



# Point Cloud Up-Sampling and Domain Adaptation

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SMART TECHNOLOGY FOR SMARTER MOBILITY

# Structure of the Presentation

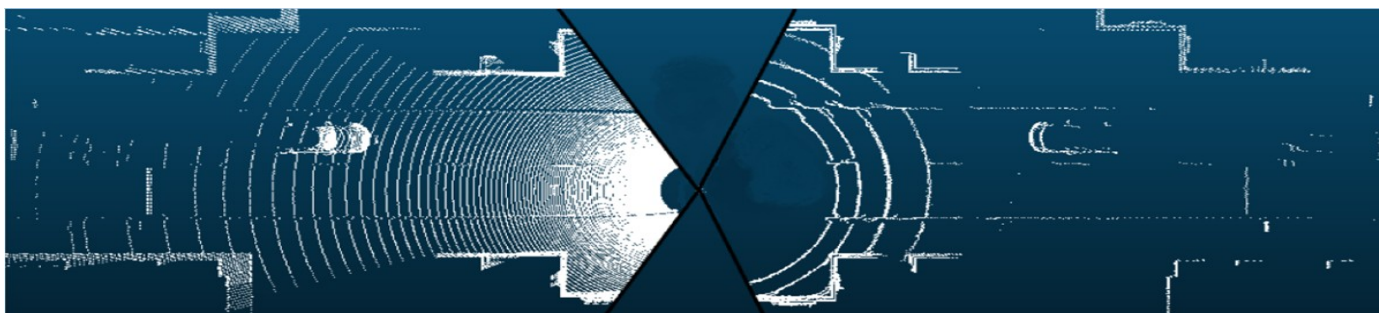
- Challenge
- Results
- Metrics
- Conclusion



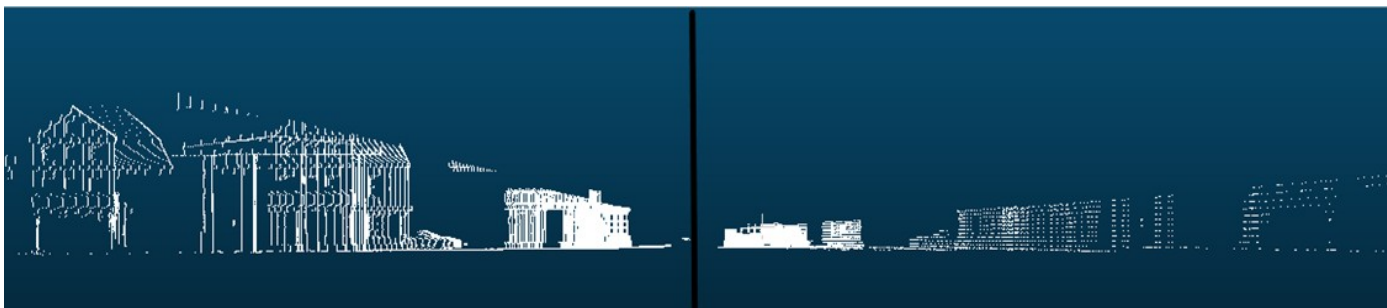
# Challenge: Comparison of Resolution

|                           |        | Horizontal |            | Vertical |            | Maximum Number Of Points | X to Upsample Vertically |
|---------------------------|--------|------------|------------|----------|------------|--------------------------|--------------------------|
|                           |        | Angle      | Resolution | Angle    | Resolution |                          | <b>x8.5</b>              |
| <b>SCALA2<sup>2</sup></b> | Input  | 133°       | 701        | 10°      | 16         | 11216                    |                          |
|                           | Pruned | 120°       | 600        | 10°      | <b>16</b>  | <b>9600</b>              |                          |
| <b>SCALA3<sup>1</sup></b> | Input  | ****       | ****       | ****     | ****       | ****                     |                          |
|                           | Pruned | 120°       | 600        | 10°      | <b>136</b> | <b>81600</b>             |                          |

Comparison of Scala 2 v/s Scala 3 Sensors



BEV Comparison Scal. 3 (Left), Scala 2 (Right)



Comparison Scala3 (Left), Scala2 (Right)



# Comparison Projection Images



Input to the Model (Scala 2 Trace)



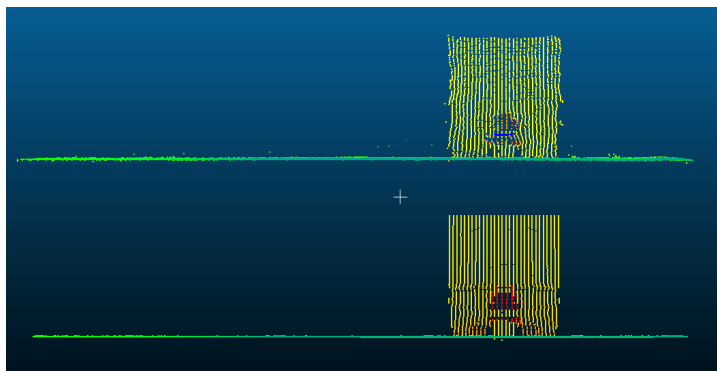
Ground Truth (Scala 3 Trace)



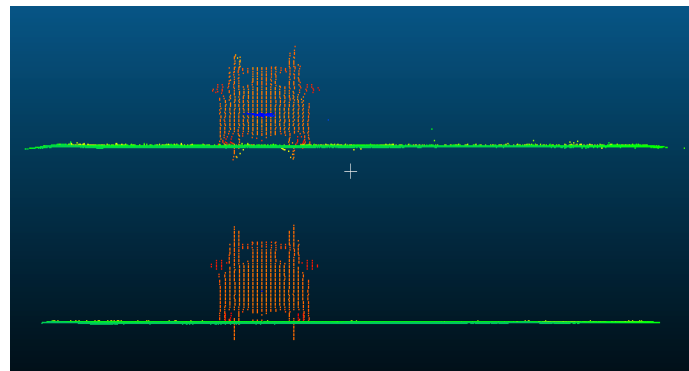
Output of the Model (Prediction)

# Outputs with Range Images Only

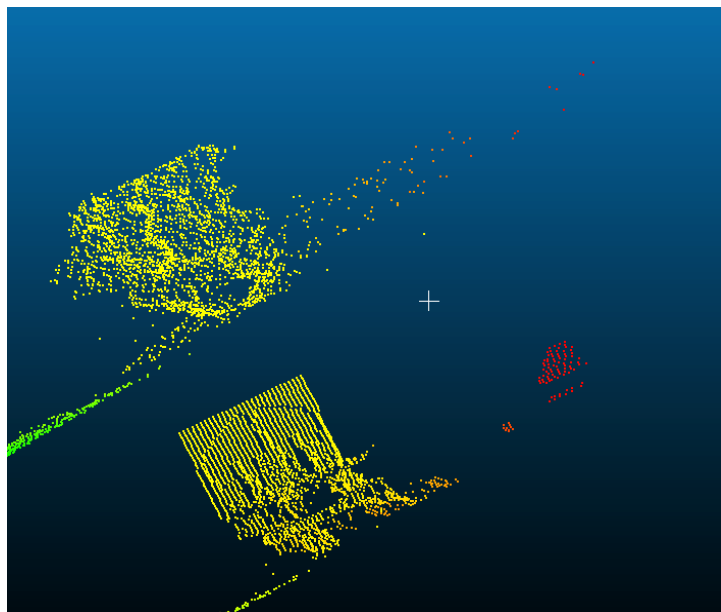
TOP: Prediction & Bottom: Ground Truth



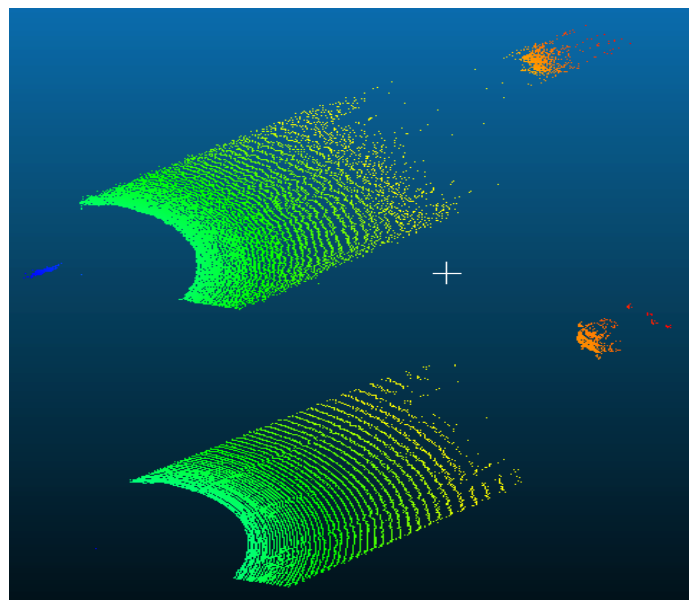
Ego view of the Truck



Ego view of the Car



Magnified Side view of the above Truck

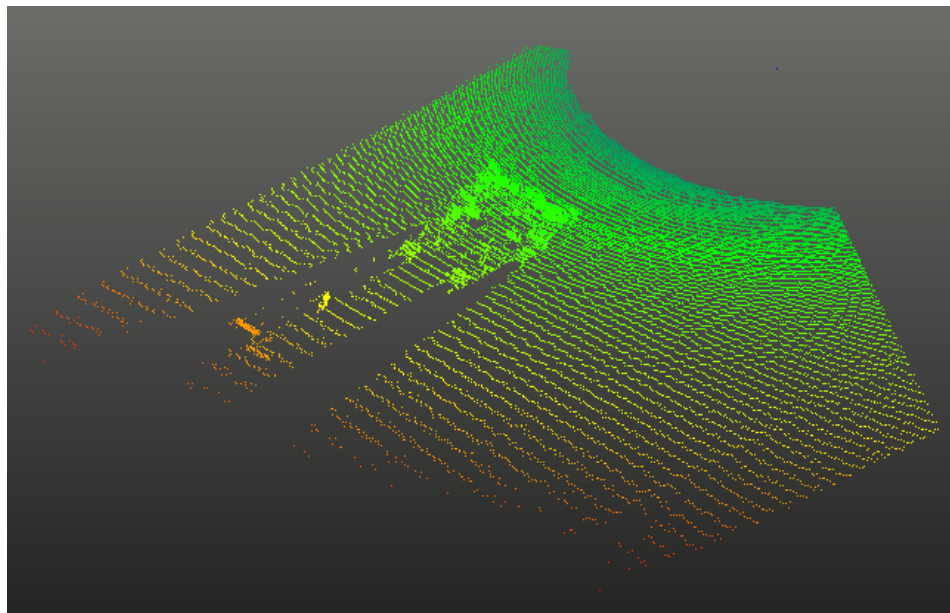


Side view of the above trace

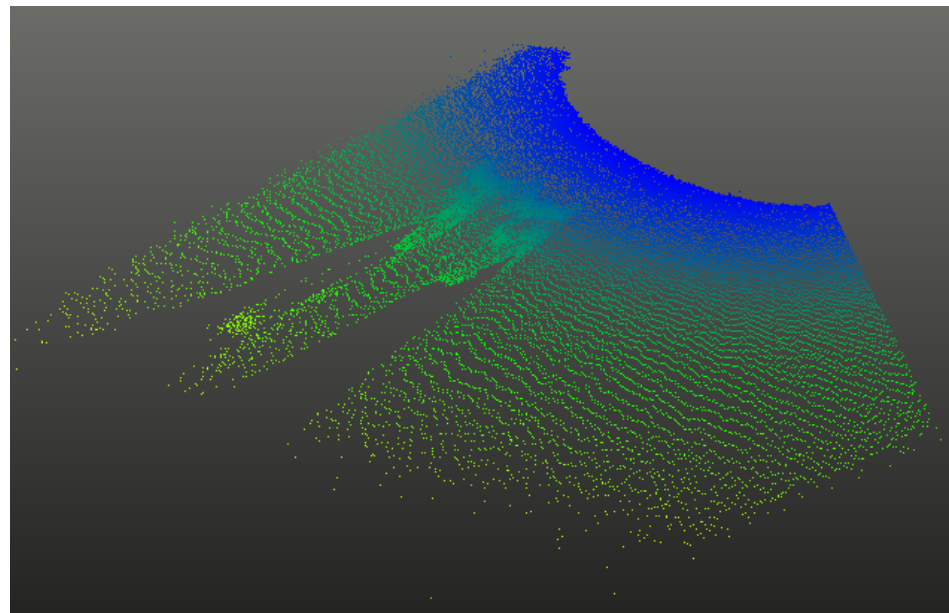




# Output: Single Traffic Object



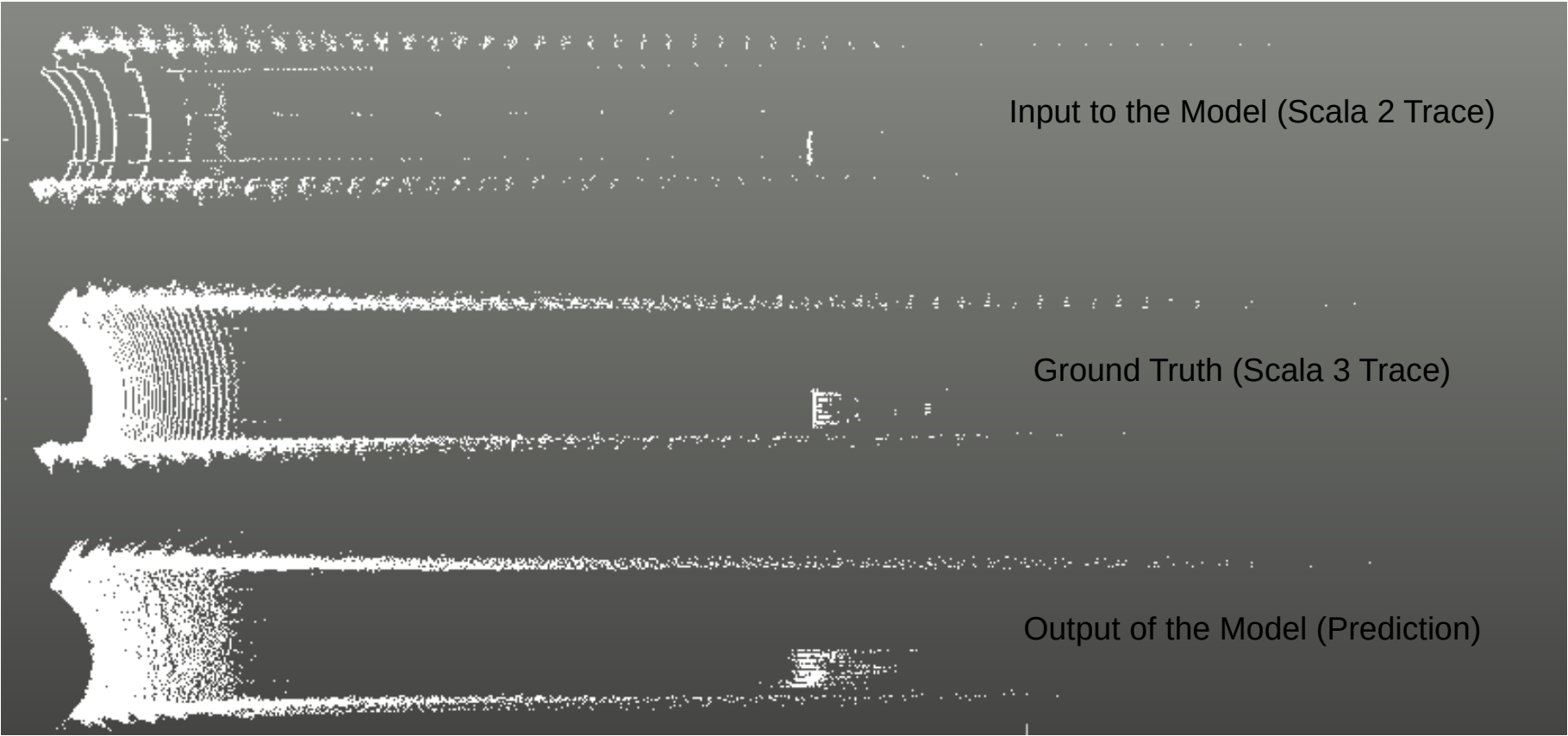
Ground Truth



Output



# Output: Bird Eye View

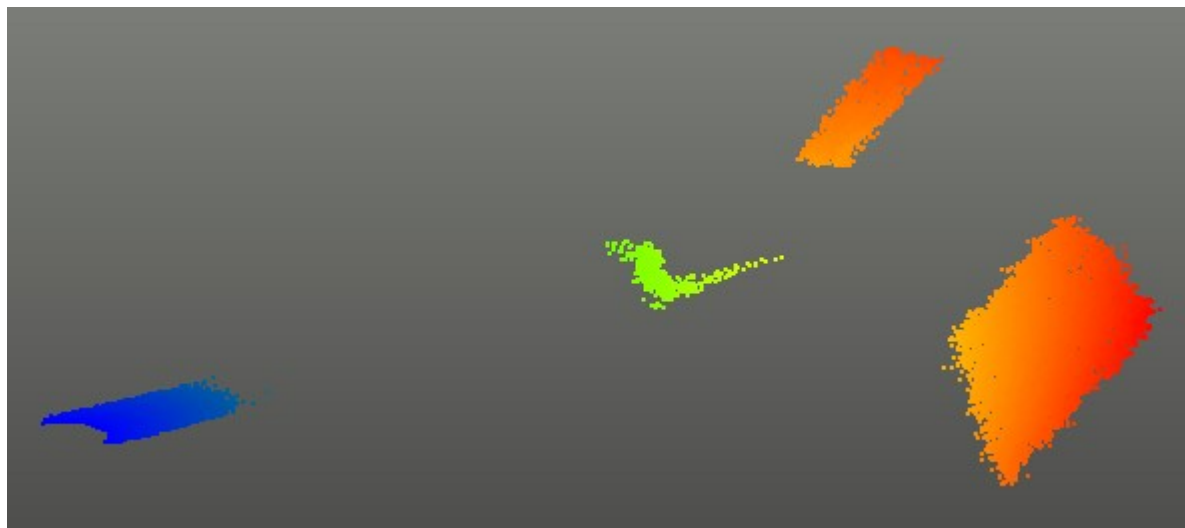




# Output: Clustering



Ground Truth (Scala 3 Trace)



Output of the Model (Prediction)





# Pix2PixHD: Metrics

- Frobenius Norm improves the Output of the Pix2PixHD Model.
- Frobenius Norm gives best results with GAN Feature Matching Loss.

| Models           | PSNR ↑        | WSN Loss ↓     | F1 Score ↑  | EMD ↓        | IOU↑        |
|------------------|---------------|----------------|-------------|--------------|-------------|
| <b>U-Net</b>     | 64.248        | 0.00012        | 0.97        | 0.04         | 0.885       |
| <b>VAE</b>       | 45.94         | 0.00015        | 0.84        | 0.200        | 0.713       |
| <b>VNL</b>       | 60.511        | 0.00015        | 0.92        | 0.0512       | 0.805       |
| <b>GAN</b>       | 35.541        | 0.0008         | 0.74        | 0.328        | 0.394       |
| <b>wGAN</b>      | 15.596        | 0.0011         | 0.62        | 0.489        | 0.347       |
| <b>Pix2PixHD</b> | <b>74.244</b> | <b>0.00006</b> | <b>1.00</b> | <b>0.024</b> | <b>0.99</b> |

Comparison of the performance of different models against different metrics



# Conclusion

## Achievements:

- Complex Traffic Object Upsampling (x8.5 times).
- Successfully accomplished Domain Adaptation from SCALA2 to SCALA3.
- Successfully train Deep Learning Model.
- Dataset Creation & Validation pipeline.
- Material Identification via Clustering.

## Future Directions:

- Real Traces Integration and Testing.
- Wider Application Exploration in Different Teams.
- Improve the Performance of the model to upsample Lane Markings.