



NPTEL ONLINE CERTIFICATION COURSES

Course Name: Deep Learning

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Department : E & ECE, IIT Kharagpur

Topic

Lecture 42: Popular CNN Models VI

CONCEPTS COVERED

Concepts Covered:

- ❑ CNN

- ❑ Challenges in Deep Learning

- ❑ GoogLeNet

- ❑ ResNet

- ❑ Momentum Optimizer



Challenges

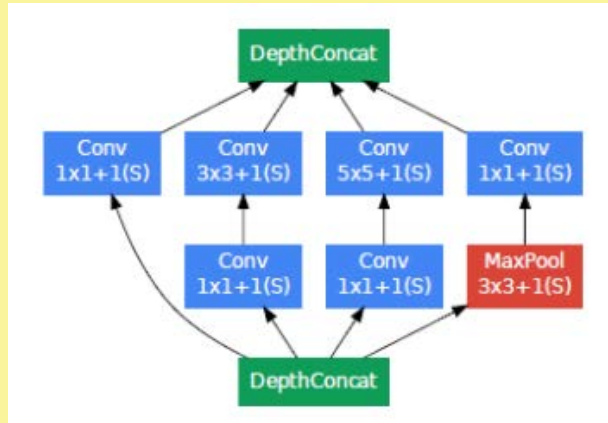
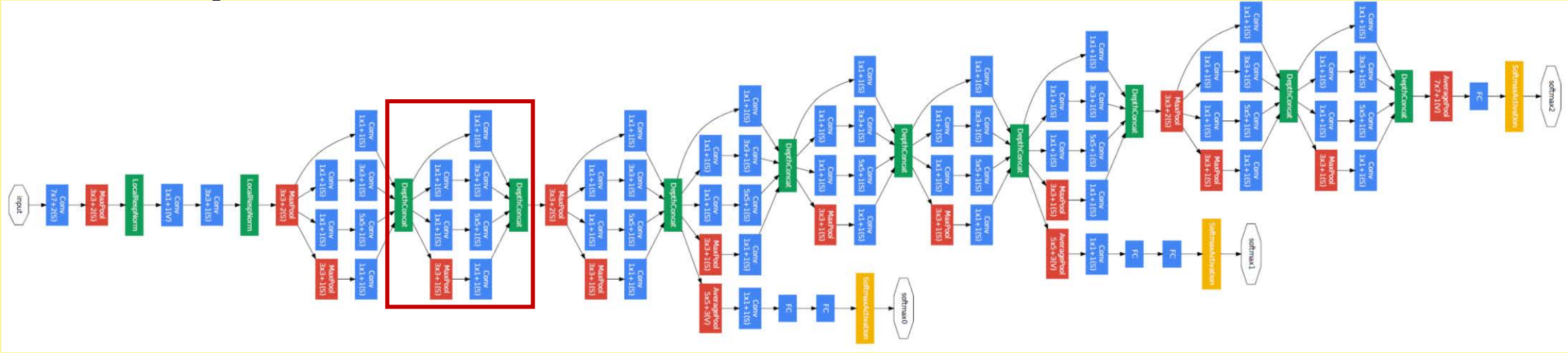
- ☐ Deep learning is data hungry.
- ☐ Overfitting or lack of generalization.
- ☐ Vanishing/Exploding Gradient Problem.
- ☐ Appropriate Learning Rate.
- ☐ Covariate Shift.
- ☐ Effective training.



Vanishing Gradient Problem

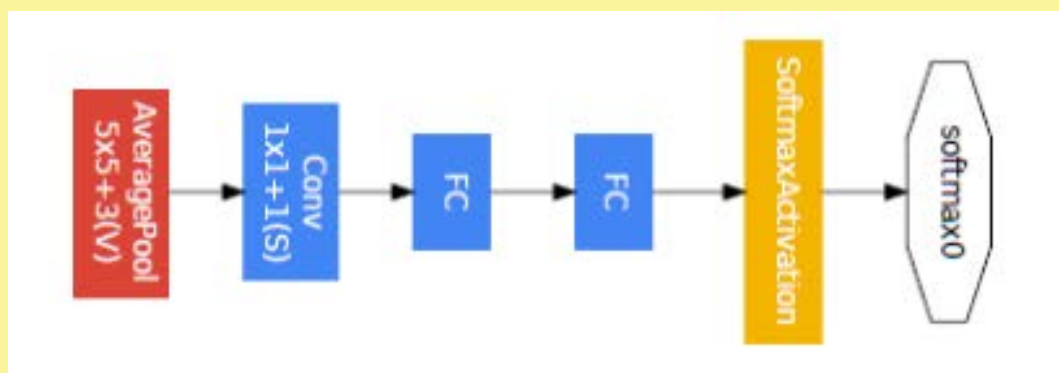
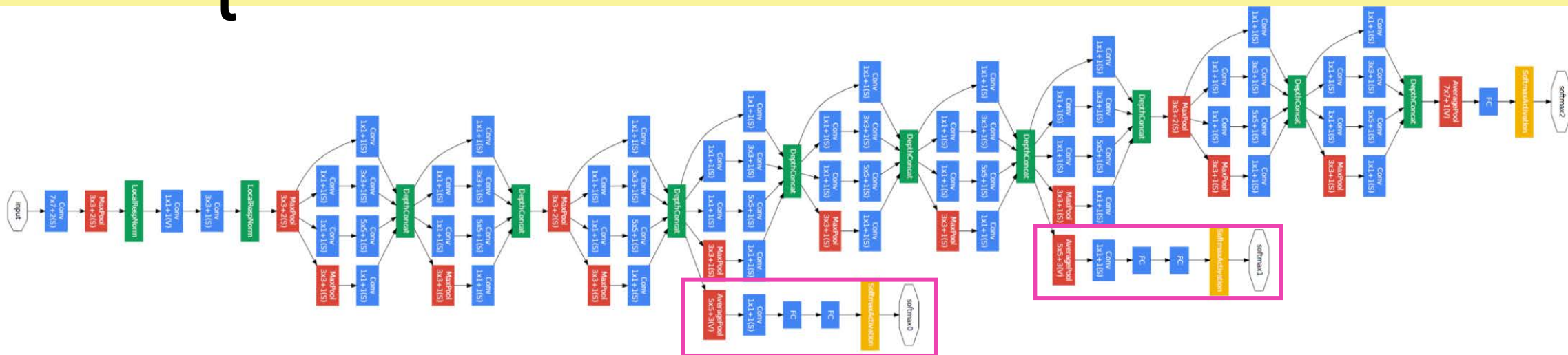
- ❑ Choice of activation function: ReLU instead of Sigmoid.
- ❑ Appropriate initialization of weights.
- ❑ Intelligent Back Propagation Learning Algorithm.





Inception Module

GoogLeNet



Auxiliary Classifier



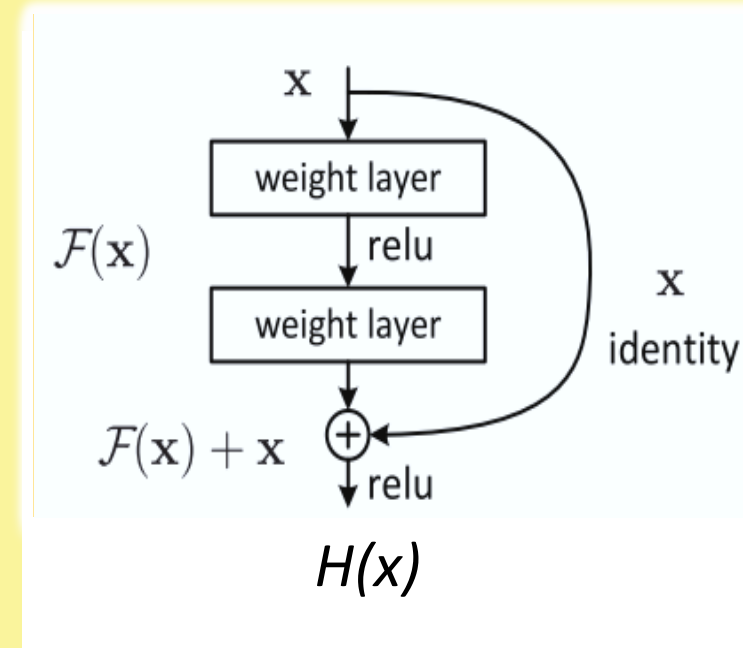
ResNet



ResNe

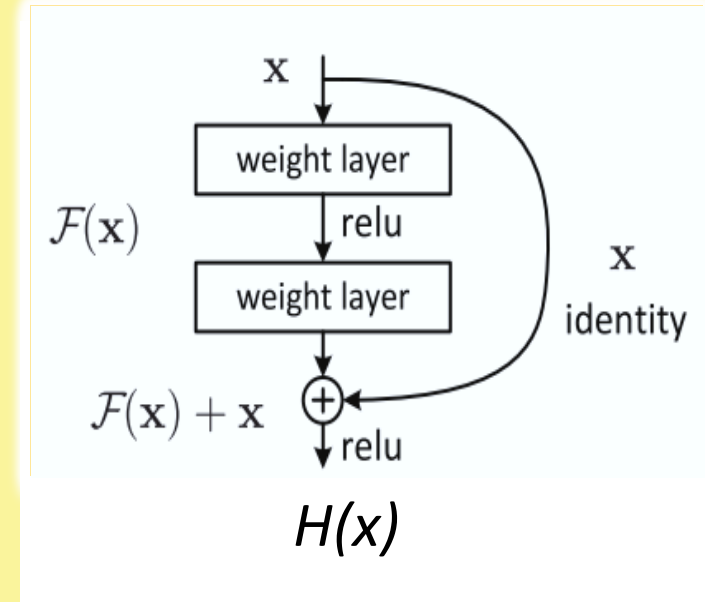
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- ❑ Core idea is: introduction of Skip Connection/ Identity Shortcut Connection that skips one or more layers.
- ❑ Stacking layers should not degrade performance compared to its shallow counterpart.
- ❑ Weight layer learns $F(x)=H(x)-x$



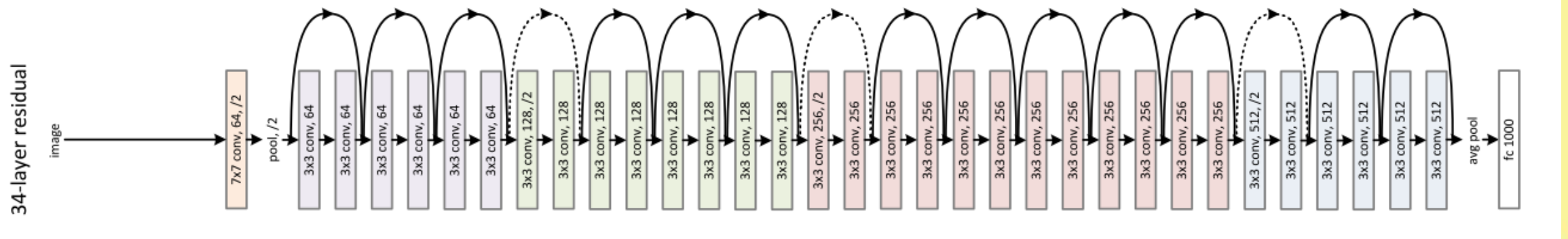
ResNe

- By stacking identity mappings the resultant deep network should give at least same performance as its shallow counterpart.
- Deeper network should not give higher training error than shallow network.
- During learning the gradient can flow to any earlier network through shortcut connections alleviating vanishing gradient problem.



ResNe t

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<https://towardsdatascience.com/an-overview-of-resnet-and-its-variants-5281e2f56035>

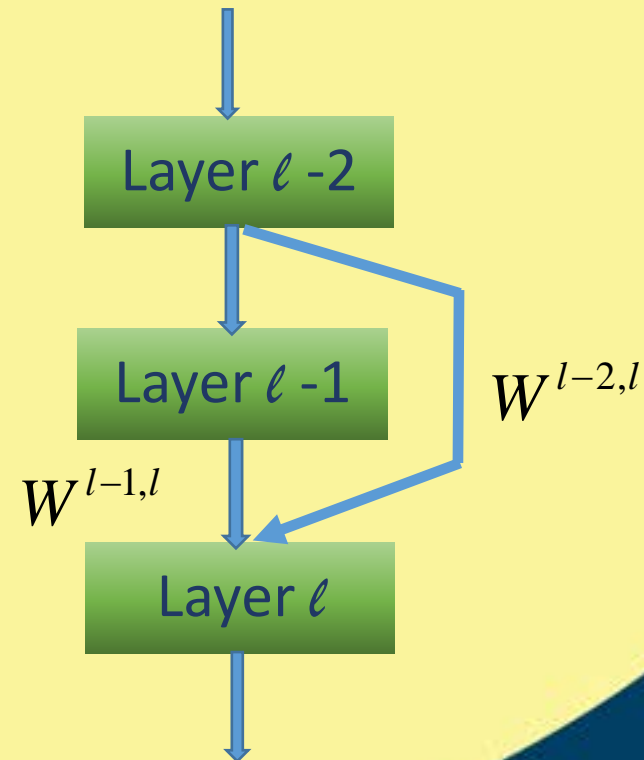
ResNe

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Forward flow:

$$\begin{aligned} a^l &= f(W^{l-1,l} \cdot a^{l-1} + b^l + W^{l-2,l} \cdot a^{l-2}) \\ &= f(Z^l + W^{l-2,l} \cdot a^{l-2}) \end{aligned}$$

$$a^l = f(Z^l + a^{l-2}) \quad \text{if same dimension}$$

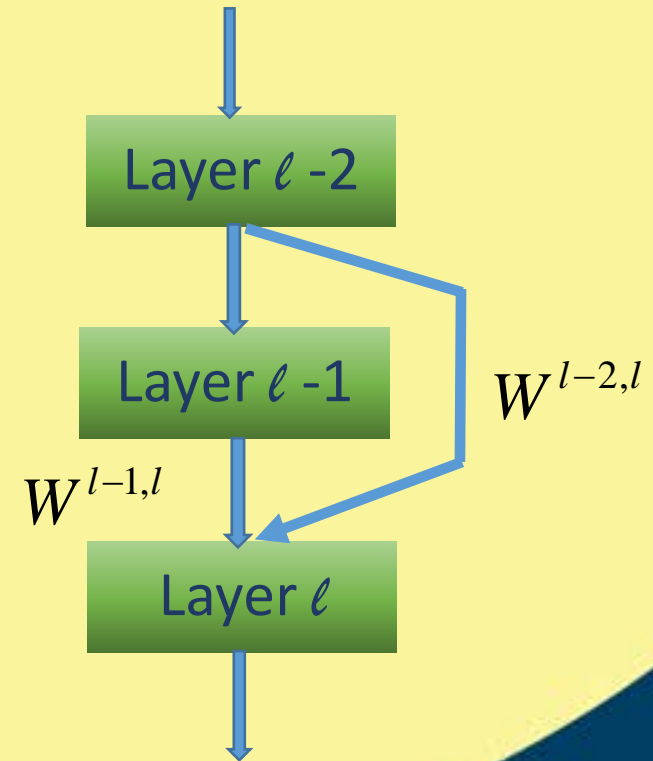


Backward Propagation:

$$\nabla W^{l-1,l} = -a^{l-1} \cdot \delta^l \quad \text{normal path}$$

$$\nabla W^{l-2,l} = -a^{l-2} \cdot \delta^l \quad \text{skip path}$$

If the skip path has fixed weights, identity matrix, then they are not updated.



Challenges

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Optimizing Gradient Descent



Gradient Descent Challenges

Challenges of Mini-batch Gradient Descent

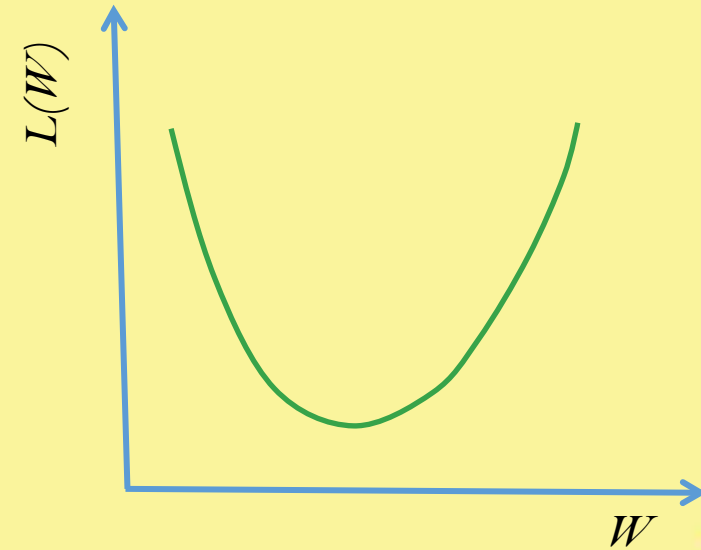
- ☐ Choice of Proper Learning Rate:
 - ☐ Too small a learning rate leads to slow convergence.
 - ☐ A large learning rate may lead to oscillation around the minima or may even diverge.



Gradient Descent Challenges

Challenges of Mini-batch Gradient Descent

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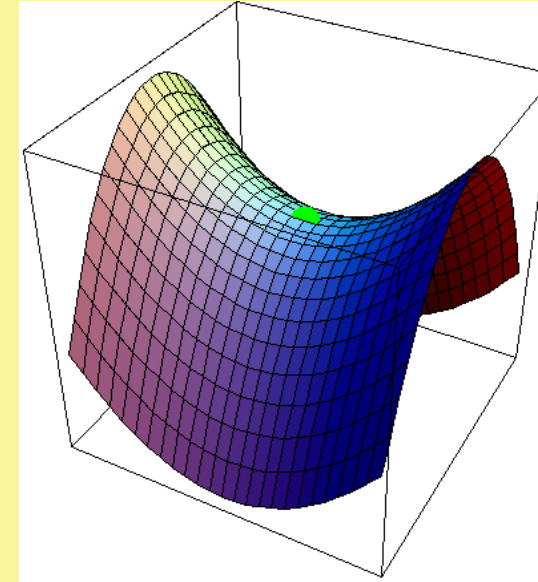
Gradient Descent Challenges

- ☐ Learning Rate Schedules: changing learning rate according to some predefined schedule.
- ☐ The same learning rate applies to all parameter updates.
- ☐ The data may be sparse and different features have very different frequencies.
- ☐ Updating all of them to the same extent might not be proper.
- ☐ Larger update for rarely occurring features might be a better choice.

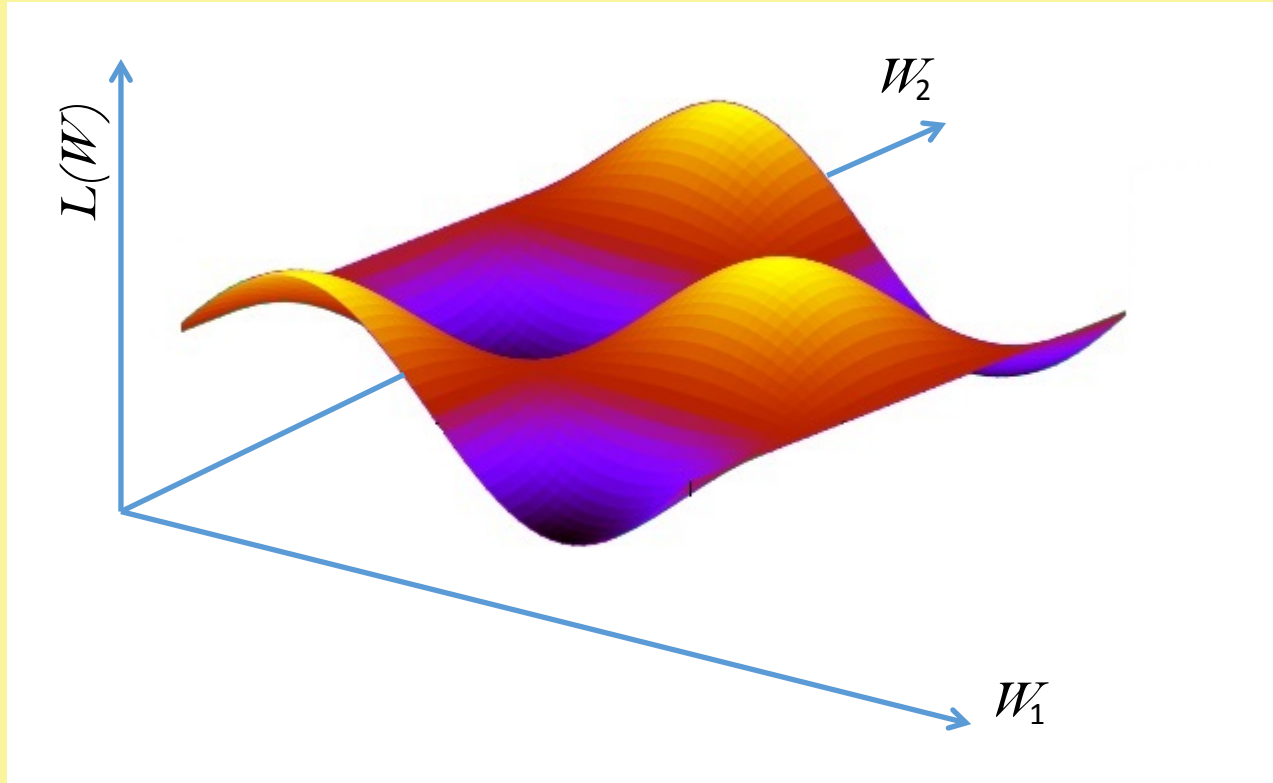


Gradient Descent Challenges

- ❑ Avoiding getting trapped in suboptimal local minima.
- ❑ Difficulty arises in from saddle points, i.e. points where one dimension slopes up and another slopes down.
- ❑ These saddle points are usually surrounded by a plateau of the same error, which makes it hard for SGD to escape, as the gradient is close to zero in all dimensions.



Momentum Optimizer





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*Thank
you*

