel inputs sequences that are be observed at the same time step as the original time series.

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- Seasonal ARMA (SARMA)

ARMA with trends and/or seasonal components.

Markov Switching ARMA (MSARMA)
 ARMA with non linearity due to different functioning regimes

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ARMA with non linearity due to different functioning regimes

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## Markov Auto Regressive M

A Markov Switching Auto Regressive MSAR model is given by

$$Y_{(k)} = \theta_0^{r(k)} + \sum_{i=1}^{n_{r(k)}} \theta_i^{r(k)} \left( Y_{(k-i)} - \theta_0^{r(k-i)} \right) + \xi_{(k)}^{r(k)}$$

where:

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#### where:

- The regime sequence  $\{r(k)\}$  follows a first order markov chain on the finite space  $\{1, \ldots, R\}$ ;
- The probabilities governing the MC transitions are defined in the transition matrix

$$\mathbf{P} = \begin{bmatrix} p_{1,1} & \dots & \dots & p_{1,R} \\ p_{2,1} & p_{2,2} & & \\ \vdots & & \ddots & & \\ p_{R,1} & & & p_{R,R} \end{bmatrix}$$

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$$\mathbf{P} = \begin{bmatrix} 0.8271 & 0.1282 & 0.0440 \\ 0.2091 & 0.4778 & 0.3130 \\ 0.0095 & 0.0093 & 0.9812 \end{bmatrix}.$$