# Ali Pakniyat

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# **EDUCATION**

McGill University, Montreal, Canada

2011 - 2016

Doctor of Philosophy, Electrical Engineering

Supervisor: Peter E. Caines

Thesis: "Optimal control of deterministic and stochastic hybrid systems: theory and applications"

Sharif University of Technology, Tehran, Iran

2008 - 2010

Master of Science, Mechanical Engineering

Supervisors: Hassan Salarieh & Aria Alasty

Thesis: "On the nonlinear dynamics and bifurcations in a new class of MEMS gyroscopes with parametric resonance"

Shiraz University, Shiraz, Iran

2004 - 2008

Bachelor of Science, Mechanical Engineering

Supervisor: Mohammad Eghtesad

Thesis: "Solving differential equations using Wavelet transform"

# ACADEMIC APPOINTMENTS

University of Michigan, Ann Arbor, USA

Georgia Institute of Technology, Atlanta, USA

2019 - present

Postdoctoral Research Fellow, Institute for Robotics and Intelligent Machines

Supervisor: Panagiotis Tsiotras

Postdoctoral Research Fellow, Department of Mechanical Engineering

2017 - 2019 Supervisor: Ramanarayan Vasudevan

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2016 - 2017

McGill University, Montreal, Canada Lecturer, Department of Electrical and Computer Engineering

# RESEARCH AREAS

Control Theory: Optimization and Optimal Control, Hybrid Systems, Stochastic Processes, Multi-Agent Systems, Mean-Field Games

Control Practice: Autonomous Driving, Vehicle Electrification, Robotics, Micro Electrical-Mechanical Systems (MEMS), Mathematical Finance, Large-Scale Networks

# **PUBLICATIONS**

#### Journal Papers

- [J6] A. Pakniyat and P. E. Caines, "On the Minimum Principle for Hybrid Systems," arXiv:1710.05521v2, 2019, Accepted for publication by the IEEE Transactions on Automatic Control
- [J5] A. Pakniyat and P. E. Caines, "On the Relation between the Minimum Principle and Dynamic Programming for Classical and Hybrid Control Systems," *IEEE Transactions on Automatic Control*, vol. 62, no. 9, pp. 4347–4362, 2017
- [J4] A. Pakniyat and P. E. Caines, "Hybrid Optimal Control of an Electric Vehicle with a Dual-Planetary Transmission," Nonlinear Analysis: Hybrid Systems, vol. 25, pp. 263–282, 2017
- [J3] M. S. R. Mousavi, A. Pakniyat, T. Wang, and B. Boulet, "Seamless Dual Brake Transmission For Electric Vehicles: Design, Control and Experiment," Mechanism and Machine Theory, vol. 94, pp. 96–118, 2015
- [J2] A. Pakniyat and H. Salarieh, "A Parametric Study on Design of a Microrate-Gyroscope with Parametric Resonance," Measurement, vol. 46, no. 8, pp. 2661–2671, 2013
- [J1] A. Pakniyat, H. Salarieh, and A. Alasty, "Stability Analysis of a New Class of MEMS Gyroscopes with Parametric Resonance," *Acta Mechanica*, vol. 223, no. 6, pp. 1169–1185, 2012

# Journal/Conference Papers

- [JC4] A. Pakniyat and P. E. Caines, "A Class of Linear Quadratic Gaussian Hybrid Optimal Control Problems with Realization–Independent Riccati Equations," *IFAC-PapersOnLine*, vol. 50, no. 1, pp. 2241–2246, 2017, also appeared in Proceedings of the International Federation of Automatic Control 20th World Congress, Toulouse, France
- [JC3] A. Pakniyat and P. E. Caines, "Time Optimal Hybrid Minimum Principle and the Gear Changing Problem for Electric Vehicles," *IFAC-PapersOnLine*, vol. 48, no. 27, pp. 187–192, 2015, also appeared in Proceedings of the 5th IFAC Conference on Analysis and Design of Hybrid Systems, Atlanta, GA, USA
- [JC2] A. Pakniyat and P. E. Caines, "On the Relation between the Hybrid Minimum Principle and Hybrid Dynamic Programming: A Linear Quadratic Example," *IFAC-PapersOnLine*, vol. 48, no. 27, pp. 169–174, 2015, also in Proceedings of the 5th IFAC Conference on Analysis and Design of Hybrid Systems, Atlanta, GA, USA
- [JC1] A. Pakniyat and P. E. Caines, "On the Minimum Principle and Dynamic Programming for Hybrid Systems," *IFAC-PapersOnLine*, vol. 47, no. 3, pp. 9629–9634, 2014, also appeared in Proceedings of the International Federation of Automatic Control 19th World Congress, Cape Town, South Africa

#### Patent

[P1] B. Boulet, M. S. R. Mousavi, H. V. Alizadeh, and A. Pakniyat, "Seamless Transmission Systems and Methods for Electric Vehicles," Jul. 11 2017, US Patent US 9,702,438 B2

#### Conference Papers

- [C12] A. Pakniyat and R. Vasudevan, "A Convex Duality Approach to Optimal Control of Killed Markov Processes," in (to appear in) the Proceedings of the 58th IEEE Conference on Decision and Control, Nice, France, 2019
- [C11] D. Firoozi, A. Pakniyat, and P. E. Caines, "A Mean Field Game Hybrid Systems Approach to Optimal Execution Problems in Finance with Stopping Times," in Proceedings of the 56th IEEE Conference on Decision and Control, Melbourne, Australia, 2017, pp. 433–441
- [C10] A. Pakniyat and P. E. Caines, "On the Stochastic Minimum Principle for Hybrid Systems," in Proceedings of the 55th IEEE Conference on Decision and Control, Las Vegas, NV, USA, 2016, pp. 1139–1144
- [C9] A. Pakniyat and P. E. Caines, "On the Minimum Principle and Dynamic Programming for Hybrid Systems with Low Dimensional Switching Manifolds," in Proceedings of the 54th IEEE Conference on Decision and Control, Osaka, Japan, 2015, pp. 2567–2573
- [C8] M. S. R. Mousavi, A. Pakniyat, M. K. Helwa, and B. Boulet, "Observer-Based Backstepping Controller Design for Gear Shift Control of a Seamless Clutchless Two-Speed Transmission for Electric Vehicles," in *Proceedings of the IEEE Vehicle Power and Propulsion Conference (VPPC)*, Montreal, QC, Canada, 2015, pp. 1–6
- [C7] A. Pakniyat and P. E. Caines, "On the Relation between the Minimum Principle and Dynamic Programming for Hybrid Systems," in Proceedings of the 53rd IEEE Conference on Decision and Control, Los Angeles, CA, USA, 2014, pp. 19–24
- [C6] A. Pakniyat and P. E. Caines, "The Gear Selection Problem for Electric Vehicles: An Optimal Control Formulation," in Proceedings of the 13th International Conference on Control Automation Robotics & Vision ICARCV, Marina Bay Sands, Singapore. IEEE, 2014, pp. 1261–1266
- [C5] M. S. R. Mousavi, A. Pakniyat, and B. Boulet, "Dynamic Modeling and Controller Design for a Seamless Two-Speed Transmission for Electric Vehicles," in *Proceedings of the 2014 IEEE Conference on Control Applications, Antibes, France*, 2014, pp. 635–640
- [C4] A. Pakniyat and P. E. Caines, "The Hybrid Minimum Principle in the Presence of Switching Costs," in Proceedings of the 52nd IEEE Conference on Decision and Control, Florence, Italy, 2013, pp. 3831–3836
- [C3] A. Pakniyat, H. Salarieh, G. Vossoughi, and A. Alasty, "A Modification on Performance of MEMS Gyroscopes by Parametro-Harmonic Excitation," in Proceedings of the 10th ASME Biennial Conference on Engineering Systems Design and Analysis, Istanbul, Turkey, 2010, pp. 433–441
- [C2] A. Pakniyat, H. Salarieh, and A. Alasty, "Stability Analysis of a Novel MEMS Gyroscope Actuated by Parametric Resonance Using Floquet Theory," in *Proceedings of the 3rd Conference on Nano-Structures, Kish Island, Persian Gulf, Iran*, 2010, pp. 1219–1221
- [C1] A. Pakniyat and M. Eghtesad, "Solving Differential Equations using Wavelet Transform," in *Proceedings of the 17th Annual International Conference on Mechanical Engineering, Tehran, Iran, 2010*, pp. 1–6, (in Persian)

#### Under Review and In-Preparation Journal Papers

- [U5] D. Firoozi, A. Pakniyat, and P. E. Caines, "A Hybrid Optimal Control Approach to LQG Mean Field Games with Switching and Stopping Strategies," arXiv:1810.02920, 2018
- [U4] A. Pakniyat and P. E. Caines, "The Stochastic Hybrid Minimum Principle."
- [U3] A. Pakniyat and R. Vasudevan, "A Convex Duality Approach to Hybrid Dynamic Programming."
- [U2] K. P. Hawkins, A. Pakniyat, E. Theodorou, and P. Tsiotras, "Forward Backward RRT: Solving Stochastic Optimal Control Problems with Branched Sampled Forward Backward SDEs."
- [U1] A. Pakniyat and P. Tsiotras, "Steering of Linear Stochastic Hybrid Systems: A Minimum Principle Approach."

#### SELECTED HONOURS AND AWARDS

▷ Canadian Marconi Graduate Award	2017
▷ Automotive Partnership Canada (APC) – Natural Sciences & Engineering Research Council (NSERC)	2012 – 2016
▶ MEDA (McGill Engineering Doctoral Award)	2011 – 2014
▷ GERAD (Groupe d'Études et de Recherche en Analyse des Décisions) Doctoral Fellowship	2015
▶ Graduate Excellence Award in Engineering – McGill University	2011 – 2014
▷ IEEE-CSS (Control Systems Society) Travel Award	2014
▷ GREAT (Graduate Research Enhancement and Travel) – McGill University	2014
▶ Ranked 2 <sup>nd</sup> among 57 students in the program of Applied Mechanics, and 3 <sup>rd</sup> among 130 students	
in the M.Sc. program of Mechanical Engineering at Sharif University of Technology	2008 – 2010
▶ Ranked 1st among 80 students in the B.Sc. program of Mechanical Engineering at Shiraz University	2004-2008

#### TEACHING EXPERIENCES

# Course Lecturer

McGill University, Course Instructor

ECSE 493 Control and Robotics Laboratory, Winter 2016, 2017

ECSE 205 Probability and Statistics for Engineers,

Fall 2016, Winter 2017

# Teaching Assistant

McGill University, Teaching Assistant

ECSE 516 Nonlinear and Hybrid Control Systems, Winter 2013, 2017

Winter 2014 ECSE 506 Stochastic Control and Decision Theory,

ECSE 500 Mathematical Foundations of Systems, Fall 2013, 2015

ECSE 493 Control and Robotics Laboratory. Winter 2014, 2015

ECSE 443 Introduction to Numerical Methods in Electrical Engineering, Winter 2014, 2015

Fall 2013, 2014, 2015, 2016 ECSE 404 Control Systems,

SHARIF UNIVERSITY OF TECHNOLOGY, Teaching Assistant

MECH 28586 Robust Control, Fall 2010

Spring 2010, Fall 2010 MECH 28416 Automatic Control.

SHIRAZ UNIVERSITY, TEACHING ASSISTANT

MECH 100531241 Mechanical Vibrations, Spring 2008

MECH 100531221 Dynamics of Machinery, Spring 2008

MECH 100531171 Machine Design II, Fall 2007

Spring 2007 MECH 100531161 Machine Design I,

MECH 100531071 Dynamics, Fall 2006

#### INVITED TALKS

2019-05-30 CIM – GERAD Informal Systems Seminar (ISS), Montreal, Canada

2019-05-27 Queen's University Control Theory Seminar, Kingston, Canada

2019-04-09 Center for Control, Dynamical Systems, and Computation (CCDC) Seminar,

2018-10-13 The 2018 Midwest Optimization Meeting,

2018-06-07 University College Dublin, School of Electrical and Electronic Engineering, Dublin, Ireland

2018-04-25 Michigan Postdoctoral Association of the College of Engineering (MPACE) Seminar,

2018-01-30 Michigan Robotics Colloquium,

2017-09-08 University of California, Santa Barbara, Department of Mechanical Engineering, Santa Barbara, USA

2017-09-05 Stanford University, Department of Aeronautics and Astronautics,

2017-01-30 University of Michigan, Department of Mechanical Engineering,

2017-01-06 University of California, Irvine, Aeronatics, Dynamics and Control Lab Seminar

2016-07-21 IEEE Montreal – Concordia University,

2016-05-11 The 7th Biannual Meeting on System and Control Theory,

2014-05-05 The 6th Biannual Meeting on System and Control Theory,

Santa Barbara, USA

Oxford (OH), USA

Ann Arbor, USA

Ann Arbor, USA

Stanford, USA

Ann Arbor, USA

Irvine, USA

Montreal, Canada

Kingston, Canada

Waterloo, Canada

#### SELECTED LEADERSHIP AND VOLUNTEER EXPERIENCES

2017 - 2019Mentor, Association for Women in Science (AWIS) - University of Michigan

Chair, Chapter 12 (Control Systems) - IEEE SEM (Southeast Michigan) Section

2018 2018

Technical Judge, Emerging Research Competition in Engineering Graduate Symposium - Univ. of Michigan

2012 - 2017

Seminar Coordinator, Informal Systems Seminars (ISS) - McGill University Charity Fundraiser, Omid Group - Hope for Children with Cancer

2013 - 2016

#### SELECTED TRAINING EXPERIENCES **Teaching Training** 2018 Postdoctoral Course on College Teaching in STEM, University of Michigan 2017 Motivating Engineering Students: Strategies to Increase Engagement, University of Michigan 2017 Perspectives on Teaching: A Faculty Panel, University of Michigan 2017 Workshop on Graduate Supervision, McGill University 2011 Graduate Teaching Workshop, McGill University General Training University of Michigan 2017 Academic Identity Management, 2017 Research Integrity Workshop, McGill University IEEE-Montreal 2016 NASA Engineering and Science Activities, 2016 Workshop on How to Organize an IEEE Event, IEEE Panel of Conference Organizers (POCO) 2014 Workshop on Basic Business Skills for Non-Business Graduate Students, McGill University 2010 Workshop on Invention: Technology Development and Commercialization, University of Southern California and Sharif University of Technology Technical Research Training Georgia Institute of Technology 2019 Southeast Controls Conference, 2018 Stochastic Control and its Application, IEEE Control Systems Society 2018 Midwest Optimization Meeting, Miami University 2018 Princeton Day of Optimization, Princeton University 2018 Midwest Robotics Workshop, Toyota Technological Institute at Chicago 2018 Meeting on System and Control Theory, University of Toronto Michigan State University

2018 Midwest Workshop on Control and Game Theory, 2017 Mean Field Games Workshop,

Institute for Pure and Applied Mathematics, Univ. of California, Los Angeles

2016 Aerospace Summer School,

Concordia University

2016 Meeting on System and Control Theory, Queen's University

2015 Workshop on Dynamic Games in Management Science,

GERAD - HEC Montréal

2015 Mathematical Cybernetics: Hybrid, Stochastic and Decentralized Systems,

Carlton University

2014 Symposium on Advanced Electric Vehicle Drivetrains,

 $McGill\ University-IEEE$ 

2014 Meeting on System and Control Theory,

University of Waterloo

# REVIEW SERVICES

Journals: IEEE Transactions on Automatic Control (TAC)

Automatica

SIAM Journal on Control and Optimization (SICON)

Systems & Control Letters (SCL) IEEE Control Systems Letters (L-CSS) Nonlinear Analysis: Hybrid Systems (NAHS)

IEEE Transactions on Systems, Man, and Cybernetics: Systems (SMC)

Nonlinear Dynamics (NODY)

Sensors - MDPI

IEEE Conference on Decision and Control (CDC) Conferences:

IFAC World Congress

IEEE American Control Conference (ACC)

ACM Conference on Hybrid Systems: Computation and Control (HSCC)

IEEE European Control Conference (ECC)

#### SELECTED REFERENCES

Peter E. Caines, Professor, Department of Electrical and Computer Engineering, McGill University peterc@cim.mcgill.ca (+1) 514 398 7129 Panagiotis Tsiotras, Professor, School of Aerospace Engineering, Georgia Institute of Technology

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Ramanarayan Vasudevan, Assistant Professor, Department of Mechanical Engineering, University of Michigan ramv@umich.edu (+1) 734 647 5560

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