

ASEN 3112

Lecture 15:

Finite Element Method 3

Dr. Johnson
Prof. Hussein

Department of Aerospace Engineering Sciences
University of Colorado Boulder

Announcements

- Upcoming due dates
 - Homework 6 (energy methods): **tomorrow, Friday**, March 6
 - Homework 7 (FEM): Friday, March 13
 - Exam 2 (beams, energy methods, FEM): Tuesday, March 17
- Note that the FEM recitation is after HW7 and Exam 2
- My Office Hours (all in AERO 302)
 - Tuesday, March 10, 9:00 – 10:00 am
 - Thursday, March 12, 11:30 am – 12:30 pm
 - *Then by appointment*

Finite Element Methods Outline



Last class (Ch. 16 & 17)

- Member stiffness equations



Today (Ch. 17 & 18)

- Transforming from local to global coordinates
- Understanding the global stiffness matrix



Thursday, March 5 (Ch. 18)

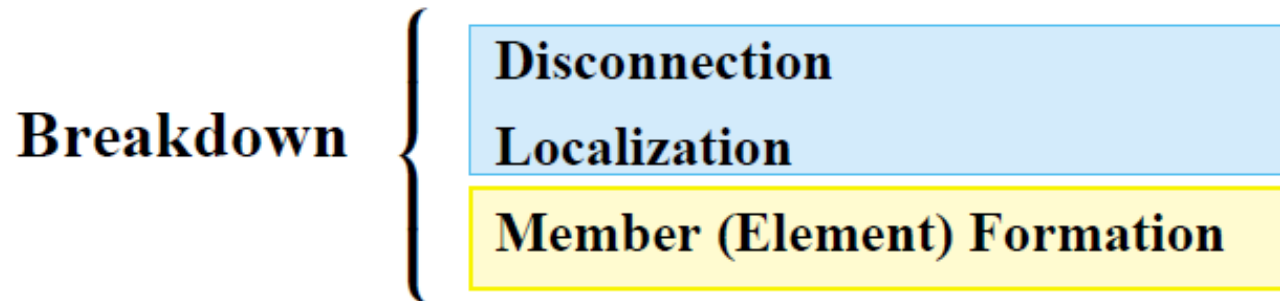
- **Assembling the global stiffness matrix**
- **Applying boundary conditions to solve**





Tuesday, March 10


- Examples
- Exam 2 review?

The Direct Stiffness Method

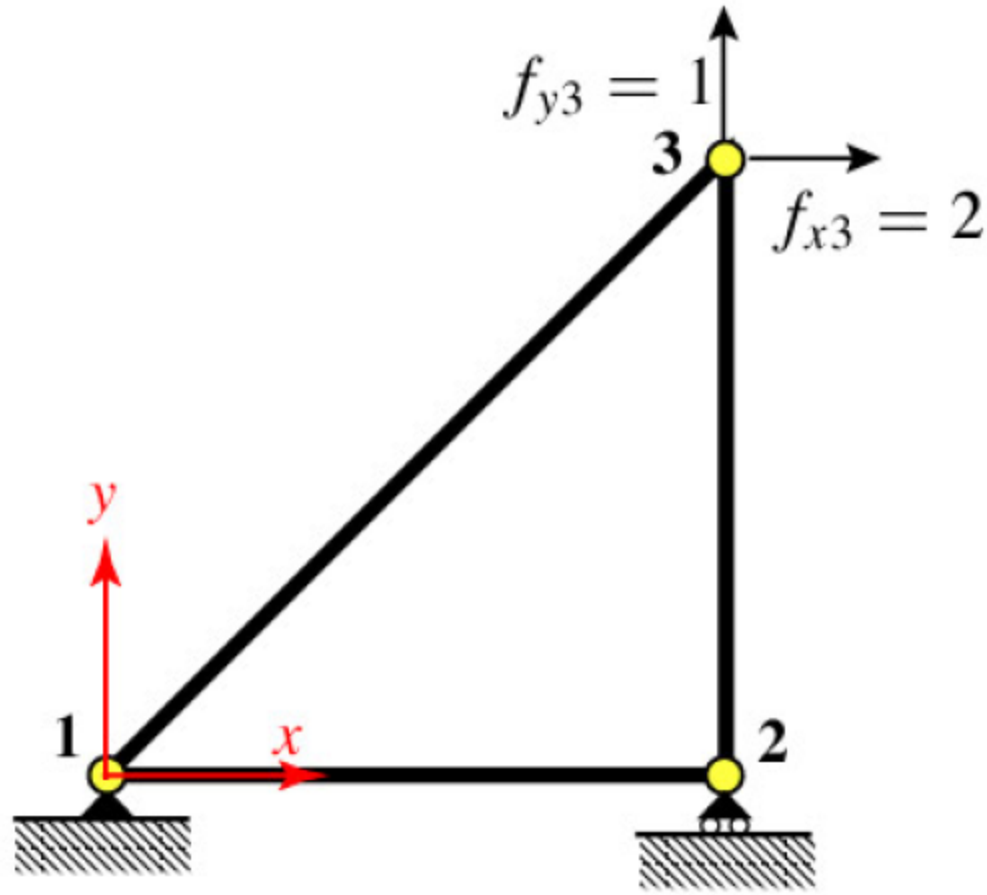


 *conceptual steps*

 *processing steps*

 *post-processing steps*

Our Example Truss



Member Stiffness Relations

- For each element, but not showing ^(e) superscript
- In local coordinates:

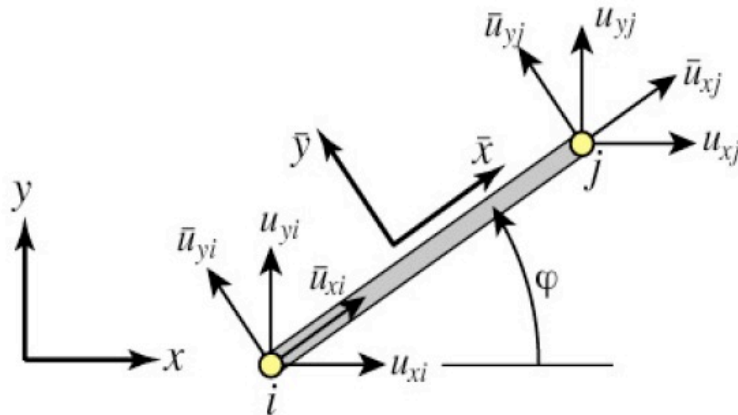
$$\begin{bmatrix} \bar{f}_{xi} \\ \bar{f}_{yi} \\ \bar{f}_{xj} \\ \bar{f}_{yj} \end{bmatrix} = \bar{\mathbf{K}} \begin{bmatrix} \bar{u}_{xi} \\ \bar{u}_{yi} \\ \bar{u}_{xj} \\ \bar{u}_{yj} \end{bmatrix} \quad \text{where} \quad \bar{\mathbf{K}} = \frac{EA}{L} \begin{bmatrix} 1 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

- In global coordinates:

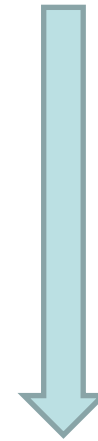
$$\begin{bmatrix} f_{xi} \\ f_{yi} \\ f_{xj} \\ f_{yj} \end{bmatrix} = \mathbf{K} \begin{bmatrix} u_{xi} \\ u_{yi} \\ u_{xj} \\ u_{yj} \end{bmatrix} \quad \text{where} \quad \mathbf{K} = \frac{EA}{L} \begin{bmatrix} c^2 & sc & -c^2 & sc \\ sc & s^2 & sc & -s^2 \\ -c^2 & sc & c^2 & sc \\ sc & -s^2 & sc & s^2 \end{bmatrix}$$

$$\text{or} \quad \mathbf{K} = \begin{bmatrix} [\hat{K}] & [-\hat{K}] \\ [-\hat{K}] & [\hat{K}] \end{bmatrix} \quad \text{where} \quad [\hat{K}] = \frac{EA}{L} \begin{bmatrix} c^2 & sc \\ sc & s^2 \end{bmatrix}$$

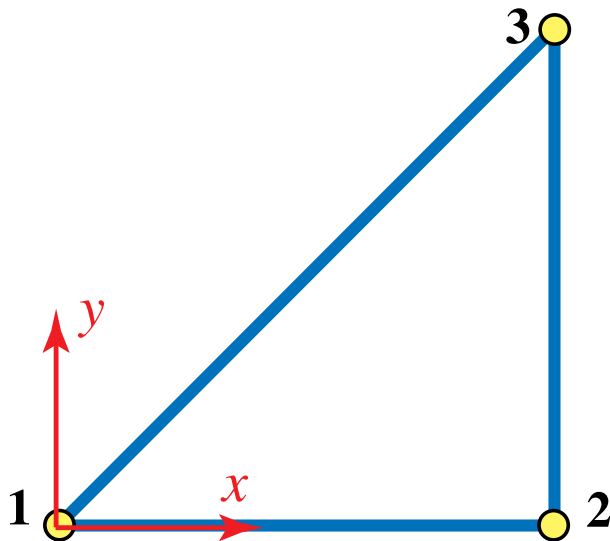
Global Stiffness Relations



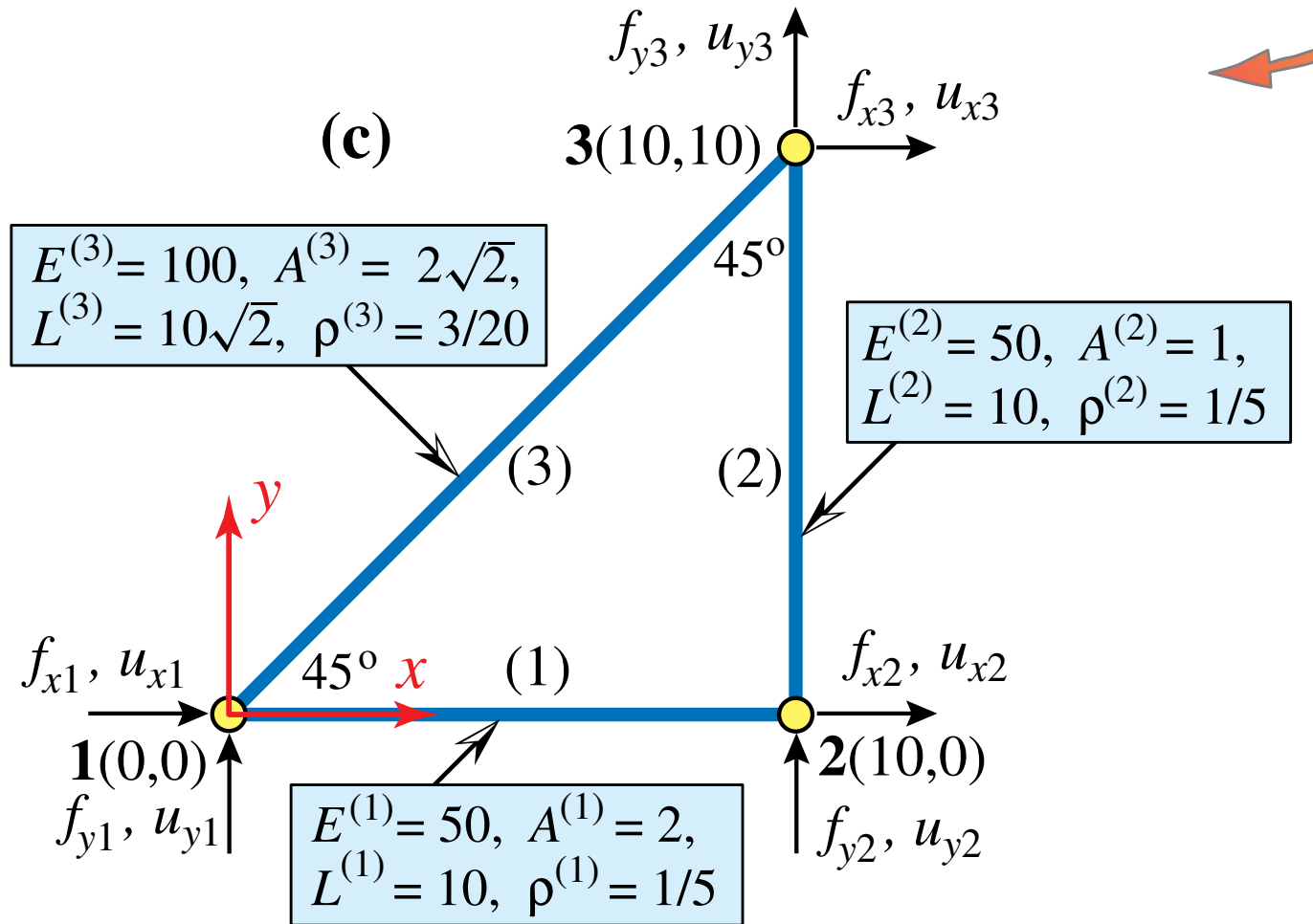
$$f^e = K^e u^e$$



$$f = \sum K u$$



Member Properties in Our Example Truss

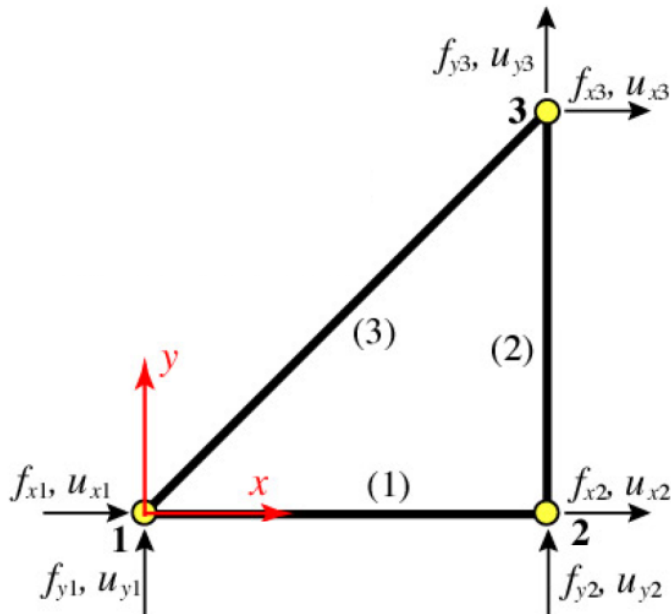


Augmented Stiffness Matrices

- Element stiffness equation augmented by “missing” DOFs to yield 6 equations
- **Only done for illustration purposes; step not explicitly needed**

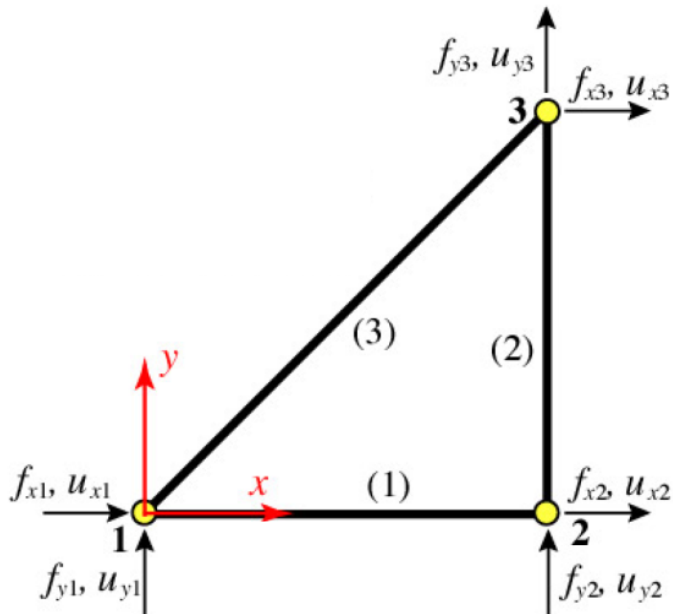
Bar 1:

$$\begin{bmatrix} f_{x1}^{(1)} \\ f_{y1}^{(1)} \\ f_{x2}^{(1)} \\ f_{y2}^{(1)} \end{bmatrix} = 10 \begin{bmatrix} 1 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} u_{x1}^{(1)} \\ u_{y1}^{(1)} \\ u_{x2}^{(1)} \\ u_{y2}^{(1)} \end{bmatrix}$$



Augmented Stiffness Matrices

- Element stiffness equation augmented by “missing” DOFs to yield 6 equations
- **Only done for illustration purposes; step not explicitly needed**



Bar 1:

$$\begin{bmatrix} f_{x1}^{(1)} \\ f_{y1}^{(1)} \\ f_{x2}^{(1)} \\ f_{y2}^{(1)} \\ f_{x3}^{(1)} \\ f_{y3}^{(1)} \end{bmatrix} = \begin{bmatrix} 10 & 0 & -10 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ -10 & 0 & 10 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} u_{x1} \\ u_{y1} \\ u_{x2} \\ u_{y2} \\ u_{x3} \\ u_{y3} \end{bmatrix}$$

Bar 2:

$$\begin{bmatrix} f_{x1}^{(2)} \\ f_{y1}^{(2)} \\ f_{x2}^{(2)} \\ f_{y2}^{(2)} \\ f_{x3}^{(2)} \\ f_{y3}^{(2)} \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 5 & 0 & -5 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -5 & 0 & 5 \end{bmatrix} \begin{bmatrix} u_{x1} \\ u_{y1} \\ u_{x2} \\ u_{y2} \\ u_{x3} \\ u_{y3} \end{bmatrix}$$

Bar 3:

$$\begin{bmatrix} f_{x1}^{(3)} \\ f_{y1}^{(3)} \\ f_{x2}^{(3)} \\ f_{y2}^{(3)} \\ f_{x3}^{(3)} \\ f_{y3}^{(3)} \end{bmatrix} = \begin{bmatrix} 10 & 10 & 0 & 0 & -10 & -10 \\ 10 & 10 & 0 & 0 & -10 & -10 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ -10 & -10 & 0 & 0 & 10 & 10 \\ -10 & -10 & 0 & 0 & 10 & 10 \end{bmatrix} \begin{bmatrix} u_{x1} \\ u_{y1} \\ u_{x2} \\ u_{y2} \\ u_{x3} \\ u_{y3} \end{bmatrix}$$

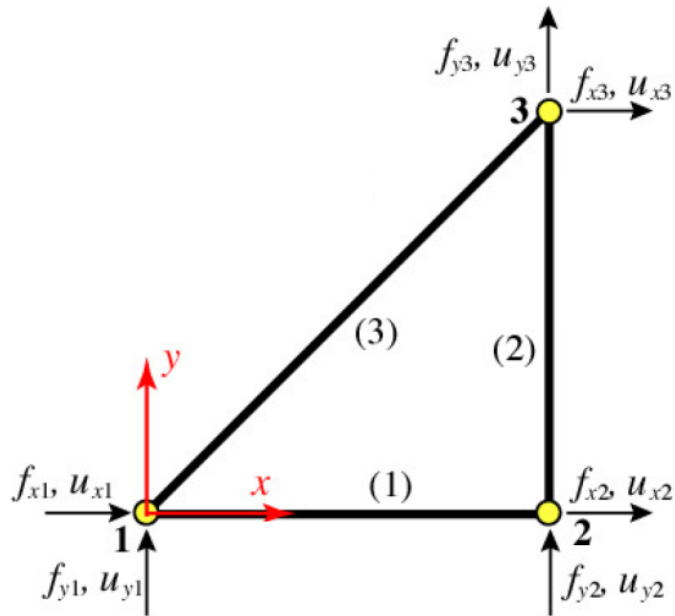
Global Stiffness Equation

$$\text{Bar 1: } \begin{bmatrix} f_{x1}^{(1)} \\ f_{y1}^{(1)} \\ f_{x2}^{(1)} \\ f_{y2}^{(1)} \\ f_{x3}^{(1)} \\ f_{y3}^{(1)} \end{bmatrix} = \begin{bmatrix} 10 & 0 & -10 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ -10 & 0 & 10 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} u_{x1} \\ u_{y1} \\ u_{x2} \\ u_{y2} \\ u_{x3} \\ u_{y3} \end{bmatrix}$$

$$\text{Bar 2: } \begin{bmatrix} f_{x1}^{(2)} \\ f_{y1}^{(2)} \\ f_{x2}^{(2)} \\ f_{y2}^{(2)} \\ f_{x3}^{(2)} \\ f_{y3}^{(2)} \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 5 & 0 & -5 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -5 & 0 & 5 \end{bmatrix} \begin{bmatrix} u_{x1} \\ u_{y1} \\ u_{x2} \\ u_{y2} \\ u_{x3} \\ u_{y3} \end{bmatrix}$$

$$\text{Bar 3: } \begin{bmatrix} f_{x1}^{(3)} \\ f_{y1}^{(3)} \\ f_{x2}^{(3)} \\ f_{y2}^{(3)} \\ f_{x3}^{(3)} \\ f_{y3}^{(3)} \end{bmatrix} = \begin{bmatrix} 10 & 10 & 0 & 0 & -10 & -10 \\ 10 & 10 & 0 & 0 & -10 & -10 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ -10 & -10 & 0 & 0 & 10 & 10 \\ -10 & -10 & 0 & 0 & 10 & 10 \end{bmatrix} \begin{bmatrix} u_{x1} \\ u_{y1} \\ u_{x2} \\ u_{y2} \\ u_{x3} \\ u_{y3} \end{bmatrix}$$

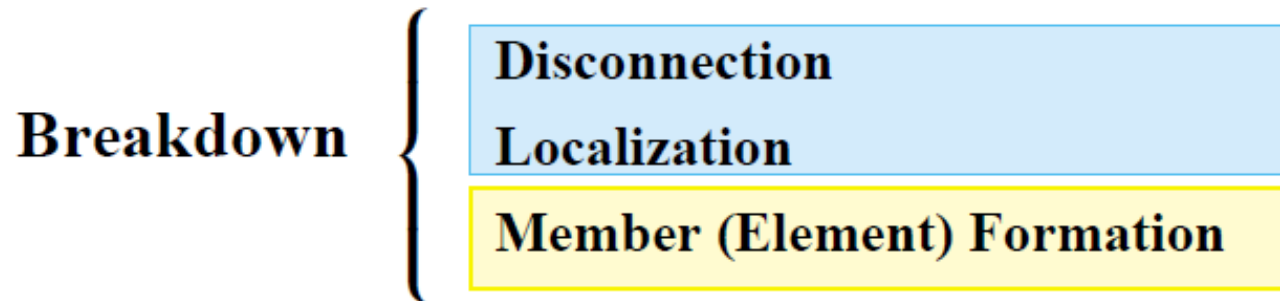
Assembly Process without Augmented Stiffness Matrices





Assembly Process


$K =$

The Direct Stiffness Method

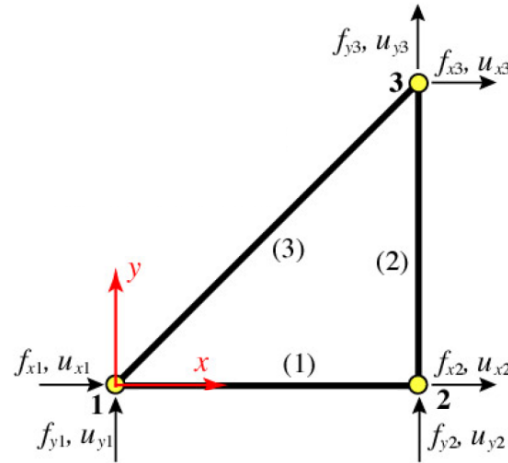
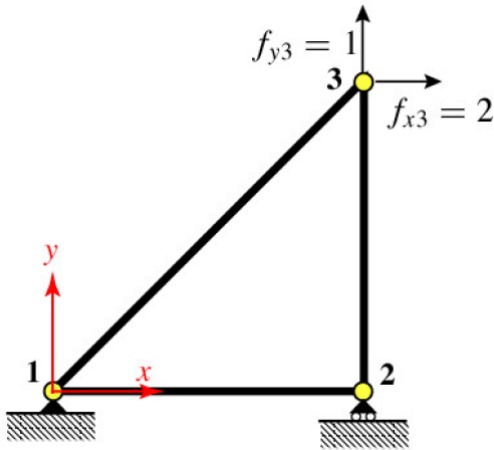


 *conceptual
steps*

 *processing
steps*

 *post-processing
steps*

Applying Boundary Conditions



Displacement BCs:

$$u_{x1} = u_{y1} = u_{y2} = 0$$

Force BCs:

$$f_{x2} = 0, \quad f_{x3} = 2, \quad f_{y3} = 1$$

Global stiffness equation:

$$\begin{bmatrix} f_{x1} \\ f_{y1} \\ f_{x2} \\ f_{y2} \\ f_{x3} \\ f_{y3} \end{bmatrix} = \begin{bmatrix} 20 & 10 & -10 & 0 & -10 & -10 \\ 10 & 10 & 0 & 0 & -10 & -10 \\ -10 & 0 & 10 & 0 & 0 & 0 \\ 0 & 0 & 0 & 5 & 0 & -5 \\ -10 & -10 & 0 & 0 & 10 & 10 \\ -10 & -10 & 0 & -5 & 10 & 15 \end{bmatrix} \begin{bmatrix} u_{x1} \\ u_{y1} \\ u_{x2} \\ u_{y2} \\ u_{x3} \\ u_{y3} \end{bmatrix}$$

Reduced Global Stiffness Equation

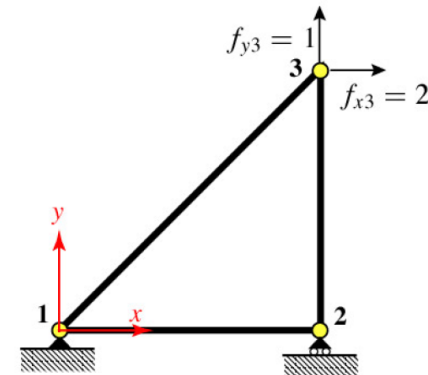
$$\begin{bmatrix}
 \cancel{20} & \cancel{10} & \cancel{-10} & \cancel{0} & \cancel{-10} & \cancel{-10} \\
 \cancel{10} & \cancel{10} & \cancel{0} & \cancel{0} & \cancel{-10} & \cancel{-10} \\
 -10 & 0 & 10 & 0 & 0 & 0 \\
 \cancel{0} & \cancel{0} & \cancel{0} & \cancel{5} & \cancel{0} & \cancel{-5} \\
 -10 & -10 & 0 & 0 & 10 & 10 \\
 -10 & -10 & 0 & -5 & 10 & 15
 \end{bmatrix}
 \begin{bmatrix}
 \cancel{u_{x1}} = 0 \\
 \cancel{u_{y1}} = 0 \\
 u_{x2} = ? \\
 \cancel{u_{y2}} = 0 \\
 u_{x3} = ? \\
 u_{y3} = ?
 \end{bmatrix}
 =
 \begin{bmatrix}
 \cancel{f_{x1}} = ? \\
 \cancel{f_{y1}} = ? \\
 f_{x2} = 0 \\
 \cancel{f_{y2}} = ? \\
 f_{x3} = 2 \\
 f_{y3} = 1
 \end{bmatrix}$$

$$\begin{bmatrix}
 10 & 0 & 0 \\
 0 & 10 & 10 \\
 0 & 10 & 15
 \end{bmatrix}
 \begin{bmatrix}
 u_{x2} \\
 u_{x3} \\
 u_{y3}
 \end{bmatrix}
 =
 \begin{bmatrix}
 0 \\
 2 \\
 1
 \end{bmatrix}$$

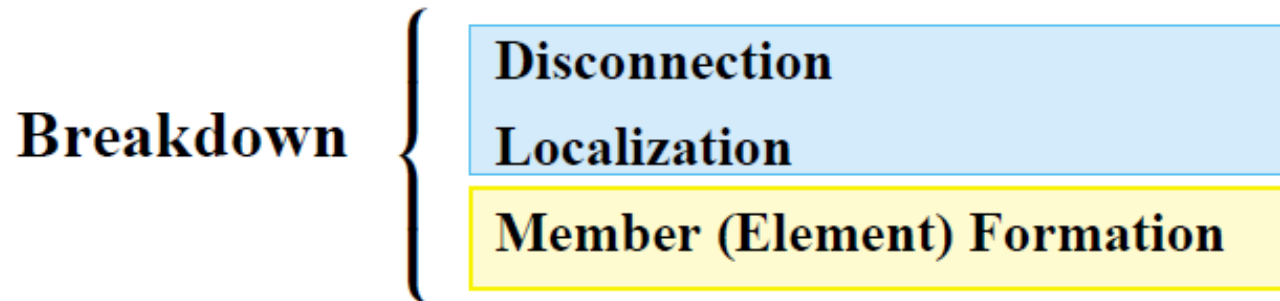
Reduced Global Stiffness Equation (System): $\tilde{\mathbf{K}}\tilde{\mathbf{u}} = \tilde{\mathbf{f}}$


Solution:


$$\begin{bmatrix}
 u_{x2} \\
 u_{x3} \\
 u_{y3}
 \end{bmatrix}
 =
 \begin{bmatrix}
 0 \\
 0.4 \\
 -0.2
 \end{bmatrix}$$




The Direct Stiffness Method



 *conceptual
steps*

 *processing
steps*

 *post-processing
steps*

Recovery of Reaction Forces

Complete Displacement Solution:

$$\begin{bmatrix} u_{x2} \\ u_{x3} \\ u_{y3} \end{bmatrix} = \begin{bmatrix} 0 \\ 0.4 \\ -0.2 \end{bmatrix}$$

Displacement BCs:

$$u_{x1} = u_{y1} = u_{y2} = 0$$

$$\begin{bmatrix} u_{x1} \\ u_{y1} \\ u_{x2} \\ u_{y2} \\ u_{x3} \\ u_{y3} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0.4 \\ -0.2 \end{bmatrix}$$

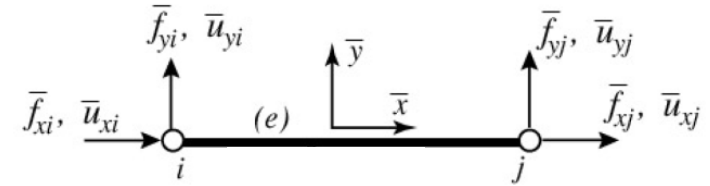
Complete Force Vector:

$$\mathbf{f} = \mathbf{K}\mathbf{u} = \begin{bmatrix} 20 & 10 & -10 & 0 & -10 & -10 \\ 10 & 10 & 0 & 0 & -10 & -10 \\ -10 & 0 & 10 & 0 & 0 & 0 \\ 0 & 0 & 0 & 5 & 0 & -5 \\ -10 & -10 & 0 & 0 & 10 & 10 \\ -10 & -10 & 0 & -5 & 10 & 15 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0.4 \\ -0.2 \end{bmatrix} = \begin{bmatrix} -2 \\ -2 \\ 0 \\ 1 \\ 2 \\ 1 \end{bmatrix}$$

support reactions

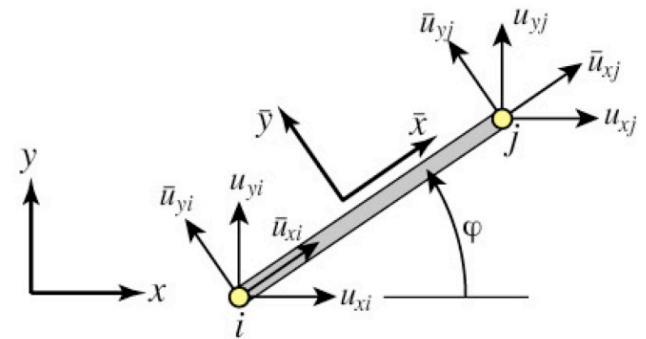
recovers applied external forces

Recovery of Internal Stress Through Displacements



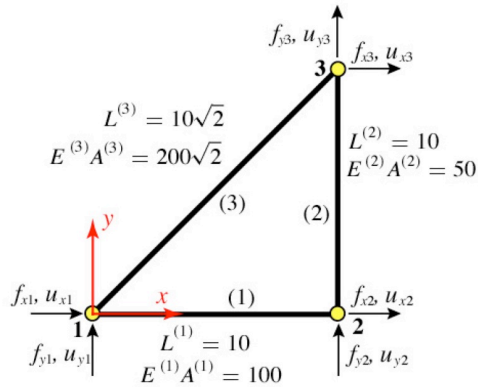
Transformation from global to local CS:

$$\underbrace{\begin{bmatrix} \bar{u}_{xi} \\ \bar{u}_{yi} \\ \bar{u}_{xj} \\ \bar{u}_{yj} \end{bmatrix}}_{\bar{\mathbf{u}}^e} = \underbrace{\begin{bmatrix} c & s & 0 & 0 \\ -s & c & 0 & 0 \\ 0 & 0 & c & s \\ 0 & 0 & -s & c \end{bmatrix}}_{\mathbf{T}^e} \underbrace{\begin{bmatrix} u_{xi} \\ u_{yi} \\ u_{xj} \\ u_{yj} \end{bmatrix}}_{\mathbf{u}^e}$$



Recovery of Internal Stress Through Displacements

Example: Bar 2



$$\begin{bmatrix} \bar{u}_{x2} \\ \bar{u}_{y2} \\ \bar{u}_{x3} \\ \bar{u}_{y3} \end{bmatrix} = \begin{bmatrix} \cos 90^\circ & \sin 90^\circ & 0 & 0 \\ -\sin 90^\circ & \cos 90^\circ & 0 & 0 \\ 0 & 0 & \cos 90^\circ & \sin 90^\circ \\ 0 & 0 & -\sin 90^\circ & \cos 90^\circ \end{bmatrix} \begin{bmatrix} u_{x2} \\ u_{y2} \\ u_{x3} \\ u_{y3} \end{bmatrix}$$

$$\begin{bmatrix} \bar{u}_{x2} \\ \bar{u}_{y2} \\ \bar{u}_{x3} \\ \bar{u}_{y3} \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 0.4 \\ -0.2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ -0.2 \\ -0.4 \end{bmatrix}$$

$$\Delta L^{(3)} = \bar{u}_{x3} - \bar{u}_{x2} = -0.2$$

$$F^{(3)} = \frac{(EA)^{(3)}}{L^{(3)}} \Delta L^{(3)} = -\frac{50}{10} 0.2 = -1$$

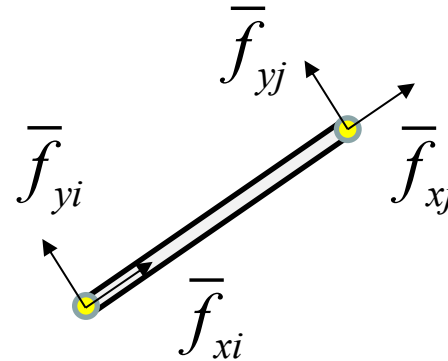
Recovery of Internal Stress Through Forces

Element Stiffness Equation in global CS:

$$\mathbf{f}^e = \mathbf{K}^e \mathbf{u}^e$$

Transformation from global to local CS:

$$\underbrace{\begin{bmatrix} \bar{f}_{xi} \\ \bar{f}_{yi} \\ \bar{f}_{xj} \\ \bar{f}_{yj} \end{bmatrix}}_{\mathbf{\bar{f}}^e} = \underbrace{\begin{bmatrix} c & s & 0 & 0 \\ -s & c & 0 & 0 \\ 0 & 0 & c & s \\ 0 & 0 & -s & c \end{bmatrix}}_{\mathbf{T}^e} \underbrace{\begin{bmatrix} f_{xi} \\ f_{yi} \\ f_{xj} \\ f_{yj} \end{bmatrix}}_{\mathbf{f}^e}$$



Note: for bar element

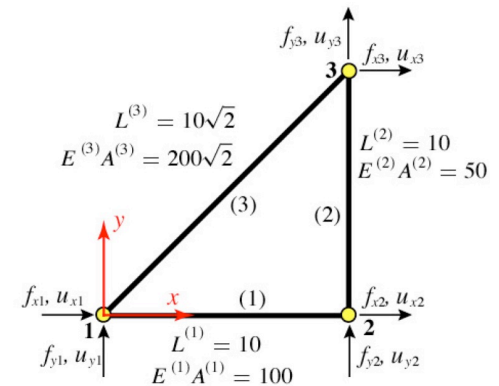
$$\bar{f}_{yi} = \bar{f}_{yj} = 0$$

Recovery of Internal Stress Through Forces

Example: Bar 2 Using nodal solution for Bar 2:

$$\mathbf{f}^e = \mathbf{K}^e \mathbf{u}^e$$

$$\begin{bmatrix} 0.0 \\ 1.0 \\ 0.0 \\ -1.0 \end{bmatrix} = 5 \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0.0 \\ 0.0 \\ 0.4 \\ -0.2 \end{bmatrix}$$

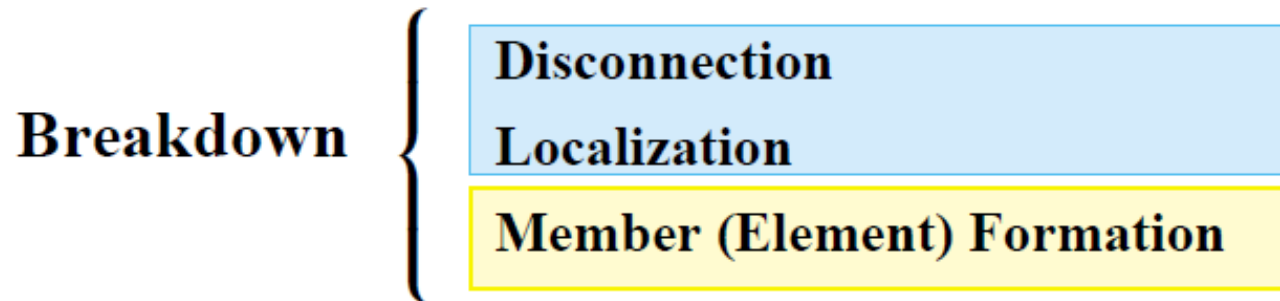



$$F = -\bar{f}_{xi} = -(c f_{xi} + s f_{yi}) \quad \text{or} \quad F = \bar{f}_{xj} = (c f_{xj} + s f_{yj})$$


$$\text{for } \cos 90 = 0 \quad \sin 90 = 1$$


$$F = -\bar{f}_{xi} = -(0 \cdot 0 + 1 \cdot 1) = -1 \quad \text{or} \quad F = \bar{f}_{xj} = (0 \cdot 0 + 1 \cdot -1) = -1$$

The Direct Stiffness Method



 *conceptual
steps*

 *processing
steps*

 *post-processing
steps*