1 5.9

$$egin{aligned} \mathbf{S} &= \mathbf{N} (\mathbf{N}^T \mathbf{N} + \lambda \Omega_N)^{-1} \mathbf{N}^T \ &= \mathbf{N} (\mathbf{N}^T (\mathbf{I} + \lambda (\mathbf{N}^T)^{-1} \Omega_N \mathbf{N}^{-1}) \mathbf{N})^{-1} \mathbf{N}^T \ &= (\mathbf{I} + \lambda \mathbf{K})^{-1} \end{aligned}$$

 $\sharp \mathbf{K} = (\mathbf{N}^T)^{-1} \Omega_N N^{-1}$

2 5.13

记 $\hat{f}_{\lambda}^{(-i)}$ 是排除第i个样本之后的拟合函数。

$$egin{aligned} \hat{f}_{\lambda}^{(-i)}(x_i) &= rac{1}{1-S_{\lambda}(i,i)} \sum_{j
eq i} S_{\lambda}(i,j) y_j \ &= \sum_{j
eq i} S_{\lambda}(i,j) y_j + S_{\lambda}(i,i) \hat{f}_{\lambda}^{(-i)}(x_i) \end{aligned}$$

也就是说

$$\hat{f}_{\lambda}^{(-i)}(x_i) = \hat{f}_{\lambda}(x_i) + S_{\lambda}(i,i)\hat{f}_{\lambda}^{(-i)}(x_i) - S_{\lambda}(i,i)y_i \ (1-S_{\lambda}(i,i))\left(\hat{f}_{\lambda}^{(-i)}(x_i) - y_i
ight) = \hat{f}_{\lambda}(x_i) - y_i \ y_i - \hat{f}_{\lambda}^{(-i)}(x_i) = rac{y_i - \hat{f}_{\lambda}(x_i)}{1-S_{\lambda}(i,i)}$$

所以

$$CV(\hat{f}_{\lambda}) = \sum_{i=1}^N \left(y_i - \hat{f}_{\lambda}^{(-i)}(x_i)
ight)^2 = \sum_{i=1}^N \left(rac{y_i - \hat{f}_{\lambda}(x_i)}{1 - S_{\lambda}(i,i)}
ight)^2$$

3 5.15

(1)

$$egin{aligned} \langle K(\cdot,x_i),f
angle_{\mathcal{H}_K} &= \left\langle \sum_{j=1}^\infty \gamma_j \phi_j(x) \phi_j(x_i), \sum_{j=1}^\infty c_j \phi_j(x)
ight
angle \\ &= \sum_{j=1}^\infty \frac{c_j \gamma_j \phi_j(x_i)}{\gamma_j} \\ &= f(x_i) \end{aligned}$$

(2)

$$egin{aligned} \langle K(\cdot,x_i),K(\cdot,x_j)
angle_{\mathcal{H}_K} &= \left\langle \sum_{k=1}^\infty \gamma_k \phi_k(x)\phi_k(x_i),\sum_{k=1}^\infty \gamma_k \phi_k(x)\phi_k(x_j)
ight
angle \\ &= \sum_{k=1}^\infty \frac{\gamma_k^2 \phi_k(x_i)\phi_k(x_j)}{\gamma_k} \\ &= K(x_i,x_j) \end{aligned}$$

(3)

$$J(g) = \left\langle \sum_{i=1}^{N} \alpha_i K(x, x_i), \sum_{i=1}^{N} \alpha_i K(x, x_i) \right
angle$$

= $\sum_{i=1}^{N} \sum_{j=1}^{N} K(x_i, x_j) \alpha_i \alpha_j$

$$egin{aligned} J(g) &= \left\langle \sum_{i=1}^N lpha_i K(x,x_i), \sum_{i=1}^N lpha_i K(x,x_i)
ight
angle \ &= \sum_{i=1}^N \sum_{j=1}^N K(x_i,x_j) lpha_i lpha_j \end{aligned}$$

(5)

$$egin{aligned} J(ilde{g}) &= J(g) + 2\langle J(g),
ho
angle + \|
ho\|_{\mathcal{H}_K}^2 \ &= J(g) + \|
ho\|_{\mathcal{H}_K}^2 \ &\geq J(g) \end{aligned}$$

由第(1)问的结论可知

$$egin{aligned} ilde{g}(x_i) &= \langle K(\cdot, x_i), ilde{g}
angle_{\mathcal{H}_K} \ &= \langle K(\cdot, x_i), g +
ho
angle_{\mathcal{H}_K} \ &= \langle K(\cdot, x_i), g
angle_{\mathcal{H}_K} \end{aligned}$$

所以

$$L(y_i, \tilde{g}(x_i)) = L(y_i, g(x_i))$$

于是

$$\sum_{i=1}^N L(y_i, ilde{g}(x_i)) + \lambda J(ilde{g}) \geq \sum_{i=1}^N L(y_i, g(x_i)) + \lambda J(g)$$

当且仅当 $\rho(x)=0$ 时,上式取等。

4 5.16

(1) 由核函数定义

$$K(x,y) = \sum_{m=1}^M h_m(x) h_m(y) = \sum_{i=1}^\infty \gamma_i \phi_i(x) \phi_i(y)$$

$$\sum_{m=1}^{M} \langle h_m(x), \phi_k(x) h_m(y) = \sum_{i=1}^{\infty} \langle \phi_i(x), \phi_k(x) \phi_i(y)
angle$$

由于 $\phi_i(x)$ 之间互相正交

$$\sum_{m=1}^M \langle h_m(x), \phi_k(x) h_m(y) = \gamma_k \phi_k(y)$$

 $\diamondsuit g_{km} = \int h_m(x)\phi_k(x)dx$,那么

$$\sum_{m=1}^M g_{km} h_m(y) = \gamma_k \phi_k(y)$$

$$\sum_{m=1}^{M}g_{km}g_{lm}=\gamma_{k}\delta_{k,l}=\sqrt{\gamma_{k}}\sqrt{\gamma_{l}}\delta_{kl}$$

记 $\mathbf{G} = \{g_{nm}\} \in \mathbb{R}^{M \times N}, \ \mathbf{V}^T = \mathbf{D}_{\gamma}^{-\frac{1}{2}}\mathbf{G}, \ \$ 有

$$\mathbf{G}\mathbf{G}^T = \mathrm{diag}\{\gamma_1, \gamma_2, \dots, \gamma_M\} = \mathbf{D}_{\gamma}$$

$$\mathbf{W}^T = \mathbf{I}$$

所以
$$\sum_{m=1}^{M} g_{km} h_m(y) = \gamma_k \phi_k(y)$$
可以写成 $\mathbf{D}_{\gamma} \phi(y) = \mathbf{G} h(y)$

$$h(x) = \mathbf{V}\mathbf{V}^T h(x) = \mathbf{V}\mathbf{D}_{\gamma}^{-rac{1}{2}}\mathbf{G}h(x) = \mathbf{V}\mathbf{D}_{\gamma}^{rac{1}{2}}\phi(x)$$

$$\diamondsuit \beta = (\beta_1, \beta_2, \dots, \beta_m)^T, \ c = \mathbf{D}_{\gamma}^{\frac{1}{2}} \mathbf{V}^T \beta$$

$$\begin{split} \min_{\left\{\beta_{m}\right\}_{1}^{M}} \sum_{i=1}^{N} \left(y_{i} - \sum_{m=1}^{M} \beta_{m} h_{m}(x_{i})\right)^{2} + \lambda \sum_{m=1}^{M} \beta_{m}^{2} \\ &= \min_{\beta} \sum_{i=1}^{N} (y_{i} - \beta^{T} \mathbf{h}(x_{i}))^{2} + \lambda \beta^{T} \beta \\ &= \min_{\beta} \sum_{i=1}^{N} (y_{i} - \beta^{T} \mathbf{V} \mathbf{D}_{\gamma}^{\frac{1}{2}} \phi(x_{i}))^{2} + \lambda \beta^{T} \beta \\ &= \min_{c} \sum_{i=1}^{N} (y_{i} - c^{T} \phi(x_{i}))^{2} + \lambda (\mathbf{V} \mathbf{D}_{\gamma}^{\frac{1}{2}} c)^{T} \mathbf{V} \mathbf{D}_{\gamma}^{\frac{1}{2}} c \\ &= \min_{c} \sum_{i=1}^{N} (y_{i} - c^{T} \phi(x_{i}))^{2} + \lambda c^{T} c \mathbf{D}_{\gamma}^{-1} \\ &= \min_{c} \sum_{i=1}^{N} \left(y_{i} - \sum_{j=1}^{\infty} c_{j} \phi_{j}(x_{i}) \right)^{2} + \lambda \sum_{j=1}^{\infty} \frac{c_{j}^{2}}{\gamma_{j}} \end{split}$$

(2)

对于 $\min_{\beta} \sum_{i=1}^{N} (y_i - \beta^T h(x_i))^2 + \lambda \beta^T \beta$,解为 $\hat{\beta} = (\mathbf{H}^T \mathbf{H} + \lambda \mathbf{I})^{-1} \mathbf{H}^T$ 。

于是

$$\begin{split} \hat{\mathbf{f}} &= \mathbf{H} (\mathbf{H}^T \mathbf{H} + \lambda \mathbf{I})^{-1} \mathbf{H}^T \\ &= \frac{1}{\lambda} \mathbf{H} \mathbf{H}^T - \frac{1}{\lambda} \mathbf{H} \mathbf{H}^T (\lambda \mathbf{I} + \mathbf{H} \mathbf{H}^T)^{-1} \mathbf{H} \mathbf{H}^T \\ &= \frac{1}{\lambda} \mathbf{H} \mathbf{H}^T \left[(\lambda \mathbf{I} + \mathbf{H} \mathbf{H}^T)^{-1} (\lambda \mathbf{I} + \mathbf{H} \mathbf{H}^T) - (\lambda \mathbf{I} + \mathbf{H} \mathbf{H}^T)^{-1} \mathbf{H} \mathbf{H}^T \right] \\ &= \frac{1}{\lambda} \mathbf{H} \mathbf{H}^T \left[(\lambda \mathbf{I} + \mathbf{H} \mathbf{H}^T)^{-1} \lambda \mathbf{I} \right] \\ &= \mathbf{H} \mathbf{H}^T (\lambda \mathbf{I} + \mathbf{H} \mathbf{H}^T)^{-1} \end{split}$$

所以 $\hat{\mathbf{f}} = \mathbf{K}(\mathbf{K} + \lambda \mathbf{I})^{-1}$ 。

(3) 由上一问的结论,知

$$egin{aligned} \hat{f}(x) &= h(x)^T \hat{eta} \ &= \sum_{i=1}^N K(x,x_i) (\mathbf{K} + \lambda \mathbf{I})^{-1} \mathbf{y} \end{aligned}$$

带入 $\hat{\alpha} = (\mathbf{K} + \lambda \mathbf{I})^{-1} \mathbf{y}$ 即可。

(4) $\lambda \neq 0$ 时上述结论依然成立。若 $\lambda = 0$, $\hat{\mathbf{f}} = \mathbf{y}$ 。