Midsemester Examination

ME 321: Advanced Mechanics of Solids

17 September 2018, 8 - 10 a.m.

Problem 1: Do the following. Notation: a - scalar, a - vector, a - tensor.

- i. Show that if \hat{n} is a unit vector, then any vector a can be written as $(a \cdot \hat{n})\hat{n} + \hat{n} \times a \times \hat{n}$.
- ii. Show that $\nabla (r^n \mathbf{r}) = r^n \mathbf{1} + n r^{n-2} \mathbf{r} \otimes \mathbf{r}$, where \mathbf{r} is the position vector with respect to the origin.
- iii. The rotational part of the deformation is given by $\mathbf{R} = \left\{ \nabla \mathbf{u} (\nabla \mathbf{u})^T \right\} / 2$. Show that $\mathbf{R} = -1 \times (\nabla \times \mathbf{u}) / 2$.
- iv. Let the fourth-order unit tensor \mathcal{I} be such that

$$\mathcal{I}: \mathbf{A} = \mathbf{A}$$
, i.e. $I_{ijkl}A_{lk} = A_{ij}$,

for all second-order tensors A. Then show that $\mathcal{I} = \hat{\mathbf{e}}_i \otimes \hat{\mathbf{e}}_j \otimes \hat{\mathbf{e}}_i$, for any orthogonal triad $\{\hat{\mathbf{e}}_i\}$. Then find the components I_{ijkl} of \mathcal{I} in terms of the Krönecker delta function.

Problem 2: Linear Momentum Balance (LMB). We have discussed that we hypothesize that for continuum materials of our interest, surfaces interact with other surfaces / external environment through traction (force per unit area) distributions. Moment distributions are ignored / not permitted, in contrast to ESO202 where they were allowed. Do the following:

a. Show that the LMB for such continuum materials may be written in indical notation as

$$\sigma_{ij,j} + \rho b_i = \rho a_i.$$

b. Show that the traction vector t acting on a surface with normal \hat{n} passing through a point P may be related to the stress σ at P by

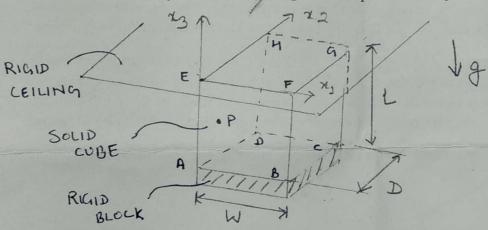
$$t = \sigma \cdot \hat{n}$$
.

- c. Now consider a complex continuum material (e.g. granular materials like sand) wherein it is useful to permit moment distributions across surfaces. Does angular momentum balance (see next problem also) hold for such materials?
- d. Write down the LMB and the traction-stress relation in indical notation for materials in which moment distributions are permitted.

Problem 3: Angular Momentum Balance (AMB). Show that AMB leads to the proof of the stress being symmetric, i.e. $\sigma = \sigma^T$. Make sure that you fill in all steps of the derivation that were skipped in class.

Problem 4: Boundary Conditions. Consider the old fashioned uniaxial tensile test shown in Fig. 1. The body being investigated is the solid cube ABCDEFGH. Gravity acts downwards in the $-\hat{e}_3$ direction. On the bottom surface $x_3 = -L$ (i.e. ABCD) we attach (stick) a rigid block of mass m, as shown. On the top surface the cube is built into (i.e. clamped to) the rigid ceiling. Do the following:

- a. Draw the free body diagram of the cube *ABCDEFGH* and the rigid block separately. Pay careful attention to which forces are present / absent.
- b. Write the boundary conditions on the top surface.
- c. Write the boundary conditions on the four side surfaces.
- d. Write the boundary conditions on the bottom surface. The rigid block cannot deform.
- e. Investigate the stress tensor σ at point P on the surface $x_2 = 0$ (i.e. ABFE). Using the boundary conditions on $x_2 = 0$ compute as many components of σ at P as possible.



Problem 5: The Compatibility Equation. The strain tensor S at location r and time t is related to the displacement field u(r,t) by

$$S = \frac{1}{2} \left\{ \nabla \mathbf{u} + (\nabla \mathbf{u})^T \right\}. \tag{1}$$

Do the following:

- a. Suppose, at a given time, we know the strain tensor field S(r,t) for all locations r. Is it always possible to integrate (1) to find the displacement field u? In other words, does a solution u always exist such that it satisfies (1) for any given S?
- b. Show that a necessary condition for (1) to be solvable is that $\nabla \times S \times \nabla = 0$.

 Hint: Recall that $S \times \nabla$ means that the curl operation is done from the right. At the same time, it is easy to show that $\nabla \times S \times \nabla = -\nabla \times (\nabla \times S)^T$.