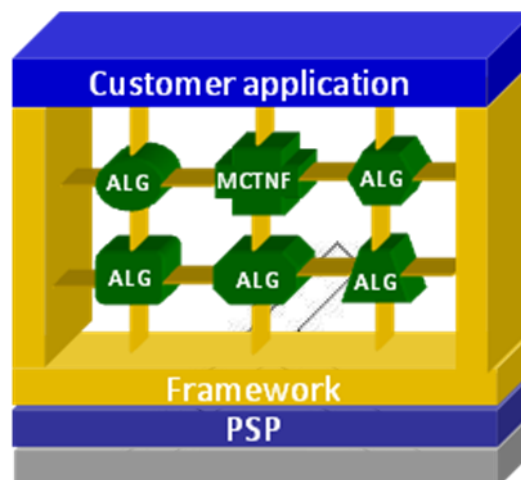




- IVIDNF1 interface compliant
- Validated on DM388 EVM
- Progressive type picture noise filtering supported
- Input picture width as multiples of 16 and height multiple of 2 is supported
- Only single past reference frame supported
- User controllable filter parameter supported
- Only pixel motion vector supported
- Unrestricted motion vector search is supported
- YUV420 semi-planar as chroma format supported



## Description

MCTNF or Motion Compensated Temporal Noise Filter is TI's proprietary Video Noise Filter algorithm implemented on DM388. MCTNF implementation is validated with Code Composer Studio version 5.1.0.09000 and code generation tools version 5.0.5.



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PRODUCT PREVIEW

January 2014

## Performance and Memory Summary

Table 1. Configuration Table

| CONFIGURATION  | ID        |
|--|-----------|
| One past reference frame, pixel motion vector, block size of 8x8 pixels.   | MCTNF_001 |
| One past reference frame, pixel motion vector, block size of 8x8 pixels with loop filtering enabled with boundary strength of '2'. | MCTNF_002 |

| CONFIGURATION ID | TEST DESCRIPTION                          | HDVICP2 PERFORMANCE STATISTICS |          |
|------------------|---|--------------------------------|----------|
|                  |   | MIN (MHZ)                      | MAX(MHZ) |
| MCTNF_001        | intotree_p1920x1080_25fps_420pl_250fr.yuv | 182                            | 183      |
| MCTNF_002        | intotree_p1920x1080_25fps_420pl_250fr.yuv | 188                            | 189      |

Table 2. Memory Statistics - Generated with Code Generation Tools Version 4.5.1

| CONFIGURATION ID | RESOLUTION | MEMORY STATISTICS <sup>1</sup> |             |            |         |       |       |       |
|------------------|------------|--------------------------------|-------------|------------|---------|-------|-------|-------|
|                  |            | PROGRAM MEMORY                 | DATA MEMORY |            |         |       |       | TOTAL |
|                  |            |                                | INTERNAL    | EXTERNAL   |         |       | STACK |       |
|                  |            |                                |             | PERSISTENT | SCRATCH | CONST |       |       |
| MCTNF_001        | 1920x1080  | 13                             | 2           | 68         | 0       | 57    | 2     | 142   |

All memory requirements are expressed in kilobytes (1 K-byte = 1024 bytes) and there could be a variation of around 1-2% in the numbers.

Table 3. Internal Data Memory Split-up

| CONFIGURATION ID | DATA MEMORY – INTERNAL <sup>2</sup> |         |                       |
|------------------|-------------------------------------|---------|-----------------------|
|                  | SHARED                              |         | INSTANCE <sup>3</sup> |
|                  | CONSTANTS                           | SCRATCH |                       |
| MCTNF_001        | 0                                   | 2       | 2                     |

<sup>2</sup> Internal memory refers to on chip memory. All memory requirements are expressed in kilobytes and there could be a variation of around 1-2% in numbers.

<sup>3</sup> I/O buffers are not included. Some of the instance memory buffers could be scratch.



## notes

- I/O buffers:
  - Input buffer size = 148.5 K-bytes (CIF, one YUV420 SP) unfiltered raw data
  - Output buffer size = 148.5 K-bytes (CIF, one YUV420 SP) filtered raw data
  - Total data memory for N non pre-emptive instances = Constants + Runtime Tables + Scratch + N \* (Instance + I/O buffers + Stack)
- Total data memory for N pre-emptive instances = Constants + Runtime Tables + N \* (Instance + I/O buffers + Stack + Scratch)

## references

- MCTNF\_DM388\_UserGuide.pdf

## glossary

|           |   |
|-----------|---|
| Constants | Elements that go into .const memory section   |
| Scratch   | Memory space that can be reused across different instances of the algorithm                           |
| Shared    | Sum of Constants and Scratch  |
| Instance  | Persistent-memory that contains persistent information - allocated for each instance of the algorithm |



**acronyms**

|       |  |
|-------|--|
| CIF   | Common Intermediate Format             |
| DMA   | Direct Memory Access                   |
| DMAN3 | DMA Manager                            |
| EVM   | Evaluation Module                      |
| MV    | Motion Vector                          |
| QCIF  | Quarter Common Intermediate Format     |
| QVGA  | Quarter Video Graphics Array           |
| SQCIF | Sub Quarter Common Intermediate Format |
| UMV   | Unrestricted Motion Vectors            |
| VGA   | Video Graphics Array                   |
| XDM   | eXpressDSP Digital Media               |

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PRODUCT PREVIEW

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