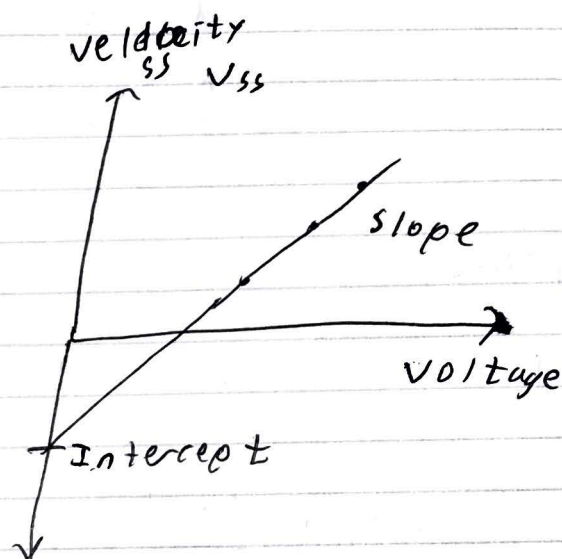
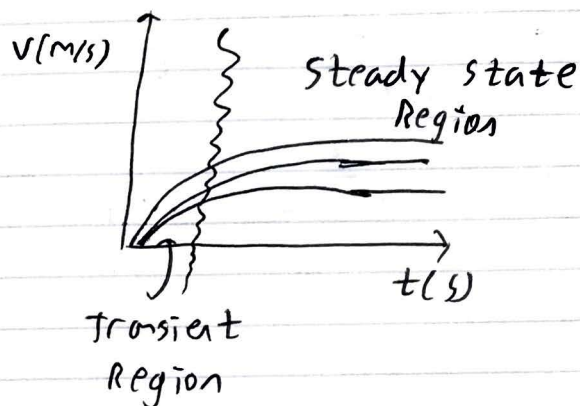


### Train Data



### Mechanical Model

$$C_i - \frac{\mu_k mg r_w}{\delta} = I_{eq} \left( \frac{a}{r_w} \right)$$

Annotations for the equation above:

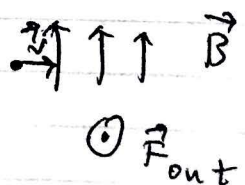
- $C_i$ : current constant
- $\mu_k$ : constant
- $m$ : mass
- $g$ : gravity
- $r_w$ : wheel radius
- $\delta$ : distance
- $I_{eq}$ : equivalent current
- $a$ : acceleration
- $r_w$ : wheel radius
- $K_v$ : constant
- $v$ : vel of train

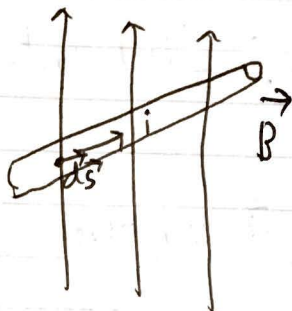
### Electrical Model

Force on a charge in  $\vec{E}$   
 $F = q\vec{E}$

- moving charges experience a force in a magnetic field

$$\vec{F} = q[\vec{v} \times \vec{B}]$$



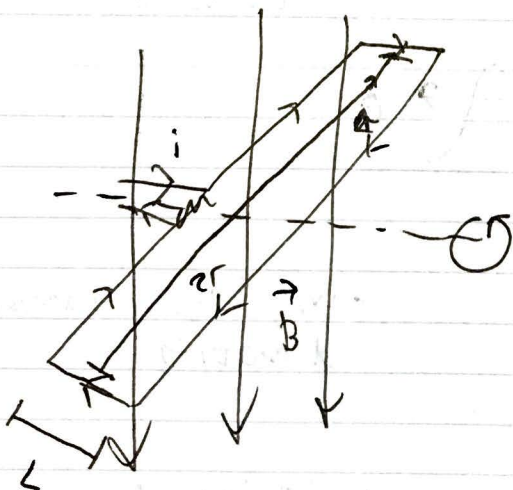
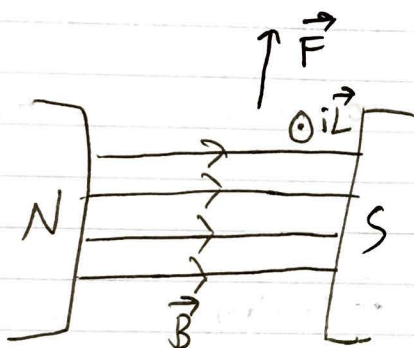


$$\vec{F} = q \frac{d\vec{s}}{dt} \times \vec{B}$$

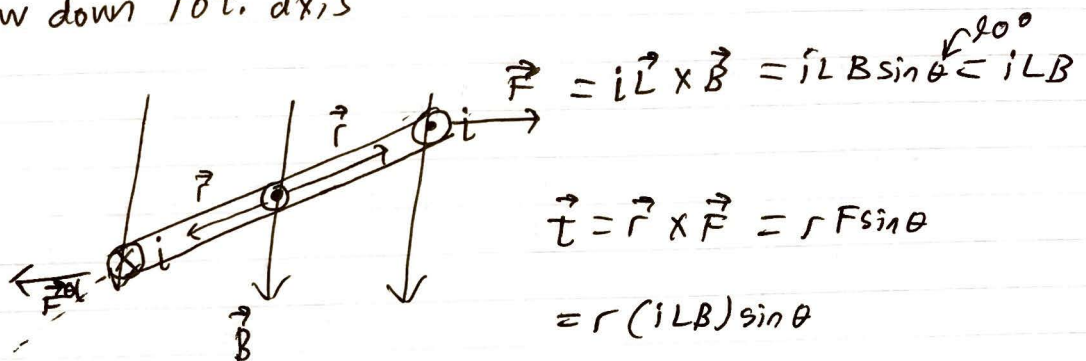
$$\vec{F} = i \vec{L} \times \vec{B}$$

external in  
all cases

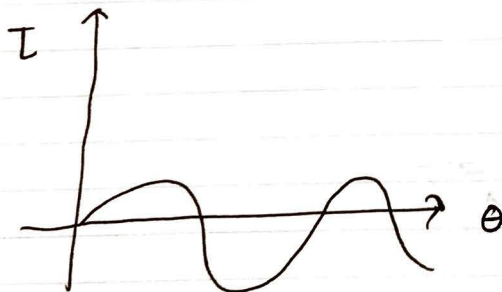
- Force on a current-carrying wire in an external magnetic field



Redraw down rot. axis



- Current will change direction to create a constant rotation ~~turn~~ in motor



- w/o changing current direction

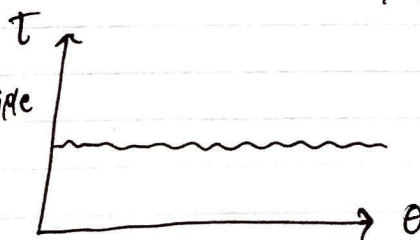


- w/ changing current direction

Looking down coil



- w/ multiple coils



$$\vec{T}_{\text{motor}} = 2r i L B \sin \theta$$

$\uparrow \quad \uparrow$   
 Area

$$\vec{T}_{\text{motor}} = i A B [\sin \theta]_{\text{avg}}$$

$$T_m = C i$$

$\uparrow$   
 Constant =  $AB [\sin \theta]_{\text{avg}}$

$$V = i R$$

$R =$  resistance of train and track

$$T_m = \frac{C V}{R}$$

Motion of Train

$$\frac{C V}{R} - K V - \frac{\mu_K m g r_w}{\gamma} = \frac{I_{\text{eq}}}{r_w} a$$

$$\frac{C V}{R K} - V - \frac{\mu_K m g r_w}{\gamma K} = \frac{I_{\text{eq}}}{r_w K} \left( \frac{dV}{dt} \right)$$

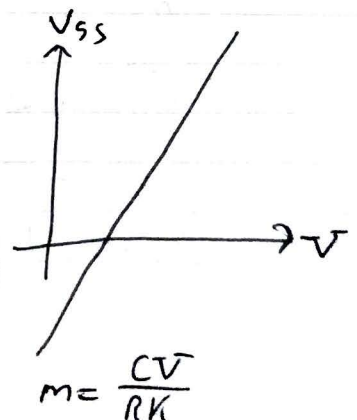
General Motion of Train Eqn

steady State

$$\frac{C V}{R K} - V - \frac{\mu_K m g r_w}{\gamma K} = 0$$

$$V_{ss} = \frac{C V}{R K} - \frac{\mu_K m g r_w}{\gamma K}$$

Intercept



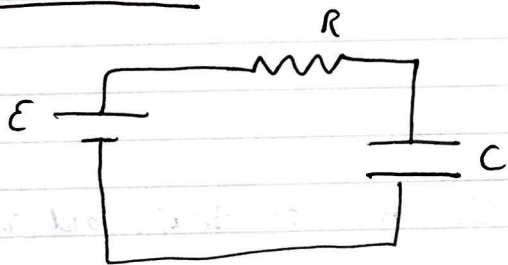
$$B - V = A \frac{dV}{dt}$$

$\overset{\text{m/s}}{B} - \overset{\text{m/s}}{V} = \overset{\text{s}}{A} \frac{\overset{\text{m/s}}{dV}}{\overset{\text{m/s}}{dt}}$   
 const.

$$B = \frac{C}{RK}$$

$$A \neq RC$$

RC Circuit



$$E - \frac{dq}{dt} R - \frac{q}{C} = 0$$

$$EC - \frac{dq}{dt} [RC] - q = 0$$

Time constant

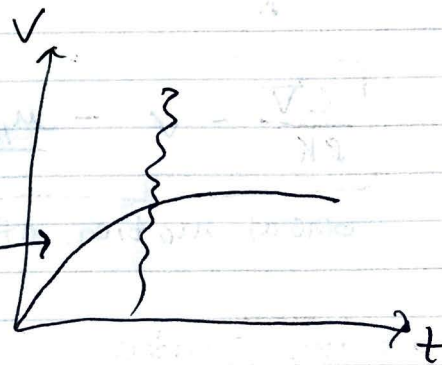
$$\int \frac{-dt}{A} = \int \frac{dV}{V-B} \quad // \quad \begin{aligned} \text{Let } u &= V-B \\ du &= dV \end{aligned}$$

$$\frac{-t}{A} = \int \frac{du}{u}$$

$$\frac{-t}{A} = \ln \left( \frac{V-B}{0-B} \right)$$

$$e^{-t/A} = \frac{V(t)-B}{0-B}$$

$$\boxed{V(t) = B(1 - e^{-t/A})}$$





$$\frac{-t}{A} = \ln\left(\frac{V(t) - B}{0 - B}\right)$$

$$\ln\left(\frac{V(t) - B}{0 - B}\right) = -\frac{1}{A} t$$

$$B = V_{ss}$$