



**Green University of Bangladesh**  
**Department of Computer Science and Engineering (CSE)**  
**Faculty of Sciences and Engineering**  
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**Lab Report: 02**  
**Course Title: Algorithm Lab**  
**Course Code: CSE 206                      Section: DA**

**Lab Report Name: Detect Cycle using BFS, topological sort, Find level use BFS, Find depth of Tree use BFS, Kruskal and Prim's find the total number of minimum spanning tree.**

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**Lab Report Status**

<b>Marks: .....</b>	<b>Signature: .....</b>
<b>Comments: .....</b>	<b>Date: .....</b>

## **Task-1:** Write a program to detect the cycle in a graph using BFS.

The given problem implements the topological sorting algorithm to detect cycles in a directed graph. Here's a step-by-step explanation of the code:

Then, it initializes an adjacency list `adj` with a size of `N` to store the directed edges between vertices. It also initializes an `InDegree` vector of size `N` with all elements initialized to 0, to store the indegree of each vertex.

The `addEdges` method takes two arguments `u` and `v` representing the source and destination vertices of the edge respectively, and updates the `adj` and `InDegree` vectors accordingly. It adds the destination vertex to the adjacency list of the source vertex and increments the indegree of the destination vertex.

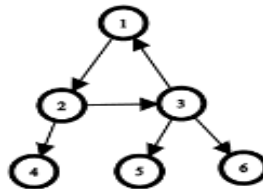
The `CheckCycle` method takes an integer `n` as an argument, representing the total number of vertices in the graph. It first creates an empty queue `q`. It pushes all the vertices that have an indegree of 0 to the queue. It then enters into a loop where it dequeues a vertex from the queue, increments a counter `count`, and prints the vertex value.

For each adjacent vertex of the dequeued vertex, the method decreases its indegree by 1. If the indegree of any adjacent vertex becomes 0, it is pushed to the queue. The loop continues until the queue is empty.



If `count` is equal to `n`, it means all vertices have been traversed, and there is no cycle in the graph. Thus, the method returns `false`. Otherwise, the method returns `true`, indicating the presence of a cycle.

Overall, the code performs the topological sorting algorithm by keeping track of the indegree of each vertex and using a queue to traverse the graph in a topological order. If a cycle is detected, it returns `true`, otherwise `false`.

## **Graph:**



# Code:

```
Lab_Report_2 > MyCode >  tast_1_Detect_Cycle_Bfs.c++ >  InDegree
1  #include <bits/stdc++.h>
2  using namespace std;
3  const int N = 999;
4  // initialize adjacency list
5  vector<int> adj[N];
6  // initialize indegree 0
7  vector<int> InDegree(N, 0);
8  // add edges method
9  void addEdges(int u, int v)
10 {
11     adj[u].push_back(v);
12     InDegree[v]++;
13 }
14
15 // topological method
16 bool CheckCycle(int n)
17 {
18     // create a queue
19     queue<int> q;
20     for (int i = 0; i < n; i++)
21     {
22         if (InDegree[i] == 0)
23         {
24             q.push(i);
25         }
26     }
27     // this process is perform when the queue is empty
28     // just initialize count variable
29     int count = 0;
30     while (!q.empty())
31     {
32         int node = q.front();
33         q.pop();
34         count++;
35         // cout << node << " ";
36         // jara node ar sathe connected tader degree 1 kore komay dibo
37         for (auto it : adj[node])
38         {
39             InDegree[it]--;
40             if (InDegree[it] == 0)
41             { // again check oi element ar moddhe kader indgree 0 tader ke
42                 // push it
43                 q.push(it);
44             }
45         }
46     }
47     if (count == n)
48         return false;
49     return true;
50 }
51 int main()
52 {
53     // input vertex and edge
54     int n, m;
55     cin >> n >> m;
```

```

50 }
51 int main()
52 {
53     // input vertex and edge
54     int n, m;
55     cin >> n >> m;
56     // input edges
57     for (int i = 0; i < m; i++)
58     {
59         int u, v;
60         cin >> u >> v;
61         addEdges(u, v);
62     }
63     // work the main funda topological sort
64     bool isCycle;
65     isCycle = CheckCycle(n);
66
67     if (isCycle)
68     {
69         cout << "\nCycle Detect!!\n";
70     }
71     else
72     {
73         cout << "\nNo Cycle\n";
74     }
75
76     return 0;
77 }

```

## Output:

```

PS C:\Users\Admin\Desktop\Code\C_C++\C++> cd "c:\Users\Admin\Desktop\Code\C_C++\C++\Lab_Report_2\MyCode"
t_Cycle_Bfs } ; if ($?) { .\tast_1_Detect_Cycle_Bfs }
6 6
1 2
2 3
3 1
3 5
3 6
2 4

Cycle Detect!!
PS C:\Users\Admin\Desktop\Code\C_C++\C++\Lab_Report_2\MyCode>

```

## **Task-2:** Write a program to find the level of each node using BFS

This problem aims to find the level of each node in an undirected graph. The level of a node is defined as the minimum number of edges required to reach that node from a given source node. In this code, the source node is assumed to be node 1.

A vector of vectors is used to represent the graph. The vector `adj[]` stores the adjacency list of each node. A vector `vis[]` is used to keep track of visited nodes during BFS traversal. A vector `level[]` is used to store the level of each node.

`addEdge()` function takes two nodes `u` and `v` as input and adds an undirected edge between them by adding `v` to the adjacency list of `u` and vice versa.

`printAdj()` function takes the number of nodes `n` as input and prints the adjacency list of each node.

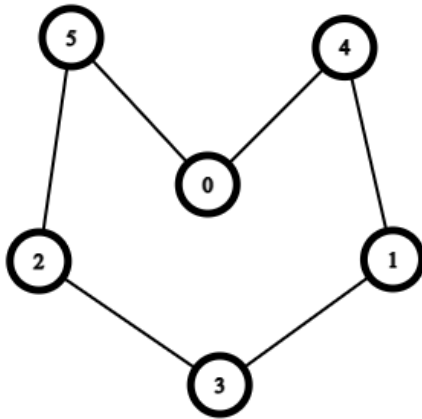
`bfs()` function takes the source node as input and performs a Breadth First Search (BFS) traversal starting from the source node. A queue of pairs is used to keep track of nodes and their corresponding levels during traversal. Initially, the source node is pushed into the queue with level 0 and marked as visited. While the queue is not empty, a node is popped from the front of the queue and its level is updated in the `level[]` vector.

For each unvisited neighbor of the current node, its level is updated as `level[current_node] + 1`, and the neighbor is pushed into the queue with its level.

Finally, it calls the `bfs()` function with the source node as input and prints the level of each node using the `level[]` vector.

Overall, this problem performs BFS traversal of the given graph starting from a source node and calculates the level of each node by counting the minimum number of edges required to reach each node from the source node.

**Graph:**



---

**Code:**

Lab\_Report\_2 > MyCode > task\_2\_level\_Bfs.c++ > bfs(int)

```
1 // find the level
2 #include <bits/stdc++.h>
3 using namespace std;
4 const int N = 999;
5 vector<int> adj[N];
6 vector<int> vis(N);
7 vector<int> level(N);
8 void addEdge(int u, int v)
9 {
10     adj[u].push_back(v);
11     adj[v].push_back(u);
12 }
13 void printAdj(int n)
14 {
15     for (int i = 0; i < n; i++)
16     {
17         cout << "Node->" << i << ": ";
18         for (int it : adj[i])
19         {
20             cout << it << "->";
21         }
22         cout << "\n";
23     }
24 }
25 void bfs(int source)
26 { // create pair first position is node and second position is level
27     queue<pair<int, int>> q;
28     // node, level
29     q.push({source, 0});
30     // starting node is visited;
31     vis[source] = 1;
32     while(!q.empty()){
33         int node=q.front().first;
34         int l=q.front().second;
35         q.pop();
36         level[node]=l;
37         for(int it: adj[node]){
38             if(vis[it]==0){
39                 q.push({it,l+1});
40                 vis[it]=1;
41             }
42         }
43     }
44 }
45
46 int main()
47 {
48     // add nodes and edges
```

```

45
46  int main()
47  {
48      // add node and edge
49      int n, m;
50      cin >> n >> m;
51      // add every edges
52      for (int i = 0; i < m; i++)
53      {
54          int u, v;
55          cin >> u >> v;
56          addEdge(u, v);
57      }
58      // present adjacency list
59      printAdj(n);
60      bfs(1);
61      // print the level for every node
62
63      for(int i=0;i<=n;i++){
64          cout<<"node: "<<i<<": "<<"level:"<<level[i]<<endl;
65      }
66      return 0;
67  }

```

**Output:**



```

PS C:\Users\Admin\Desktop\Code\C_C++\C++\Lab_Report_2\MyCode>
task_2_level_Bfs } ; if ($?) { .\task_2_level_Bfs }
6 6
5 0
4 0
5 2
4 1
2 3
3 1
Node->0: 5->4->
Node->1: 4->3->
Node->2: 5->3->
Node->3: 2->1->
Node->4: 0->1->
Node->5: 0->2->
node: 0: level:2
node: 1: level:0
node: 2: level:2
node: 3: level:1
node: 4: level:1
node: 5: level:3
node: 6: level:0
PS C:\Users\Admin\Desktop\Code\C_C++\C++\Lab_Report_2\MyCode>

```

**Task-3:** Write a program to perform topological sort using BFS.

This problem performs topological sorting on a directed acyclic graph (DAG). Topological sorting is a way of ordering the vertices of a graph such that for every directed edge  $(u, v)$ , vertex  $u$  comes before vertex  $v$  in the ordering.

The code uses an adjacency list to represent the graph, where each index of the vector represents a vertex, and the values stored in the vector are the adjacent vertices. The InDegree vector keeps track of the number of incoming edges for each vertex.

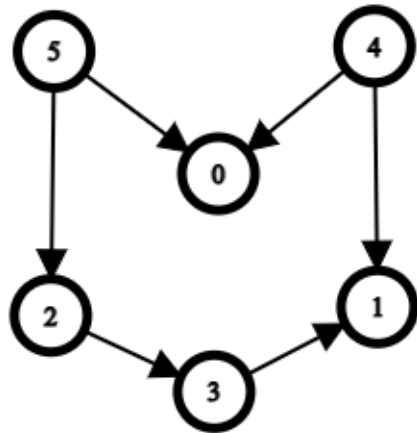
The addEdges method adds an edge to the graph by adding the destination vertex to the adjacency list of the source vertex and incrementing the indegree of the destination vertex.

The topological method performs the topological sort. It starts by pushing all vertices with an indegree of 0 to a queue. Then, it processes the vertices in the queue one by one, printing them out and reducing the indegree of

their adjacent vertices by 1. If the indegree of an adjacent vertex becomes 0, it is added to the queue. This process continues until the queue becomes empty.

In summary, topological sorting performs on a DAG represented by an adjacency list and indegree vector.

## **Graph:**



# Code:

```
17
18 #include <bits/stdc++.h>
19 using namespace std;
20 const int N = 999;
21 // initialize adjacency list
22 vector<int> adj[N];
23 // initialize indegree 0
24 vector<int> InDegree(N, 0);
25
26 // add edges method
27 void addEdges(int u, int v)
28 {
29     adj[u].push_back(v);
30     InDegree[v]++;
31 }
32
33 // topological method
34 void topological(int n)
35 {
36     // create a queue
37     queue<int> q;
38     // for(int i=0;i<n;i++){
39     //     for(auto in:adj[i]){
40     //         InDegree[in]++;
41     //     }
42     // }
43     // push all the node which indegree is 0
44     for(int i=0;i<n;i++){
45         if(InDegree[i]==0){
46             q.push(i);
47         }
48     }
49     // this process is perform when the queue is empty
50     while(!q.empty()){
51         int node=q.front();
52         q.pop();
53         cout<<node<<" ";
54         // jara node ar sathe connected tader degree 1 kore komay dibo
55         for(auto it:adj[node]){
56             InDegree[it]--;
57             if(InDegree[it]==0){ //again check oi element ar moddhe kader indgree 0 tader ke
58                 //push it
59                 q.push(it);
60             }
61         }
62     }
```

```

63
64 }
65 int main()
66 {
67     // input vertex and edge
68     int n, m;
69     cin >> n >> m;
70     // input edges
71     for (int i = 0; i < m; i++)
72     {
73         int u, v;
74         cin >> u >> v;
75         addEdges(u, v);
76     }
77     // work the main funda topological sort
78     topological(n);
79
80     return 0;
81 }

```

## Output:

```

Task_3_topo } ; int (*p) { : Task_3_topo }
6 6
5 0
4 0
5 2
4 1
2 3
3 1
4 5 0 2 3 1
PS C:\Users\Admin\Desktop\Code\C_C++\C++\Lab_Report_2\MyCode>

```

## Task-4: Write a program to find the minimum depth of a binary tree.

This problem is used to find the minimum depth of a binary tree.

First, a binary tree is defined using the Node structure. The structure contains three fields: data, left and right. The data field stores the value of the node, the left field points to the left child node and the right field points to the right child node.

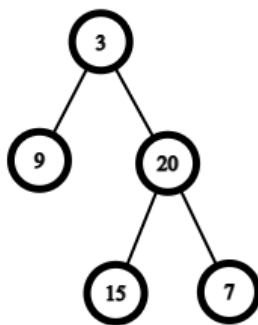
The minDepth() function takes the root node of the binary tree as input and returns the minimum depth of the tree. If the root node is NULL, the function returns 0. A queue is created using the queue this queue type is Node pointer. The queue stores nodes of the binary tree.

The root node is pushed into the queue. The variable depth is initialized to 1. It will be used to keep track of the current depth of the tree. A while loop is executed until the queue becomes empty. Inside the while loop, the size of the queue is stored in the variable size.

Another while loop is executed until size becomes 0. Inside this while loop, the front node of the queue is removed and stored in the variable root. If the left and right child nodes of the root node are both NULL, it means that the root node is a leaf node. Therefore, the function returns the current depth.

If the left child node of the root node is not NULL, it is pushed into the queue. If the right child node of the root node is not NULL, it is pushed into the queue. After processing all nodes at the current level, the depth variable is incremented. After the while loop completes, the function returns the final depth of the tree.

## Graph:



---

# Code:

```
lab_report_2 / myCode / task_1_minDepth1 / minDepth(Node)
1 // minimum depth
2 #include <bits/stdc++.h>
3 using namespace std;
4 struct Node
5 {
6     int data;
7     Node *left, *right;
8     Node(int value){
9         value=data;
10        left=right=NULL;
11    }
12 };
13 int minDepth(Node *root){
14     if(root==NULL)
15         return 0;
16     // create queue which type is node
17     queue<Node *>q;
18     // push root node first
19     q.push(root);
20     // initialize depth is 1
21     int depth=1;
22     while(!q.empty()){
23         int size=q.size();
24         // cout<<size<<endl;
25         while(size-->0){
26             Node *root=q.front();
27             q.pop();
28             // cout<<"root: "<<root->data<<endl;
29             if(root->left==NULL && root->right==NULL)
30                 // return depth find for leaf node
31                 return depth;
32             // check left node element is exist if exist then push it
33             if(root->left!=NULL)
34                 q.push(root->left);
35             // check right node element is exist if exist then push it
36             if(root->right!=NULL)
37                 q.push(root->right);
38         }
39         // increment depth after processing all nodes at the current level
40         depth++;
41     }
42     // return final depth
43     return depth;
44 }
45 int main()
46 {
47     Node *root;
48     root=new Node(3);
49     root->left=new Node(9);
```

```

39         // increment depth after processing all the
40         depth++;
41     }
42     // return final depth
43     return depth;
44 }
45 int main()
46 {
47     Node *root;
48     root=new Node(3);
49     root->left=new Node(9);
50     root->right=new Node(20);
51     root->right->left=new Node(15);
52     root->right->right=new Node(9);
53
54     cout<<minDepth(root)<<endl;
55     return 0;
56 }

```

## Output:

```

PS C:\Users\Admin\Desktop\Code\C_C++\C++\Lab_Report_2\MyCode> cd
task_4_MinDepth } ; if ($?) { .\task_4_MinDepth }
Minimum depth:
2
PS C:\Users\Admin\Desktop\Code\C_C++\C++\Lab_Report_2\MyCode>

```

**Task-5:** Write a program to find the number of distinct minimum spanning trees for a given weighted graph using Kruskal algorithm.

The code defines a struct Edge to represent an edge in the graph. The struct has three integer fields: u and v represent the endpoints of the edge, and w represents the weight of the edge.

The code defines a function kruskal that takes a vector of Edge objects and the number of vertices in the graph, and returns a vector of Edge objects representing the MST of the graph. The function first initializes a vector mst to store the edges in the MST, and a vector parent to store the parent of each vertex in the MST. Initially, each vertex is its own parent. The function then sorts the input edges by weight using

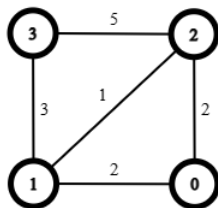
the sort function and a comparison function `cmp`. The function then iterates over the sorted edges, adding each edge to the MST if its endpoints have different parents. If an edge is added to the MST, the function updates the parent of all vertices in the subtree rooted at the endpoint with the old parent to the new parent.

The code defines a function `count_msts` that takes a vector of `Edge` objects and the number of vertices in the graph, and returns the number of distinct MSTs of the graph. The function first finds the MST of the input graph using the `kruskal` function. The function then initializes a variable `count` to 0, and iterates over each edge in the MST. For each edge, the function creates a copy of the input edges with the current edge removed, and finds the MST of the new graph using the `kruskal` function. The function then computes the weight of the new MST, and if it is equal to the weight of the original MST, the function increments `count`. Finally, the function returns `count`.

In the main function, the code defines a small example graph with 4 vertices and 5 edges, and calls the `count_msts` function to count the number of distinct MSTs of the graph. The function prints the result to the console.

In summary, this code demonstrates a technique for counting the number of distinct minimum spanning trees of a graph by using Kruskal's algorithm to find the MST and then iterating over all possible MSTs by removing each edge from the MST and finding the new MST.

## Graph:



---



**Code:**

Lab\_Report\_2 > Others > kkn.c++ > ...

```
1  #include <bits/stdc++.h>
2  using namespace std;
3  struct Edge {
4      int u, v, w;
5      Edge(int uu, int vv, int ww) : u(uu), v(vv), w(ww) {}
6  };
7
8  bool cmp(Edge& a, Edge& b) {
9      return a.w < b.w;
10 }
11
12 vector<Edge> kruskal(vector<Edge>& edges, int n) {
13     vector<Edge> mst;
14     vector<int> parent(n);
15     for (int i = 0; i < n; i++) {
16         parent[i] = i;
17     }
18     sort(edges.begin(), edges.end(), cmp);
19     for (Edge e : edges) {
20         int pu = parent[e.u];
21         int pv = parent[e.v];
22         if (pu != pv) {
23             mst.push_back(e);
24             for (int i = 0; i < n; i++) {
25                 if (parent[i] == pv) {
26                     parent[i] = pu;
27                 }
28             }
29         }
30     }
31     return mst;
32 }
33
34 int count_msts(vector<Edge>& edges, int n) {
35     int mst_weight = 0;
36     vector<Edge> mst = kruskal(edges, n);
37     for (Edge e : mst) {
38         mst_weight += e.w;
39     }
40     int count = 0;
41     for (int i = 0; i < mst.size(); i++) {
42         vector<Edge> new_edges = edges;
43         new_edges.erase(new_edges.begin() + i);
44         vector<Edge> new_mst = kruskal(new_edges, n);
45         int new_weight = 0;
46         for (Edge e : new_mst) {
47             new_weight += e.w;
48         }
```

```

53     {
54         int u = parent[i];
55         int v = i;
56         int weight = 0;
57         for (Edge &e : g.adj[u])
58         {
59             if (e.v == v)
60             {
61                 weight = e.weight;
62                 break;
63             }
64         }
65         edges.push_back(Edge(v, weight));
66     }
67
68     sort(edges.begin(), edges.end(), [](Edge &a, Edge &b)
69         { return a.weight < b.weight; });
70
71     vector<int> rank(g.V, 0);
72     vector<int> parent(g.V, -1);
73     for (int i = 0; i < g.V; i++)
74     {
75         parent[i] = i;
76     }
77     for (int i = 0; i < edges.size(); i++)
78     {
79         int u = edges[i].v;
80         int v = parent[u];
81         while (u != v)
82         {
83             parent[u] = v;
84             u = parent[u];
85             v = parent[v];
86         }
87         if (parent[edges[i].v] != parent[edges[i - 1].v] || i == 0)
88         {
89             count++;
90         }
91     }
92     return count;
93 }
94
95 int main()
96 {
97     int V = 4;
98     Graph g;
99     g.V = V;
100     g.adj = vector<vector<Edge>>(V);
101
102     g.adj[0].push_back(Edge(1, 2));
103     g.adj[1].push_back(Edge(0, 2));
104
105     g.adj[0].push_back(Edge(2, 3));
106     g.adj[2].push_back(Edge(0, 3));
107
108     g.adj[1].push_back(Edge(2, 1));
109     g.adj[2].push_back(Edge(1, 1));
110
111     g.adj[1].push_back(Edge(3, 4));
112     g.adj[3].push_back(Edge(1, 4));
113
114     g.adj[2].push_back(Edge(3, 5));
115     g.adj[3].push_back(Edge(2, 5));
116
117     int msts = count_msts(g);
118     cout << "Number of distinct minimum spanning trees: " << msts << endl;
119
120     return 0;
121 }
122

```

```

45         new_weight = 0;
46         for (Edge e : new_mst) {
47             new_weight += e.w;
48         }
49         if (new_weight == mst_weight) {
50             count++;
51         }
52     }
53     return count;
54 }
55
56 int main() {
57     int n = 4;
58     vector<Edge> edges;
59     edges.push_back(Edge(0, 1, 2));
60     edges.push_back(Edge(0, 2, 2));
61     edges.push_back(Edge(1, 2, 1));
62     edges.push_back(Edge(1, 3, 3));
63     edges.push_back(Edge(2, 3, 5));
64     int count = count_msts(edges, n);
65     cout << "Number of distinct minimum spanning trees: " << count << endl;
66     return 0;
67 }

```

## Output:

```

PROBLEMS  OUTPUT  DEBUG CONSOLE  TERMINAL  COMMENTS
PS C:\Users\Admin\Desktop\Code\C_C++\C++> cd "c:\Users\Admin\
Number of distinct minimum spanning trees: 2
PS C:\Users\Admin\Desktop\Code\C_C++\C++\Lab_Report_2\Others>

```

**Task-6:** Write a program to find the number of distinct minimum spanning trees for a given weighted graph using the Prim algorithm.

The first step is to define two data structures: Edge and Graph. Edge represents an edge in the graph and contains the destination vertex  $v$  and the weight of the edge. Graph contains the number of vertices  $V$  and an adjacency list representation of the graph. The `count_msts` function takes a Graph object `g` as input and returns an integer representing the number of distinct minimum spanning trees in the graph.

The function initializes a variable count to 0 to count the number of MSTs. It initializes three vectors: parent, dist, and visited, each with size V. parent stores the parent of each vertex in the MST dist stores the distance from the source vertex to each vertex visited is used to mark visited vertices.

It also initializes a priority queue pq to store the vertices to be processed. It is a min heap where the top element has the minimum distance. The function loops over all vertices in the graph and performs the following steps for each vertex:

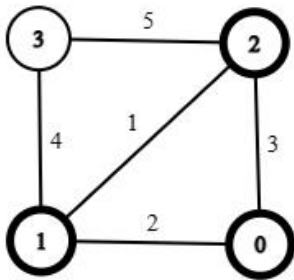
It assigns the distance from the source vertex to all vertices to be INT\_MAX and marks all vertices as unvisited. It pushes the source vertex into the priority queue with distance 0. It loops while the priority queue is not empty:

It pops the vertex with the minimum distance from the priority queue. If the vertex is already visited, it continues to the next iteration of the loop. Otherwise, it marks the vertex as visited and updates the distance of all its neighbors in the priority queue if the new distance is smaller than the current distance.

After the loop, parent vector contains the parent of each vertex in the MST. For each MST, the function constructs a vector of Edge objects representing the edges in the MST. The function sorts the vector of edges in non-decreasing order of weight. It initializes two vectors rank and parent, each with size V rank stores the rank of each vertex in the union-find data structure.

parent stores the parent of each vertex in the union-find data structure. It sets the parent of each vertex to itself initially. The function loops over the sorted edges and performs the following steps for each edge: It finds the parent of the source vertex u and the parent of the destination vertex v. It performs union-by-rank by making the parent of the vertex with smaller rank the parent of the other vertex. If the parent of the destination vertex v is different from the parent of the source vertex u, it increments the count variable. The function returns the final value of the count variable.

## **Graph:**



---

**Code:**

Lab\_Report\_2 > Others > ppn.c++ > ...

```
1  #include <bits/stdc++.h>
2  using namespace std;
3  struct Edge
4  {
5      int v, weight;
6      Edge(int v, int w) : v(v), weight(w) {}
7  };
8
9  struct Graph
10 {
11     int V;
12     vector<vector<Edge>> adj;
13 };
14 int count_msts(Graph &g)
15 {
16     int count = 0;
17     vector<int> parent(g.V, -1);
18     vector<int> dist(g.V, INT_MAX);
19     vector<bool> visited(g.V, false);
20     priority_queue<pair<int, int>, vector<pair<int, int>>, greater<pair<int, int>>> pq;
21
22     for (int s = 0; s < g.V; s++)
23     {
24         dist.assign(g.V, INT_MAX);
25         visited.assign(g.V, false);
26         pq.push(make_pair(0, s));
27         dist[s] = 0;
28
29         while (!pq.empty())
30         {
31             int u = pq.top().second;
32             pq.pop();
33             if (visited[u])
34             {
35                 continue;
36             }
37             visited[u] = true;
38             for (Edge &e : g.adj[u])
39             {
40                 int v = e.v;
41                 int weight = e.weight;
42                 if (!visited[v] && weight < dist[v])
43                 {
44                     dist[v] = weight;
45                     parent[v] = u;
46                     pq.push(make_pair(dist[v], v));
47                 }
48             }
49         }
50
51         vector<Edge> edges;
52         for (int i = 1; i < g.V; i++)
53         {
54             int u = parent[i];
55             int v = i;
```

```

53     {
54         int u = parent[i];
55         int v = 1;
56         int weight = 0;
57         for (Edge &e : g.adj[u])
58         {
59             if (e.v == v)
60             {
61                 weight = e.weight;
62                 break;
63             }
64         }
65         edges.push_back(Edge(v, weight));
66     }
67
68     sort(edges.begin(), edges.end(), [](Edge &a, Edge &b)
69         { return a.weight < b.weight; });
70
71     vector<int> rank(g.V, 0);
72     vector<int> parent(g.V, -1);
73     for (int i = 0; i < g.V; i++)
74     {
75         parent[i] = 1;
76     }
77     for (int i = 0; i < edges.size(); i++)
78     {
79         int u = edges[i].v;
80         int v = parent[u];
81         while (u != v)
82         {
83             parent[u] = v;
84             u = parent[u];
85             v = parent[v];
86         }
87         if (parent[edges[i].v] != parent[edges[i - 1].v] || i == 0)
88         {
89             count++;
90         }
91     }
92     return count;
93 }
94
95
96 int main()
97 {
98     int V = 4;
99     Graph g;
100     g.V = V;
101     g.adj = vector<vector<Edge>>>(V);
102
103     g.adj[0].push_back(Edge(1, 2));
104     g.adj[1].push_back(Edge(0, 2));
105
106     g.adj[0].push_back(Edge(2, 3));
107     g.adj[2].push_back(Edge(0, 3));
108
109     g.adj[1].push_back(Edge(2, 1));
110     g.adj[2].push_back(Edge(1, 1));
111
112     g.adj[1].push_back(Edge(3, 4));
113     g.adj[3].push_back(Edge(1, 4));
114
115     g.adj[2].push_back(Edge(3, 5));
116     g.adj[3].push_back(Edge(2, 5));
117
118     int msts = count_msts(g);
119     cout << "Number of distinct minimum spanning trees: " << msts << endl;
120
121     return 0;
122 }

```

# Output:

Output

/tmp/HWNf2VvhPY.o

Number of distinct minimum spanning trees: 12