

Elliptic Curve Digital Signature Algorithm

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Public Key Cryptography

- ▶ Two keys (called a keypair)
 - ▶ Public: the whole world can know this
 - ▶ Private: only the owner knows this
- ▶ Four operations
 - ▶ $\text{Sign}(\text{Message}, \text{Private}) \rightarrow \text{Signature}$
 - ▶ $\text{Verify}(\text{Message}, \text{Signature}, \text{Public}) \rightarrow \text{Boolean}$
 - ▶ $\text{Encrypt}(\text{Message}, \text{Public}) \rightarrow \text{Cyphertext}$
 - ▶ $\text{Decrypt}(\text{Cyphertext}, \text{Private}) \rightarrow \text{Message}$
- ▶ ECDSA is a widely-used (SSH, SSL/TLS) signature algorithm
 - ▶ Supports Sign and Verify

Cryptography and the Swarm

- ▶ Original motivation: the universal dataplane
 - ▶ Storage component of SwarmOS
 - ▶ Large network (10^{10} nodes)
 - ▶ Many low power sensors (μW)
 - ▶ Some high power servers
- ▶ Goal: all storage is fault-tolerant
 - ▶ Byzantine fault tolerance algorithm
 - ▶ Sign every message on the sensors
- ▶ Problem: ECDSA is **mJ** per signature!

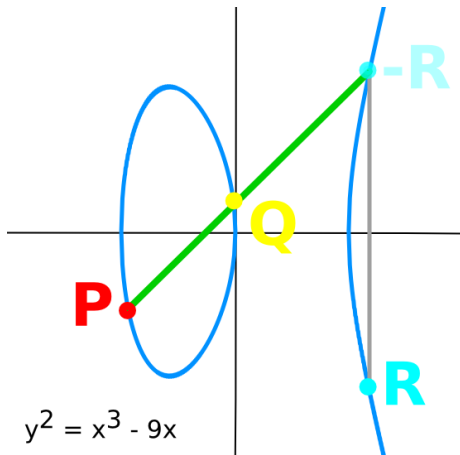
The Discrete Logarithm Problem

- ▶ $b^k = g$
 - ▶ Difficult in one direction (given b and g find k)
 - ▶ Easy in another direction (given b and k find g)
- ▶ At the center of many public-key crypto schemes
- ▶ Only asymmetric for some groups
 - ▶ $(\mathbb{Z}_p)^\times$: Integers modulo some prime, repeating multiplication
 - ▶ $GF(p)$: Elliptic curves modulo some prime, repeating addition
- ▶ Integer fields have a sub-linear algorithm

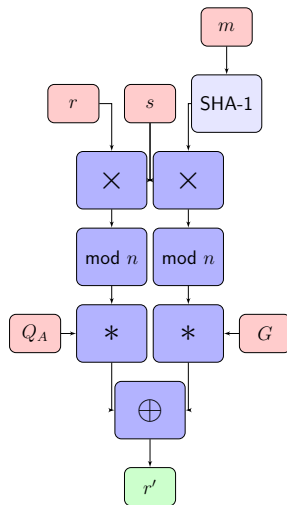
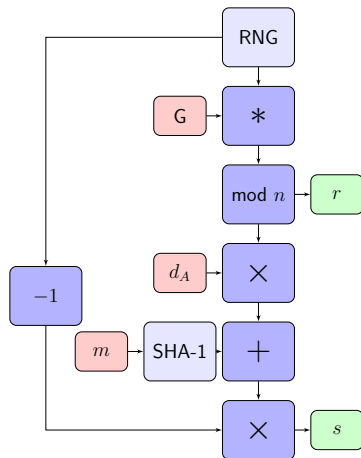
Security Level	DSA	ECDSA	Ratio
80	1024	160	3:1
112	2048	224	6:1
128	3072	256	10:1
192	7680	384	32:1
256	15360	512	64:1

Elliptic Curve Cryptography

- ▶ Elliptic curve: the set of points that satisfy $y^2 = x^3 + ax + b$
 - ▶ Need a finite field \rightarrow everything's modular
 - ▶ Needs to be difficult \rightarrow modulo a large number
- ▶ Add and multiply defined to satisfy a field



ECDSA



Point Operations

- ▶ ECDSA is essentially point multiply and some cleanup
 - ▶ Point Multiply: O(million) cycles
 - ▶ Cleanup: O(thousand) cycles
- ▶ Point multiplication is defined as repeated point doubling
- ▶ Point doubling is defined as

$$\left(\frac{(3P_x^2 + a)}{(2P_y)} - P_x \right)^2 * \left(\frac{(3P_x^2 + a)}{(2P_y)} \right) - P_y$$

- ▶ Simplifies to 5 modular multiplies and one modular divide
 - ▶ Modular operations are modulo a large (O(256-bit)) number

The Design Space

- ▶ A whole bunch of math
 - ▶ Data types: Points, Modular integers, and integers
 - ▶ Arithmetic operations: Add, Subtract, Multiply, Invert
- ▶ Everything boils down to integer arithmetic and control logic
 - ▶ What should be in software, what should be in hardware?
- ▶ Unfortunately, it's too big!
 - ▶ 2^{12} software configurations!

Hardware-Software Cotuning

- ▶ OpenSSL is the industry standard, but it's difficult to hack on
- ▶ Wrote our own ECDSA implementation in C++
- ▶ Generates software for a family of ECDSA accelerators

```
palmer palmer-caldesktop rocket-ecc $ time make check | tail -n0
real    12m1.390s
user    63m20.796s
sys     7m37.179s
```

```
palmer palmer-caldesktop rocket-ecc $ ptest | tail -n4
NRUN    6895
NPASS   6895
NFAIL   0
NEROR   0
```

The (Reduced) Design Space

Point Multiplication

- ▶ Control logic
- ▶ Point Addition
 - ▶ Control logic
 - ▶ Modular multiply
 - ▶ Control logic
 - ▶ Integer shifts, adds
- ▶ Modular inverse
 - ▶ Control logic
 - ▶ Integer shifts, adds

- ▶ Two interesting hardware configurations
 - ▶ Point multiply hardware block
 - ▶ Modular multiply, inverse hardware blocks

Results

Platform	Power mJ/op	Speed op/sec	Area mm ²
OpenSSL (45nm)	20	1000	
x86 (45 nm)	4000	5	
Rocket	800	0.05	
Virtex 2 (90nm)	4000	250	
Virtex 6 (45nm)	500	4000	
Mod Mul	200	0.3	0.04
Mod Mul+Div	2	20	0.10
Point Add+DbI	0.5	100	0.31
Point Mul	0.06	400	0.35

Future Work

- ▶ Time-space tradeoffs
 - ▶ Montgomery multipliers
 - ▶ Projective point representation
- ▶ Parallel software, multiple signatures in flight
- ▶ Hard-coded curve parameters
- ▶ 300MHz clock