

Concepts

Variables

Pressure - Normal force per unit area exerted on a surface due to the time rate of change of momentum of the gas particles impacting said surface.

$$P = \lim_{dA \rightarrow 0} \frac{dF_n}{dA}$$

Density - Mass per unit volume.

$$\rho = \lim_{dV \rightarrow 0} \frac{dm}{dV}$$

Temperature - Change in kinetic energy due to random molecular motion.

$$KE = \frac{3}{2}kT$$

Flow Velocity - Velocity due to organized motion.

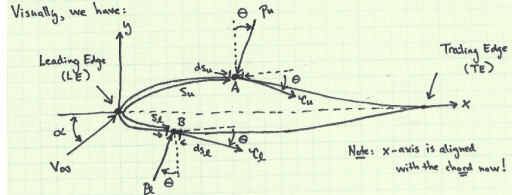
$$\vec{v} = \frac{d}{dt}\vec{x}$$

Forces and Moments

Causes of forces and moments on an aerodynamic body:

Pressure Distribution over the body surface.

Shear Stress Distribution over the surface.



Lift and Drag per Unit Span:

$$L' = N' \cos \alpha - A' \sin \alpha$$

$$D' = N' \sin \alpha + A' \cos \alpha$$

Normal Force per Unit Span:

$$N' = \int_{LE}^{TE} (P_u \cos \theta + \tau_u \sin \theta) ds_u + \int_{LE}^{TE} (P_l \cos \theta - \tau_l \sin \theta) ds_l$$

Axial Force per Unit Span:

$$A' = \int_{LE}^{TE} (-P_u \sin \theta + \tau_u \cos \theta) ds_u + \int_{LE}^{TE} (P_l \sin \theta + \tau_l \cos \theta) ds_l$$

Moment per Unit Span:

$$M'_* = \int_{LE}^{TE} [(P_u \cos \theta + \tau_u \sin \theta)(x - x^*) - (P_u \sin \theta - \tau_u \cos \theta)(y - y^*)] ds_u$$

$$+ \int_{LE}^{TE} [(-P_l \cos \theta + \tau_l \sin \theta)(x - x^*) + (P_l \sin \theta + \tau_l \cos \theta)(y - y^*)] ds_l$$

When $x^* = y^* = 0$ we obtain the moment about the leading edge.

Center of Pressure:

$$x_{cp} = -\frac{M'_{LE}}{N'}$$

Force and Moment Coefficients

Dynamic Pressure: $q = \frac{1}{2} \rho_{\infty} v_{\infty}^2$ **Reference Area:** S

Reference Length: L or c

Lift Coefficient: $c_L = \frac{L}{q_{\infty} S}$

Drag Coefficient: $c_D = \frac{D}{q_{\infty} S}$

Moment Coefficient: $c_M = \frac{M}{q_{\infty} S L}$

Buckingham Pi Theorem

If we have a physically meaningful equation such as:

$$f(P_1, P_2, \dots, P_N) = 0$$

where P_i are physical variables in terms of K independent physical units (mass, length, time, temperature) then it can be restated as:

$$F(\Pi_1, \Pi_2, \dots, \Pi_{N-K}) = 0 \text{ or}$$

$$\Pi_{N-K} = G(\Pi_1, \Pi_2, \dots, \Pi_{N-K-1})$$

where Π_i are dimensionless variables known as Pi Groups.

Calculus Review

Vector Calculus

Magnitude: $|\vec{A}| = \sqrt{A_1^2 + A_2^2 + A_3^2}$

Dot Product: $\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z = |\vec{A}| |\vec{B}| \cos \theta$

Cross Product: $\vec{A} \times \vec{B} = (A_y B_z - A_z B_y) \hat{i} + (A_z B_x - A_x B_z) \hat{j} + (A_x B_y - A_y B_x) \hat{k}$

$|\vec{A} \times \vec{B}| = |\vec{A}| |\vec{B}| \sin \theta$

Gradient of Scalar Field: $\vec{\nabla} p = \frac{\partial p}{\partial x} \hat{i} + \frac{\partial p}{\partial y} \hat{j} + \frac{\partial p}{\partial z} \hat{k}$ vector field

Directional Derivative: $\frac{dp}{ds} = \vec{\nabla} p \cdot \vec{s}$ -> unit vector in \vec{s} direction.

Divergence of a Vector Field: $\text{div} \vec{V} = \vec{\nabla} \cdot \vec{V} = \frac{\partial V_x}{\partial x} + \frac{\partial V_y}{\partial y} + \frac{\partial V_z}{\partial z}$ scalar field

Curl of a Vector Field: $\text{curl} \vec{V} = \vec{\nabla} \times \vec{V} = (\frac{\partial V_z}{\partial y} - \frac{\partial V_y}{\partial z}) \hat{i} + (\frac{\partial V_x}{\partial z} - \frac{\partial V_z}{\partial x}) \hat{j} + (\frac{\partial V_y}{\partial x} - \frac{\partial V_x}{\partial y}) \hat{k}$

Integrals

Stokes' Theorem: $\oint_C \vec{A} \cdot d\vec{s} = \iint_S (\vec{\nabla} \times \vec{A}) \cdot d\vec{S}$

Divergence Theorem: $\oint_S \vec{A} \cdot d\vec{S} = \iiint_V (\vec{\nabla} \cdot \vec{A}) dV$

Gradient Theorem: $\oint_S p d\vec{S} = \iiint_V \vec{\nabla} p dV$