Energy-based models (EBM), part 1

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- Reminder: estimation of statistical models
- Definition of energy-based models (= unnormalized statistical models)
- How to estimate EBMs? Why maximum likelihood is difficult.
- Score matching, one solution to EBM estimation
- Denoising score matching, a computationally simpler alternative

Literature: Murphy's book Chapter 24

Reminder: Estimation of (ordinary) statistical models

Assume a random variable/vector \mathbf{x} comes from the family of probability densities $p(\mathbf{x}; \theta)$

$$\mathbf{x} \sim p(\mathbf{x}; \boldsymbol{\theta})$$
 (1)

but we don't know the true value of heta, denoted by $heta^*$

- For example, p could be normal distribution, θ is mean and/or variance parameters
- We observe a sample of \mathbf{x} , i.e. N observations from $p(\mathbf{x}; \boldsymbol{\theta}^*)$

$$[\mathbf{x}(1), \mathbf{x}(2), \dots, \mathbf{x}(N)] \tag{2}$$

- ightharpoonup Fundamental problem: estimate heta based on the sample
 - lacktriangle Find a good "guess" or "approximation" of the generating $oldsymbol{ heta}^*$
- Classic method: maximum likelihood estimation (MLE)



New problem: Estimation of energy-based models (EBM)

- ► Also called estimation of *unnormalized* statistical models
- As above, we want to estimate the parameters of a model
- lacktriangle As usual, the data is a multivariate random vector $\mathbf{x} \in \mathbb{R}^n$
- ▶ But here: pdf is known only up to a multiplicative constant

$$p_{\mathsf{norm}}(\mathbf{x}; \boldsymbol{\theta}) = \frac{1}{Z(\boldsymbol{\theta})} p_{\mathsf{un}}(\mathbf{x}; \boldsymbol{\theta})$$

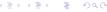
with p_{norm} : actual pdf, and p_{un} : unnormalized version of pdf

- ▶ Functional form of p_{un} is "known" (can be easily computed)
- Normalization constant (= "partition function") $Z(\theta)$ "unknown", i.e. cannot be easily computed
- By definition of a pdf, must integrate to unity, and thus:

$$Z(\theta) = \int_{\boldsymbol{\xi} \in \mathbb{R}^n} p_{\mathsf{un}}(\boldsymbol{\xi}; \boldsymbol{\theta}) \, d\boldsymbol{\xi} \tag{3}$$

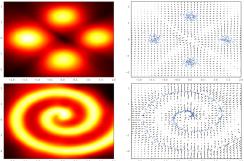
but computing this is very difficult in high dimensions

► Thus, p_{norm} cannot be easily computed either



Motivation in unsupervised deep learning

- ► We want use a NN as a general model of data pdf
- $p_{un}(\mathbf{x}; \boldsymbol{\theta})$ is given by the output of a neural network with scalar output; $\boldsymbol{\theta}$ is network parameters
- \triangleright Extremely difficult to calculate Z by integration (Eq. 3)
- ightharpoonup But using special methods, we can learn heta and pdf:



Right: Data points in blue (and stuff explained later).

Left: Pdf learned by methods explained below.

In general, what is the utility of EBM estimation?

- 1. If we have a simple parametric model as p_{un} , the parameters often have interesting *interpretations*:
 - Parameters with physical, biological etc. meaning, in case of a scientific model
 - $\,\rightarrow\,$ This utility is same as in classical statistical modelling
- 2. If we train a NN as p_{un} , we get a very general model of the probability density. Useful for:
 - Data generation (later lecture)
 - Visualization of density (in small dimensions)
 - ▶ Bayesian inference, using EBM as prior (not in this course)
 - Many more applications...
 - ightarrow This utility is more specific to deep learning

Why MLE fails for EBM

lacktriangle Consider Gaussian model with zero mean, variance σ^2

$$p_{\text{norm}}(x; \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp(-\frac{1}{2\sigma^2}x^2)$$
 (4)

- Here, normalization constant $Z(\sigma^2) = \sqrt{2\pi\sigma^2}$
- Suppose we don't know Z and want to estimate an EBM

$$p_{\rm un}(x;\sigma^2) = \exp(-\frac{1}{2\sigma^2}x^2) \tag{5}$$

▶ Given sample $x_1, ..., x_N$, let us (foolishly) try MLE using p_{un}

$$\log L_{\rm un}(\sigma^2) = -\sum_{i=1}^{N} \frac{1}{2\sigma^2} x_i^2 = -\frac{1}{2\sigma^2} \sum_{i=1}^{N} x_i^2$$
 (6)

▶ Maximized by $\sigma^2 \to \infty$ for any sample \Rightarrow MLE fails



How can we approach EBM estimation?

- Denote the true distribution of data by p_x.
- ▶ A general theoretical approach is to define some kind of "distance" D and minimize it:

$$\min_{\boldsymbol{\theta}} \mathcal{D}(p_{\mathsf{un}}(.;\boldsymbol{\theta}), p_{\mathsf{x}}) \tag{7}$$

- Such \mathcal{D} is often called *divergence* in this context, since it may not be a true distance in mathematical sense
- Important point is that for the divergence it should hold:

$$\mathcal{D}(p,q) = 0 \Leftrightarrow p = q \tag{8}$$

- Many such divergences exist for normalized densities
 - Even MLE can be formulated as minimization of a divergence called "Kullback-Leibler"
- ► The trick is to find one that is easy to compute but still statistically good...
- ... and in our context, even works without normalization!



Definition of "score function" (in this context)

▶ Define model score function $\mathbb{R}^n \to \mathbb{R}^n$ as

$$\phi(oldsymbol{\xi};oldsymbol{ heta}) = egin{pmatrix} rac{\partial \log p_{\mathsf{norm}}(oldsymbol{\xi};oldsymbol{ heta})}{\partial oldsymbol{\xi}_1} \ dots \ rac{\partial \log p_{\mathsf{norm}}(oldsymbol{\xi};oldsymbol{ heta})}{\partial oldsymbol{\xi}_n} \end{pmatrix} =
abla_{oldsymbol{\xi}} \log p_{\mathsf{norm}}(oldsymbol{\xi};oldsymbol{ heta})$$

where p_{norm} is normalized model density.

- This is more precisely called the Stein score;
 Cf. Fisher score which is derivative wrt. parameter θ
- $ightharpoonup \phi(\xi;\theta)$ does not depend on $Z(\theta)$ because

$$\phi(\xi; \theta) = \nabla_{\xi} \log \frac{1}{Z(\theta)} p_{un}(\xi; \theta)$$

$$= \nabla_{\xi} \log p_{un}(\xi; \theta) - \nabla_{\xi} \log Z(\theta) = \nabla_{\xi} \log p_{un}(\xi; \theta) - 0 \quad (9)$$

► As far as score function is concerned, *no need* to compute normalization constant Z, non-normalized pdf p_{un} is enough!



Score matching: definition of objective function

- How to use the score function for estimating parameters?
- Define data score function as

$$\phi_{\mathsf{x}}(\xi) =
abla_{\xi} \log p_{\mathsf{x}}(\xi)$$

where observed data is assumed to follow pdf $p_x(.)$.

Estimate parameters by minimizing distance between model score function $\phi(.;\theta)$ and score of observed data $\phi_x(.)$:

$$J(\boldsymbol{\theta}) = \frac{1}{2} \int_{\boldsymbol{\xi} \in \mathbb{R}^n} p_{\mathbf{x}}(\boldsymbol{\xi}) \|\phi(\boldsymbol{\xi}; \boldsymbol{\theta}) - \phi_{\mathbf{x}}(\boldsymbol{\xi})\|^2 d\boldsymbol{\xi}$$
 (10)

$$\hat{m{ heta}} = rg \min_{m{ heta}} J(m{ heta})$$

- This gives a consistent estimator almost by construction
- (Some call this "score-based modelling" instead of EBM)
- But: computation of this is not straightforward...



A computational trick: central theorem of score matching

- In objective function we have score of data distribution $\phi_{\mathbf{x}}(.)$... Not easy to compute. But there is a trick:
- Write out squared norm in objective function $J(\theta)$:

$$\frac{1}{2}\int p_{\mathbf{x}}(\boldsymbol{\xi})\|\phi(\boldsymbol{\xi};\boldsymbol{\theta})\|^2d\boldsymbol{\xi} - \int p_{\mathbf{x}}(\boldsymbol{\xi})\phi_{\mathbf{x}}(\boldsymbol{\xi})^T\phi(\boldsymbol{\xi};\boldsymbol{\theta})d\boldsymbol{\xi} + \text{const.}$$

- **Constant does not depend on** θ **. First term easy to compute.**
- ► The trick is to use *integration by parts* on second term. In one dimension:

$$\int p_{x}(x)(\log p_{x})'(x)\phi(x;\theta)dx = \int p_{x}(x)\frac{p'_{x}(x)}{p_{x}(x)}\phi(x;\theta)dx$$
$$= \int p'_{x}(x)\phi(x;\theta)dx = 0 - \int p_{x}(x)\phi'(x;\theta)dx$$

• We got rid of score function of data distribution $p_{\mathbf{x}}(x)$!



Theorem on score matching

▶ We have now (kind of) proven:

Theorem

Assume some regularity conditions, and smooth densities. Then, the score matching objective function J can be expressed as

$$J(\boldsymbol{\theta}) = \int_{\boldsymbol{\xi} \in \mathbb{R}^n} p_{\mathbf{x}}(\boldsymbol{\xi}) \sum_{j=1}^n \left[\partial_j \phi_j(\boldsymbol{\xi}; \boldsymbol{\theta}) + \frac{1}{2} \phi_j(\boldsymbol{\xi}; \boldsymbol{\theta})^2 \right] d\boldsymbol{\xi} + const.$$
 (10)

where the constant does not depend on heta, and

$$\phi_j(\boldsymbol{\xi};\boldsymbol{\theta}) = \frac{\partial \log p_{un}(\boldsymbol{\xi};\boldsymbol{\theta})}{\partial \xi_j}, \ \partial_j \phi_j(\boldsymbol{\xi};\boldsymbol{\theta}) = \frac{\partial^2 \log p_{un}(\boldsymbol{\xi};\boldsymbol{\theta})}{\partial \xi_j^2}$$



Final method of score matching

- ▶ Replace integration over data density $p_x(.)$ by sample average
 - transform a theoretical distance to a concrete learning objective
- ▶ Given N observations $\mathbf{x}(1), \dots, \mathbf{x}(N)$, we have objective

$$\widetilde{J}(\boldsymbol{\theta}) = \frac{1}{N} \sum_{i=1}^{N} \sum_{j=1}^{n} \left[\partial_{j} \phi_{j}(\mathbf{x}(i); \boldsymbol{\theta}) + \frac{1}{2} \phi_{j}(\mathbf{x}(i); \boldsymbol{\theta})^{2} \right]$$
(10)

where ϕ_j is *j*-th entry in score function (partial derivative of non-normalized model log-density log p_{un}), and $\partial_j \phi_j$ a second partial derivative. *All derivatives are with respect to* x_j !

- ▶ No difficult integrals; no ϕ_x or p_x left!
- \triangleright Only needs evaluation of some derivatives of p_{un}
- ► Thus: a computationally relatively simple and statistically consistent method for parameter estimation in EBM
- But: while no integration, needs higher derivatives...



Example of Gaussian multivariate precision

- Precision = inverse of covariance, denote by M
- Let's pretend we cannot normalize Gaussian pdf (zero-mean):

$$\rho_{un}(\mathbf{x}; \mathbf{M}) = \frac{1}{Z(\mathbf{M})} \exp(-\frac{1}{2} \mathbf{x}^T \mathbf{M} \mathbf{x})$$
 (11)

We calculate (in exercises)

$$\phi(\mathbf{x}; \mathbf{M}) = -\mathbf{M}\mathbf{x}, \quad \partial_j \phi_j(\mathbf{x}; \mathbf{M}) = -m_{jj}$$

and obtain

$$\widetilde{J}(\mathbf{M}) = \frac{1}{N} \sum_{i=1}^{N} \left[\sum_{j} -m_{jj} + \frac{1}{2} \mathbf{x}(i)^{T} \mathbf{M} \mathbf{M} \mathbf{x}(i) \right]$$
(12)

- Quadratic function! Easy to optimize.
- ► In 1D: $J(\sigma^2) = -\sigma^{-2} + \frac{1}{2}\sigma^{-4}\sum_i x_i^2/N$, cf. with the foolish MLE attempt a few slides ago
- Turns our to be equal to MLE: optimizing M is inverse of sample covariance



Denoising score matching (DSM)

- Second derivatives in basic SM expensive to compute in a NN
- ▶ DSM: using denoising autoencoders to estimate score
- ► Easy to implement in a NN, no need for higher derivatives
- Denoising autoencoders (reminder):
 - 1. Add (small, Gaussian) noise \mathbf{n} to the data to get $\tilde{\mathbf{x}} = \mathbf{x} + \mathbf{n}$
 - 2. Train NN to learn a denoising function to reconstruct ${\bf x}$ from $\tilde{{\bf x}}$
- Objective function formulated as

$$J(\boldsymbol{\theta}) = \sum_{i=1}^{N} \|\mathbf{x}(i) - [\tilde{\mathbf{x}}(i) + \sigma^2 \phi(\tilde{\mathbf{x}}(i); \boldsymbol{\theta})]\|^2$$
 (13)

where noise is Gaussian of covariance σ^2 I, ϕ is NN with parameters θ ; nonlinearity "split" in special way

Deep theorem: Minimizing this will lead to ϕ which is the score function of $\tilde{\mathbf{x}}$ (note: not original \mathbf{x})

Connection between score function and denoising

- How come learning to denoise gives us the score function?
- Assume as above

$$\tilde{\mathbf{x}} = \mathbf{x} + \mathbf{n} \tag{14}$$

- n is Gaussian with covariance C_n.
- ▶ The optimal prediction of \mathbf{x} from $\tilde{\mathbf{x}}$ is given by

Theorem (Tweedie-Miyasawa)

$$E\{\mathbf{x}|\tilde{\mathbf{x}}\} = \tilde{\mathbf{x}} + \mathbf{C}_{\mathbf{n}}\phi_{\tilde{\mathbf{x}}}(\tilde{\mathbf{x}}) \tag{15}$$

- ► Add to this a well-known property of conditional expectation: it minimizes the least-squares error in prediction
- So, predicting **x** from $\tilde{\mathbf{x}}$ as in the the right-hand-side of (15) by least-squares regression is optimized by the score function: $\phi(\tilde{\mathbf{x}}; \boldsymbol{\theta}) = \phi_{\tilde{\mathbf{x}}}(\tilde{\mathbf{x}}) \Rightarrow \mathsf{DSM}$ works.

Proof of Tweedie-Miyasawa formula (optional)

Denote the pdf of \mathbf{n} as $\psi(\mathbf{n}) = \frac{1}{(2\pi)^{d/2} |\mathbf{C_n}|^{1/2}} \exp(-\frac{1}{2} \mathbf{n}^T \mathbf{C_n}^{-1} \mathbf{n})$. To prove the theorem, we start by the simple identity

$$p_{\tilde{\mathbf{x}}}(\tilde{\mathbf{x}}) = \int p(\tilde{\mathbf{x}}|\mathbf{x})p_{\mathbf{x}}(\mathbf{x})d\mathbf{x} = \int \psi(\tilde{\mathbf{x}} - \mathbf{x})p_{\mathbf{x}}(\mathbf{x})d\mathbf{x}$$
(16)

based first, on definition of marginal pdf, and second, the noise model saying $p(\tilde{\mathbf{x}}|\mathbf{x}) = \psi(\tilde{\mathbf{x}} - \mathbf{x})$. Now, we take derivatives of both sides (ignoring the middle term)

$$\nabla_{\tilde{\mathbf{x}}} \rho_{\tilde{\mathbf{x}}}(\tilde{\mathbf{x}}) = \int \mathbf{C}_{\mathbf{n}}^{-1}(\mathbf{x} - \tilde{\mathbf{x}}) \psi(\tilde{\mathbf{x}} - \mathbf{x}) \rho_{\mathbf{x}}(\mathbf{x}) d\mathbf{x}$$
 (17)

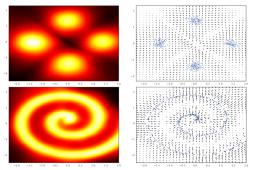
We divide both sides by $p_{\tilde{\mathbf{x}}}(\tilde{\mathbf{x}})$, multiply by $\mathbf{C_n}$, and rearrange:

$$\mathbf{C}_{\mathbf{n}}\phi_{\tilde{\mathbf{x}}}(\tilde{\mathbf{x}}) = \int (\mathbf{x} - \tilde{\mathbf{x}})\psi(\tilde{\mathbf{x}} - \mathbf{x})p_{\mathbf{x}}(\mathbf{x})/p_{\tilde{\mathbf{x}}}(\tilde{\mathbf{x}})d\mathbf{x}$$
$$= \int \mathbf{x}p(\mathbf{x}|\tilde{\mathbf{x}})d\mathbf{x} - \tilde{\mathbf{x}} \int p(\mathbf{x}|\tilde{\mathbf{x}})d\mathbf{x} \quad (18)$$

The last integral is equal to unity, which proves $Eq_{-}(15)$ \square

Earlier example revisited

- ▶ $\log p_{un}(\mathbf{x}; \boldsymbol{\theta})$ is given by the output of a neural network with scalar output; $\boldsymbol{\theta}$ is network parameters
- A neural network is here estimated by DSM



Left: Pdf learned by DSM.

Right: Data points in blue, learned score function as arrows

Summary: EBM part 1

- ▶ Definition of EBM: an unnormalized statistical model
- Lack of normalization makes estimation much more difficult
- Estimation not possible with maximum likelihood
- Score matching is one approach
 - Completely ignores normalization constant
- Basic SM still has annoying higher derivatives
- Denoising SM gets rid of higher derivatives
 - Equivalent to a denoising autoencoder
- Very general method for approximating data pdf
 - but small problem: DSM approximates pdf of *noisy* data only