

1.2 Supposed  $\mathbf{a} = xz^3\mathbf{e}_x - 2x^2yz\mathbf{e}_y + 2yz^4\mathbf{e}_z$ , calculate rotation on point  $M(1, -1, -1)$ .

1.3 Supposed  $\varphi(x, y, z) = 3x^2y - y^3z^2$ , calculate  $\nabla\varphi$  on point  $M(1, -2, 1)$ .

1.4 calculate  $\nabla\left(\frac{1}{r}\right)$ .

1.2

设  $\mathbf{a} = xz^3\mathbf{e}_x - 2x^2yz\mathbf{e}_y + 2yz^4\mathbf{e}_z$ , 求  $M(1, -1, -1)$  点的旋度。

$$\begin{aligned}\text{解 } \nabla \times \mathbf{a} &= \left( \mathbf{e}_x \frac{\partial}{\partial x} + \mathbf{e}_y \frac{\partial}{\partial y} + \mathbf{e}_z \frac{\partial}{\partial z} \right) \times (xz^3\mathbf{e}_x - 2x^2yz\mathbf{e}_y + 2yz^4\mathbf{e}_z) \\ &= \left( \frac{\partial(2yz^4)}{\partial y} - \frac{\partial(-2x^2yz)}{\partial z} \right) \mathbf{e}_x + \left( \frac{\partial(xz^3)}{\partial z} - \frac{\partial(2yz^4)}{\partial x} \right) \mathbf{e}_y + \left( \frac{\partial(-2x^2yz)}{\partial x} - \frac{\partial(xz^3)}{\partial y} \right) \mathbf{e}_z \\ &= (2z^4 + 2x^2y)\mathbf{e}_x + (3xz^2)\mathbf{e}_y + (-4xyz)\mathbf{e}_z\end{aligned}$$

所以在  $M(1, -1, -1)$  点的旋度为

$$\nabla \times \mathbf{a} = 3\mathbf{e}_y - 4\mathbf{e}_z$$

$$1.3 \text{ 解: } \nabla\varphi = \frac{\partial\varphi}{\partial x}\mathbf{e}_x + \frac{\partial\varphi}{\partial y}\mathbf{e}_y + \frac{\partial\varphi}{\partial z}\mathbf{e}_z$$

$$\begin{aligned}&= \frac{\partial(3x^2y - y^3z^2)}{\partial x}\mathbf{e}_x + \frac{\partial(3x^2y - y^3z^2)}{\partial y}\mathbf{e}_y + \frac{\partial(3x^2y - y^3z^2)}{\partial z}\mathbf{e}_z \\ &= 6xy\mathbf{e}_x + (3x^2 - 3y^2z^2)\mathbf{e}_y - 2y^3z\mathbf{e}_z \\ &= -12\mathbf{e}_x - 9\mathbf{e}_y + 16\mathbf{e}_z\end{aligned}$$

1.4 解: (1) 在直角坐标系中,

$$\begin{aligned}\nabla\left(\frac{1}{r}\right) &= \nabla\left(\frac{1}{\sqrt{x^2 + y^2 + z^2}}\right) = \nabla\left[(x^2 + y^2 + z^2)^{-1/2}\right] \\ &= \frac{\partial(x^2 + y^2 + z^2)^{-1/2}}{\partial x}\mathbf{e}_x + \frac{\partial(x^2 + y^2 + z^2)^{-1/2}}{\partial y}\mathbf{e}_y + \frac{\partial(x^2 + y^2 + z^2)^{-1/2}}{\partial z}\mathbf{e}_z \\ &= -x(x^2 + y^2 + z^2)^{-3/2}\mathbf{e}_x - y(x^2 + y^2 + z^2)^{-3/2}\mathbf{e}_y - z(x^2 + y^2 + z^2)^{-3/2}\mathbf{e}_z \\ &= -\frac{x\mathbf{e}_x + y\mathbf{e}_y + z\mathbf{e}_z}{(x^2 + y^2 + z^2)^{3/2}} = -\frac{\mathbf{r}}{r^3}\end{aligned}$$

(2) 在球坐标系和圆柱坐标系中,

$$\nabla\left(\frac{1}{r}\right) = \mathbf{e}_r \frac{\partial}{\partial r}\left(\frac{1}{r}\right) = -\mathbf{e}_r \frac{1}{r^2} = -\frac{\mathbf{r}}{r^3}$$

1.9 There are vectors  $\mathbf{A}$  and  $\mathbf{B}$ , they satisfy

$$\begin{aligned}\mathbf{A} &= \mathbf{e}_r z^2 \sin \phi + \mathbf{e}_\phi z^2 \cos \phi + \mathbf{e}_z 2rz \sin \phi \\ \mathbf{B} &= \mathbf{e}_x (3y^2 - 2x) + \mathbf{e}_y x^2 + \mathbf{e}_z 2z\end{aligned}$$

(1) which vector can be denoted as gradient of scalar function? And which vector can be denoted as rotation of vector function?

(2) calculate the distribution of vector's source.

1.9 分析：一个无旋矢量场可用一标量函数的梯度来表示，一个无散矢量场可用一矢量函数的旋度来表示。若矢量的散度或旋度不为零，则分别表示了该矢量的源分布。

解：(1) 在柱坐标系中  $\mathbf{A}$  的旋度为

$$\begin{aligned}\nabla \times \mathbf{A} &= \begin{vmatrix} \frac{\mathbf{e}_r}{r} & \mathbf{e}_\phi & \frac{\mathbf{e}_z}{r} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ B_r & rB_\phi & B_z \end{vmatrix} = \begin{vmatrix} \frac{\mathbf{e}_r}{r} & \mathbf{e}_\phi & \frac{\mathbf{e}_z}{r} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ z^2 \sin \phi & rz^2 \cos \phi & 2rz \sin \phi \end{vmatrix} \\ &= \mathbf{e}_r (2z \cos \phi - 2z \cos \phi) + \mathbf{e}_\phi (2z \sin \phi - 2z \sin \phi) + \mathbf{e}_z \left( \frac{z^2 \cos \phi}{r} - \frac{z^2 \cos \phi}{r} \right) = 0\end{aligned}$$

在柱坐标中  $\mathbf{A}$  的散度为

$$\begin{aligned}\nabla \cdot \mathbf{A} &= \frac{1}{r} \frac{\partial}{\partial r} (rz^2 \sin \phi) + \frac{1}{r} \frac{\partial}{\partial \phi} (z^2 \cos \phi) + \frac{\partial}{\partial z} (2rz \sin \phi) \\ &= \frac{z^2 \sin \phi}{r} - \frac{z^2 \sin \phi}{r} + 2r \sin \phi = 2r \sin \phi\end{aligned}$$

可见，矢量  $\mathbf{A}$  为一个有散无旋场，可以用一个标量函数的梯度表示，

其源分布为  $\nabla \cdot \mathbf{A} = 2r \sin \phi$

(2) 在直角坐标系中  $\mathbf{B}$  的散度和旋度分别为

$$\begin{aligned}\nabla \times \mathbf{B} &= \mathbf{e}_x \left( \frac{\partial B_z}{\partial y} - \frac{\partial B_y}{\partial z} \right) + \mathbf{e}_y \left( \frac{\partial B_x}{\partial z} - \frac{\partial B_z}{\partial x} \right) + \mathbf{e}_z \left( \frac{\partial B_y}{\partial x} - \frac{\partial B_x}{\partial y} \right) \\ &= \mathbf{e}_x \left[ \frac{\partial}{\partial y} (2z) - \frac{\partial}{\partial z} (x^2) \right] + \mathbf{e}_y \left[ \frac{\partial}{\partial z} (3y^2 - 2x) - \frac{\partial}{\partial x} (2z) \right] + \mathbf{e}_z \left[ \frac{\partial}{\partial x} (x^2) - \frac{\partial}{\partial y} (3y^2 - 2x) \right] \\ &= 0 + 0 + \mathbf{e}_z (2x - 6y) = \mathbf{e}_z (2x - 6y)\end{aligned}$$

$$\nabla \cdot \mathbf{B} = \frac{\partial B_x}{\partial x} + \frac{\partial B_y}{\partial y} + \frac{\partial B_z}{\partial z} = \frac{\partial}{\partial x} (3y^2 - 2x) + \frac{\partial}{\partial y} (x^2) + \frac{\partial}{\partial z} (2z) = -2 + 0 + 2 = 0$$

可见，矢量  $\mathbf{B}$  为一个无散有旋矢量，可以用一个矢量的旋度表示，其源分布为

$$\nabla \times \mathbf{B} = \mathbf{e}_z(2x - 6y)$$