

Graph Neural Networks

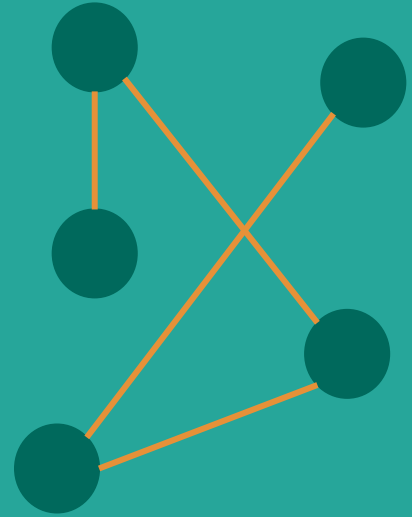
Inspired from my University Thesis and UPenn ESE 5140

Hetav Pandya (HP)

Watch out for the KitKat
questions!



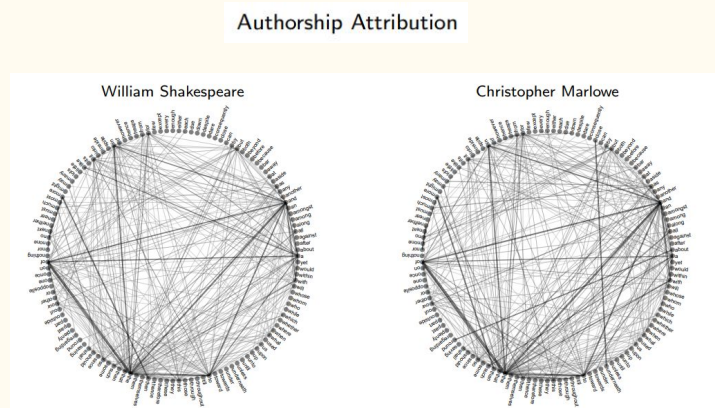
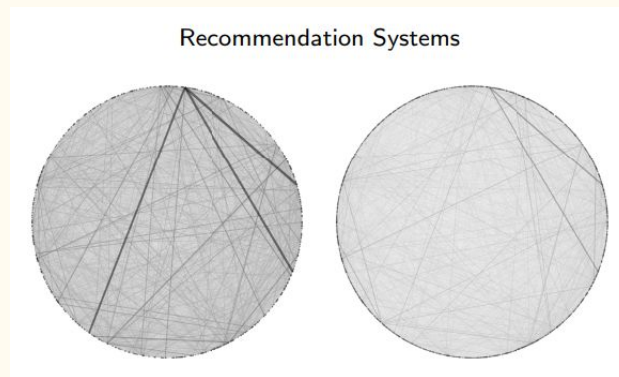
Let's talk about
Graph Networks!



Explicit and Implicit cases

Social media networks, ASIC design problems, devices on a network...

But you don't need an explicit graphical structure to exploit graphical algorithms and techniques!

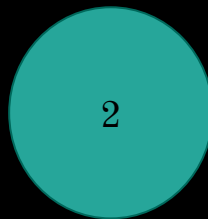
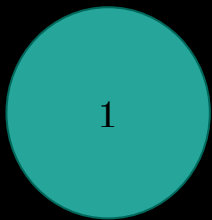


Some business use cases

- Document Classification and Information Extraction
- Personalized Content Delivery
- Telecommunications Network Management
- Mapping spread of infectious diseases
- Determining political bias in a section of population
- Detecting anomalies and potential threats in network traffic
- Molecular property prediction in drugs

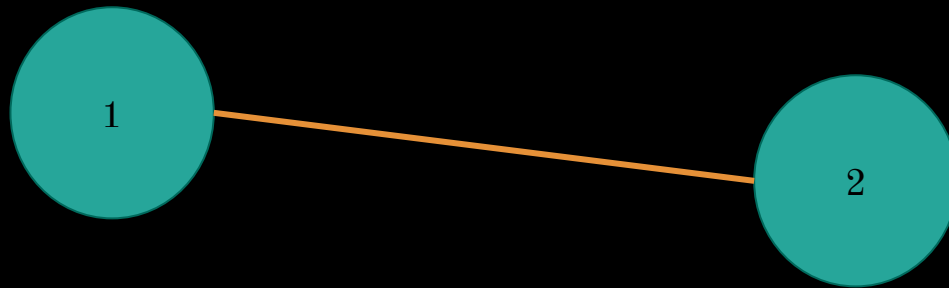
The basics





Nodes

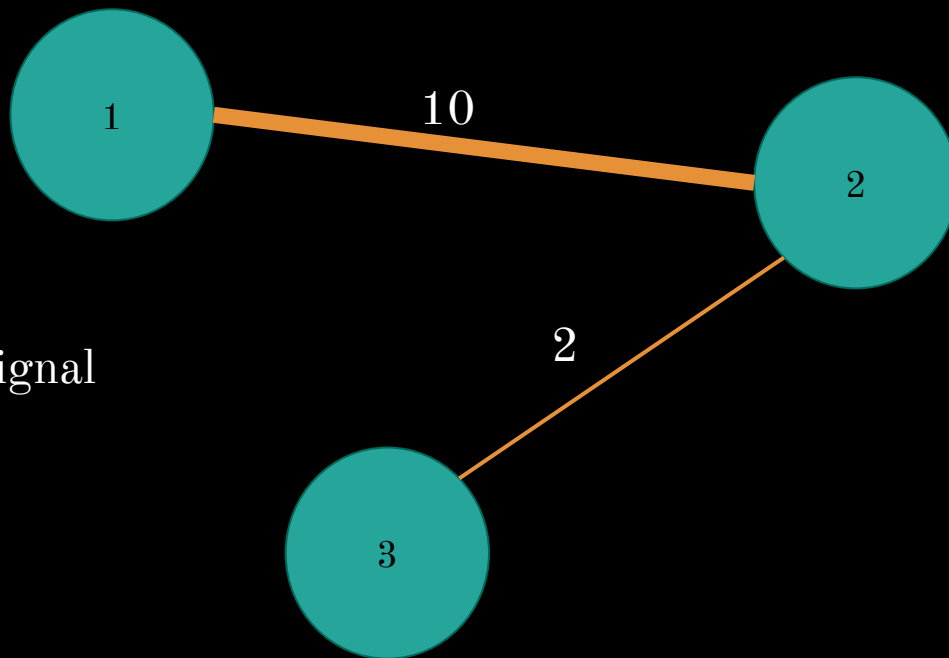




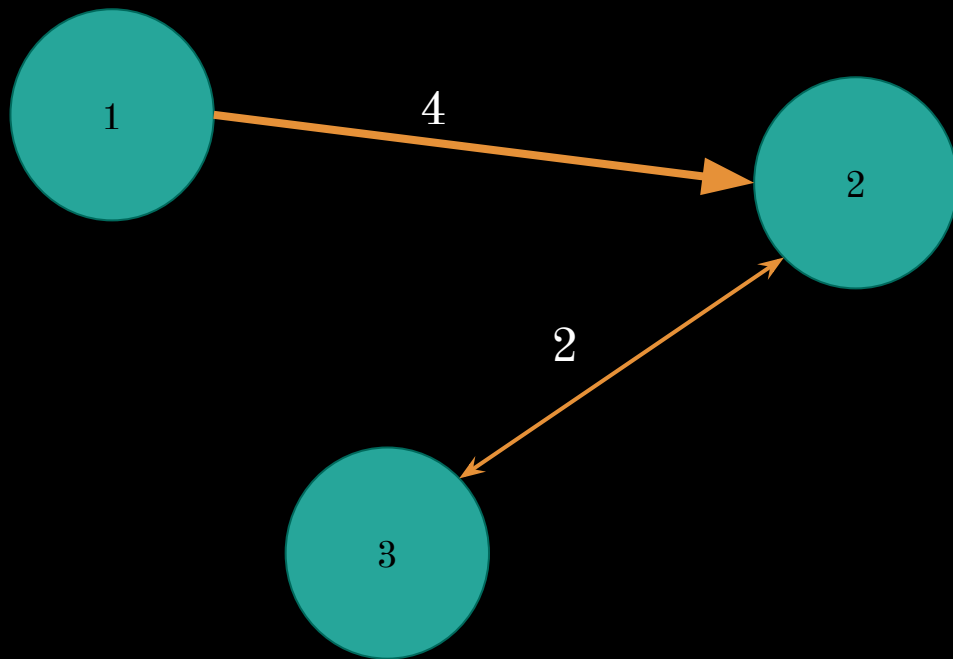
Edges



Weights / Signal
Values



Direction



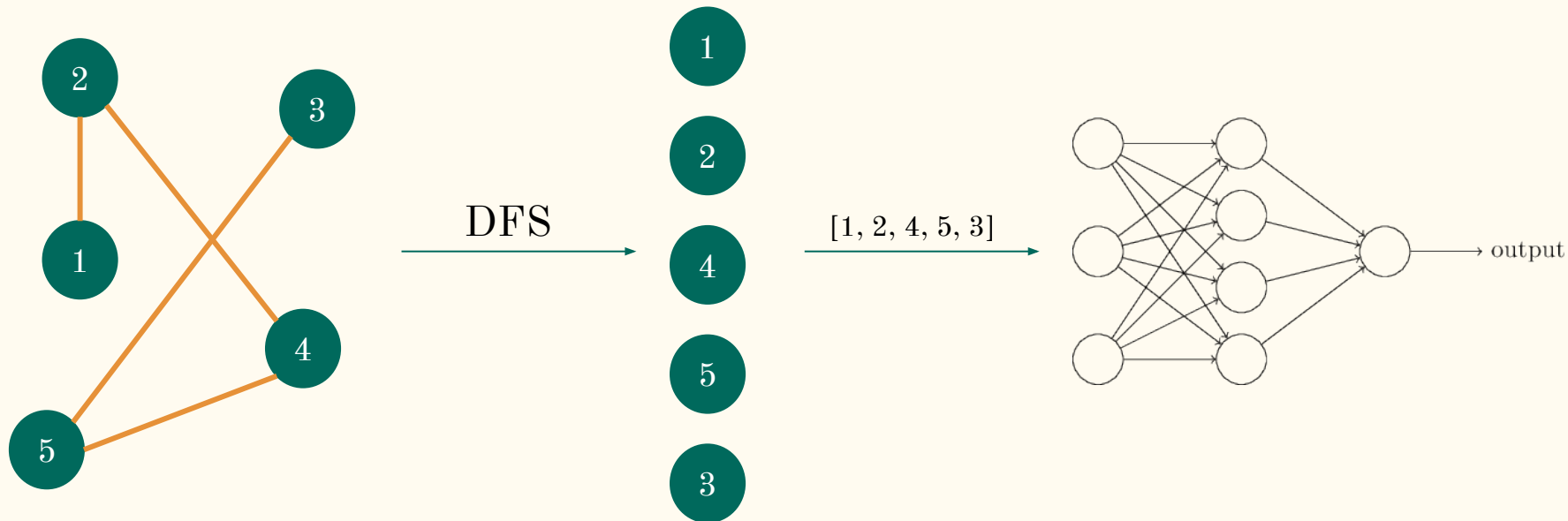
First iteration

Let's logically build up a GNN

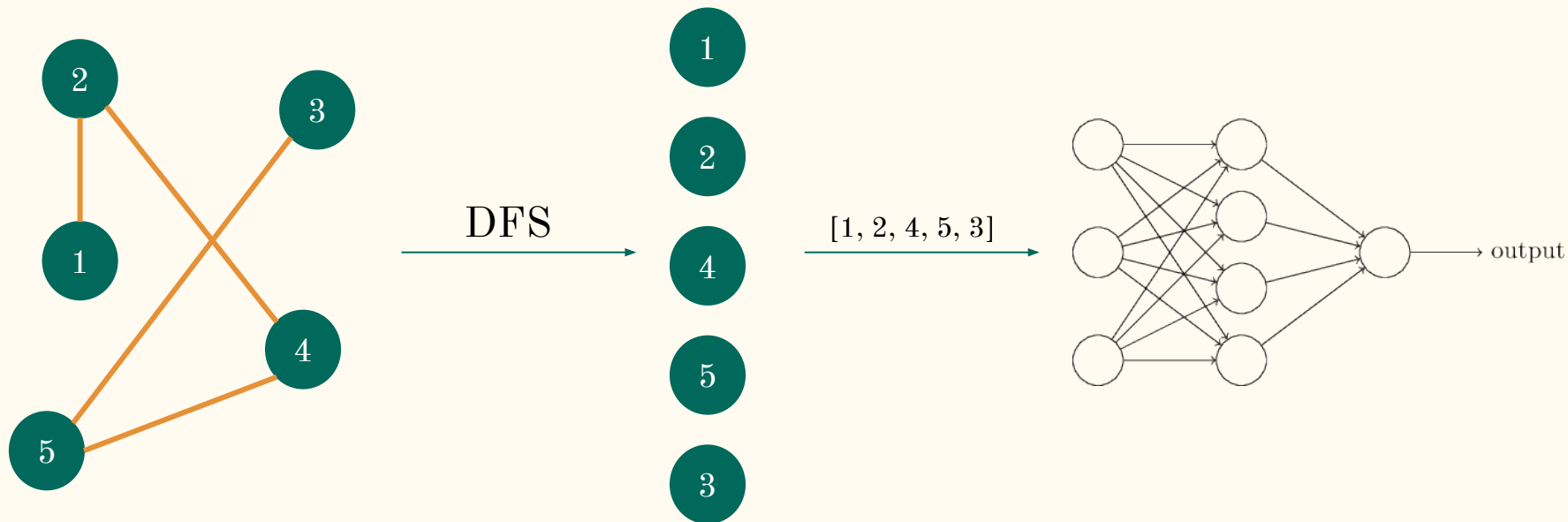
- What do we have?
- A Graph
- Concept of neural network



Iteration 1:

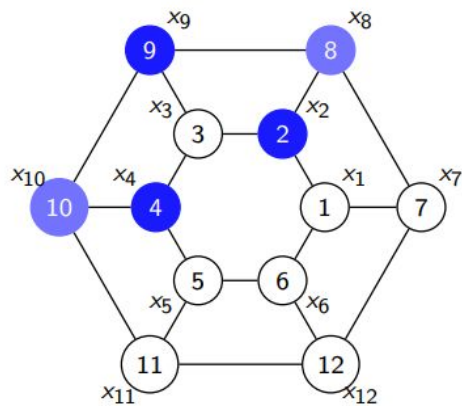


Iteration 1: What are we missing?

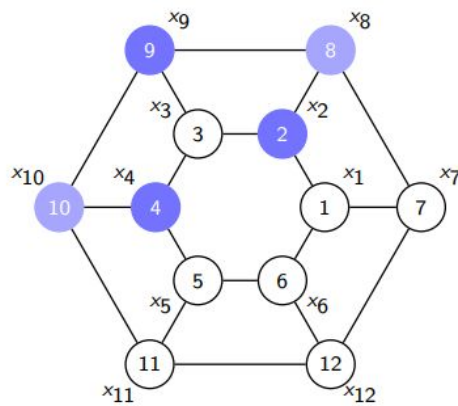




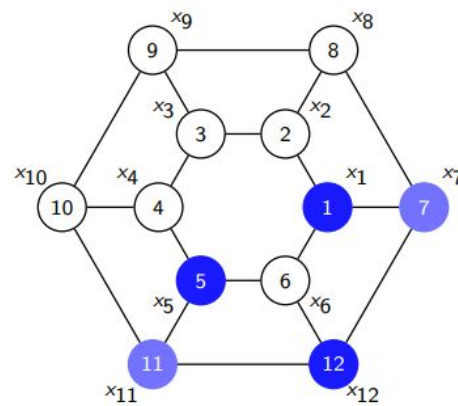
Iteration 1: What are we missing?



Training Data



Test Data #1



Test Data #2

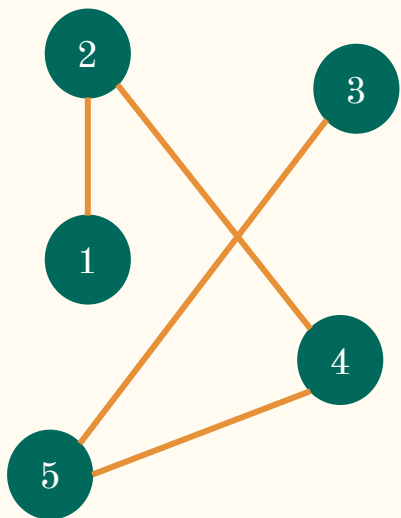
Second iteration

Let's logically build up a GNN

- What do we have?
 - A Graph
 - Concept of neural network
 - Need to encode the graph relationships
-

Let's introduce
the concept of
Graph Shift
Operators

Adjacency Matrix: S



0	1	0	0	0
1	0	0	1	0
0	0	0	0	1
0	1	0	0	1
0	0	1	1	0

Types of Graph Shift Operators

Adjacency Matrix

Does not have degree info

Laplacian Matrix

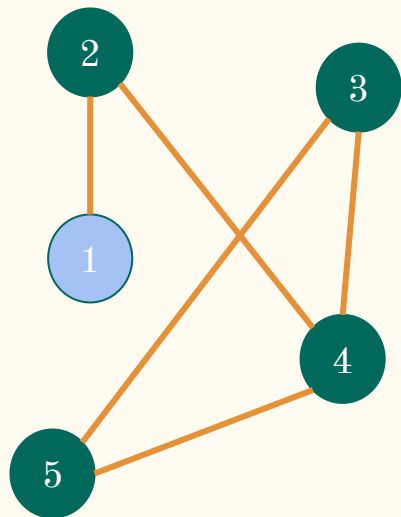
Has degree info

Normalized Adjacency Matrix

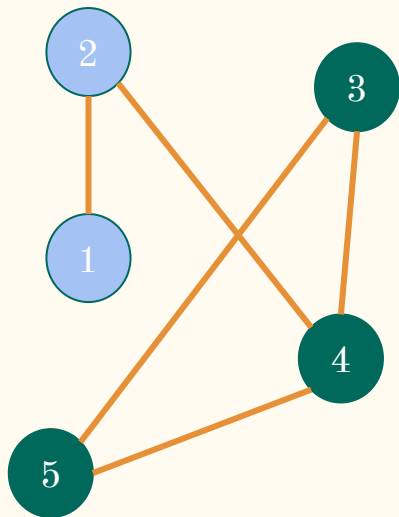
Normalized Laplacian Matrix

Convolution with Graph Shift Operator

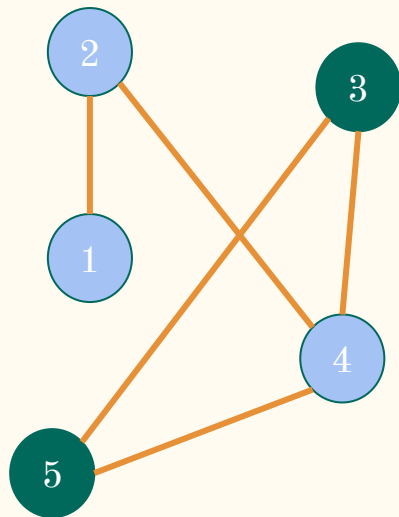
$$\sum_{k=0}^{\infty} h_k \mathbf{S}^k \mathbf{x}$$



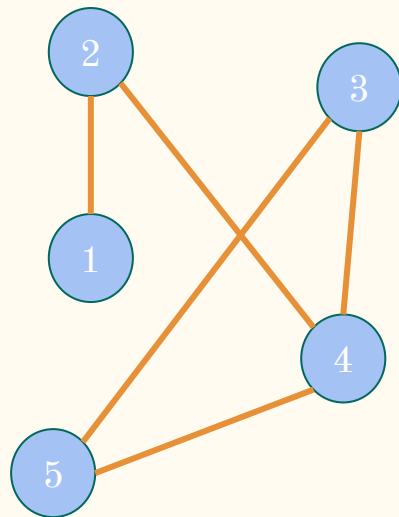
$$h_0 \mathbf{S}^0 \mathbf{x}$$



$$h_1 \mathbf{S}^1 \mathbf{x}$$



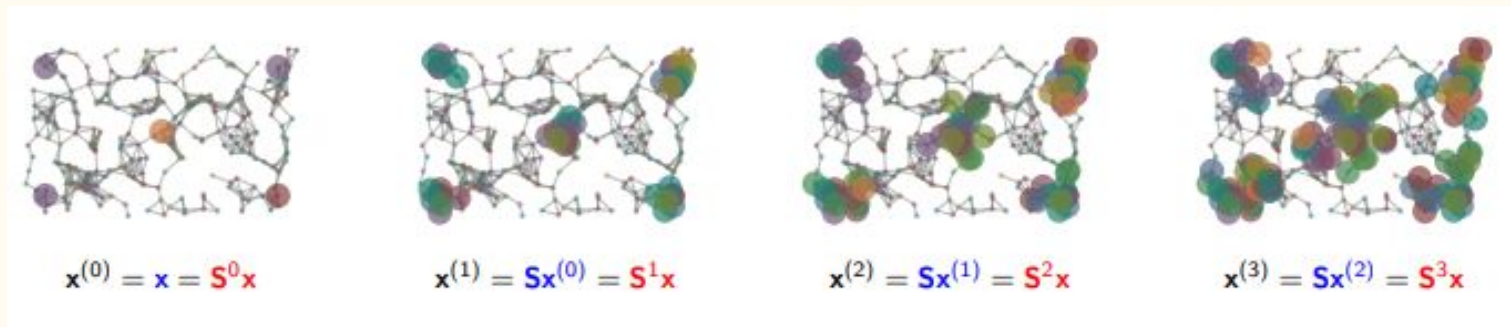
$$h_2 \mathbf{S}^2 \mathbf{x}$$



$$h_3 \mathbf{S}^3 \mathbf{x}$$

Convolution with Graph Shift Operator

Real-life example



Notice that we started with 5 nodes and the shift operator gives us information about graph locality and connections



But we are still missing a very important piece!

Hint: We are relying on a “linear” combination of matrix S multiplications.

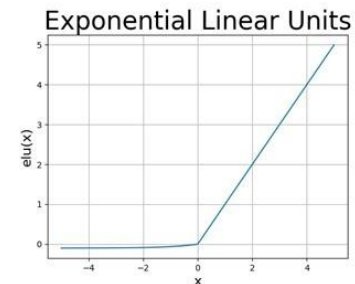
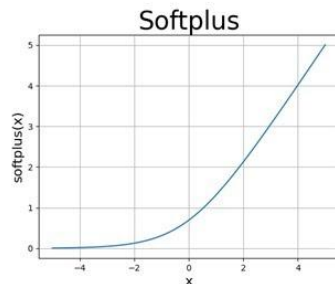
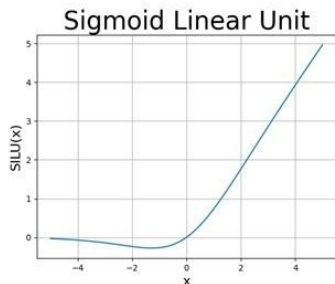
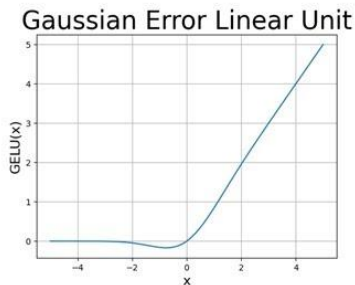
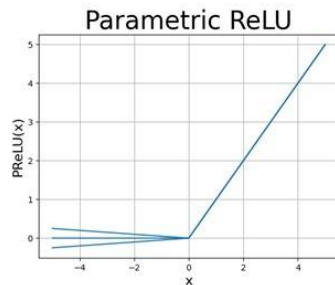
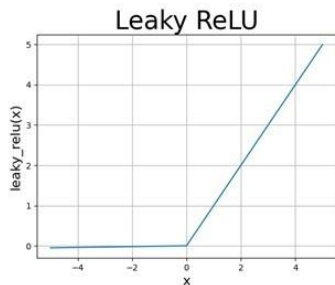
Third iteration

Let's logically build up a GNN

- What do we have?
 - A Graph
 - Concept of neural network
 - Graph Shift Operator
 - Need for non-linearity
-

What are non-linearities?

ReLU Variants



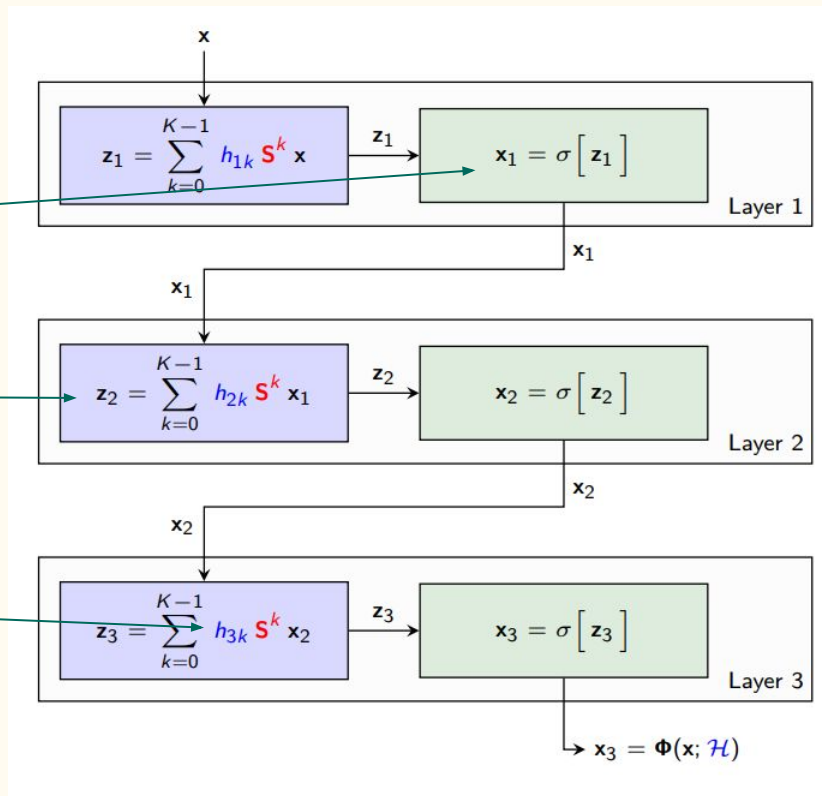
Nonlinearity implies that the relationship between input and output is more complex and cannot be expressed as a simple linear function.

How does it all come together!

Non-linearity

Convolutional filters

Trainable parameters (h)



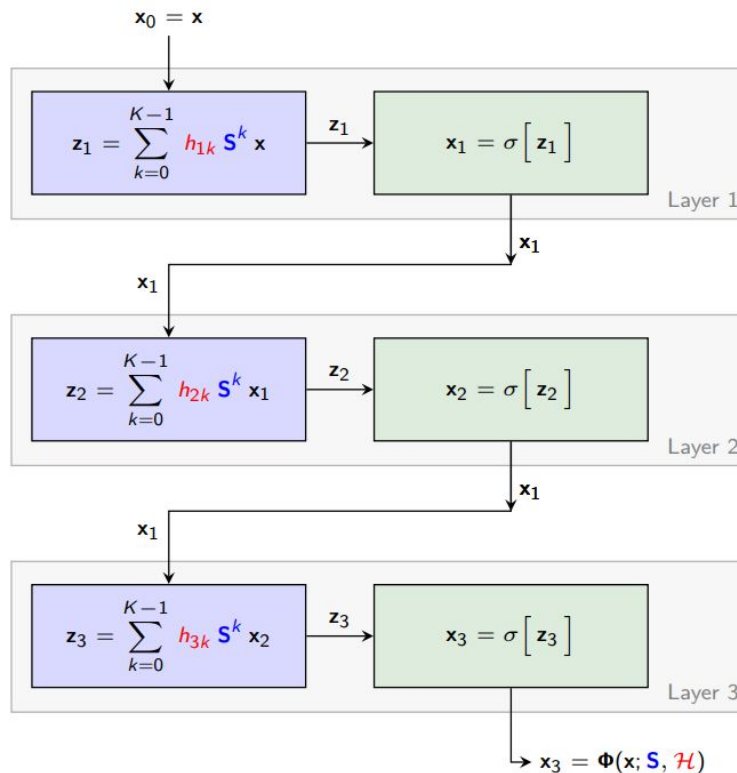
The process of training...

- Learn Optimal GNN tensor $\mathcal{H}^* = (\mathbf{h}_1^*, \mathbf{h}_2^*, \mathbf{h}_3^*)$ as

$$\mathcal{H}^* = \operatorname{argmin}_{\mathcal{H}} \sum_{(\mathbf{x}, \mathbf{y}) \in \mathcal{T}} \ell(\Phi(\mathbf{x}; \mathbf{S}, \mathcal{H}), \mathbf{y})$$

- Optimization is over tensor only. Graph \mathbf{S} is given

⇒ Prior information given to the GNN



Demo Time!

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If time permits...

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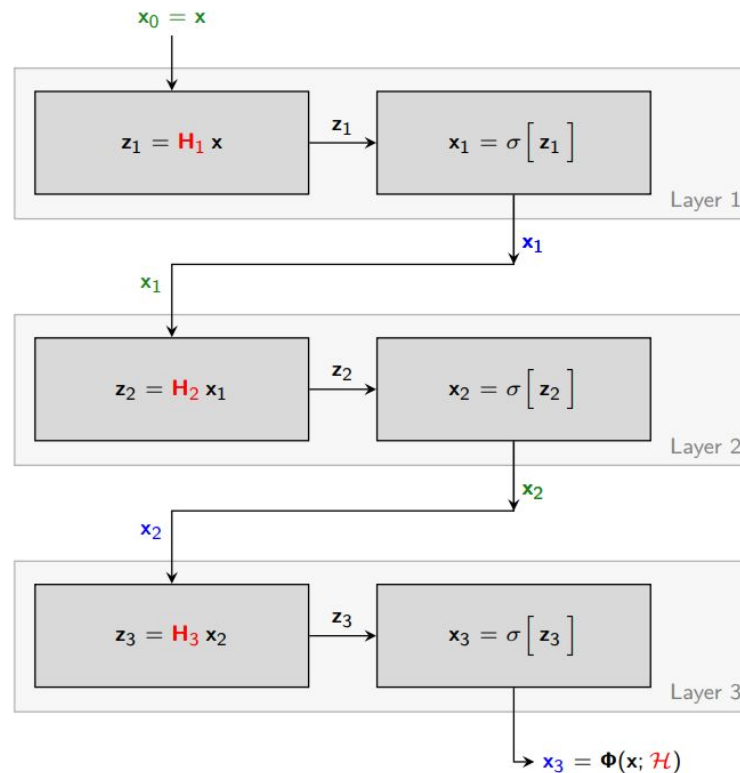
A brief discussion about FCNN

- Illustrate definition with an FCNN with 3 layers

- Feed input signal $\mathbf{x} = \mathbf{x}_0$ into Layer 1

$$\mathbf{x}_1 = \sigma[\mathbf{z}_1] = \sigma[\mathbf{H}_{1k} \mathbf{x}_0]$$

- Output $\Phi(\mathbf{x}; \mathcal{H})$ Parametrized by $\mathcal{H} = [\mathbf{H}_1, \mathbf{H}_2, \mathbf{H}_3]$





FCNN vs GNN

Which one would theoretically perform better?

- ▶ Since the GNN is a particular case of a fully connected NN, the latter attains a smaller cost

$$\min_{\mathcal{H}} \sum_{(\mathbf{x}, \mathbf{y}) \in \mathcal{T}} \ell(\Phi(\mathbf{x}; \mathcal{H}), \mathbf{y}) \leq \min_{\mathcal{H}} \sum_{(\mathbf{x}, \mathbf{y}) \in \mathcal{T}} \ell(\Phi(\mathbf{x}; \mathbf{S}, \mathcal{H}), \mathbf{y})$$

- ▶ The fully connected NN does better. But this holds for the training set
- ▶ In practice, the GNN does better because it generalizes better to unseen signals
 - ⇒ Because it exploits internal symmetries of graph signals codified in the graph shift operator

Laplacian Shift Operators

Laplacian Matrix

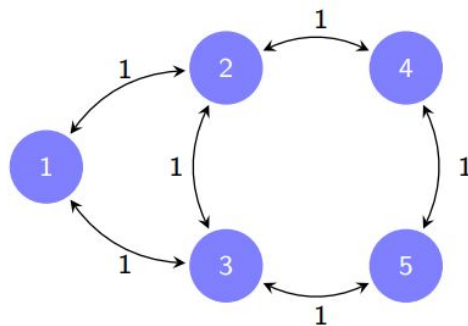
► The **Laplacian** matrix of a graph with adjacency matrix **A** is $\Rightarrow \mathbf{L} = \mathbf{D} - \mathbf{A} = \text{diag}(\mathbf{A}\mathbf{1}) - \mathbf{A}$

► Can also be written explicitly in terms of graph weights $A_{ij} = w_{ij}$

\Rightarrow Off diagonal entries $\Rightarrow L_{ij} = -A_{ij} = -w_{ij}$

\Rightarrow Diagonal entries $\Rightarrow L_{ii} = d_i = \sum_{j \in n(i)} w_{ij}$

$$\mathbf{L} = \begin{bmatrix} 2 & -1 & -1 & 0 & 0 \\ -1 & 3 & -1 & -1 & 0 \\ -1 & -1 & 3 & 0 & -1 \\ 0 & -1 & 0 & 2 & -1 \\ 0 & 0 & -1 & -1 & 2 \end{bmatrix}$$



Thank you!



Let's keep
connected!



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University of Toronto Alumnus | Compute...



Feedback!

