

Diffusion Video Autoencoders: Toward Temporally Consistent Face Video Editing via Disentangled Video Encoding

Gyeongman Kim¹ Hajin Shim¹ Hyunsu Kim² Yunjey Choi² Junho Kim² Eunho Yang^{1,3}

¹Korea Advanced Institute of Science and Technology (KAIST), South Korea

²NAVER AI Lab ³AITRICS, South Korea

{gmkim, shimazing, eunhoy}@kaist.ac.kr {hyunsu1125.kim, yunjey.choi, jhkim.ai}@navercorp.com



Figure 1. Face video editing. Our editing method shows improvement compared to the baseline [33] in terms of temporal consistency (left, “eyeglasses”) and robustness to the unusual case such as the hand-occluded face (right, “beard”).

Abstract

Inspired by the impressive performance of recent face image editing methods, several studies have been naturally proposed to extend these methods to the face video editing task. One of the main challenges here is temporal consistency among edited frames, which is still unresolved. To this end, we propose a novel face video editing framework based on diffusion autoencoders that can successfully extract the decomposed features - for the first time as a face video editing model - of identity and motion from a given video. This modeling allows us to edit the video by simply manipulating the temporally invariant feature to the desired direction for the consistency. Another unique strength of our model is that, since our model is based on diffusion models, it can satisfy both reconstruction and edit capabilities at the same time, and is robust to corner cases in wild face videos (e.g. occluded faces) unlike the existing GAN-based methods.

1. Introduction

As one of the standard tasks in computer vision to change various face attributes such as hair color, gender, or glasses of a given face image, face editing has been continuously gaining attention due to its various applications and entertainment. In particular, with the improvement of analysis and manipulation techniques for recent Generative Adversarial Network (GAN) models [8, 12, 21, 27, 28], we simply can do this task by manipulating a given image’s latent feature. In addition, very recently, many methods for face image editing also have been proposed based on Diffusion Probabilistic Model (DPM)-based methods that show high-quality and flexible manipulation performance [3, 13, 16, 18, 22, 24].

Naturally, further studies [2, 33, 39] have been proposed to extend image editing methods to incorporate the temporal axis for videos. Now, given real videos with a human face, these studies try to manipulate some target facial attributes with the other remaining features and motion in-

tact. They all basically edit each frame of a video independently via off-the-shelf StyleGAN-based image editing techniques [21, 27, 39].

Despite the advantages of StyleGAN in this task such as high-resolution image generation capability and highly disentangled semantic representation space, one harmful drawback of GAN-based editing methods is that the encoded real images cannot perfectly be recovered by the pretrained generator [1, 25, 32]. Especially, if a face in a given image is unusually decorated or occluded by some objects, the fixed generator cannot synthesize it. For perfect reconstruction, several methods [6, 26] are suggested to further tune the generator for GAN-inversion [25, 32] on one or a few target images, which is computationally expensive. Moreover, after the fine-tuning, the original editability of GANs cannot be guaranteed. This risk could be worse in video domain since we have to finetune the model on the multiple frames.

Aside from the reconstruction issue of existing GAN based methods, it is critical in video editing tasks to consider the temporal consistency among edited frames to produce realistic results. To address this, some prior works rely on the smoothness of the latent trajectory of the original frames [33] or smoothen the latent features directly [2] with simply taking the same editing step for all frames. However, smoothness does not ensure temporal consistency. Rather, the same editing step can make different results for different frames because it can be unintentionally entangled with irrelevant motion features. For example, in the middle row of Fig. 1, eyeglasses vary across time and sometimes diminish when the man closes his eyes.

In this paper, we propose a novel video editing framework for human face video, termed *Diffusion Video Autoencoder*, that resolves the limitations of the prior works. First, instead of GAN-based editing methods suffering from imperfect reconstruction quality, we newly introduce diffusion based model for face video editing tasks. As the recently proposed *diffusion autoencoder* (DiffAE) [22] does, our model learns a semantically meaningful latent space that can perfectly recover the original image back and are directly editable. Not only that, for the first time as a video editing model, encode the decomposed features of the video: 1) identity feature shared by all frames, 2) feature of motion or facial expression in each frame, and 3) background feature that could not have high-level representation due to large variances. Then, for consistent editing, we simply manipulate a single invariant feature for the desired attribute (single editing operation per video), which is also computationally beneficial compared to the prior works that require editing the latent features of all frames.

We experimentally demonstrate that our model appropriately decomposes videos into time-invariant and per-frame variant features and can provide temporally consistent manipulation. Specifically, we explore two ways of manipula-

tions. The first one is to edit features in the predefined set of attributes by moving semantic features to the target direction found by learning linear classifier in semantic representation space on annotated CelebA-HQ dataset [10]. Additionally, we explore the text-based editing method that optimizes a time-invariant latent feature with CLIP loss [7]. It is worth noting that since we cannot fully generate edited images for CLIP loss due to the computational cost, we propose the novel strategy that rather uses latent state of intermediate time step for the efficiency.

To summarize, our contribution is four-fold:

- We devise diffusion video autoencoders based on diffusion autoencoders [22] that decompose the video into a single time-invariant and per-frame time-variant features for temporally consistent editing.
- Based on the decomposed representation of diffusion video autoencoder, face video editing can be conducted by editing only the single time-invariant identity feature and decoding it together with the remaining original features.
- Owing to the nearly-perfect reconstruction ability of diffusion models, our framework can be utilized to edit exceptional cases such that a face is partially occluded by some objects as well as usual cases.
- In addition to the existing predefined attributes editing method, we propose a text-based identity editing method based on the local directional CLIP loss [7, 23] for the intermediate generated product of diffusion video autoencoders.

2. Related Work

Video editing When editing a given real video, it is essential to preserve temporal consistency. First, Lai *et al.* [15] considers editing global features of videos such as artistic style transfer, colorization, image enhancement, etc. To encourage temporal consistency, they train sequential image translator with temporal loss defined as the warping error between the output frames.

Different from this work, our target task is to edit facial attributes of human face video. In other words, we aim to change face-related attributes such as eyeglasses, beard, etc. For this task, Yao *et al.* [39] is the first that propose the editing pipeline: 1) align and crop the target face area, 2) encode these frames to latent features, manipulate and decode them and 3) unalign and paste the edited frames to the original video. However, every step of this pipeline is conducted independently for each frame. For the manipulation step, they try to find disentangled edit directions for a desired attribute and take the same step for every frame, while expecting the disentanglement brings consistency automatically. However, the results show inconsistency and

we conjecture that both latent space and learned direction are still entangled with many other attributes. Next, Tzabari *et al.* [33] additionally fine-tune the pretrained StyleGAN [26] to enhance reconstructability. Meanwhile, they assume that temporal consistency would be preserved when applying the same editing step to the latent features of the original frames. However, their assumption is not always true for all attributes, especially for beard and eyeglasses as shown in Fig. 1. Alaaf *et al.* [2] also try to avoid temporal inconsistency by smoothing latent features.

While the methods in the previous paragraph handle inconsistency implicitly, several works [37, 38] try to solve it more directly. After per-frame editing, Xu *et al.* [38] further optimize latent codes and the pretrained StyleGAN to enhance consistency between the frame pairs defined by involving bi-directional optical flow. On the other hand, Xia *et al.* [37] propose to learn the dynamics of inverted GAN latent codes of video frames. The learned dynamics is used to generate the subsequent latent features after editing only the first frame.

Additionally, although Skorokhodov *et al.* [29] mainly target to generate video, they also demonstrate manipulation results of the generated video. They model the video with a time-invariant content code and per-frame motion codes. Based on this modeling, the generated video can be manipulated with a target text by optimizing its content vector with CLIP loss. However, they cannot edit the real videos due to the absence of an encoding method. In contrast, our proposed method is capable of encoding and manipulating realistic face videos.

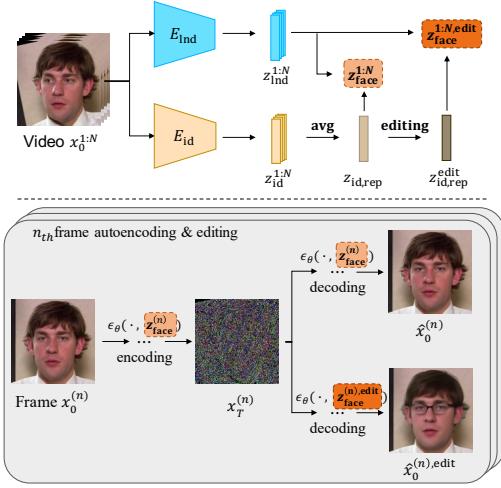
Diffusion models Denoising diffusion probabilistic models (DDPMs) [9] associate image generation with the sequential denoising process of isotropic Gaussian noise. The model is trained to predict the noise from the input image. Unlike other generative models such as GANs and most traditional-style VAEs that encode input data in a low-dimensional space, diffusion models have a latent space that is the same size as the input. Although DDPMs require a lot of feed-forward steps to generate samples, their image fidelity and diversity are superior to other types of generative models. Compared to DDPMs that assume a Markovian noise-injecting forward diffusion process, Denoising diffusion implicit models (DDIMs) [31] assume a non-Markovian forward process that has the same marginal distribution with DDPMs, and use its corresponding reverse denoising process for sampling, which enables acceleration of the rather onerous sampling process of DDPMs. DDIMs also utilize a deterministic forward-backward process and therefore shows nearly-perfect reconstruction ability, which is not the case for DDPMs. In this paper, we adopt conditional DDIMs to encode, manipulate and decode real videos.

Image editing with diffusion models There are various attempts to manipulate images with diffusion models [3, 13, 16, 18, 22, 24] such as text-guided inpainting [3, 18, 24], stroke-based editing [16], and style-transfer [13]. Among those, we are especially interested in facial attribute editing tasks. Kim *et al.* [13] propose text-based image manipulation by optimizing an unconditional diffusion model to minimize local directional CLIP loss [7]. This method is superior to GAN-based methods as it can successfully edit even occluded or overly decorated faces by the excellent reconstruction ability of diffusion models. However, due to the absence of semantically meaningful latent space, there exist some semantic features that are unable to be changed. Another parallel work proposes diffusion autoencoder (DiffAE) [22], which takes a learnable encoder to obtain semantic representations of which the underlying diffusion model is conditioned. The model can perform face attribute manipulation by moving the semantic vector to a target direction. Based on DiffAEs, we design our diffusion video autoencoders to perform temporally-consistent video editing.

3. Preliminaries

Diffusion probabilistic models (DPMs) DPMs [9, 30] are generative models that attempt to approximate the data distribution $q(x_0)$ via $p_\theta(x_0)$ from the reverse prediction of Markovian diffusion process $q(x_{1:T}|x_0) = \prod_{t=1}^T q(x_t|x_{t-1})$. Here, the forward process of DPM is a Gaussian noise perturbation $q(x_t|x_{t-1}) = \mathcal{N}(\sqrt{1-\beta_t}x_{t-1}, \beta_t I)$ where β_t is fixed or learned variance schedule with increasing $\beta_1 < \beta_2 < \dots < \beta_N$, adding gradually increasing noise to data x_0 , and its reverse process is denoising of x_t step by step in reverse order. From this definition, a noisy image x_t at step t can be expressed as $x_t = \sqrt{\alpha_t}x_0 + \sqrt{1-\alpha_t}\epsilon$, $\epsilon \sim \mathcal{N}(0, I)$ where $\alpha_t = \prod_{s=1}^t (1 - \beta_s)$. While the true reverse process $q(x_{t-1}|x_t)$ is intractable, diffusion models approximate $q(x_{t-1}|x_t, x_0)$ with $p_\theta(x_{t-1}|x_t) = \mathcal{N}(\mu_\theta(x_t, t), \sigma_t)$ by minimizing the variational lower bound of negative log-likelihood. Finally, by reparameterizing μ_θ , the objective is given as $\mathbb{E}_{x_0 \sim q(x_0), \epsilon_t \sim \mathcal{N}(0, I), t} \|\epsilon_\theta(x_t, t) - \epsilon_t\|_2^2$ where the parameterized model $\epsilon_\theta(x_t, t)$ estimates the true Gaussian noise term $\frac{1}{\sqrt{1-\alpha_t}}(x_t - \sqrt{\alpha_t}x_0)$ in the forward process.

Speeding up a time-consuming sampling process of diffusion models is one of the core research topics related to diffusion models [19, 31]. Among others, Song *et al.* [31] propose DDIM, which assumes a non-Markovian forward process $q(x_t|x_{t-1}, x_0)$ that has the same marginal distribution $q(x_t|x_0)$ with DDPMs. The corresponding generative process of DDIM is $x_{t-1} = \sqrt{\alpha_{t-1}}f_\theta(x_t, t) + \sqrt{1-\alpha_{t-1}-\sigma_t^2}\epsilon_\theta(x_t, t) + \sigma_t^2 z$ where $z \sim \mathcal{N}(0, I)$, σ is sampling stochasticity and $f_\theta(x_t, t)$, the estimated value of



(a) Video autoencoding and editing pipeline.

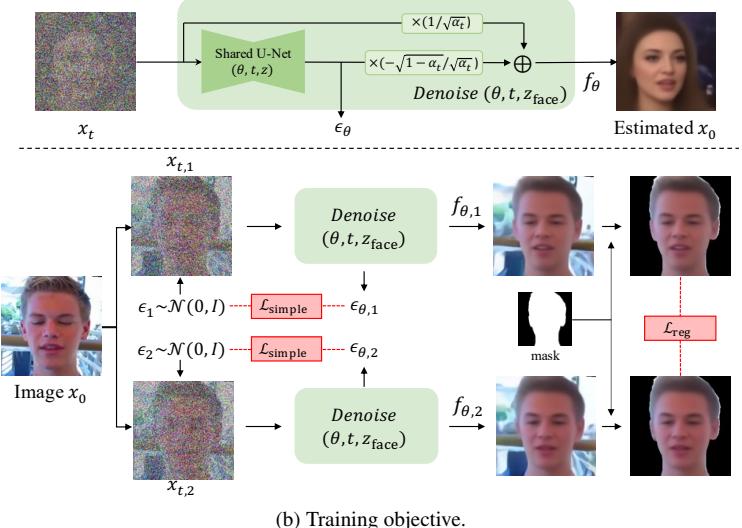


Figure 2. Overview of our Diffusion Video Autoencoder.

x_0 at time step t , is as follow:

$$f_\theta(x_t, t) = \frac{x_t - \sqrt{1 - \alpha_t} \epsilon_\theta(x_t, t)}{\sqrt{\alpha_t}}.$$

When σ is set to 0, this process becomes deterministic. The deterministic forward process can be defined by treating the reverse sampling process as an ordinary differential equation (ODE) and inverse it. With deterministic forward and reverse processes, we can obtain the latent code of each original sample, which can reconstruct the original sample through the reverse process.

Diffusion autoencoders Due to the determinacy of its sampling process, DDIM can reconstruct the original image x_0 from x_T obtained through T forward process steps. While x_T can be considered as a latent state with the same size as x_0 , it does not contain high-level semantic information [22]. To supplement this, Prechakul *et al.* propose diffusion autoencoder (DiffAE) [22] based on DDIM. DiffAE utilizes two forms of latent variables: z_{sem} for the useful high-level semantic representation and x_T for the remaining low-level stochasticity information. DiffAE introduces a semantic encoder $\text{Enc}(x_0)$ which extracts z_{sem} from an image, and makes a noise estimator $\epsilon_\theta(x, t, z_{\text{sem}})$ conditioned on z_{sem} . Stochastic latent x_T is calculated through the deterministic DDIM forward process [31] that involves the noise estimator ϵ_θ given z_{sem} . Then, (z_{sem}, x_T) is decoded to reconstruct the corresponding original image x_0 with $p_\theta(x_{0:T}|z_{\text{sem}}) = p(x_T) \prod_{t=1}^T p_\theta(x_{t-1}|x_t, z_{\text{sem}})$. DiffAE is trained with simple DDPM loss, as done with DDIM. The differences between DiffAE and DDIM are that an additional variable z_{sem} is involved as a conditioning variable

during the reverse process (and thus the training process) and that the noise estimator ϵ_θ and semantic encoder Enc are jointly trained. As a result, through the training phase, z_{sem} is learned to capture the high-level semantic information of the image, and the low-level stochastic variations remain in x_T .

4. Diffusion Video Autoencoders

In this section, we introduce a video autoencoder, called *Diffusion Video Autoencoder*, specially designed for face video editing to have 1) superb reconstruction performance and 2) an editable representation space for the identity feature of the video disentangled with the per-frame features changing over time. The details of the model components and the training procedure are explained in Sec. 4.1 and then two different editing methods based on our model are presented in Sec. 4.2. We provide the overview in Fig. 2.

4.1. Disentangled Video Encoding

To encode the video with N frames $\{x_0^{(n)}\}_{n=1}^N$, we consider the time-invariant feature of human face videos as human identity information, and the time-dependent feature for each frame as motion and background information. Among these three, identity or motion information relevant to a face are appropriate to be projected to a low-dimensional space to extract high-level representation. Comparatively, the background shows high variance with arbitrary details and changes more with the head movement by cropping and aligning the face region. Therefore, it could be very difficult to encode the background information into a high-level semantic space. Thus, identity and motion features are encoded in high-level semantic space $z_{\text{face}}^{(n)}$, com-

bining identity feature z_{id} of the video and motion feature $z_{\text{ind}}^{(n)}$ of each frame, and the background feature is encoded in noise map $x_T^{(n)}$ (see Fig. 2a). We denote z_{id} without superscript (n) for frame index since it is the time-invariant and shared across all frames of the video.

To achieve this decomposition, our model consists of two separated semantic encoders - an ID encoder E_{id} and a landmark encoder E_{ind} - and a conditional noise estimator ϵ_θ for diffusion modeling. The encoded features $(z_{\text{id}}, z_{\text{ind}}^{(n)})$ by the two encoders are concatenated and passed through an MLP to finally get a face-related feature z_{face} . Next, to encode noise map $x_T^{(n)}$, we run the deterministic forward process of DDIM using noise estimator ϵ_θ with conditioned on $z_{\text{face}}^{(n)}$. Since noise map $x_T^{(n)}$ is a spatial variable with the same size as the image, it is expected that information in the background can be encoded more easily without loss of spatial information. Then, the encoded features $(x_T^{(n)}, z_{\text{face}}^{(n)})$ can be reconstructed to the original frame by running generative reverse process of conditional DDIM in a deterministic manner:

$$p_\theta(x_{0:T}|z_{\text{face}}) = p(x_T) \prod_{t=1}^T p_\theta(x_{t-1}|x_t, z_{\text{face}}).$$

To obtain the identity feature disentangled with the motion, we choose to leverage a pretrained model for identity detection, named ArcFace [5]. ArcFace is trained to classify human identity in face images regardless of poses or expressions, so we expect it to provide the disentangled property we need. Nevertheless, when an identity feature is extracted for each frame through the pretrained identity encoder, the feature may be slightly different for each frame because some frames may have partial identity features for some reasons (e.g. excessive side view poses). To alleviate this issue, we average the ID features $z_{\text{id}}^{(n)} = E_{\text{id}}(x_0^{(n)})$ of all frames in the inference phase. Similarly, we obtain per-frame motion information via a pretrained landmark detection model [4] which outputs the position of face landmarks. Several studies [20,34] have shown that it is possible to have a sufficiently disentangled nature by extracting features through a pretrained encoder without learning. Therefore, diffusion video autoencoders extract an identity and also a landmark feature of the image through the pretrained encoders and map them together to the high-level semantic space for face features through an additional learnable MLP.

Next, we explain how the learnable part of our model is trained. Fig. 2b summarizes our training process. For simplicity, from now on, we drop the superscript of frame index. Our objective consists of two parts. The first one is the simple version of DDPM loss [9] as

$$\mathcal{L}_{\text{simple}} = \mathbb{E}_{x_0 \sim q(x_0), \epsilon_t \sim \mathcal{N}(0, I), t} \|\epsilon_\theta(x_t, t, z_{\text{face}}) - \epsilon_t\|_1$$

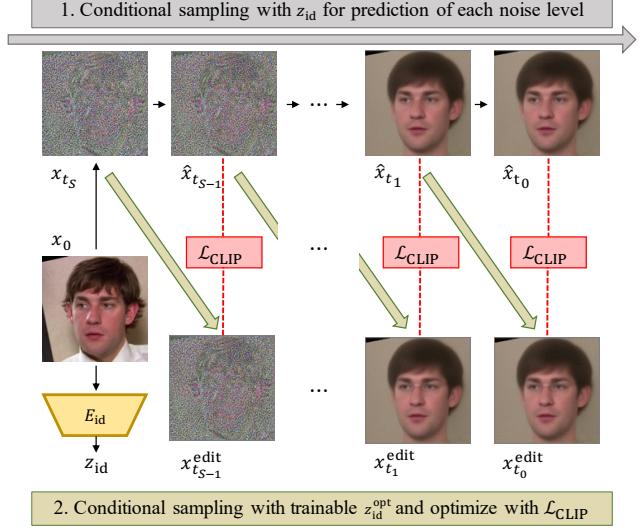


Figure 3. Process of computing noisy CLIP loss.

where z_{face} is an encoded high-level feature of input image x_0 . It encourages the useful information of the image to be well contained in the semantic latent z_{face} and exploited by ϵ_θ for denoising. Secondly, we devise a regularization loss to hinder face information (identity and motion) from leaking to x_T but contained in z_{face} as much as possible for clear decomposition between background and face information. If some face information is lost in z_{face} , the lost information would remain in the noise latent x_T unintentionally. To avoid it, we sample two different Gaussian noises ϵ_1 and ϵ_2 to obtain different noisy samples $x_{t,1}$ and $x_{t,2}$ respectively. Then, we minimize the difference between the estimated original images $f_{\theta,1}$ and $f_{\theta,2}$ except the background part as:

$$\mathcal{L}_{\text{reg}} = \mathbb{E}_{x_0 \sim q(x_0), \epsilon_1, \epsilon_2 \sim \mathcal{N}(0, I), t} \|f_{\theta,1} \odot m - f_{\theta,2} \odot m\|_1$$

where m is a segmentation mask of a face region in the original image x_0 and $f_{\theta,i} = f_\theta(x_{t,i}, t, z_{\text{face}})$. As a result, the effect of noise in x_t on the face region will be reduced and z_{face} will be responsible for face features for the generation (See Fig. 7). In other words, the facial features are encouraged to be contained in the high-level semantic latent z_{face} as much as possible. In Sec. 5.5, we demonstrate the desired effect of \mathcal{L}_{reg} . The final loss of diffusion video autoencoders is as follows: $\mathcal{L}_{\text{dva}} = \mathcal{L}_{\text{simple}} + \mathcal{L}_{\text{reg}}$.

4.2. Video Editing Framework

We now describe our video editing framework with our diffusion video autoencoders. First, all video frames $\{I_n\}_{n=1}^N$ are aligned and cropped for interesting face regions as in [33]. The cropped frames $\{x_0^{(n)}\}_{n=1}^N$ are then encoded to latent features using our diffusion video autoencoder. To extract the representative identity feature of the

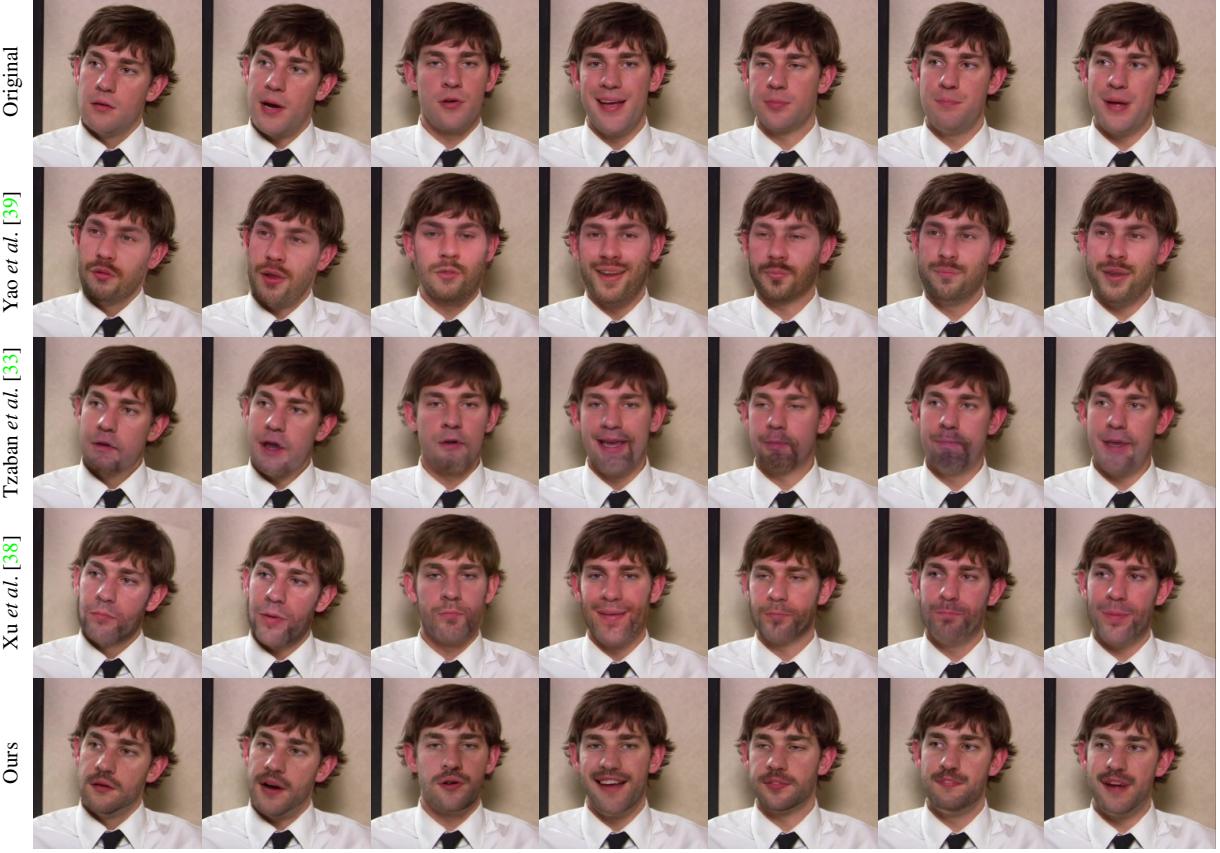


Figure 4. Comparison of temporal consistency to the previous video editing methods for ‘beard’.

video, we average ID features of each frame as

$$z_{\text{id}, \text{rep}} = \frac{1}{N} \sum_{n=1}^N (z_{\text{id}}^{(n)}),$$

where $z_{\text{id}}^{(n)} = E_{\text{id}}(x_0^{(n)})$. Similarly, the per-frame landmark feature is computed as $z_{\text{lnd}}^{(n)} = E_{\text{lnd}}(x_0^{(n)})$ to finally obtain per-frame face features $z_{\text{face}}^{(n)} = \text{MLP}(z_{\text{id}, \text{rep}}, z_{\text{lnd}}^{(n)})$. After that, we compute $x_T^{(n)}$ with DDIM forward process conditioning $z_{\text{face}}^{(n)}$. Thereafter, manipulation is conducted by editing $z_{\text{id}, \text{rep}}$ to $z_{\text{id}, \text{rep}}^{\text{edit}}$ using a pretrained linear attribute-classifier of the ID space or text-based optimization which we will discuss in more detail later. After modifying the representative identity feature $z_{\text{id}, \text{rep}}^{\text{edit}}$, the edited frame $x_0^{(n), \text{edit}}$ is generated by the conditional reverse process with $(z_{\text{face}}^{(n), \text{edit}}, x_T^{(n)})$ where $z_{\text{face}}^{(n), \text{edit}} = \text{MLP}(z_{\text{id}, \text{rep}}^{\text{edit}}, z_{\text{lnd}}^{(n)})$. Afterward, as with all previous work, the face part of the edited frame is pasted to the corresponding area of the original frame to create a clean final result. For this process, we segment face regions using a pretrained segmentation network [40].

Below, we explore two editing methods for our video

editing framework.

Classifier-based editing First, as in DiffAE [22], we train a linear classifier $C_{\text{attr}}(z_{\text{id}}) = \text{sigmoid}(w_{\text{attr}}^{\top} z_{\text{id}})$ for each attribute attr on CelebA-HQ’s [11] with its attribute annotation in the identity feature space. To change attr , we move the identity feature z_{id} to $\ell_2\text{Norm}(z_{\text{id}} + sw_{\text{attr}})$ with a scale hyperparameter s .

CLIP-based editing Since the pretrained classifier allows editing only for several pre-defined attributes, we additionally devise the CLIP-guidance identity feature optimization method. Directional CLIP loss [7] requires two images corresponding to one for neutral text and one for target text, respectively. It implies that we need the synthesized images with our diffusion model, which is costly with full generative process. Therefore, to reduce the computational cost, we use the drastically reduced number of steps S ($\ll T$) for image sampling. In other words, we consider the time steps t_1, t_2, \dots, t_S where $0 = t_0 < t_1 < \dots < t_S \leq T$ and evenly split T . Thereafter, we compute x_{t_S} from the given image x_0 that we want to edit (normally chosen as the first frame $x_0^{(1)}$ of the video) through S -step of forward

Table 1. **Quantitative reconstruction results** on the randomly chosen 20 videos in VoxCeleb1 testset. The reported values are the mean of the averaged per-frame measurements for each video.

Method	SSIM \uparrow	MS-SSIM \uparrow	LPIPS \downarrow	MSE \downarrow
e4e [32]	0.509	0.761	0.157	0.037
PTI [26]	0.765	0.939	0.063	0.007
Ours ($T = 20$)	0.540	0.905	0.228	0.016
Ours ($T = 100$)	0.922	0.989	0.045	0.002

process with $z_{\text{id}} = E_{\text{id}}(x_0)$. Through the sequential reverse steps from x_{t_s} , we recover \hat{x}_{t_s} for each time t_s where $s = (S - 1), \dots, 0$ with the original z_{id} . Meanwhile, $x_{t_s}^{\text{edit}}$ are obtained by the single reverse step from $\hat{x}_{t_{s+1}}$ but with variable $z_{\text{id}}^{\text{opt}}$ being optimized initialized to z_{id} (See Fig. 3). Finally, we minimize the directional CLIP loss [7] between intermediate images \hat{x}_{t_s} and $x_{t_s}^{\text{edit}}$, which are still noisy, for all s with a neutral (e.g. “face”) and a target text (e.g. “face with eyeglasses”). We choose intermediate images $x_{t_s}^{\text{edit}}$, \hat{x}_{t_s} from $\hat{x}_{t_{s+1}}$ instead of estimated x_0 to compute CLIP loss because to estimate x_0 directly from x_{t_s} is incomplete and erroneous for large t_s . Therefore, we expect that conservatively choosing $x_{t_{s-1}}$ instead of the estimate x_0 will help to find the edit direction more reliably. We refer the reader to Supplementary for the ablation study of our noisy CLIP loss. In addition to the CLIP loss, to preserve the remaining attributes, we also use ID loss (cosine distance between z_{id} and $z_{\text{id}}^{\text{opt}}$) and ℓ_1 loss between \hat{x}_{t_s} and $x_{t_s}^{\text{edit}}$ for all s . After all, the learned editing step $\Delta z_{\text{id}} = z_{\text{id}}^{\text{opt}} - z_{\text{id}}$ is applied to $z_{\text{id}, \text{rep}}$ for final video editing.

5. Experiments

In this section, we present the experimental results to confirm reconstruction performance (Sec. 5.1), temporally consistent editing ability (Sec. 5.2), robustness to the unusual samples (Sec. 5.3), and disentanglement of the encoded features (Sec. 5.4) with further ablation study (Sec. 5.5). For this purpose, we train our diffusion video autoencoder on 77294 videos of the VoxCeleb1 dataset [17]. As preprocessing, frames of the video are aligned and cropped as in [33] like the FFHQ dataset. Next, they are resized to the size of 256^2 . For the noise estimator ϵ_θ , the UNet improved by [19] is used, and we train diffusion video autoencoder for 1 million steps with a batch size of 16.

5.1. Reconstruction

For video editing, the ability to reconstruct the original video from the encoded one must be preceded. Otherwise, we will lose the original one before we even edit the video. To compare this ability with baselines quantitatively, we measure frequently used metrics for reconstruction - SSIM [35], Multi-scaled (MS) SSIM [36], LPIPS [41] and MSE - on randomly selected 20 videos in the testset of VoxCeleb1.

Table 2. **Quantitative results** to evaluate temporal consistency. TL-ID and TG-ID imply local consistency between adjacent frames and global consistency across all frames, respectively, in terms of identity. Ours show the best global coherency and comparable local consistency to the baselines.

Method	TL-ID	TG-ID
Yao <i>et al.</i> [39]	0.989	0.920
Tzaban <i>et al.</i> [33]	0.997	0.961
Xu <i>et al.</i> [38]	1.002	0.983
Ours	0.995	0.996

As baselines, we compared our model with the GAN-based inversion method e4e [32] and PTI [26] used by Yao *et al.* [39], Tzaban *et al.* [33] respectively. For PTI, the implementation of Tzaban *et al.* [33] are used with its default hyperparameters. Since StyleGAN-based methods handle the higher resolution images with the size of 1024^2 , we resize the reconstructed results to 256^2 for comparison. For our method, we vary the number of timesteps T of the reverse and the forward process to observe computational cost and image quality trade-offs. In table Tab. 1, our diffusion video autoencoder with $T = 100$ shows the best reconstruction ability and still outperforms e4e with only $T = 20$.

5.2. Temporal Consistency

In Fig. 4, a visual comparison is conducted to evaluate the video editing performance of our diffusion video autoencoder qualitatively. We edit the given video to generate a beard through text-based guidance except for Yao *et al.* [39], which only allows to edit pre-defined attributes, by moving to the opposite direction of “no_beard”. As a result, we demonstrate that only our diffusion video autoencoder successfully produces the consistent result. Specifically, Yao *et al.* [39] fails to preserve the original identity due to the limitations of GAN inversion. In the result of Tzaban *et al.* [33] the shape and the amount of beard constantly changes according to the lip motion. Although Xu *et al.* [38] shows better but not perfect consistency, the motions unintentionally changes as a side-effect. The inconsistency can be observed more clearly between the second and the fifth column except for ours showing the reliable result.

Furthermore, we quantitatively evaluate the temporal consistency of Fig. 4 in Tab. 2. Although there is no perfect metric for temporal consistency of videos, TL-ID and TG-ID [33] imply the local and global consistency of identity between intra-video frames compared to the original. These metrics can be interpreted as being consistent as the original is when their values are close to 1. We emphasize that we greatly improve global consistency. TL-ID of Xu *et al.* [38] is larger than 1 because the motion of the editing results shrink so that the adjacent frames become closer to each other than the original.



Figure 5. Editing wild face videos that GAN-based prior works struggled with. Classifier-based editing is used to make the person "young" (up) or change a "gender" (below).



Figure 6. Demonstration of the disentangled video encoding.

5.3. Editing Wild Face Videos

Owing to the reconstructability of diffusion models, editing wild videos that are difficult to inversion by GAN-based methods becomes possible. As shown in Fig. 5, unlike others, our method robustly reconstructs and edits the given images effectively.

5.4. Decomposed Features Analysis

To demonstrate whether the diffusion video autoencoder decomposes the features adequately, we examine the synthesized images by changing each element of the decomposed features. To this end, we encode the frames of two different videos and then generate samples with a random noise or exchange the respective elements with each other in Fig. 6. When we decode the semantic latent z_{face} with a Gaussian noise instead of the original noise latent x_T , it has a blurry



Figure 7. Ablation of using regularization loss for training. Regularization loss helps the model to contain identity and motion information in z_{face} as much as possible.

background that is different from the original one, while identity and head pose are preserved considerably. This result implies that x_T contains only the background information, as we intended. Moreover, the generated images with switched identity, motion, and background feature confirm that the features are properly decomposed and the diffusion video autoencoder can produce a realistic image even with the new combination of the features. However, with extreme changes in the head position, the background occluded by the face is not properly generated because the taken x_T has no information about background in that area (See the last column of the lower example in Fig. 6).

5.5. Ablation Study

We further conduct an ablation study on our proposed regularization loss \mathcal{L}_{reg} . First, we train the model with the same setting but ablating \mathcal{L}_{reg} . As shown in Fig. 7, neither model has a problem with reconstruction. However, without the regularization loss, the identity changes significantly according to the random noise. Thus we can conclude that the regularization loss helps the model to decompose features effectively.

6. Conclusions

To tackle the temporal consistency problem in editing human face video, we have proposed a novel framework with the newly designed video diffusion autoencoder which encodes the identity, motion, and background information in a disentangled manner and decodes after editing a single identity feature. Through the disentanglement, the most valuable strength of our framework is that we can search the desired editing direction for only one frame and then edit

the remaining frames with temporal consistency by moving the representative video identity feature. Additionally, the wild face video can be reliably edited by the advantage of the diffusion model that is superior in reconstruction to GAN. Finally, we have explored to optimize the semantic identity feature with CLIP loss for text-based video editing.

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A. Detailed Experimental Settings

A.1. Architecture

We use the model based on the improved version of DDIM [19]. We use linear beta scheduling for β_t from 0.0001 to 0.02 with $T = 1000$. This model has UNet structure with the blocks that consist of the residual and the attention blocks. With the number of base channels as 128, the number of channels are multiplied by $[1, 1, 2, 2, 4, 4]$ for each block in down sampling layers respectively and spatial size is down-scaled by half. It is reversed in the up-sampling layers. Attention resolution is [16]. The dimension of z_{face} is 512. Time is first embedded into 128 dimensional vector by positional encoding and projected to 512 dimensional vector using a 2-layer MLP with SiLU activation. In each residual block, the time embedding for diffusion modeling and the face feature z_{face} are first transformed by their corresponding SiLU-Linear layers respectively and these conditions are applied by AdaGN. In more detail, after the input of the residual block is passed to GroupNorm(32)-SiLU-Conv3x3-GroupNorm(32), each channel is scaled and shifted using time embedding. Similarly, after SiLU-Conv3x3-GroupNorm(32), channels are scaled and shifted by the transformed z_{face} . Final block output is obtained after SiLU-Dropout-Conv3x3 following skip connection of the block input. We refer the readers to the implementation code for more details.

A.2. Training Configuration

We optimize the learnable parameters jointly on 77294 videos of VoxCeleb1 dataset [17]. The videos are aligned and cropped for interesting face regions as in Tzaban *et al.* [33]. We use 4 GPUs and Adam optimizer [14] with the learning rate of 1e-4. Total training steps are 1 million and 4 frames per video so the total of 16 frames for 4 videos are taken for a single training step.

A.3. Manipulation

Classifier-based editing The linear classifiers C_{attr} are trained on CelebA-HQ with attribute annotations in the normalized identity feature space. The classifier is optimized for 10 epochs with the batch size of 32 with a learning rate of 1e-3. Before taken by the classifier, ID features are normalized by the mean and standard deviation of ID features of all samples in VoxCeleb1 testset. Therefore, normalization and denormalization are conducted before and after the ID features are moved by the desired direction w_{attr} as $\ell_2\text{Norm}(\text{DeNorm}(\text{Norm}(z_{\text{id}}) + sw_{\text{attr}}))$ where s is the hyperparameter for the editing step size, Norm/DeNorm is normalizing and denormalizing function with the statistics of ID features respectively, and $\ell_2\text{Norm}$ is the normalization function that makes the ℓ_2 norm of vectors equal to 1. We use ℓ_2 normalization because E_{id} outputs vectors after

normalizing their size to 1.

CLIP-based editing For CLIP-based editing, we use ViT-B/16 among different CLIP architectures. We optimize a ID feature of a single selected frame (usually the first frame of the video) with the Adam optimizer to minimize the CLIP loss. We consider $S = 5$ for the number of intermediate latent states. After conduction optimization, the learned editing direction Δz_{id} multiplied by the editing step size is added to the representative identity feature of the video $z_{\text{id}, \text{rep}}$. The final edited feature is obtained by applying $\ell_2\text{Norm}$. The search spaces of remaining hyperparameters are provided in Tab. 3.

Table 3. Hyperparameter search space

Parameter	Search space
learning rate	[2e-3, 4e-3, 6e-3]
Weight of CLIP loss	[3]
Weight of ID loss	[1, 3, 5]
Weight of ℓ_1	[1, 3, 5]
Editing step size	[0.1, 0.5, 1.0, 1.5, 2.0, 2.5]
Optimization steps	[2000]

B. Ablation of Noisy CLIP Loss

In this section, we conduct ablation study of our noisy CLIP loss introduced in Sec. 4.2. We compare our CLIP-based editing method using noisy CLIP loss (See Fig. 3) with the way that uses estimated x_0 conditioned by $z_{\text{id}}^{\text{opt}}$ as the target image and the original x_0 as the neutral image for each time step t_s to compute the directional CLIP loss, which is similar to the method suggested by Kim *et al.* [13]. The results are presented in Fig. 8. For fair comparison, we use the same weights for ℓ_1 loss and ID loss.

To help readers understand, we first briefly explain the directional CLIP loss [7] and DiffusionCLIP [13] before we address the ablation results. The directional CLIP loss compares the direction from neutral image embedding to target image embedding with the direction from neutral text embedding to target text embedding in the CLIP space to edit the target image to match the target text. Kim *et al.* [13] propose an image manipulation method, named DiffusionCLIP, that optimize the unconditional diffusion model ϵ_θ with the directional CLIP loss [7]. To preserve the original images to some extent, Kim *et al.* [13] consider the latent states of the original images in not the whole but just a partial range such as $[0, T/2]$ obtained by sparsely passing though the range with the deterministic forward process of DDIM. In the GPU-efficient version of DiffusionCLIP, they take a estimated x_0 from the latent states in considered intermediate time steps as the target images and compare them with the clean original image x_0 as the neutral image.

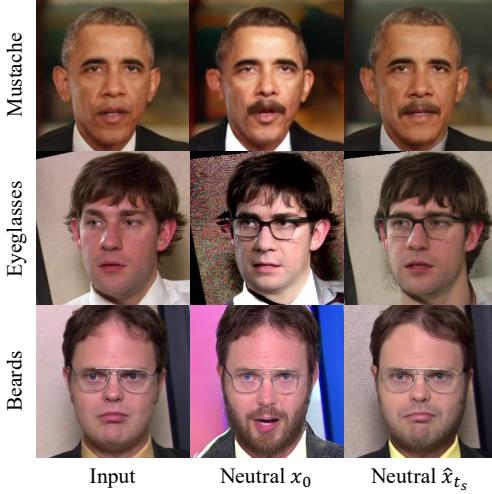


Figure 8. Ablation of using clean image x_0 or intermediate noisy image \hat{x}_{t_s} for a neutral image in directional CLIP loss. As the target image, the former uses estimated x_0 at the intermediate time step like [13] and the latter uses $x_{t_s}^{\text{edit}}$.

Going back to the ablation study, unlike Kim *et al.* [13], we consider the entire range $[0, T]$ to start conditional sampling from the noise that only has background information and split the range in total S steps (*e.g.* $S = 5$) for computational efficiency. In this case, applying CLIP loss between the original image (neutral) and the estimated x_0 (target) makes identity to be altered as in the second column of Fig. 8 because the difference between the estimated x_0 at time t and the clean image x_0 becomes larger as t goes larger. To overcome this phenomenon, we apply CLIP loss between the intermediate outputs \hat{x}_{t_s} (conditioned on original z_{id} for the neutral images) and $x_{t_s}^{\text{edit}}$ (conditioned on trainable $z_{\text{id}}^{\text{opt}}$ for the target images). In the last column of Fig. 8, the original identity is well preserved with the desired features edited properly. From these results, we conclude that applying the CLIP loss between the images on the same level of uncertainty like our method leads relatively stable editing results.

C. More Editing Results

We show additional video editing results with classifier-based editing in Figs. 9 and 10 and CLIP-based editing in Figs. 11 and 12. These results demonstrate that our video editing method has temporal consistency for other attributes as well.

D. Comparison

We attach the video file ‘Comparison_video.mov’ Fig. 4 in the zip file. In the video, the result of Yao *et al.* [39] shows altered identity, the result of Tzaban *et al.* [33] shows

temporal inconsistency that beard fades away as the mouth opens, and the result of Xu *et al.* [38] shows unnatural movements with the mouth not opening as much as the original and inconsistency of the beard. On the other hand, ours demonstrates much improvement in terms of the temporal consistency and identity preservation.

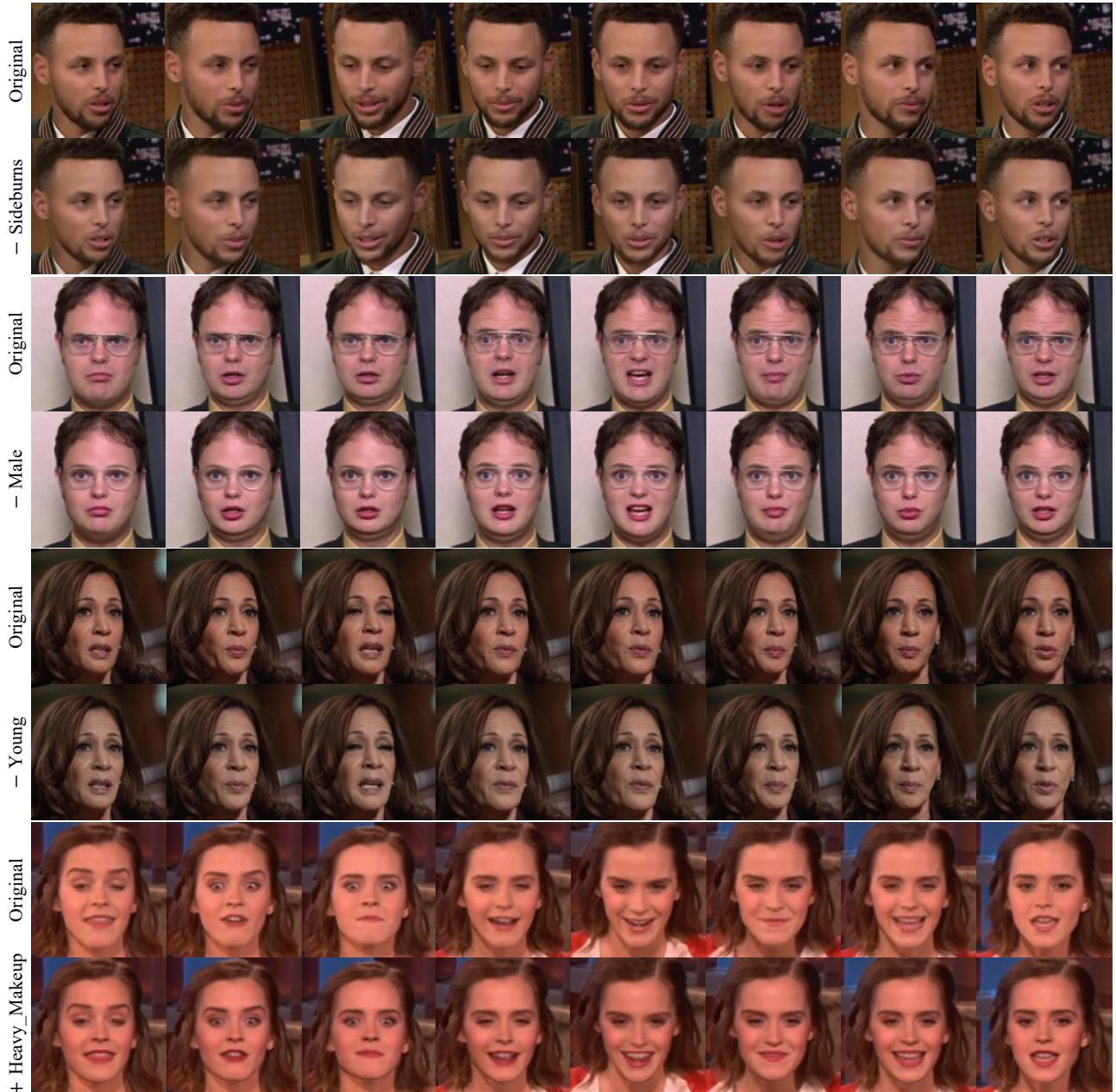


Figure 9. Classifier-based video editing on the other videos not in VoxCeleb1.

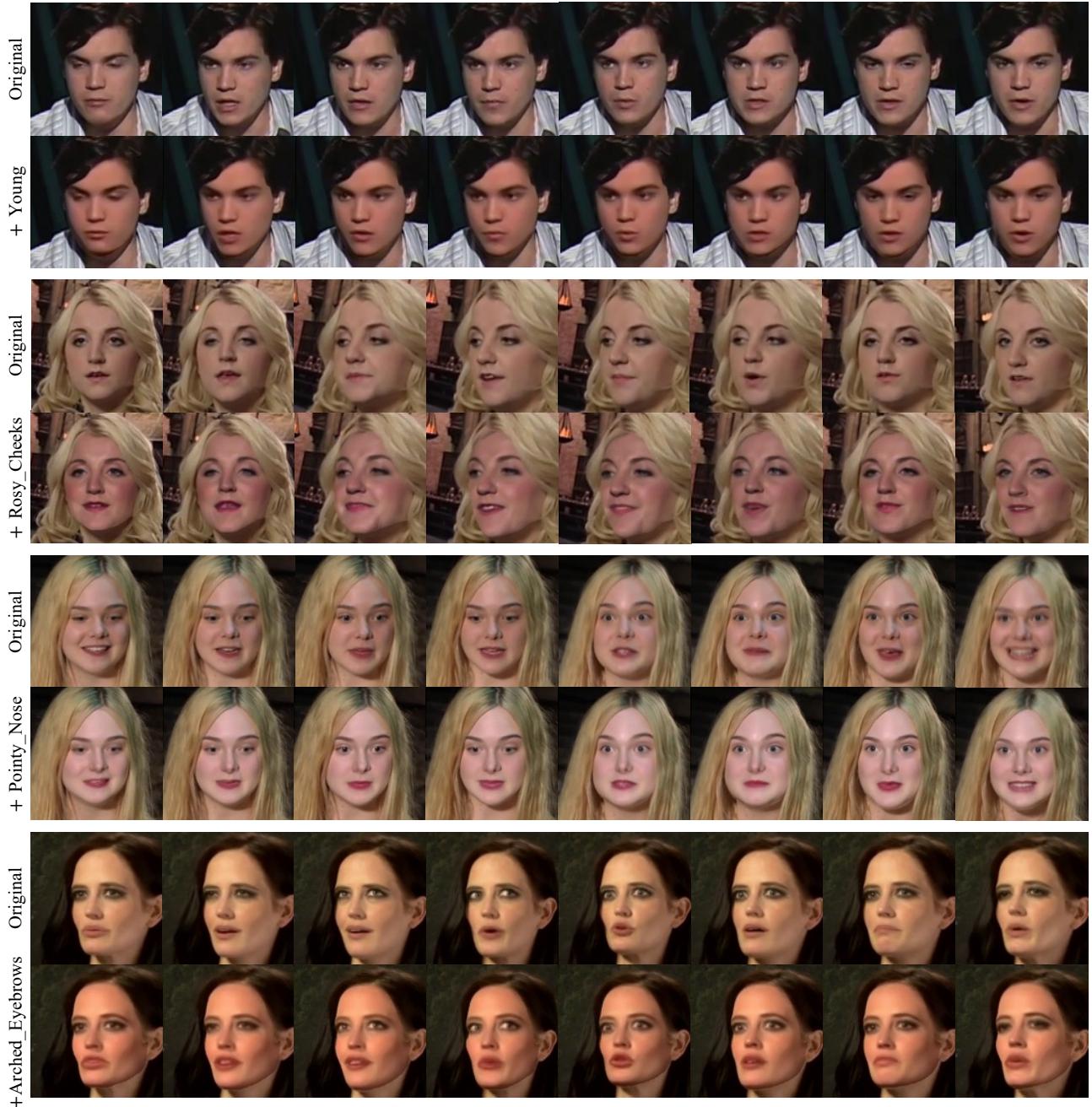


Figure 10. Classifier-based video editing on VoxCeleb1 testset.



Figure 11. CLIP-based video editing on the other videos not in VoxCeleb1.



Figure 12. CLIP-based video editing on VoxCeleb1 testset.