**setPower()**

**Description**

Control a joints speed and direction with percentage. Power value can be from -100.0 to +100.0. If the value is bigger than 0, the joint turns clockwise. Smaller than 0, the joint turns counterclockwise.

**Syntax**

ArgonBase. ArgonJoint.setPower( power )

or

ArgonArm.ArgonJoint.setPower( power )

**Parameters**

power (*float*): power value (-100.0, +100.0)

**Returns**

None

**Examples**