

ASEN 3112

Spring 2020

Lecture 9

Whiteboard

February 13, 2020

1 Mechanics of materials is concerned with the relationship between forces and deformation

General treatment of these two quantities are facilitated by:

- stress (σ_{ij})
 - strain (ϵ_{ij})
- $i, j = x, y, z$

- work (W) and strain energy (U)

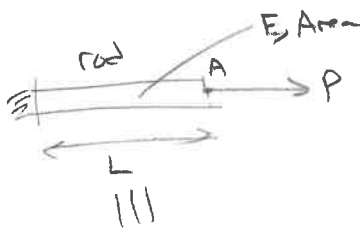
$\sigma_{ij}, \epsilon_{ij}$ - tensors - coordinate dependent

W, U - scalars - coordinate invariant

advantage
of energy method

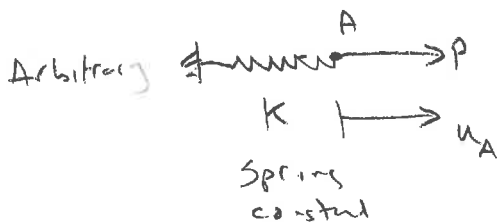
Basic Principle

Force-displacement



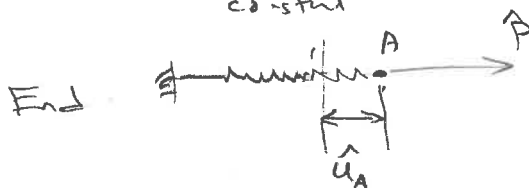
Conservation of Energy

- No work is lost
- External work is stored as internal energy



$$dP = K du_A$$

infinitesimal
treatment

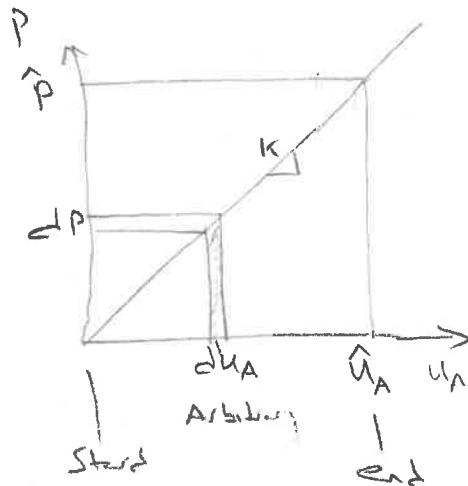


$$\hat{P} = K \hat{u}_A$$

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Consider relationship

variable $P = P(u_A) = K u_A$ constant variable



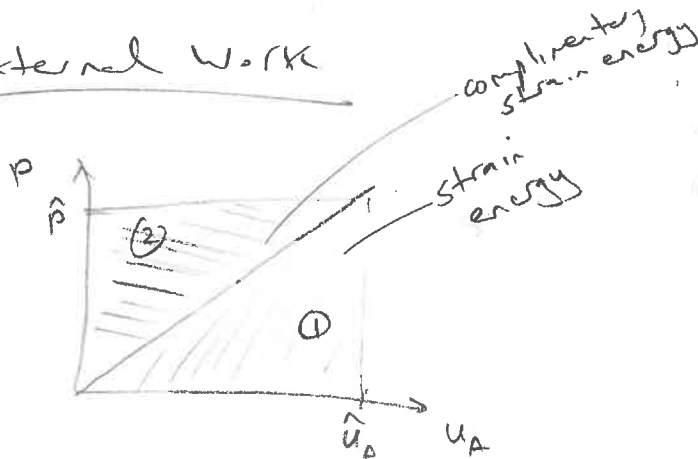
linear system

$$dP = K du_A$$

$$\int_0^{\hat{P}} dP = \int_0^{\hat{u}_A} K du_A$$

$$\hat{P} = K u_A \Big|_0^{\hat{u}_A} = K \hat{u}_A$$

External Work



Area (1) = Area (2)
for linear system

$$W_e = \frac{1}{2} K \hat{u}_A^2$$

$$(\hat{P} = K \hat{u}_A \Rightarrow \hat{u}_A = \frac{\hat{P}}{K})$$

$$= \frac{1}{2} K \hat{u}_A \left(\frac{\hat{P}}{K} \right)$$

$$W_e = \frac{1}{2} \hat{P} \hat{u}_A$$

$$\int dW_e = \int_0^{\hat{u}_A} P du_A$$

$$W_e = \int_0^{\hat{u}_A} K u_A du_A$$

$$W_e = \frac{1}{2} K \hat{u}_A^2$$

$$\int dW_e = \int_0^{\hat{P}} u_A dP$$

$$W_e = \int_0^{\hat{P}} \frac{1}{K} P dP$$

$$W_e = \frac{1}{2K} \hat{P}^2$$

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— work done on body = Δ in energy stored in body

change

strain energy U

for non-dissipative systems

$$W_e = U$$

— Conservation of Energy

$$W_e + W_i = 0$$

↳ internal work

$$\therefore W_i = -U$$

Recorder loaded spring



Free body diagram

internal point experiencing internal force

$$W_e = \frac{1}{2} \hat{P} \hat{u}_A$$

$$W_i = \frac{1}{2} \hat{F}_{int} \hat{u}_A$$

$$W_e + W_i = 0$$

$$\frac{1}{2} \hat{P} \hat{u}_A + \frac{1}{2} \hat{F}_{int} \hat{u}_A = 0$$

$$\Rightarrow \hat{F}_{int} = -P = -K u_A$$

Strain strain

$$U = -W_i = -\frac{1}{2} \hat{F}_{int} \hat{u}_A$$


$$U = \frac{1}{2} K \hat{u}_A^2 = \frac{1}{2} \frac{1}{K} (F_{int})^2$$

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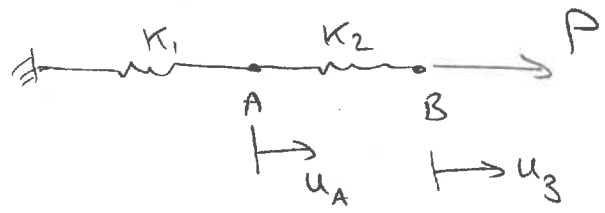
Notation clarity

\hat{u}_A : maximum displacement of point A
(not vector)

[Side note: $\vec{u}_A = u_{Ax} \vec{i} + u_{Ay} \vec{j}$]



Example



Write an expression for strain energy U for this system.

(load until $u_A \rightarrow \hat{u}_A$
 $u_B \rightarrow \hat{u}_B$)

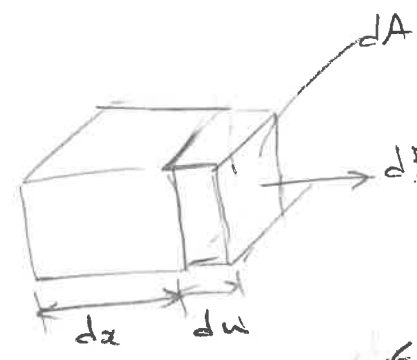
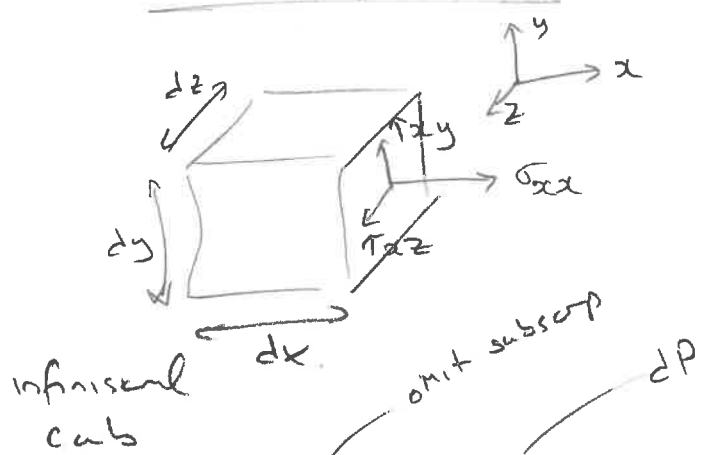
$$U = \frac{1}{2} k_1 \hat{u}_A^2 + \frac{1}{2} k_2 (\hat{u}_B - \hat{u}_A)^2$$

Strain energy in Spring 1

Strain energy in Spring 2

Now, introduce σ_{ij} , ϵ_{ij} into energy formulae

Elastic Strain Energy



du (subscript omitted)

$$dF = \sigma_{xx} dA$$

$$= \sigma_{xx} dy dz$$

$$\epsilon_{xx} = \frac{du}{dx}$$

$$du = \epsilon_{xx} dx$$

$$dW = \frac{1}{2} dF du = \frac{1}{2} \sigma_{xx} \epsilon_{xx} \underbrace{dx dy dz}_{dV}$$

||
 $du =$

$$\frac{du}{dV} = u_0 \Big|_{xx} = \frac{1}{2} \sigma_{xx} \epsilon_{xx}$$

strain energy density

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Generalize to 3D

$$U_0 = \frac{1}{2} (\sigma_{xx} \epsilon_{xx} + \sigma_{yy} \epsilon_{yy} + \sigma_{zz} \epsilon_{zz} + \tau_{xy} \gamma_{xy} + \tau_{yz} \gamma_{yz} + \tau_{xz} \gamma_{xz})$$

Elastic strain energy U

$$U = \int_V dU = \iiint_{xyz} U_0 dx dy dz$$

Clicker 2

$$W_c = mg(\Delta h), \quad h: \text{height}$$

$$= (1 \text{ kN})(2 \text{ m})$$

$$= 2 \text{ kNm}$$

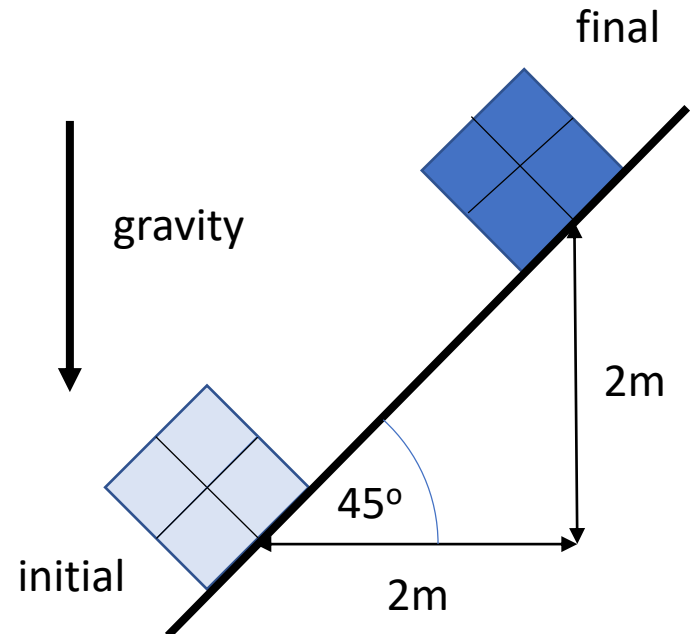
→ (b)

Clicker Question 1

Lecture 9

You need to push the rigid mass with a weight of 1kN up an inclined plane. What work do you need to perform? Ignore friction.

- (a) $\sqrt{2}\text{kNm}$
- (b) 2kNm
- (c) 1kNm
- (d) none of the above



Clicker Question 2

Lecture 9

You slowly place a sphere with a weight of 10 kN at the center of an elastic beam. At the end of this quasi-static loading process the beam deflects by 0.1 m. How much external work has been performed on the beam and is stored in the beam?

- (a) 1 kNm
- (b) 2 kNm
- (c) 0.5 kNm
- (d) none of the above

