

**ASEN 3112**

**Spring 2020**

**Lecture 18**

**Whiteboard**

March 19, 2020

L18  
1

Continue IDOT, Damping, Free

Characteristic equation;

$$\underbrace{\lambda^2}_a + \underbrace{2\zeta\omega_n\lambda}_b + \underbrace{\omega_n^2}_c = 0$$

Quadratic equation:  $a=1$ ,  $b=2\zeta\omega_n$ ,  $c=\omega_n^2$

$$\lambda = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$= \frac{-2\zeta\omega_n \pm \sqrt{4\zeta^2\omega_n^2 - 4\omega_n^2}}{2}$$

$$\lambda = -\zeta\omega_n \pm \omega_n\sqrt{\zeta^2 - 1}$$

Recall solution:  $x(t) = Ae^{\lambda t}$

complex  $A = A_{\text{real}} + iA_{\text{imag}}$

Consider 4 possible classes of problems:

I Undamped case:  $\zeta = 0$ ,  $\lambda = \pm \omega_n\sqrt{-1} = \pm i\omega_n$

$$x(t) = \underline{A} e^{\pm i\omega_n t}$$

$$= \underline{A_1 \cos \omega_n t + A_2 \sin \omega_n t} \quad [1]$$

(like last lecture, except we  
are now using  $A_1, A_2$  instead  
of  $B_1, B_2$ )

real  
numbers

$A_1, A_2$  obtained using the initial conditions.

$$x(0) = x_0, \quad \dot{x}(0) = v_0$$

$\uparrow$   
 $t=0$

See last lecture...

Now consider three different damping cases:

[2] Underdamped  $\zeta < 1$ ,  $\lambda = -\zeta\omega_n \pm i\omega_n \sqrt{1-\zeta^2}$

$\omega_d$   
damped frequency  
of vibration  
(damped natural frequency)

$$x(t) = e^{-\zeta\omega_n t} \left[ A_1 e^{i\omega_d t} + A_2 e^{-i\omega_d t} \right]$$

$$= e^{-\zeta\omega_n t} \left[ A_1 (\cos\omega_d t + i\sin\omega_d t) + A_2 (\cos\omega_d t - i\sin\omega_d t) \right]$$

$$x(t) = e^{-\zeta\omega_n t} \left[ \underline{B_1} \cos\omega_d t + \underline{B_2} \sin\omega_d t \right]$$

where  $B_1 = A_1 + A_2$ ,  $B_2 = (A_1 - A_2)i$

$\downarrow$   
Real

$$= e^{-\zeta\omega_n t} \bar{B} \sin(\omega_d t + \psi)$$

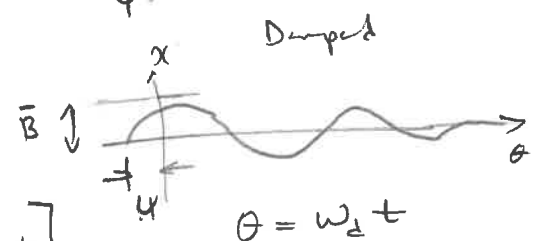
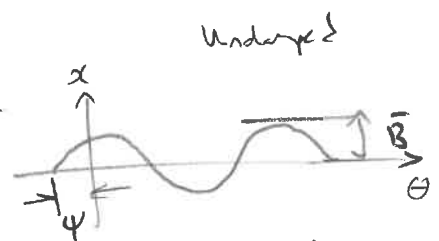
where  $\bar{B} = \sqrt{B_1^2 + B_2^2}$ ,  $\psi = \tan^{-1} \frac{B_1}{B_2}$

See lecture notes — for shape of signal

Solve  $B_1, B_2$  using initial conditions

$$x(0) = x_0, \quad \dot{x}(0) = v_0$$

$$x(t) = e^{-\zeta\omega_n t} \left[ x_0 \cos\omega_d t + \frac{v_0 + \zeta\omega_n x_0}{\omega_d} \sin\omega_d t \right]$$



[2]

$\frac{40}{3}$  [3] overdamped  $\zeta > 1$ ,  $\lambda = -\zeta\omega_n \pm \omega_n\sqrt{\zeta^2 - 1}$

Note:  $\zeta > 1$  implies  $c > c_c$  i.e.  $c > 2\sqrt{km}$

$$x(t) = e^{-\zeta\omega_n t} \left[ A_1 e^{\frac{(\omega_n\sqrt{\zeta^2-1})t}{\omega^*}} + A_2 e^{-\frac{(\omega_n\sqrt{\zeta^2-1})t}{\omega^*}} \right]$$

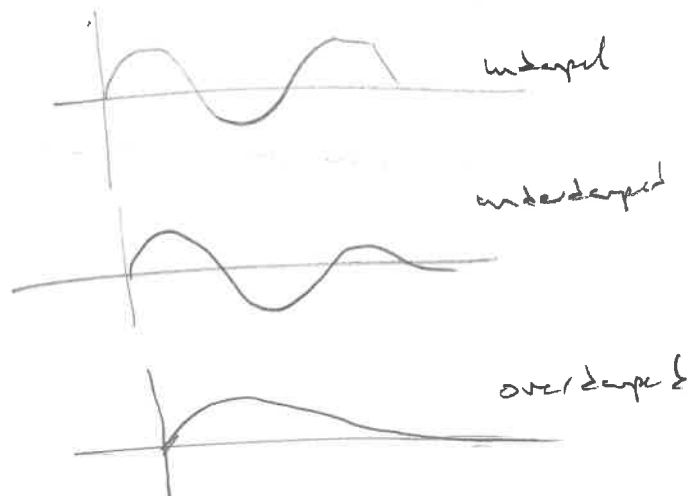
$$\omega^* = \omega_n\sqrt{\zeta^2 - 1}$$

Consider initial conditions  $x(0) = x_0$ ,  $\dot{x}(0) = v_0$

$$x(t) = e^{-\zeta\omega_n t} \left[ x_0 \cosh \omega^* t + \frac{v_0 + \zeta\omega_n x_0}{\omega^*} \sinh \omega^* t \right]$$

[3]

Sec lecture  
notes for  
figures showing  
response



[4] Critically damped  $\zeta = 1$ ,  $\lambda = -\zeta\omega_n$

Note:  $\zeta = 1$  implies  $c = c_c$  i.e.  $c = 2\sqrt{km}$

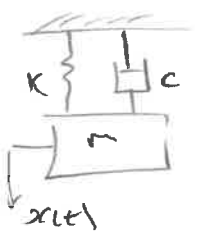
Assume solution  $x(t) = (A + At)e^{-\zeta\omega_n t}$

Note: As  $t \rightarrow \infty$ ,  $e^{-\zeta\omega_n t}$  goes to zero,  $x(t) \rightarrow 0$

Consider initial conditions  $x(0) = x_0$ ,  $\dot{x}(0) = v_0$ :

$$x(t) = [x_0 + (v_0 + \omega_n x_0)t] e^{-\omega_n t}$$

[4]

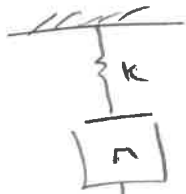


L18  
4

SDoF

- Undamped
- Forced

Steady-state harmonic excitation  
with amplitude  $F$ , frequency  $\omega$



$$\omega_n = \sqrt{\frac{k}{m}}$$

$f(t) = F \sin \omega t$ ,  $\omega$  = excitation frequency

EOM

$$m\ddot{x} + kx = f(t)$$

$$m\ddot{x} + kx = F \sin \omega t$$

$$\ddot{x} + \frac{k}{m}x = \frac{F}{m} \sin \omega t$$

$$\ddot{x} + \omega_n^2 x = \frac{F}{m} \sin \omega t$$

Solution:  $x(t) = x_p(t) + x_h(t)$

particular  
solution  
(steady-state)

homogeneous  
solution  
(transient)

Form of  $x_h$  is just like what we obtained for the free 1DOF case.

Assume  $x_p(t) = X \sin \omega t$

$\dot{x}_p(t) = \omega X \cos \omega t$

$\ddot{x}_p(t) = -\omega^2 X \sin \omega t$

Substitute  $x_p$  into EOM (assuming EOM in  $x_p$ )

$$[-\omega^2 + \omega_n^2]X \sin \omega t = F \sin \omega t$$

$$X = \frac{F/m}{\omega_n^2 - \omega^2}$$

Note: if  $\omega = \omega_n$ ,  $X \rightarrow \infty$   
(resonance!!)

L18  
5

Define  $\eta = \frac{\omega}{\omega_n}$

Divide by  $\omega_n^2$

(Note:  $\frac{F}{m} = \frac{K}{m} = \frac{F}{\cancel{m}} \times \frac{\cancel{m}}{K} = \frac{F}{K}$ )

$$X = \frac{F/K}{1-\eta^2}$$

let  $\delta_0 = F/K$  = static deflection

$$X = \frac{\delta_0}{1-\eta^2}, \quad \frac{X}{\delta_0} = \frac{1}{1-\eta^2} \text{ : Receptance}$$

$$x_p(t) = \frac{\delta_0}{1-\eta^2} \sin \omega t$$

ss. solution of 1DOF, undamped forced.

Total solution:

$$x(t) = x_p(t) + x_h(t)$$

↳ in terms of  $B_1, B_2$

Need initial conditions to solve for  $B_1, B_2$

considering the total solution  $x(t)$

$$\dot{x}(t) = \dot{x}_p(t) + \dot{x}_h(t)$$

To solve for  $B_1, B_2$  at  $t=0$

L19  
6

SDOF

- Damped
- Forced



$f(t) = F e^{i\omega t}$  (define in this manner  
 $\therefore$  in damped system,  
the response has a  
phase)

EOM

$$m\ddot{x} + c\dot{x} + kx = f(t) = F e^{i\omega t}$$

$$\ddot{x} + \frac{c}{m}\dot{x} + \frac{k}{m}x = \frac{f(t)}{m} = \frac{F}{m} e^{i\omega t}$$

$$\ddot{x} + 2\zeta\omega_n\dot{x} + \omega_n^2 x = \frac{F}{m} e^{i\omega t}$$

Assume  $x_p(t) = X e^{i\omega t}$

$X$ : complex.

$$\dot{x}_p(t) = +i\omega X e^{i\omega t} \quad \text{if } X = X_{\text{real}} + iX_{\text{imag}}$$

$$\ddot{x}_p(t) = -\omega^2 X e^{i\omega t}$$

Plug into EOM:

$$[-\omega^2 + 2\zeta\omega_n i\omega + \omega_n^2] X = \frac{F}{m}$$

Divide

$$X = \frac{F/m}{\omega_n^2 - \omega^2 + 2\zeta\omega_n i\omega}$$

Divide by  $\omega_n^2$

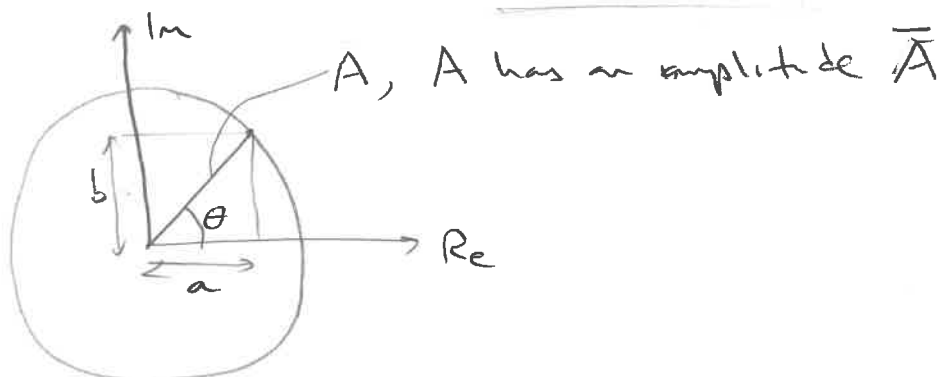
$$X = \frac{F/k}{1 - \eta^2 + i2\zeta\eta} = \frac{\delta_{st}}{1 - \eta^2 + i2\zeta\eta}$$

$$\frac{X}{\delta_{st}} = \frac{1}{1 - \eta^2 + i2\zeta\eta}$$

U8  
7

## Side Note

Consider  $A$ : complex  $A = a + ib$



$$\bar{A} = \sqrt{a^2 + b^2}, \quad \theta = \tan^{-1} \frac{b}{a}$$

Therefore:

$$X = \frac{S_{st}}{\sqrt{(1-\eta^2)^2 + (2\zeta\eta)^2}} e^{-i\phi}, \quad \phi = \tan^{-1} \frac{2\zeta\eta}{1-\eta^2}$$

$$x_p(t) = \frac{S_{st}}{\sqrt{(1-\eta^2)^2 + (2\zeta\eta)^2}} e^{i(\omega t - \phi)}$$

cos + i sin

Physical steady state response.

$$x_p(t) \Big|_{\text{phys}} = \text{Im}[x_p(t)]$$

imaginary part



