

# Final decomposition model

**ESTP Training** 

Eurostat

## Regression model

Additive case:

$$y_c = \alpha \cdot cal + \beta \cdot out + \gamma \cdot reg + \mu$$

Multiplicative case:

$$ln(y_c) - ln(lp) = \alpha \cdot cal + \beta \cdot out + \gamma \cdot reg + \mu$$

- $cal = [tde \ ee \ omhe]$
- $out = [out_t \quad out_s \quad out_i]$
- $reg = [reg_t \ reg_s \ reg_i \ reg_{sa} \ reg_y \ reg_u]$
- $\mu$  = "linearized series"

#### Handling of the regression variables

Code	Description	Y_lin	T	S	- 1	SA
tde	Trading days (default, holidays, user-defined)	Х		Х		
ee	Easter	Х		Х		
omhe	Other moving holidays (TODO: Ramadan)	Х		Х		
AO	Additive outlier	Х			X	Х
TC	Transitory change	X			Х	Х
LS	Level shift	Х	Х			Х
SO, SLS	Seasonal outlier / seasonal level shift	Х		Х		
Reg_i	Regression variables allocated to irregular, IV (p)	Х			Χ	Х
Reg_t	Regression variables allocated to trend, ramps, IV (p)	X	X			Х
Reg_s	Regression variables allocated to seasonal, IV (p)	Х				
Reg_sa	Regression variables allocated to seas. adjusted	Х				X
Reg_y	Regression variables removed before decomposition					
Reg_u	Regression variables unallocated to a component	Х	р	p	р	р

p stands for partially

### Decomposition

Additive case:

$$\gamma_u \cdot reg_u + \mu = y_{cmp} = t_{cmp} + s_{cmp} + i_{cmp}$$

• Multiplicative case:

$$\gamma_u \cdot reg_u + \mu = y_{lin} = t_{lin} + s_{lin} + i_{lin}$$

$$exp(\gamma_u \cdot reg_u + \mu) = y_{cmp}$$

$$= t_{cmp} \cdot s_{cmp} \cdot i_{cmp}$$

#### Final decomposition

#### Additive case:

$$\checkmark t = out_t + reg_t + t_{cmp}$$

$$\checkmark s = cal + out_s + reg_s + s_{cmp}$$

$$\checkmark i = out_i + reg_i + i_{cmp}$$

$$\checkmark sa = t + i + reg_{sa} = y_c - reg_y - s$$

$$\checkmark y_c = s + t + i + reg_v$$

#### • Multiplicative case:

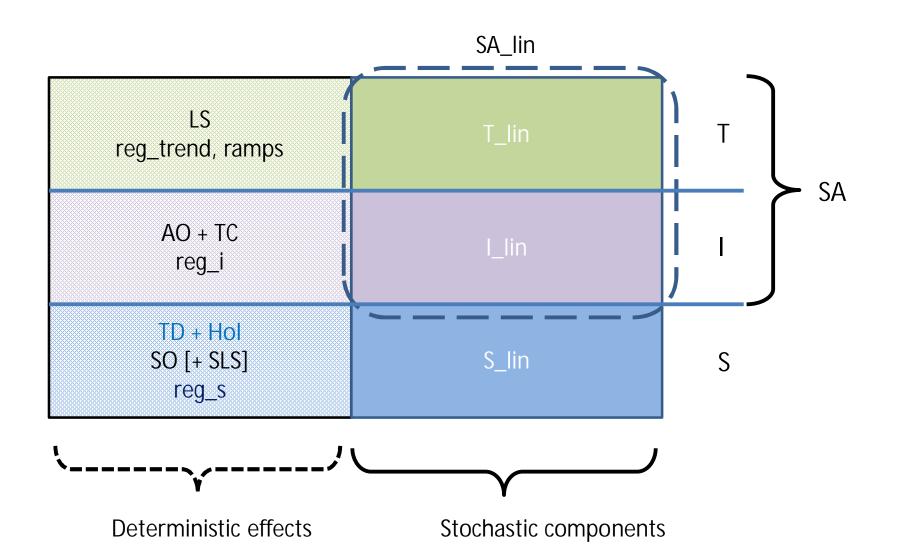
$$✓ t = exp(out_t \cdot reg_t) \cdot t_{cmp}$$

$$✓ s = exp(cal \cdot lp \cdot out_s \cdot reg_s) \cdot s_{cmp} = exp(cal \cdot out_s \cdot reg_s) \cdot s_{cmp}$$

$$✓ i = exp(out_i \cdot reg_i) \cdot i_{cmp}$$

$$✓ sa = t \cdot i \cdot exp(reg_{sa}) = (y_c/exp(reg_y))/s$$

$$✓ y_c/exp(reg_v) = s \cdot t \cdot i$$



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